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Chapter 1. C Language

This chapter describes the target specific features of the C language, including language extensions that are not standard in ISO-C. For example, pragmas are a way to control the compiler from within the C source.

The TASKING VX-toolset for ARM[®] C compiler fully supports the ISO-C standard and adds extra possibilities to program the special functions of the target.

In addition to the standard C language, the compiler supports the following:

- · attribute to specify alignment and absolute addresses
- · intrinsic (built-in) functions that result in target specific assembly instructions
- pragmas to control the compiler from within the C source
- predefined macros
- the possibility to use assembly instructions in the C source
- · keywords for inlining functions and programming interrupt routines
- libraries

All non-standard keywords have two leading underscores (___).

In this chapter the target specific characteristics of the C language are described, including the above mentioned extensions.

1.1. Data Types

The TASKING C compiler for the ARM supports the following data types.

С Туре	Size	Align	Limits
_Bool	1	8	0 or 1
signed char	8	8	[-2 ⁷ , 2 ⁷ -1]
unsigned char	8	8	[0, 2 ⁸ -1]
short	16	16	[-2 ¹⁵ , 2 ¹⁵ -1]
unsigned short	16	16	[0, 2 ¹⁶ -1]
int	32	32	[-2 ³¹ , 2 ³¹ -1]
unsigned int	32	32	[0, 2 ³² -1]
enum	32	32	[-2 ³¹ , 2 ³¹ -1]
long	32	32	[-2 ³¹ , 2 ³¹ -1]
unsigned long	32	32	[0, 2 ³² -1]
long long	64	64	[-2 ⁶³ , 2 ⁶³ -1]

С Туре	Size	Align	Limits
unsigned long long	64	64	[0, 2 ⁶⁴ -1]
float (23-bit mantissa)	32	32	[-3.402E+38, -1.175E-38] [+1.175E-38, +3.402E+38]
double long double (52-bit mantissa)	64	64	[-1.797E+308, -2.225E-308] [+2.225E-308, +1.797E+308]
_Imaginary float	32	32	[-3.402E+38i, -1.175E-38i] [+1.175E-38i, +3.402E+38i]
_Imaginary double _Imaginary long double	64	64	[-1.797E+308i, -2.225E-308i] [+2.225E-308i, +1.797E+308i]
_Complex float	64	32	real part + imaginary part
_Complex double _Complex long double	128	64	real part + imaginary part
pointer to data or function	32	32	[0, 2 ³² -1]

1.2. Changing the Alignment: __unaligned, __packed__ and __align()

Normally data, pointers and structure members are aligned according to the table in the previous section.

Suppress alignment

With the type qualifier <u>unaligned</u> you can specify to suppress the alignment of objects or structure members. This can be useful to create compact data structures. In this case the alignment will be one bit for bit-fields or one byte for other objects or structure members.

At the left side of a pointer declaration you can use the type qualifier <u>unaligned</u> to mark the pointer value as potentially unaligned. This can be useful to access externally defined data. However the compiler can generate less efficient instructions to dereference such a pointer, to avoid unaligned memory access.

You can always convert a normal pointer to an unaligned pointer. Conversions from an unaligned pointer to an aligned pointer are also possible. However, the compiler will generate a warning in this situation, with the exception of the following case: when the logical type of the destination pointer is char or void, no warning will be generated.

Example:

```
struct
{
    char c;
    __unaligned int i; /* aligned at offset 1 ! */
} s;
__unaligned int * up = & s.i;
```

Packed structures

To prevent alignment gaps in structures, you can use the attribute __packed__. When you use the attribute __packed__ directly after the keyword struct, all structure members are marked __unaligned. For example the following two declarations are the same:

```
struct __packed__
{
    char c;
    int i;
} s1;

struct
{
    __unaligned char c;
    __unaligned int i;
} s2;
```

The attribute __packed__ has the same effect as adding the type qualifier __unaligned to the declaration to suppress the standard alignment.

You can also use __packed__ in a pointer declaration. In that case it affects the alignment of the pointer itself, not the value of the pointer. The following two declarations are the same:

```
int * __unaligned p;
int * p __packed__;
```

Change alignment

With the attribute $__{align(n)}$ you can overrule the default alignment of objects or structure members to n bytes.

1.3. Placing an Object at an Absolute Address: __at()

With the attribute __at() you can specify an absolute address.

The compiler checks the address range, the alignment and if an object crosses a page boundary.

Examples

```
unsigned char Display[80*24] __at( 0x2000 );
```

The array <code>Display</code> is placed at address <code>0x2000</code>. In the generated assembly, an absolute section is created. On this position space is reserved for the variable <code>Display</code>.

```
int i _{at(0x1000)} = 1;
```

The variable i is placed at address 0x1000 and is initialized.

```
void f(void) __at( 0xf0ff + 1 ) { }
```

The function f is placed at address 0xf100.

Restrictions

Take note of the following restrictions if you place a variable at an absolute address:

- The argument of the __at() attribute must be a constant address expression.
- You can place only global variables at absolute addresses. Parameters of functions, or automatic variables within functions cannot be placed at absolute addresses.
- A variable that is declared extern, is not allocated by the compiler in the current module. Hence it is
 not possible to use the keyword __at() on an external variable. Use __at() at the definition of the
 variable.
- · You cannot place structure members at an absolute address.
- Absolute variables cannot overlap each other. If you declare two absolute variables at the same address, the assembler and/or linker issues an error. The compiler does not check this.

1.4. Using Assembly in the C Source: __asm()

With the keyword __asm you can use assembly instructions in the C source and pass C variables as operands to the assembly code. Be aware that C modules that contain assembly are not portable and harder to compile in other environments.

The compiler does not interpret assembly blocks, but passes the assembly code to the assembly source file; they are regarded as a black box. So, it is your responsibility to make sure that the assembly block is syntactically correct. Possible errors can only be detected by the assembler.

General syntax of the __asm keyword

__asm("instruction_template"

```
[ : output param list
         [ : input_param_list
         [ : register_save_list]] );
instruction template
                                   Assembly instructions that may contain parameters from the input
                                   list or output list in the form: \( \mathbb{p} arm_n r \]. regnum
      %parm_nr[.regnum]
                                   Parameter number in the range 0 .. 9. With the optional .regnum you
                                   can access an individual register from a register pair or register quad.
                                   For example, with register pair r0r1, .0 selects register r0.
                                   [[ "=[&]constraint_char"(C_expression)],...]
output_param_list
                                   [[ "constraint char"(C expression)],...]
input param list
      &
                                   Says that an output operand is written to before the inputs are read,
                                   so this output must not be the same register as any input.
      constraint char
                                   Constraint character: the type of register to be used for the
                                   C expression. See the table below.
      C expression
                                   Any C expression. For output parameters it must be an Ivalue, that
                                   is, something that is legal to have on the left side of an assignment.
```

register_save_list [["register_name"],...]

register_name Name of the register you want to reserve. Note that saving too much

registers can make register allocation impossible.

Specifying registers for C variables

With a *constraint character* you specify the register type for a parameter.

You can reserve the registers that are used in the assembly instructions, either in the parameter lists or in the reserved register list (*register_save_list*). The compiler takes account of these lists, so no unnecessary register saves and restores are placed around the inline assembly instructions.

Constraint character	Туре	Operand	Remark
R	general purpose register (64 bits)	r0 r11	Thumb mode r0 r7 Based on the specified register, a register pair is formed (64-bit). For example r0r1.
r	general purpose register	r0 r11, lr	Thumb mode r0 r7
i	immediate value	#value	
I	label	label	
m	memory label	variable	stack or memory operand, a fixed address
number	type of operand it is associated with	same as %number	Input constraint only. The <i>number</i> must refer to an output parameter. Indicates that %number and number are the same register. Use %number.0 and %number.1 to indicate the first and second half of a register pair when used in combination with R.

Loops and conditional jumps

The compiler does not detect loops with multiple __asm() statements or (conditional) jumps across __asm() statements and will generate incorrect code for the registers involved.

If you want to create a loop with __asm(), the whole loop must be contained in a single __asm() statement. The same counts for (conditional) jumps. As a rule of thumb, all references to a label in an __asm() statement must be in that same statement. You can use numeric labels for these purposes.

Example 1: no input or output

A simple example without input or output parameters. You can use any instruction or label. When it is required that a sequence of $_asm()$ statements generates a contiguous sequence of instructions, then they can be best combined to a single $_asm()$ statement. Compiler optimizations can insert instruction(s) in between $_asm()$ statements. Note that you can use standard C escape sequences. Use newline characters '\n' to continue on a new line in a $_asm()$ statement. For multi-line output, use tab characters '\t' to indent instructions.

Example 2: using output parameters

Assign the result of inline assembly to a variable. With the constraint \mathbf{r} a general purpose register is chosen for the parameter; the compiler decides which register it uses. The \$0 in the instruction template is replaced with the name of this register. The compiler generates code to assign the result to the output variable.

Generated assembly code:

```
mov r0,#0xff
ldr r1,.L2
str r0,[r1,#0]
bx lr
.size main,$-main
.align 4
.L2:
.dw out
```

Example 3: using input parameters

Assign a variable to a register. A register is chosen for the parameter because of the constraint r; the compiler decides which register is best to use. The \$0 in the instruction template is replaced with the name of this register. The compiler generates code to move the input variable to the input register. Because there are no output parameters, the output parameter list is empty. Only the colon has to be present.

Generated assembly code:

```
ldr r0,.L2
ldr r0,[r0,#0]
MOV R0,r0
bx lr
.size initreg,$-initreg
.align 4
```

```
.L2:
```

Example 4: using input and output parameters

Add two C variables and assign the result to a third C variable. Registers are used for the input and output parameters (constraint r, 0 for out, 1 for in1, 2 for in2 in the instruction template). The compiler generates code to move the input expressions into the input registers and to assign the result to the output variable.

```
int in1, in2, out;
void add32( void )
 __asm( "add %0, %1, %2"
        : "=r" (out)
        : "r" (in1), "r" (in2) );
Generated assembly code:
     ldr
             r0,.L2
     ldr
             r1,[r0,#0]
     ldr
             r0,[r0,#4]
     add r0, r1, r0
     ldr
             r1,.L2
     str
             r0,[r1,#8]
     bx
             lr
     .size
             add32,$-add32
     .align 4
.L2:
             in1
     .dw
     .section
                .bss
     .global in1
     .align 4
in1: .type
             object
     .size
             in1,4
     .ds
     .global in2
     .align 4
in2: .type
             object
     .size
             in2,4
     .ds
     .global out
     .align 4
out: .type
             object
```

.size

out,4

```
.ds 4
```

Example 5: reserving resisters

Sometimes an instruction knocks out certain specific registers. The most common example of this is a function call, where the called function is allowed to do whatever it likes with some registers. If this is the case, you can list specific registers that get clobbered by an operation after the inputs.

Same as Example 4, but now register r0 is a reserved register. You can do this by adding a reserved register list (: "r0"). As you can see in the generated assembly code, register r0 is not used (the first register used is r1).

Generated assembly code:

```
ldr
             r2,.L2
             r2,[r1,#0]
     ldr
    ldr
            r1,[r1,#4]
    add r1, r2, r1
    ldr
            r0,.L2
             r1,[r0,#8]
    str
    bx
             add32,$-add32
     .size
     .align 4
.L2:
     .dw
             in1
```

Example 6: input and output are the same

If the input and output must be the same you must use a number constraint. The following example increments the value of the input variable invar and returns this value to outvar. Since the assembly instruction has to use only one register, the return value has to go in the same place as the input value. Parameter %0 corresponds to outvar. To indicate that invar uses the same register as outvar, the input constraint '0' is used which indicates that invar also corresponds to %0.

```
int outvar;

void increment(int invar)
{
    __asm ("add %0, %1, #1": "=r"(outvar): "0"(invar) );
}
```

Generated assembly code:

```
increment: .type func
   add r0, r0, #1
   ldr   r1,.L2
   str   r0,[r1,#0]
   bx   lr
   .size   add32,$-add32
   .align 4
.L2:
   .dw   outvar
```

Example 7: accessing individual registers in a register pair

You can access the individual registers in a register pair by adding a '.' after the operand specifier in the assembly part, followed by the index in the register pair.

The first 1dr instruction uses index #0 of argument 2 (which is a double placed in a RxRy register) and the second 1dr instruction uses index #1. The input operand is located in register pair r2/r3. The assembly output becomes:

```
r2,r0
    mov
             r3,r1
    mov
     ldr r0, [r2, \#0]; selects r2 from r2/r3
    ldr r1, [r3, #0]; selects r3 from r2/r3
    ldr
             r2,.L2
    str
             r0,[r2,#0]
    str
             r1,[r2,#4]
    bx
            lr
            foo,$-foo
     .size
     .align 4
.L2:
     .dw
             out1
```

If the index is not a valid index (for example, the register is not a register pair, or the argument has not a register constraint), the '.' is passed into the assembly output. This way you can still use the '.' in assembly instructions.

1.5. Pragmas to Control the Compiler

Pragmas are keywords in the C source that control the behavior of the compiler. Pragmas overrule compiler options.

The syntax is:

```
#pragma pragma-spec pragma-arguments [on | off | default | restore]
or:
    _Pragma( "pragma-spec pragma-arguments [on | off | default | restore]" )
```

Some pragmas can accept the following special arguments:

on switch the flag on (same as without argument)

off switch the flag off

default set the pragma to the initial value

restore restore the previous value of the pragma

The compiler recognizes the following pragmas, other pragmas are ignored.

alias symbol=defined_symbol

Define *symbol* as an alias for *defined_symbol*. It corresponds to an equate directive (.EQU) at assembly level. The *symbol* should not be defined elsewhere, and *defined_symbol* should be defined with static storage duration (not extern or automatic).

call {near | far | default | restore}

By default, functions are called with 26-bit PC-relative calls. This *near* call is directly coded into the instruction, resulting in higher execution speed and smaller code size. The destination address of a near call must be located within +/-32 MB from the program counter.

The other call mode is a 32-bit indirect call. With *far* calls you can address the full range of memory. The address is first loaded into a register after which the call is executed.

See C compiler option --call (-m).

extension isuffix [on | off | default | restore]

Enables a language extension to specify imaginary floating-point constants. With this extension, you can use an "i" suffix on a floating-point constant, to make the type _Imaginary.

float 0.5i

extern symbol

Normally, when you use the C keyword extern, the compiler generates an .EXTERN directive in the generated assembly source. However, if the compiler does not find any references to the extern symbol in the C module, it optimizes the assembly source by leaving the .EXTERN directive out.

With this pragma you can force an external reference (.EXTERN assembler directive), even when the symbol is not used in the module.

inline / noinline / smartinline

See Section 1.8.2, Inlining Functions: inline.

macro / nomacro [on | off | default | restore]

Turns macro expansion on or off. By default, macro expansion is enabled.

message "message" ...

Print the message string(s) on standard output.

nomisrac [nr,...] [default | restore]

Without arguments, this pragma disables MISRA-C checking. Alternatively, you can specify a comma-separated list of MISRA-C rules to disable.

See C compiler option --misrac and Section 4.6, C Code Checking: MISRA-C.

optimize [flags | default | restore] / endoptimize

You can overrule the C compiler option --optimize for the code between the pragmas optimize and endoptimize. The pragma works the same as C compiler option --optimize.

See Section 4.5, Compiler Optimizations.

profile [flags | default | restore] / endprofile

Control the profile settings. The pragma works the same as C compiler option --profile. Note that this pragma will only be checked at the start of a function. endprofile switches back to the previous profiling settings.

profiling [on | off | default | restore]

If profiling is enabled on the command line (C compiler option --profile), you can disable part of your source code for profiling with the pragmas profiling off and profiling.

protect [on | off | default | restore] / endprotect

With these pragmas you can protect sections against linker optimizations. This excludes a section from unreferenced section removal and duplicate section removal by the linker. endprotect restores the default section protection.

runtime [flags | default | restore]

With this pragma you can control the generation of additional code to check for a number of errors at run-time. The pragma argument syntax is the same as for the arguments of the C compiler option --runtime. You can use this pragma to control the run-time checks for individual statements. In addition, objects declared when the "bounds" sub-option is disabled are not bounds checked. The "malloc" sub-option cannot be controlled at statement level, as it only extracts an alternative malloc implementation from the library.

section [name=]{suffix |-f|-m|-fm} [default | restore] / endsection

Rename sections by adding a *suffix* to all section names specified with *name*, or restore default section naming. If you specify only a *suffix* (without a name), the suffix is added to all section names. See C compiler option --rename-sections and assembler directive . SECTION for more information.

section_code_init [on | off | default | restore] / section_no_code_init

Copy or do not copy code sections from ROM to RAM at application startup.

section_const_init [on | off | default | restore] / section_no_const_init

Copy or do not copy read-only data sections from ROM to RAM at application startup.

source [on | off | default | restore] / nosource

With these pragmas you can choose which C source lines must be listed as comments in assembly output.

See C compiler option --source.

stdinc [on | off | default | restore]

This pragma changes the behavior of the #include directive. When set, the C compiler options --include-directory and --no-stdinc are ignored.

linear_switch / jump_switch / binary_switch / smart_switch / tbb_switch / tbh_switch / no tbh_switch

With these pragmas you can overrule the compiler chosen switch method:

linear_switch Force jump chain code. A jump chain is comparable with an if/else-if/else construction.

jump_switch	Force jump table code. A jump table is a table filled with jump instructions for each possible switch value. The switch argument is used as an index to jump within this table.
binary_switch	Force binary lookup table code. A binary search table is a table filled with a value to compare the switch argument with and a target address to jump to.
smart_switch	Let the compiler decide the switch method used.
tbb_switch	Force use of the tbb instruction. Uses a table of 8-bit jump offsets.
tbh_switch	Force use of the tbh instruction. Uses a table of 8-bit jump offsets.
no_tbh_switch	Same as smart_switch, but do not use the tbh instruction.

See Section 1.7, Switch Statement.

tradeoff {level | default | restore}

Specify tradeoff between speed (0) and size (4). See C compiler option --tradeoff

warning [number,...] [default | restore]

With this pragma you can disable warning messages. If you do not specify a warning number, all warnings will be suppressed.

weak symbol

Mark a symbol as "weak" (. WEAK assembler directive). The symbol must have external linkage, which means a global or external object or function. A static symbol cannot be declared weak.

A weak external reference is resolved by the linker when a global (or weak) definition is found in one of the object files. However, a weak reference will not cause the extraction of a module from a library to resolve the reference. When a weak external reference cannot be resolved, the null pointer is substituted.

A weak definition can be overruled by a normal global definition. The linker will not complain about the duplicate definition, and ignore the weak definition.

1.6. Predefined Preprocessor Macros

The TASKING C compiler supports the predefined macros as defined in the table below. The macros are useful to create conditional C code.

Macro	Description
ARM	Expands to 1 for the ARM toolset, otherwise unrecognized as macro.
BIG_ENDIAN	Expands to 1 if big-endian mode is selected (optionendianness=big), otherwise unrecognized as macro.

Macro	Description
BUILD	Identifies the build number of the compiler, composed of decimal digits for the build number, three digits for the major branch number and three digits for the minor branch number. For example, if you use build 1.22.1 of the compiler,BUILD expands to 1022001. If there is no branch number, the branch digits expand to zero. For example, build 127 results in 127000000.
CARM	Expands to 1 for the ARM toolset, otherwise unrecognized as macro.
CPU	Expands to the ARM architecture name (optioncpu=arch. When nocpu is supplied, this symbol is not defined.
CPU_arch	A symbol is defined depending on the optioncpu=arch. The arch is converted to uppercase. For example, ifcpu=ARMv4T is specified the symbolCPU_ARMV4T is defined. When nocpu is supplied, this symbolCPU_ARMV4T is the default.
DATE	Expands to the compilation date: "mmm dd yyyy".
DOUBLE_FP	Expands to 1 if you did not use optionno-double (Treat 'double' as 'float'), otherwise unrecognized as macro.
DSPC	Indicates conformation to the DSP-C standard. It expands to 1.
DSPC_VERSION	Expands to the decimal constant 200001L.
FILE	Expands to the current source file name.
LINE	Expands to the line number of the line where this macro is called.
LITTLE_ENDIAN	Expands to 1 if little-endian mode is selected (optionendianness=little), otherwise unrecognized as macro. This is the default.
PROF_ENABLE	Expands to 1 if profiling is enabled, otherwise expands to 0.
REVISION	Expands to the revision number of the compiler. Digits are represented as they are; characters (for prototypes, alphas, betas) are represented by -1. Examples: v1.0r1 -> 1, v1.0rb -> -1
SINGLE_FP	Expands to 1 if you used optionno-double (Treat 'double' as 'float'), otherwise unrecognized as macro.
STDC	Identifies the level of ANSI standard. The macro expands to 1 if you set optionlanguage (Control language extensions), otherwise expands to 0.
STDC_HOSTED	Always expands to 0, indicating the implementation is not a hosted implementation.
STDC_VERSION	Identifies the ISO-C version number. Expands to 199901L for ISO C99 or 199409L for ISO C90.
TASKING	Identifies the compiler as a TASKING compiler. Expands to 1 if a TASKING compiler is used.
THUMB	Expands to 1 if you used optionthumb, otherwise unrecognized as macro.
TIME	Expands to the compilation time: "hh:mm:ss"

Macro	Description
	Identifies the version number of the compiler. For example, if you use version 3.0r1 of the compiler,VERSION expands to 3000 (dot and revision number are omitted, minor version number in 3 digits).

Example

```
#ifdef __CARM__
/* this part is only compiled for the ARM */
...
#endif
```

1.7. Switch Statement

The TASKING C compiler supports three ways of code generation for a switch statement: a jump chain (linear switch), a jump table or a binary search table.

A *jump chain* is comparable with an if/else-if/else construction. A *jump table* is a table filled with jump instructions for each possible switch value. The switch argument is used as an index to jump within this table. A *binary search table* is a table filled with a value to compare the switch argument with and a target address to jump to.

#pragma smart_switch is the default of the compiler. The compiler tries to use the switch method which uses the least space in ROM (table size in ROMDATA plus code to do the indexing). With the C compiler option --tradeoff you can tell the compiler to emphasis more on speed than on ROM size.

For a switch with a long type argument, only binary search table code is used.

For an int type argument, a jump table switch is only possible when all case values are in the same 256 value range (the high byte value of all programmed cases are the same).

Especially for large switch statements, the jump table approach executes faster than the binary search table approach. Also the jump table has a predictable behavior in execution speed: independent of the switch argument, every case is reached in the same execution time. However, when the case labels are distributed far apart, the jump table becomes sparse, wasting code memory. The compiler will not use the jump table method when the waste becomes excessive.

With a small number of cases, the jump chain method can be faster in execution and shorter in size.

For ARMv7M a switch using the tbh instruction gets priority over a normal switch table implementation.

How to overrule the default switch method

You can overrule the compiler chosen switch method by using a pragma:

<pre>#pragma linear_switch</pre>	force jump chain code
<pre>#pragma jump_switch</pre>	force jump table code
<pre>#pragma binary_switch</pre>	force binary search table code
#pragma smart switch	let the compiler decide the switch method used

```
#pragma tbb_switch force use of tbb instruction (uses a table of 8-bit jump offsets)

#pragma tbh_switch force use of tbh instruction (uses a table of 16-bit jump offsets)

#pragma no_tbh_switch same as smart_switch, but do not use tbh instruction
```

Using a pragma cannot overrule the restrictions as described earlier.

The switch pragmas must be placed before the switch statement. Nested switch statements use the same switch method, unless the nested switch is implemented in a separate function which is preceded by a different switch pragma.

Example:

```
/* place pragma before function body */
#pragma jump_switch

void test(unsigned char val)
{ /* function containing the switch */
    switch (val)
    {
        /* use jump table */
    }
}
```

1.8. Functions

1.8.1. Calling Convention

Parameter Passing

A lot of execution time of an application is spent transferring parameters between functions. The fastest parameter transport is via registers. Therefore, function parameters are first passed via registers. If no more registers are available for a parameter, the compiler pushes parameters on the stack.

Registers available for parameter passing are r0, r1, r2 and r3.

Parameter Type	Registers used for parameters
_Bool, char, short, int, long, float, 32-bit pointer, 32-bit struct	R0, R1, R2, R3
long long, double, 64-bit struct	R0R1, R1R2, R2R3

The parameters are processed from left to right. The first not used and fitting register is used. Registers are searched for in the order listed above. When a parameter is > 64 bit, or all registers are used, parameter passing continues on the stack. The stack grows from higher towards lower addresses. The first parameter is pushed at the lowest stack address. The alignment on the stack depends on the data type as listed in Section 1.1, Data Types.

Examples:

Function Return Values

The C compiler uses registers to store C function return values, depending on the function return types.

Return Type	Register
_Bool, char, short, int, long, float, 32-bit pointer, 32-bit struct	R0
long long, double, 64-bit struct	R0R1

Objects larger than 64 bits are returned via the stack.

1.8.2. Inlining Functions: inline

With the C compiler option --optimize=+inline, the C compiler automatically inlines small functions in order to reduce execution time (smart inlining). The compiler inserts the function body at the place the function is called. The C compiler decides which functions will be inlined. You can overrule this behavior with the two keywords inline (ISO-C) and __noinline.

With the inline keyword you force the compiler to inline the specified function, regardless of the optimization strategy of the compiler itself:

```
inline unsigned int abs(int val)
{
    unsigned int abs_val = val;
    if (val < 0) abs_val = -val;
    return abs_val;
}</pre>
```

If a function with the keyword inline is not called at all, the compiler does not generate code for it.

You must define inline functions in the same source module as in which you call the function, because the compiler only inlines a function in the module that contains the function definition. When you need to call the inline function from several source modules, you must include the definition of the inline function in each module (for example using a header file).

With the __noinline keyword, you prevent a function from being inlined:

```
__noinline unsigned int abs(int val)
{
    unsigned int abs_val = val;
    if (val < 0) abs_val = -val;
    return abs_val;
}</pre>
```

Using pragmas: inline, noinline, smartinline

Instead of the inline qualifier, you can also use #pragma inline and #pragma noinline to inline a function body:

```
#pragma inline
unsigned int abs(int val)
{
    unsigned int abs_val = val;
    if (val < 0) abs_val = -val;
    return abs_val;
}
#pragma noinline
void main( void )
{
    int i;
    i = abs(-1);
}</pre>
```

If a function has an inline/__noinline function qualifier, then this qualifier will overrule the current pragma setting.

With the #pragma noinline/#pragma smartinline you can temporarily disable the default behavior that the C compiler automatically inlines small functions when you turn on the C compiler option --optimize=+inline.

With the C compiler options --inline-max-incr and --inline-max-size you have more control over the automatic function inlining process of the compiler.

Combining inline with __asm to create intrinsic functions

With the keyword __asm it is possible to use assembly instructions in the body of an inline function. Because the compiler inserts the (assembly) body at the place the function is called, you can create your own intrinsic function. See Section 1.8.4.1, Writing Your Own Intrinsic Function.

1.8.3. Interrupt Functions / Exception Handlers

The TASKING C compiler supports a number of function qualifiers and keywords to program exception handlers. An exception handler (or: interrupt function) is called when an exception occurs.

The ARM supports seven types of exceptions. The next table lists the types of exceptions and the processor mode that is used to process that exception. When an exception occurs, execution is forced from a fixed memory address corresponding to the type of exception. These fixed addresses are called the exception vectors.

Exception type	Mode	Normal address	High vector address	Function type qualifier
Reset	Supervisor	0x00000000	0xFFFF0000	
Undefined instructions	Undefined	0x0000004	0xFFFF0004	interrupt_und

Exception type	Mode	Normal address	High vector address	Function type qualifier
Supervisor call (software interrupt)	Supervisor	0x00000008	0xFFFF0008	interrupt_svc
Prefetch abort	Abort	0x000000C	0xFFFF000C	interrupt_iabt
Data abort	Abort	0x0000010	0xFFFF0010	interrupt_dabt
IRQ (interrupt)	IRQ	0x00000018	0xFFFF0018	interrupt_irq
FIQ (fast interrupt)	FIQ	0x000001C	0xFFFF001C	interrupt_fiq

ARMv6-M and ARMv7-M (M-profile architectures) have a different exception model. Read the *ARM Architecture Reference Manual* for details.

1.8.3.1. Defining an Exception Handler: __interrupt Keywords

```
You can define six types of exception handlers with the function type qualifiers __interrupt_und, __interrupt_svc, __interrupt_iabt, __interrupt_dabt, __interrupt_irq and __interrupt_fiq. You can also use the general __interrupt() function qualifier.
```

Interrupt functions and other exception handlers cannot return anything and must have a **void** argument type list:

```
void __interrupt_xxx
isr( void )
{
...
}
void __interrupt(n)
isr2( void )
{
...
}
```

Example

```
void __interrupt_irq serial_receive( void )
{
    ...
}
```

Vector symbols

When you use one or more of these <u>__interrupt_xxx</u> function qualifiers, the compiler generates a corresponding vector symbol to designate the start of an exception handler function. The linker uses this symbol to automatically generate the exception vector.

Function type qualifier	Vector symbol	Vector symbol M-profile
interrupt_und	_vector_1	-
interrupt_svc	_vector_2	_vector_11
interrupt_iabt	_vector_3	-
interrupt_dabt	_vector_4	-
interrupt_irq	_vector_6	-
interrupt_fiq	_vector_7	-
interrupt(n)	_vector_n	_vector_n

Note that the reset handler is designated by the symbol _START instead of _vector_0 (_vector_1 for M-profile architectures).

You can prevent the compiler from generating the _vector_n symbol by specifying the function qualifier __novector. This can be necessary if you have more than one interrupt handler for the same exception, for example for different IRQ's or for different run-time phases of your application. Without the __novector function qualifier the compiler generates the _vector_n symbol multiple times, which results in a link error.

```
void __interrupt_irq __novector another_handler( void )
{
    ... // used __novector to prevent multiple _vector_6 symbols
}
```

Enable interrupts in exception handlers (not for M-profile architectures)

Normally interrupts are disabled when an exception handler is entered. With the function qualifier __nesting_enabled you can force that the link register (LR) is saved and that interrupts are enabled. For example:

```
void __interrupt_svc __nesting_enabled svc( int n )
{
   if ( n == 2 )
   {
      __svc(3);
   }
   ...
}
```

1.8.3.2. Interrupt Frame: __frame()

With the function type qualifier __frame() you can specify which registers and SFRs must be saved for a particular interrupt function. Only the specified registers will be pushed and popped from the stack. If you do not specify the function qualifier __frame(), the C compiler determines which registers must be pushed and popped. The syntax is:

```
void __interrupt_xxx
    __frame(reg[, reg]...) isr( void )
{
```

```
. . .
}
```

where, *reg* can be any register defined as an SFR. The compiler generates a warning if some registers are missing which are normally required to be pushed and popped in an interrupt function prolog and epilog to avoid run-time problems.

Example

```
__interrupt_irq __frame(R4,R5,R6) void alarm( void )
{
...
}
```

1.8.4. Intrinsic Functions

Some specific assembly instructions have no equivalence in *C. Intrinsic functions* give the possibility to use these instructions. Intrinsic functions are predefined functions that are recognized by the compiler. The compiler generates the most efficient assembly code for these functions.

The compiler always inlines the corresponding assembly instructions in the assembly source (rather than calling it as a function). This avoids parameter passing and register saving instructions which are normally necessary during function calls.

Intrinsic functions produce very efficient assembly code. Though it is possible to inline assembly code by hand, intrinsic functions use registers even more efficiently. At the same time your C source remains very readable.

You can use intrinsic functions in C as if they were ordinary C (library) functions. All intrinsics begin with a double underscore character (___).

The TASKING ARM C compiler recognizes the following intrinsic functions:

alloc

```
void * volatile __alloc( __size_t size );
```

Allocate memory. Returns a pointer to space of size bytes on the stack of the calling function. Memory allocated through this function is freed when the calling function returns. This function is used internally for variable length arrays, it is not to be used by end users.

free

```
void volatile __free( void *p );
```

Deallocates the memory pointed to by p. p must point to memory earlier allocated by a call to __alloc().

__nop

```
void __nop( void );
```

Generate NOP instruction.

__get_return_address

```
__codeptr volatile __get_return_address( void );
```

Used by the compiler for profiling when you compile with the option --profile. Returns the return address of a function.

__getspsr

```
unsigned int volatile __getspsr( void );
```

Get the value of the SPSR status register. Returns the value of the status register SPSR.

__setspsr

```
unsigned int volatile __setspsr( int set, int clear);
```

Set or clear bits in the SPSR status register. Returns the new value of the SPSR status register.

Example:.

__getcpsr

```
unsigned int volatile __getcpsr( void );
```

Get the value of the CPSR status register. Returns the value of the status register CPSR.

__setcpsr

```
unsigned int volatile __setcpsr( int set, int clear);
```

Set or clear bits in the CPSR status register. Returns the new value of the CPSR status register.

__getapsr

```
unsigned int volatile __getapsr( void );
```

Get the value of the APSR status register (ARMv6-M and ARMv7-M). Returns the value of the status register APSR.

__setapsr

```
unsigned int volatile __setapsr( int set, int clear);
```

Set or clear bits in the APSR status register (ARMv6-M and ARMv7-M). Returns the new value of the APSR status register.

__getipsr

```
unsigned int volatile __getipsr( void );
```

Get the value of the IPSR status register (ARMv6-M and ARMv7-M). Returns the value of the status register IPSR.

__SVC

```
void volatile __svc(int number);
```

Generates a supervisor call (software interrupt). Number must be a constant value.

1.8.4.1. Writing Your Own Intrinsic Function

Because you can use any assembly instruction with the __asm() keyword, you can use the __asm() keyword to create your own intrinsic functions. The essence of an intrinsic function is that it is inlined.

- 1. First write a function with assembly in the body using the keyword __asm(). See Section 1.4, *Using Assembly in the C Source:* __asm()
- 2. Next make sure that the function is inlined rather than being called. You can do this with the function qualifier inline. This qualifier is discussed in more detail in Section 1.8.2, *Inlining Functions: inline*.

```
inline int __my_pow( int base, int power )
{
    int result;

    __asm( "mov %0,%1\n"
        "1:\n\t"
        "subs %2,%2,#1\n\t"
        "mulne %0,%0,%1\n\t"
        "bne lp\n\t", %2"
        : "=&r"(result)
        : "r"(base), "r"(power) );

    return result;
}

void main(void)
{
    int result;
```

```
// call to function __my_pow
   result = _{my_pow(3,2)};
}
Generated assembly code:
main:
       .type func
    ; __my_pow code is inlined here
               r0,#2
        mov
             r1,#3
        mov
        mov r2,r1
1:
        subs r0,r0,#1
        mulne r2,r2,r1
        bne
             1p
```

As you can see, the generated assembly code for the function $__{my_pow}$ is inlined rather than called. Numeric labels are used for the loop.

Chapter 2. C++ Language

The TASKING C++ compiler (**cparm**) offers a new approach to high-level language programming for your ARM architecture. The C++ compiler accepts the C++ language as defined by the ISO/IEC 14882:1998 standard and modified by TC1 for that standard. It also accepts the language extensions of the C compiler (see Chapter 1, *C Language*).

This chapter describes the C++ language implementation and some specific features.

Note that the C++ language itself is not described in this document. For more information on the C++ language, see

- The C++ Programming Language (second edition) by Bjarne Straustrup (1991, Addison Wesley)
- ISO/IEC 14882:1998 C++ standard [ANSI] More information on the standards can be found at http://www.ansi.org/

2.1. C++ Language Extension Keywords

The C++ compiler supports the same language extension keywords as the C compiler. When option --strict is used, the extensions will be disabled.

Additionally the following language extensions are supported:

attributes

Attributes, introduced by the keyword __attribute__, can be used on declarations of variables, functions, types, and fields. The alias, aligned, cdecl, const, constructor, deprecated, destructor, format, format_arg, init_priority, malloc, mode, naked, no_check_memory_usage, no_instrument_function, nocommon, noreturn, packed, pure, section, sentinel, stdcall, transparent_union, unused, used, visibility, volatile, and weak attributes are supported.

pragmas

The C++ compiler supports the same pragmas as the C compiler and some extra pragmas as explained in Section 2.7, *Pragmas to Control the C++ Compiler*. Pragmas give directions to the code generator of the compiler.

2.2. C++ Dialect Accepted

The C++ compiler accepts the C++ language as defined by the ISO/IEC 14882:1998 standard and modified by TC1 for that standard.

Command line options are also available to enable and disable anachronisms and strict standard-conformance checking.

2.2.1. Standard Language Features Accepted

The following features not in traditional C++ (the C++ language of "The Annotated C++ Reference Manual" by Ellis and Stroustrup (ARM)) but in the standard are implemented:

- The dependent statement of an if, while, do-while, or for is considered to be a scope, and the restriction on having such a dependent statement be a declaration is removed.
- The expression tested in an if, while, do-while, or for, as the first operand of a "?" operator, or as an operand of the "&&", ":", or "!"operators may have a pointer-to-member type or a class type that can be converted to a pointer-to-member type in addition to the scalar cases permitted by the ARM.
- Qualified names are allowed in elaborated type specifiers.
- A global-scope qualifier is allowed in member references of the form x.::A::B and p->::A::B.
- The precedence of the third operand of the "?" operator is changed.
- If control reaches the end of the main() routine, and main() has an integral return type, it is treated as if a return 0; statement were executed.
- Pointers to arrays with unknown bounds as parameter types are diagnosed as errors.
- A functional-notation cast of the form A() can be used even if A is a class without a (nontrivial) constructor. The temporary created gets the same default initialization to zero as a static object of the class type.
- A cast can be used to select one out of a set of overloaded functions when taking the address of a function.
- Template friend declarations and definitions are permitted in class definitions and class template definitions.
- Type template parameters are permitted to have default arguments.
- Function templates may have nontype template parameters.
- A reference to const volatile cannot be bound to an rvalue.
- Qualification conversions, such as conversion from T** to T const * const * are allowed.
- Digraphs are recognized.
- Operator keywords (e.g., not, and, bitand, etc.) are recognized.
- Static data member declarations can be used to declare member constants.
- When option --wchar t-keyword is set, wchar t is recognized as a keyword and a distinct type.
- bool is recognized.
- RTTI (run-time type identification), including dynamic_cast and the typeid operator, is implemented.

- Declarations in tested conditions (in if, switch, for, and while statements) are supported.
- Array new and delete are implemented.
- New-style casts (static_cast, reinterpret_cast, and const_cast) are implemented.
- Definition of a nested class outside its enclosing class is allowed.
- mutable is accepted on non-static data member declarations.
- Namespaces are implemented, including using declarations and directives. Access declarations are broadened to match the corresponding using declarations.
- Explicit instantiation of templates is implemented.
- The typename keyword is recognized.
- explicit is accepted to declare non-converting constructors.
- The scope of a variable declared in the for-init-statement of a for loop is the scope of the loop (not the surrounding scope).
- Member templates are implemented.
- The new specialization syntax (using "template <>") is implemented.
- Cv-qualifiers are retained on rvalues (in particular, on function return values).
- The distinction between trivial and nontrivial constructors has been implemented, as has the distinction between PODs and non-PODs with trivial constructors.
- The linkage specification is treated as part of the function type (affecting function overloading and implicit conversions).
- extern inline functions are supported, and the default linkage for inline functions is external.
- A typedef name may be used in an explicit destructor call.
- · Placement delete is implemented.
- An array allocated via a placement new can be deallocated via delete.
- Covariant return types on overriding virtual functions are supported.
- enum types are considered to be non-integral types.
- Partial specialization of class templates is implemented.
- Partial ordering of function templates is implemented.
- Function declarations that match a function template are regarded as independent functions, not as "guiding declarations" that are instances of the template.
- It is possible to overload operators using functions that take enum types and no class types.

- Explicit specification of function template arguments is supported.
- Unnamed template parameters are supported.
- The new lookup rules for member references of the form x.A::B and p->A::B are supported.
- The notation :: template (and ->template, etc.) is supported.
- In a reference of the form f()->g(), with g a static member function, f() is evaluated. The ARM specifies that the left operand is not evaluated in such cases.
- enum types can contain values larger than can be contained in an int.
- Default arguments of function templates and member functions of class templates are instantiated only
 when the default argument is used in a call.
- String literals and wide string literals have const type.
- Class name injection is implemented.
- Argument-dependent (Koenig) lookup of function names is implemented.
- Class and function names declared only in unqualified friend declarations are not visible except for functions found by argument-dependent lookup.
- A void expression can be specified on a return statement in a void function.
- Function-try-blocks, i.e., try-blocks that are the top-level statements of functions, constructors, or destructors, are implemented.
- Universal character set escapes (e.g., \uabcd) are implemented.
- On a call in which the expression to the left of the opening parenthesis has class type, overload resolution looks for conversion functions that can convert the class object to pointer-to-function types, and each such pointed-to "surrogate function" type is evaluated alongside any other candidate functions.
- Dependent name lookup in templates is implemented. Nondependent names are looked up only in the
 context of the template definition. Dependent names are also looked up in the instantiation context, via
 argument-dependent lookup.
- Value-initialization is implemented. This form of initialization is indicated by an initializer of "()" and causes zeroing of certain POD-typed members, where the usual default-initialization would leave them uninitialized.
- A partial specialization of a class member template cannot be added outside of the class definition.
- Qualification conversions may be performed as part of the template argument deduction process.
- The export keyword for templates is implemented.

2.2.2. C++0x Language Features Accepted

The following features added in the working paper for the next C++ standard (expected to be completed in 2009 or later) are enabled in C++0x mode (with option --c++0x). Several of these features are also enabled in default (nonstrict) C++ mode.

• A "right shift token" (>>) can be treated as two closing angle brackets. For example:

 The friend class syntax is extended to allow nonclass types as well as class types expressed through a typedef or without an elaborated type name. For example:

Mixed string literal concatenations are accepted (a feature carried over from C99):

```
wchar_t *str = "a" L"b"; // OK, same as L"ab".
```

- Variadic macros and empty macro arguments are accepted, as in C99.
- A trailing comma in the definition of an enumeration type is silently accepted (a feature carried over from C99):

```
enum E \{ e, \};
```

- If the command line option --long-long is specified, the type long long is accepted. Unsuffixed integer literals that cannot be represented by type long, but could potentially be represented by type unsigned long, have type long long instead (this matches C99, but not the treatment of the long long extension in C89 or default C++ mode).
- The keyword typename followed by a qualified-id can appear outside a template declaration.

2.2.3. Anachronisms Accepted

The following anachronisms are accepted when anachronisms are enabled (with --anachronisms):

- overload is allowed in function declarations. It is accepted and ignored.
- Definitions are not required for static data members that can be initialized using default initialization.
 The anachronism does not apply to static data members of template classes; they must always be defined.
- The number of elements in an array may be specified in an array delete operation. The value is
 ignored.
- A single operator++() and operator--() function can be used to overload both prefix and postfix operations.
- The base class name may be omitted in a base class initializer if there is only one immediate base class.
- Assignment to this in constructors and destructors is allowed. This is allowed only if anachronisms
 are enabled and the "assignment to this" configuration parameter is enabled.
- A bound function pointer (a pointer to a member function for a given object) can be cast to a pointer to a function.
- A nested class name may be used as a non-nested class name provided no other class of that name has been declared. The anachronism is not applied to template classes.
- A reference to a non-const type may be initialized from a value of a different type. A temporary is created, it is initialized from the (converted) initial value, and the reference is set to the temporary.
- A reference to a non-const class type may be initialized from an rvalue of the class type or a derived class thereof. No (additional) temporary is used.
- A function with old-style parameter declarations is allowed and may participate in function overloading
 as though it were prototyped. Default argument promotion is not applied to parameter types of such
 functions when the check for compatibility is done, so that the following declares the overloading of
 two functions named f:

```
int f(int);
int f(x) char x; { return x; }
```

Note that in C this code is legal but has a different meaning: a tentative declaration of £ is followed by its definition.

 When option --nonconst-ref-anachronism is set, a reference to a non-const class can be bound to a class rvalue of the same type or a derived type thereof.

```
struct A {
   A(int);
   A operator=(A&);
   A operator+(const A&);
```

```
};
main () {
    A b(1);
    b = A(1) + A(2); // Allowed as anachronism
}
```

2.2.4. Extensions Accepted in Normal C++ Mode

The following extensions are accepted in all modes (except when strict ANSI/ISO violations are diagnosed as errors or were explicitly noted):

• A friend declaration for a class may omit the class keyword:

```
class A {
    friend B; // Should be "friend class B"
};
```

• Constants of scalar type may be defined within classes:

```
class A {
    const int size = 10;
    int a[size];
};
```

• In the declaration of a class member, a qualified name may be used:

```
struct A {
   int A::f(); // Should be int f();
};
```

- The restrict keyword is allowed.
- Implicit type conversion between a pointer to an extern "C" function and a pointer to an extern "C++" function is permitted. Here's an example:

This extension is allowed in environments where C and C++ functions share the same calling conventions. It is enabled by default.

A "?" operator whose second and third operands are string literals or wide string literals can be implicitly converted to "char *" or "wchar_t *". (Recall that in C++ string literals are const. There is a deprecated implicit conversion that allows conversion of a string literal to "char *", dropping the const. That conversion, however, applies only to simple string literals. Allowing it for the result of a "?" operation is an extension.)

```
char *p = x ? "abc" : "def";
```

- Default arguments may be specified for function parameters other than those of a top-level function declaration (e.g., they are accepted on typedef declarations and on pointer-to-function and pointer-to-member-function declarations).
- Non-static local variables of an enclosing function can be referenced in a non-evaluated expression (e.g., a sizeof expression) inside a local class. A warning is issued.
- In default C++ mode, the friend class syntax is extended to allow nonclass types as well as class types expressed through a typedef or without an elaborated type name. For example:

 In default C++ mode, mixed string literal concatenations are accepted. (This is a feature carried over from C99 and also available in GNU modes).

```
wchar_t *str = "a" L"b"; // OK, same as L"ab".
```

- In default C++ mode, variadic macros are accepted. (This is a feature carried over from C99 and also available in GNU modes.)
- In default C++ mode, empty macro arguments are accepted (a feature carried over from C99).
- A trailing comma in the definition of an enumeration type is silently accepted (a feature carried over from C99):

```
enum E \{ e, \};
```

2.3. GNU Extensions

The C++ compiler can be configured to support the GNU C++ mode (command line option --g++). In this mode, many extensions provided by the GNU C++ compiler are accepted. The following extensions are provided in GNU C++ mode.

- · Extended designators are accepted
- · Compound literals are accepted.
- · Non-standard anonymous unions are accepted

The typeof operator is supported. This operator can take an expression or a type (like the sizeof operator, but parentheses are always required) and expands to the type of the given entity. It can be used wherever a typedef name is allowed

```
typeof(2*2.3) d; // Declares a "double"
typeof(int) i; // Declares an "int"
```

This can be useful in macro and template definitions.

• The __extension__ keyword is accepted preceding declarations and certain expressions. It has no effect on the meaning of a program.

```
__extension__ __inline__ int f(int a) {
    return a > 0 ? a/2 : f(__extension__ 1-a);
}
```

• In all GNU C modes and in GNU C++ modes with gnu_version < 30400, the type modifiers signed, unsigned, long and short can be used with typedef types if the specifier is valid with the underlying type of the typedef in ANSI C. E.g.:

- If the command line option --long-long is specified, the extensions for the long long and unsigned long long types are enabled.
- Zero-length array types (specified by [0]) are supported. These are complete types of size zero.
- C99-style flexible array members are accepted. In addition, the last field of a class type have a class type whose last field is a flexible array member. In GNU C++ mode, flexible array members are treated exactly like zero-length arrays, and can therefore appear anywhere in the class type.
- The C99 Pragma operator is supported.
- The gcc built-in <stdarg.h> and <varargs.h> facilities (__builtin_va_list, __builtin_va_arg, ...) are accepted.
- The sizeof operator is applicable to void and to function types and evaluates to the value one.
- Variables can be redeclared with different top-level cv-qualifiers (the new qualification is merged into existing qualifiers). For example:

• The "assembler name" of variables and routines can be specified. For example:

```
int counter __asm__("counter_v1") = 0;
```

Register variables can be mapped on specific registers using the asm keyword.

```
register int i asm("eax");
    // Map "i" onto register eax.
```

- The keyword inline is ignored (with a warning) on variable declarations and on block-extern function declarations.
- · Excess aggregate initializers are ignored with a warning.

```
struct S { int a, b; };
struct S a1 = { 1, 2, 3 };
    // "3" ignored with a warning; no error
int a2[2] = { 7, 8, 9 };
    // "9" ignored with a warning; no error
```

- Expressions of types void*, void const*, void volatile* and void const volatile* can be dereferenced; the result is an Ivalue.
- The __restrict__ keyword is accepted. It is identical to the C99 restrict keyword, except for its spelling.
- Out-of-range floating-point values are accepted without a diagnostic. When IEEE floating-point is being
 used, the "infinity" value is used.
- Extended variadic macros are supported.
- Dollar signs (\$) are allowed in identifiers.
- Hexadecimal floating point constants are recognized.
- The __asm__ keyword is recognized and equivalent to the asm token. Extended syntax is supported
 to indicate how assembly operands map to C/C++ variables.

```
asm("fsinx %1,%0" : "=f"(x) : "f"(a));
    // Map the output operand on "x",
    // and the input operand on "a".
```

- The \e escape sequence is recognized and stands for the ASCII "ESC" character.
- The address of a statement label can be taken by use of the prefix "&&" operator, e.g., void *a = &&L. A transfer to the address of a label can be done by the "goto *" statement, e.g., goto *a.
- Multi-line strings are supported, e.g.,

```
char *p = "abc
def";
```

ASCII "NULL" characters are accepted in source files.

- A source file can end with a backslash ("\") character.
- Case ranges (e.g., "case 'a' ... 'z':") are supported.
- A number of macros are predefined in GNU mode. See Section 2.8, *Predefined Macros*.
- A predefined macro can be undefined.
- A large number of special functions of the form __builtin_xyz (e.g., __builtin_alloca) are predeclared.
- Some expressions are considered to be constant-expressions even though they are not so considered in standard C and C++. Examples include "((char *)&((struct S *)0)->c[0]) (char *)0" and "(int)"Hello" & 0".
- The macro __GNUC__ is predefined to the major version number of the emulated GNU compiler. Similarly, the macros __GNUC_MINOR__ and __GNUC_PATCHLEVEL__ are predefined to the corresponding minor version number and patch level. Finally, __VERSION__ is predefined to a string describing the compiler version.
- The __thread specifier can be used to indicate that a variable should be placed in thread-local storage (requires gnu_version >= 30400).
- An extern inline function that is referenced but not defined is permitted (with a warning).
- Trigraphs are ignored (with a warning).
- Non-standard casts are allowed in null pointer constants, e.g., (int)(int *)0 is considered a null pointer constant in spite of the pointer cast in the middle.
- Statement expressions, e.g., ({int j; j = f(); j;)} are accepted. Branches into a statement expression are not allowed. In C++ mode, branches out are also not allowed. Variable-length arrays, destructible entities, try, catch, local non-POD class definitions, and dynamically-initialized local static variables are not allowed inside a statement expression.
- Labels can be declared to be local in statement expressions by introducing them with a __label__ declaration.

```
({ __label__ lab; int i = 4; lab: i = 2*i-1; if (!(i%17)) goto lab; i; })
```

• Not-evaluated parts of constant expressions can contain non-constant terms:

```
int i;
int a[ 1 || i ]; // Accepted in g++ mode
```

• Casts on an Ivalue that don't fall under the usual "Ivalue cast" interpretation (e.g., because they cast to a type having a different size) are ignored, and the operand remains an Ivalue. A warning is issued.

```
int i;
(short)i = 0; // Accepted,cast is ignored; entire int is set
```

 Variable length arrays (VLAs) are supported. GNU C also allows VLA types for fields of local structures, which can lead to run-time dependent sizes and offsets. The C++ compiler does not implement this, but instead treats such arrays as having length zero (with a warning); this enables some popular programming idioms involving fields with VLA types.

- Complex type extensions are supported (these are the same as the C99 complex type features, with the elimination of _Imaginary and the addition of __complex, __real, __imag, the use of "~" to denote complex conjugation, and complex literals such as "1.2i").
- If an explicit instantiation directive is preceded by the keyword extern, no (explicit or implicit) instantiation is for the indicated specialization.
- An explicit instantiation directive that names a class may omit the class keyword, and may refer to a typedef.
- An explicit instantiation or extern template directive that names a class is accepted in an invalid namespace.
- std::type_info does not need to be introduced with a special pragma.
- A special keyword __null expands to the same constant as the literal "0", but is expected to be used
 as a null pointer constant.
- When gnu_version < 30400, names from dependent base classes are ignored only if another name would be found by the lookup.

 A non-static data member from a dependent base class, which would usually be ignored as described above, is found if the lookup would have otherwise found a nonstatic data member of an enclosing class (when gnu_version is < 30400).

```
template <class T> struct C {
   struct A { int i; };
   struct B: public A {
     void f() {
```

```
i = 0; // g++ uses A::i not C::i
};
int i;
};
```

A new operation in a template is always treated as dependent (when gnu_version >= 30400).

When doing name lookup in a base class, the injected class name of a template class is ignored.

```
namespace N {
    template <class T> struct A {};
}
struct A {
    int i;
};
struct B : N::A<int> {
    B() { A x; x.i = 1; } // g++ uses ::A, not N::A
};
```

The injected class name is found in certain contexts in which the constructor should be found instead.

```
struct A {
     A(int) {};
};
A::A a(1);
```

• In a constructor definition, what should be treated as a template argument list of the constructor is instead treated as the template argument list of the enclosing class.

```
template <int ul> struct A { };
template <> struct A<1> {
   template<class T> A(T i, int j);
};

template <> A<1>::A<1>(int i, int j) { }
   // accepted in g++ mode
```

• A difference in calling convention is ignored when redeclaring a typedef.

- The macro __gnug__ is defined identically to __gnuc__ (i.e., the major version number of the GNU compiler version that is being emulated).
- The macro _GNU_SOURCE is defined as "1".
- Guiding declarations (a feature present in early drafts of the standard, but not in the final standard) are disabled.
- Namespace std is predeclared.
- No connection is made between declarations of identical names in different scopes even when these names are declared extern "C". E.g.,

```
extern "C" { void f(int); }
namespace N {
    extern "C" {
        void f() {} // Warning (not error) in g++ mode
    }
}
int main() { f(1); }
```

This example is accepted by the C++ compiler, but it will emit two conflicting declarations for the function f.

• When a using-directive lookup encounters more than one extern "C" declaration (created when more than one namespace declares an extern "C" function of a given name, as described above), only the first declaration encountered is considered for the lookup.

```
extern "C" int f(void);
extern "C" int g(void);
namespace N {
    extern "C" int f(void); // same type
    extern "C" void g(void); // different type
};
using namespace N;
int i = f(); // calls ::f
int j = g(); // calls ::f
```

• The definition of a member of a class template that appears outside of the class definition may declare a nontype template parameter with a type that is different than the type used in the definition of the class template. A warning is issued (GNU version 30300 and below).

```
template <int I> struct A { void f(); };
template <unsigned int I> void A<I>::f(){}
```

• A class template may be redeclared with a nontype template parameter that has a type that is different than the type used in the earlier declaration. A warning is issued.

```
template <int I> class A;
template <unsigned int I> class A {};
```

• A friend declaration may refer to a member typedef.

```
class A {
    class B {};
    typedef B my_b;
    friend class my_b;
};
```

• When a friend class is declared with an unqualified name, the lookup of that name is not restricted to the nearest enclosing namespace scope.

• A friend class declaration can refer to names made visible by using-directives.

```
namespace N { struct A { }; }
using namespace N;
struct B {
   void f() { A a; }
   friend struct A; // in g++ mode N::A,
};   // not a new declaration of ::A
```

An inherited type name can be used in a class definition and later redeclared as a typedef.

In a catch clause, an entity may be declared with the same name as the handler parameter.

```
try { }
catch(int e) {
   char e;
}
```

- The diagnostic issued for an exception specification mismatch is reduced to a warning if the previous declaration was found in a system header.
- The exception specification for an explicit template specialization (for a function or member function) does not have to match the exception specification of the corresponding primary template.
- A template argument list may appear following a constructor name in constructor definition that appears outside of the class definition:

```
template <class T> struct A {
    A();
};
template <class T> A<T>::A<T>(){}
```

When gnu_version < 30400, an incomplete type can be used as the type of a nonstatic data member
of a class template.

```
class B;
template <class T> struct A {
    B b;
};
```

• A constructor need not provide an initializer for every nonstatic const data member (but a warning is still issued if such an initializer is missing).

- Exception specifications are ignored on function definitions when support for exception handling is disabled (normally, they are only ignored on function declarations that aren't definitions).
- A friend declaration in a class template may refer to an undeclared template.

```
template <class T> struct A {
   friend void f<>(A<T>);
};
```

When gnu_version is < 30400, the semantic analysis of a friend function defined in a class template is
performed only if the function is actually used and is done at the end of the translation unit (instead of
at the point of first use).

• A function template default argument may be redeclared. A warning is issued and the default from the initial declaration is used.

```
template<class T> void f(int i = 1);
template<class T> void f(int i = 2){}
int main() {
    f<void>();
}
```

 A definition of a member function of a class template that appears outside of the class may specify a default argument.

```
template <class T> struct A { void f(T); };
template <class T> void A<T>::f(T value = T() ) { }
```

• Function declarations (that are not definitions) can have duplicate parameter names.

```
void f(int i, int i); // Accepted in GNU C++ mode
```

- Default arguments are retained as part of deduced function types.
- A namespace member may be redeclared outside of its namespace.
- A template may be redeclared outside of its class or namespace.

```
namespace N {
    template< typename T > struct S {};
}
template< typename T > struct N::S;
```

• The injected class name of a class template can be used as a template template argument.

```
template <template <class> class T> struct A {};
template <class T> struct B {
    A<B> a;
};
```

A partial specialization may be declared after an instantiation has been done that would have used the
partial specialization if it had been declared earlier. A warning is issued.

```
template <class T> class X {};
X<int*> xi;
template <class T> class X<T*> {};
```

• The "." or "->" operator may be used in an integral constant expression if the result is an integral or enumeration constant:

```
struct A { enum { e1 = 1 }; };
int main () {
   A a;
   int x[a.e1]; // Accepted in GNU C++ mode
   return 0;
}
```

Strong using-directives are supported.

```
using namespace debug __attribute__((strong));
```

 Partial specializations that are unusable because of nondeducible template parameters are accepted and ignored.

```
template<class T> struct A {class C { };};
template<class T> struct B {enum {e = 1}; };
template <class T> struct B<typename A<T>::C> {enum {e = 2}; };
int main(int argc, char **argv) {
    printf("%d\n", B<int>::e);
    printf("%d\n", B<A<int>::C>::e);
}
```

Template parameters that are not used in the signature of a function template are not ignored for partial
ordering purposes (i.e., the resolution of core language issue 214 is not implemented) when gnu_version
is < 40100.

• Prototype instantiations of functions are deferred until the first actual instantiation of the function to allow the compilation of programs that contain definitions of unusable function templates (gnu_version 30400 and above). The example below is accepted when prototype instantiations are deferred.

 When doing nonclass prototype instantiations (e.g., gnu_version 30400 and above), the severity of the diagnostic issued if a const template static data member is defined without an initializer is reduced to a warning.

```
template <class T> struct A {
    static const int i;
};
template <class T> const int A<T>::i;
```

When doing nonclass prototype instantiations (e.g., gnu_version 30400 and above), a template static
data member with an invalid aggregate initializer is accepted (the error is diagnosed if the static data
member is instantiated).

```
struct A {
    A(double val);
};
template <class T> struct B {
    static const A I[1];
};
template <class T> const A B<T>::I[1]= {
    {1.,0.,0.,0.}
};
```

The following GNU extensions are *not* currently supported:

- The forward declaration of function parameters (so they can participate in variable-length array parameters).
- GNU-style complex integral types (complex floating-point types are supported)
- · Nested functions

2.4. Namespace Support

Namespaces are enabled by default. You can use the command line option --no-namespaces to disable the features.

When doing name lookup in a template instantiation, some names must be found in the context of the template definition while others may also be found in the context of the template instantiation. The C++ compiler implements two different instantiation lookup algorithms: the one mandated by the standard (referred to as "dependent name lookup"), and the one that existed before dependent name lookup was implemented.

Dependent name lookup is done in strict mode (unless explicitly disabled by another command line option) or when dependent name processing is enabled by either a configuration flag or command line option.

Dependent Name Processing

When doing dependent name lookup, the C++ compiler implements the instantiation name lookup rules specified in the standard. This processing requires that non-class prototype instantiations be done. This in turn requires that the code be written using the typename and template keywords as required by the standard.

Lookup Using the Referencing Context

When not using dependent name lookup, the C++ compiler uses a name lookup algorithm that approximates the two-phase lookup rule of the standard, but does so in such a way that is more compatible with existing code and existing compilers.

When a name is looked up as part of a template instantiation but is not found in the local context of the instantiation, it is looked up in a synthesized instantiation context that includes both names from the context of the template definition and names from the context of the instantiation. Here's an example:

```
namespace N {
   int q(int);
    int x = 0;
    template <class T> struct A {
       T f(T t) { return q(t); }
        T f() { return x; }
    };
}
namespace M {
   int x = 99i
   double q(double);
   N::A<int> ai;
                      // N::A<int>::f(int) calls
    int i = ai.f(0);
                       // N::q(int)
   int i2 = ai.f();
                      // N::A<int>::f() returns
                       // 0 (= N::x)
   N::A<double> ad;
    double d = ad.f(0); // N::A<double>::f(double)
                       // calls M::q(double)
    double d2 = ad.f(); // N::A<double>::f() also
                        // returns 0 (= N::x)
}
```

The lookup of names in template instantiations does not conform to the rules in the standard in the following respects:

- Although only names from the template definition context are considered for names that are not functions, the lookup is not limited to those names visible at the point at which the template was defined.
- Functions from the context in which the template was referenced are considered for all function calls
 in the template. Functions from the referencing context should only be visible for "dependent" function
 calls.

Argument Dependent Lookup

When argument-dependent lookup is enabled (this is the default), functions made visible using argument-dependent lookup overload with those made visible by normal lookup. The standard requires that this overloading occurs even when the name found by normal lookup is a block extern declaration. The C++ compiler does this overloading, but in default mode, argument-dependent lookup is suppressed when the normal lookup finds a block extern.

This means a program can have different behavior, depending on whether it is compiled with or without argument-dependent lookup --no-arg-dep-lookup, even if the program makes no use of namespaces. For example:

2.5. Template Instantiation

The C++ language includes the concept of *templates*. A template is a description of a class or function that is a model for a family of related classes or functions. For example, one can write a template for a Stack class, and then use a stack of integers, a stack of floats, and a stack of some user-defined type. In the source, these might be written Stack<int>, Stack<float>, and Stack<X>. From a single source description of the template for a stack, the compiler can create *instantiations* of the template for each of the types required.

The instantiation of a class template is always done as soon as it is needed in a compilation. However, the instantiations of template functions, member functions of template classes, and static data members of template classes (hereafter referred to as template entities) are not necessarily done immediately, for several reasons:

- One would like to end up with only one copy of each instantiated entity across all the object files that make up a program. (This of course applies to entities with external linkage.)
- The language allows one to write a specialization of a template entity, i.e., a specific version to be used in place of a version generated from the template for a specific data type. (One could, for example, write a version of Stack<int>, or of just Stack<int>::push, that replaces the template-generated version; often, such a specialization provides a more efficient representation for a particular data type.) Since the compiler cannot know, when compiling a reference to a template entity, if a specialization for that entity will be provided in another compilation, it cannot do the instantiation automatically in any source file that references it.
- C++ templates can be exported (i.e., declared with the keyword export). Such templates can be used
 in a translation unit that does not contain the definition of the template to instantiate. The instantiation
 of such a template must be delayed until the template definition has been found.
- The language also dictates that template functions that are not referenced should not be compiled, that, in fact, such functions might contain semantic errors that would prevent them from being compiled.
 Therefore, a reference to a template class should not automatically instantiate all the member functions of that class.

¹Since templates are descriptions of entities (typically, classes) that are parameterizable according to the types they operate upon, they are sometimes called *parameterized types*.

(It should be noted that certain template entities are always instantiated when used, e.g., inline functions.)

From these requirements, one can see that if the compiler is responsible for doing all the instantiations automatically, it can only do so on a program-wide basis. That is, the compiler cannot make decisions about instantiation of template entities until it has seen all the source files that make up a complete program.

This C++ compiler provides an instantiation mechanism that does automatic instantiation at link time. For cases where you want more explicit control over instantiation, the C++ compiler also provides instantiation modes and instantiation pragmas, which can be used to exert fine-grained control over the instantiation process.

2.5.1. Automatic Instantiation

The goal of an automatic instantiation mode is to provide painless instantiation. You should be able to compile source files to object code, then link them and run the resulting program, and never have to worry about how the necessary instantiations get done.

In practice, this is hard for a compiler to do, and different compilers use different automatic instantiation schemes with different strengths and weaknesses:

• AT&T/USL/Novell's *cfront* product saves information about each file it compiles in a special directory called ptrepository. It instantiates nothing during normal compilations. At link time, it looks for entities that are referenced but not defined, and whose mangled names indicate that they are template entities. For each such entity, it consults the ptrepository information to find the file containing the source for the entity, and it does a compilation of the source to generate an object file containing object code for that entity. This object code for instantiated objects is then combined with the "normal" object code in the link step.

If you are using *cfront* you must follow a particular coding convention: all templates must be declared in .h files, and for each such file there must be a corresponding .cc file containing the associated definitions. The compiler is never told about the .cc files explicitly; one does not, for example, compile them in the normal way. The link step looks for them when and if it needs them, and does so by taking the .h filename and replacing its suffix. 2

This scheme has the disadvantage that it does a separate compilation for each instantiated function (or, at best, one compilation for all the member functions of one class). Even though the function itself is often quite small, it must be compiled along with the declarations for the types on which the instantiation is based, and those declarations can easily run into many thousands of lines. For large systems, these compilations can take a very long time. The link step tries to be smart about recompiling instantiations only when necessary, but because it keeps no fine-grained dependency information, it is often forced to "recompile the world" for a minor change in a \cdot h file. In addition, *cfront* has no way of ensuring that preprocessing symbols are set correctly when it does these instantiation compilations, if preprocessing symbols are set other than on the command line.

 Borland's C++ compiler instantiates everything referenced in a compilation, then uses a special linker to remove duplicate definitions of instantiated functions.

If you are using Borland's compiler you must make sure that every compilation sees all the source code it needs to instantiate all the template entities referenced in that compilation. That is, one cannot refer

²The actual implementation allows for several different suffixes and provides a command line option to change the suffixes sought.

to a template entity in a source file if a definition for that entity is not included by that source file. In practice, this means that either all the definition code is put directly in the .h files, or that each .h file includes an associated .cc (actually, .cpp) file.

Our approach is a little different. It requires that, for each instantiation of a non-exported template, there is some (normal, top-level, explicitly-compiled) source file that contains the definition of the template entity, a reference that causes the instantiation, and the declarations of any types required for the instantiation.³ This requirement can be met in various ways:

- The Borland convention: each .h file that declares a template entity also contains either the definition of the entity or includes another file containing the definition.
- Implicit inclusion: when the compiler sees a template declaration in a .h file and discovers a need to instantiate that entity, it is given permission to go off looking for an associated definition file having the same base name and a different suffix, and it implicitly includes that file at the end of the compilation. This method allows most programs written using the *cfront* convention to be compiled with our approach. See Section 2.5.4, *Implicit Inclusion*.
- The ad hoc approach: you make sure that the files that define template entities also have the definitions
 of all the available types, and add code or pragmas in those files to request instantiation of the entities
 there.

Exported templates are also supported by our automatic instantiation method, but they require additional mechanisms explained further on.

The automatic instantiation mode is enabled by default. It can be turned off by the command line option --no-auto-instantiation. If automatic instantiation is turned off, the extra information about template entities that could be instantiated in a file is not put into the object file.

2.5.2. Instantiation Modes

Normally, when a file is compiled, template entities are instantiated everywhere where they are used. The overall instantiation mode can, however, be changed by a command line option:

--instantiate=used

Instantiate those template entities that were used in the compilation. This will include all static data members for which there are template definitions. This is the default.

--instantiate=all

Instantiate all template entities declared or referenced in the compilation unit. For each fully instantiated template class, all of its member functions and static data members will be instantiated whether or not they were used. Non-member template functions will be instantiated even if the only reference was a declaration.

³Isn't this always the case? No. Suppose that file A contains a definition of class x and a reference to Stack<X>::push, and that file B contains the definition for the member function push. There would be no file containing both the definition of push and the definition of x.

--instantiate=local

Similar to **--instantiate=used** except that the functions are given internal linkage. This is intended to provide a very simple mechanism for those getting started with templates. The compiler will instantiate the functions that are used in each compilation unit as local functions, and the program will link and run correctly (barring problems due to multiple copies of local static variables.) However, one may end up with many copies of the instantiated functions, so this is not suitable for production use. **--instantiate=local** cannot be used in conjunction with automatic template instantiation. If automatic instantiation is enabled by default, it will be disabled by the **--instantiate=local** option.

In the case where the **ccarm** command is given a single file to compile and link, e.g.,

ccarm test.cc

the compiler knows that all instantiations will have to be done in the single source file. Therefore, it uses the **--instantiate=used** mode and suppresses automatic instantiation.

2.5.3. Instantiation #pragma Directives

Instantiation pragmas can be used to control the instantiation of specific template entities or sets of template entities. There are three instantiation pragmas:

- The **instantiate** pragma causes a specified entity to be instantiated.
- The do_not_instantiate pragma suppresses the instantiation of a specified entity. It is typically used
 to suppress the instantiation of an entity for which a specific definition will be supplied.
- The **can_instantiate** pragma indicates that a specified entity can be instantiated in the current compilation, but need not be; it is used in conjunction with automatic instantiation, to indicate potential sites for instantiation if the template entity turns out to be required.

The argument to the instantiation pragma may be:

- a template class name A<int>
- a template class declaration class A<int>
- a member function name A<int>::f
- a static data member name A<int>::i
- a static data declaration int A<int>::i
- a member function declaration void A<int>::f(int,char)
- a template function declaration char* f(int, float)

A pragma in which the argument is a template class name (e.g., A<int> or class A<int>) is equivalent to repeating the pragma for each member function and static data member declared in the class. When instantiating an entire class a given member function or static data member may be excluded using the do_not_instantiate pragma. For example,

```
#pragma instantiate A<int>
#pragma do_not_instantiate A<int>::f
```

The template definition of a template entity must be present in the compilation for an instantiation to occur. If an instantiation is explicitly requested by use of the **instantiate** pragma and no template definition is available or a specific definition is provided, an error is issued.

```
template <class T> void f1(T);  // No body provided
template <class T> void g1(T);  // No body provided

void f1(int) {}  // Specific definition
void main()
{
    int i;
    double d;
    f1(i);
    f1(d);
    g1(i);
    g1(d);
}
#pragma instantiate void f1(int) // error - specific
    // definition
#pragma instantiate void g1(int) // error - no body
    // provided
```

f1(double) and g1(double) will not be instantiated (because no bodies were supplied) but no errors will be produced during the compilation (if no bodies are supplied at link time, a linker error will be produced).

A member function name (e.g., A<int>::f) can only be used as a pragma argument if it refers to a single user defined member function (i.e., not an overloaded function). Compiler-generated functions are not considered, so a name may refer to a user defined constructor even if a compiler-generated copy constructor of the same name exists. Overloaded member functions can be instantiated by providing the complete member function declaration, as in

```
#pragma instantiate char* A<int>::f(int, char*)
```

The argument to an instantiation pragma may not be a compiler-generated function, an inline function, or a pure virtual function.

2.5.4. Implicit Inclusion

When implicit inclusion is enabled, the C++ compiler is given permission to assume that if it needs a definition to instantiate a template entity declared in a .h file it can implicitly include the corresponding .cc file to get the source code for the definition. For example, if a template entity ABC::f is declared in file xyz.h, and an instantiation of ABC::f is required in a compilation but no definition of ABC::f appears in the source code processed by the compilation, the compiler will look to see if a file xyz.cc exists, and if so it will process it as if it were included at the end of the main source file.

To find the template definition file for a given template entity the C++ compiler needs to know the path name specified in the original include of the file in which the template was declared and whether the file

was included using the system include syntax (e.g., #include <file.h>). This information is not available for preprocessed source containing #line directives. Consequently, the C++ compiler will not attempt implicit inclusion for source code containing #line directives.

The file to be implicitly included is found by replacing the file suffix with each of the suffixes specified in the instantiation file suffix list. The normal include search path mechanism is then used to look for the file to be implicitly included.

By default, the list of definition-file suffixes tried is .c, .cc, .cpp, and .cxx.

Implicit inclusion works well alongside automatic instantiation, but the two are independent. They can be enabled or disabled independently, and implicit inclusion is still useful when automatic instantiation is not done.

The implicit inclusion mode can be turned on by the command line option --implicit-include.

Implicit inclusions are only performed during the normal compilation of a file, (i.e., not when doing only preprocessing). A common means of investigating certain kinds of problems is to produce a preprocessed source file that can be inspected. When using implicit inclusion it is sometimes desirable for the preprocessed source file to include any implicitly included files. This may be done using the command line option --no-preprocessing-only. This causes the preprocessed output to be generated as part of a normal compilation. When implicit inclusion is being used, the implicitly included files will appear as part of the preprocessed output in the precise location at which they were included in the compilation.

2.5.5. Exported Templates

Exported templates are templates declared with the keyword export. Exporting a class template is equivalent to exporting each of its static data members and each of its non-inline member functions. An exported template is special because its definition does not need to be present in a translation unit that uses that template. In other words, the definition of an exported (non-class) template does not need to be explicitly or implicitly included in a translation unit that instantiates that template. For example, the following is a valid C++ program consisting of two separate translation units:

```
// File 1:
#include <stdio.h>
static void trace() { printf("File 1\n"); }

export template < class T > T const& min(T const&, T const&);
int main()
{
    trace();
    return min(2, 3);
}

// File 2:
#include <stdio.h>
static void trace() { printf("File 2\n"); }

export template < class T > T const& min(T const & a, T const & b)
{
    trace();
```

```
return a<b? a: b;
}</pre>
```

Note that these two files are separate translation units: one is not included in the other. That allows the two functions trace() to coexist (with internal linkage).

Support for exported templates is enabled by default, but you can turn it off with command line option --no-export.

2.5.5.1. Finding the Exported Template Definition

The automatic instantiation of exported templates is somewhat similar (from a user's perspective) to that of regular (included) templates. However, an instantiation of an exported template involves at least two translation units: one which requires the instantiation, and one which contains the template definition.

When a file containing definitions of exported templates is compiled, a file with a .et suffix is created and some extra information is included in the associated .ti file. The .et files are used later by the C++ compiler to find the translation unit that defines a given exported template.

When a file that potentially makes use of exported templates is compiled, the compiler must be told where to look for <code>.et</code> files for exported templates used by a given translation unit. By default, the compiler looks in the current directory. Other directories may be specified with the <code>command line option --template-directory</code>. Strictly speaking, the <code>.et</code> files are only really needed when it comes time to generate an instantiation. This means that code using exported templates can be compiled without having the definitions of those templates available. Those definitions must be available when explicit instantiation is done.

The .et files only inform the C++ compiler about the location of exported template definitions; they do not actually contain those definitions. The sources containing the exported template definitions must therefore be made available at the time of instantiation. In particular, the export facility is *not* a mechanism for avoiding the publication of template definitions in source form.

2.5.5.2. Secondary Translation Units

An instantiation of an exported template can be triggered by an explicit instantiation directive, or by the command line option --instantiate=used. In each case, the translation unit that contains the initial point of instantiation will be processed as the *primary translation unit*. Based on information it finds in the .et files, the C++ compiler will then load and parse the translation unit containing the definition of the template to instantiate. This is a *secondary translation unit*. The simultaneous processing of the primary and secondary translation units enables the C++ compiler to create instantiations of the exported templates (which can include entities from both translation units). This process may reveal the need for additional instantiations of exported templates, which in turn can cause additional secondary translation units to be loaded.

When secondary translation units are processed, the declarations they contain are checked for consistency. This process may report errors that would otherwise not be caught. Many these errors are so-called "ODR violations" (ODR stands for "one-definition rule"). For example:

⁴As a consequence, using exported templates may require considerably more memory that similar uses of regular (included) templates.

If there are no errors, the instantiations are generated in the output associated with the primary translation unit. This may also require that entities with internal linkage in secondary translation units be "externalized" so they can be accessed from the instantiations in the primary translation unit.

2.5.5.3. Libraries with Exported Templates

Typically a (non-export) library consists of an include directory and a lib directory. The include directory contains the header files required by users of the library and the lib directory contains the object code libraries that client programs must use when linking programs.

With exported templates, users of the library must also have access to the source code of the exported templates and the information contained in the associated .et files. This information should be placed in a directory that is distributed along with the include and lib directories: This is the export directory. It must be specified using the command line option --template-directory when compiling client programs.

The recommended procedure to build the export directory is as follows:

- 1. For each . et file in the original source directory, copy the associated source file to the export directory.
- 2. Concatenate all of the .et files into a single .et file (e.g., mylib.et) in the export directory. The individual .et files could be copied to the export directory, but having all of the .et information in one file will make use of the library more efficient.
- 3. Create an export_info file in the export directory. The export_info file specifies the include search paths to be used when recompiling files in the export directory. If no export_info file is provided, the include search path used when compiling the client program that uses the library will also be used to recompile the library exported template files.

The export info file consists of a series of lines of the form

```
include=x
```

or

```
sys_include=x
```

where x is a path name to be placed on the include search path. The directories are searched in the order in which they are encountered in the export_info file. The file can also contain comments, which begin with a "#", and blank lines. Spaces are ignored but tabs are not currently permitted. For example:

The include directories to be used for the xyz library

```
include = /disk1/xyz/include
sys_include = /disk2/abc/include
include=/disk3/jk1/include
```

The include search path specified for a client program is ignored by the C++ compiler when it processes the source in the export library, except when no <code>export_info</code> file is provided. Command line macro definitions specified for a client program are also ignored by the C++ compiler when processing a source file from the export library; the command line macros specified when the corresponding <code>.et</code> file was produced do apply. All other compilation options (other than the include search path and command line macro definitions) used when recompiling the exported templates will be used to compile the client program.

When a library is installed on a new system, it is likely that the export_info file will need to be adapted to reflect the location of the required headers on that system.

2.6. Extern Inline Functions

Depending on the way in which the C++ compiler is configured, out-of-line copies of extern inline functions are either implemented using static functions, or are instantiated using a mechanism like the template instantiation mechanism. Note that out-of-line copies of inline functions are only required in cases where the function cannot be inlined, or when the address of the function is taken (whether explicitly by the user, by implicitly generated functions, or by compiler-generated data structures such as virtual function tables or exception handling tables).

When static functions are used, local static variables of the functions are promoted to global variables with specially encoded names, so that even though there may be multiple copies of the code, there is only one copy of such global variables. This mechanism does not strictly conform to the standard because the address of an extern inline function is not constant across translation units.

When the instantiation mechanism is used, the address of an extern inline function is constant across translation units, but at the cost of requiring the use of one of the template instantiation mechanisms, even for programs that don't use templates. Definitions of extern inline functions can be provided either through use of the automatic instantiation mechanism or by use of the --instantiate=used or --instantiate=all instantiation modes. There is no mechanism to manually control the definition of extern inline function bodies.

2.7. Pragmas to Control the C++ Compiler

Pragmas are keywords in the C++ source that control the behavior of the compiler. Pragmas overrule compiler options.

The syntax is:

```
#pragma pragma-spec
```

The C++ compiler supports the following pragmas and all C compiler pragmas that are described in Section 1.5, *Pragmas to Control the Compiler*

instantiate / do_not_instantiate / can_instantiate

These are template instantiation pragmas. They are described in detail in Section 2.5.3, *Instantiation #pragma Directives*.

hdrstop / no_pch

These are precompiled header pragmas. They are described in detail in Section 2.9, *Precompiled Headers*.

once

When placed at the beginning of a header file, indicates that the file is written in such a way that including it several times has the same effect as including it once. Thus, if the C++ compiler sees #pragma once at the start of a header file, it will skip over it if the file is #included again.

A typical idiom is to place an #ifndef guard around the body of the file, with a #define of the guard variable after the #ifndef:

```
#pragma once    // optional
#ifndef FILE_H
#define FILE_H
... body of the header file ...
#endif
```

The #pragma once is marked as optional in this example, because the C++ compiler recognizes the #ifndef idiom and does the optimization even in its absence. #pragma once is accepted for compatibility with other compilers and to allow the programmer to use other guard-code idioms.

ident

This pragma is given in the form:

```
#pragma ident "string"
or
#ident "string"
```

2.8. Predefined Macros

The C++ compiler defines a number of preprocessing macros. Many of them are only defined under certain circumstances. This section describes the macros that are provided and the circumstances under which they are defined.

Macro	Description
ABI_COMPATIBILITY_VERSION	Defines the ABI compatibility version being used. This macro is set to 9999, which means the latest version. This macro is used when building the C++ library.
ABI_CHANGES_FOR_RTTI	This macro is set to TRUE, meaning that the ABI changes for RTTI are implemented. This macro is used when building the C++ library.
ABI_CHANGES_FOR_ARRAY_NEW_AND_DELETE	This macro is set to TRUE, meaning that the ABI changes for array new and delete are implemented. This macro is used when building the C++ library.
ABI_CHANGES_FOR_PLACEMENT_DELETE	This macro is set to TRUE, meaning that the ABI changes for placement delete are implemented. This macro is used when building the C++ library.
ARRAY_OPERATORS	Defined when array new and delete are enabled. This is the default.
BASE_FILE	Similar toFILE but indicates the primary source file rather than the current one (i.e., when the current file is an included file).
BIG_ENDIAN	Expands to 1 if big-endian mode is selected (optionendianness=big), otherwise unrecognized as macro.
_BOOL	Defined when bool is a keyword. This is the default.
BUILD	Identifies the build number of the C++ compiler, composed of decimal digits for the build number, three digits for the major branch number and three digits for the minor branch number. For example, if you use build 1.22.1 of the compiler,BUILD expands to 1022001. If there is no branch number, the branch digits expand to zero. For example, build 127 results in 127000000.
CHAR_MIN /CHAR_MAX	Used in limits.h to define the minimum/maximum value of a plain char respectively.

Macro	Description
CPARM	Identifies the C++ compiler. You can use this symbol to flag parts of the source which must be recognized by the cparm C++ compiler only. It expands to 1.
cplusplus	Always defined.
CPU	Expands to a string with the CPU supplied with the optioncpu. When nocpu is supplied, this symbol is not defined.
DATE	Defined to the date of the compilation in the form "Mmm dd yyyy".
DELTA_TYPE	Defines the type of the offset field in the virtual function table. This macro is used when building the C++ library.
DOUBLE_FP	Expands to 1 if you did <i>not</i> use optionno-double (Treat 'double' as 'float'), otherwise unrecognized as macro.
embedded_cplusplus	Defined as 1 in Embedded C++ mode.
EXCEPTIONS	Defined when exception handling is enabled (exceptions).
FILE	Expands to the current source file name.
FUNCTION	Defined to the name of the current function. An error is issued if it is used outside of a function.
func	Same asFUNCTION in GNU mode.
IMPLICIT_USING_STD	Defined when the standard header files should implicitly do a using-directive on the std namespace (using-std).
JMP_BUF_ELEMENT_TYPE	Specifies the type of an element of the setjmp buffer. This macro is used when building the C++ library.
JMP_BUF_NUM_ELEMENTS	Defines the number of elements in the setjmp buffer. This macro is used when building the C++ library.
LINE	Expands to the line number of the line where this macro is called.
LITTLE_ENDIAN	Expands to 1 if little-endian mode is selected (optionendianness=little), otherwise unrecognized as macro. This is the default.
NAMESPACES	Defined when namespaces are supported (this is the default, you can disable support for namespaces with no-namespaces).

Macro	Description
NO_LONG_LONG	Defined when the long long type is not supported. This is the default.
NULL_EH_REGION_NUMBER	Defines the value used as the null region number value in the exception handling tables. This macro is used when building the C++ library.
PLACEMENT_DELETE	Defined when placement delete is enabled.
PRETTY_FUNCTION	Defined to the name of the current function. This includes the return type and parameter types of the function. An error is issued if it is used outside of a function.
PTRDIFF_MIN /PTRDIFF_MAX	Used in stdint.h to define the minimum/maximum value of a ptrdiff_t type respectively.
REGION_NUMBER_TYPE	Defines the type of a region number field in the exception handling tables. This macro is used when building the C++ library.
REVISION	Expands to the revision number of the C++ compiler. Digits are represented as they are; characters (for prototypes, alphas, betas) are represented by -1. Examples: v1.0r1 -> 1, v1.0rb -> -1
RTTI	Defined when RTTI is enabled (rtti).
RUNTIME_USES_NAMESPACES	Defined when the run-time uses namespaces.
SIGNED_CHARS	Defined when plain char is signed.
SINGLE_FP	Expands to 1 if you used optionno-double (Treat 'double' as 'float'), otherwise unrecognized as macro.
SIZE_MIN /SIZE_MAX	Used in stdint.h to define the minimum/maximum value of a size_t type respectively.
STDC	Always defined, but the value may be redefined.
STDC_VERSION	Identifies the ISO-C version number. Expands to 199901L for ISO C99, but the value may be redefined.
_STLP_NO_IOSTREAMS	Defined when optionio-streams is not used. This disables I/O stream functions in the STLport C++ library.
TASKING	Always defined for the TASKING C++ compiler.

Macro	Description
THUMB	Expands to 1 if you used optionthumb, otherwise unrecognized as macro.
TIME	Expands to the compilation time: "hh:mm:ss"
TYPE_TRAITS_ENABLED	Defined when type traits pseudo-functions (to ease the implementation of ISO/IEC TR 19768; e.g.,is_union) are enabled. This is the default in C++ mode.
VAR_HANDLE_TYPE	Defines the type of the variable-handle field in the exception handling tables. This macro is used when building the C++ library.
VERSION	Identifies the version number of the C++ compiler. For example, if you use version 2.1r1 of the compiler,VERSION expands to 2001 (dot and revision number are omitted, minor version number in 3 digits).
VIRTUAL_FUNCTION_INDEX_TYPE	Defines the type of the virtual function index field of the virtual function table. This macro is used when building the C++ library.
VIRTUAL_FUNCTION_TYPE	Defines the type of the virtual function field of the virtual function table. This macro is used when building the C++ library.
WCHAR_MIN /WCHAR_MAX	Used in stdint.h to define the minimum/maximum value of a wchar_t type respectively.
_WCHAR_T	Defined when wchar_t is a keyword.

2.9. Precompiled Headers

It is often desirable to avoid recompiling a set of header files, especially when they introduce many lines of code and the primary source files that #include them are relatively small. The C++ compiler provides a mechanism for, in effect, taking a snapshot of the state of the compilation at a particular point and writing it to a disk file before completing the compilation; then, when recompiling the same source file or compiling another file with the same set of header files, it can recognize the "snapshot point", verify that the corresponding precompiled header (PCH) file is reusable, and read it back in. Under the right circumstances, this can produce a dramatic improvement in compilation time; the trade-off is that PCH files can take a lot of disk space.

2.9.1. Automatic Precompiled Header Processing

When --pch appears on the command line, automatic precompiled header processing is enabled. This means the C++ compiler will automatically look for a qualifying precompiled header file to read in and/or will create one for use on a subsequent compilation.

The PCH file will contain a snapshot of all the code preceding the "header stop" point. The header stop point is typically the first token in the primary source file that does not belong to a preprocessing directive, but it can also be specified directly by **#pragma hdrstop** (see below) if that comes first. For example:

```
#include "xxx.h"
#include "yyy.h"
int i;
```

The header stop point is int (the first non-preprocessor token) and the PCH file will contain a snapshot reflecting the inclusion of xxx.h and yyy.h. If the first non-preprocessor token or the #pragma hdrstop appears within a #if block, the header stop point is the outermost enclosing #if. To illustrate, heres a more complicated example:

```
#include "xxx.h"
#ifndef YYY_H
#define YYY_H 1
#include "yyy.h"
#endif
#if TEST
int i;
#endif
```

Here, the first token that does not belong to a preprocessing directive is again int, but the header stop point is the start of the #if block containing it. The PCH file will reflect the inclusion of xxx.h and conditionally the definition of xyyh and inclusion of yyyh, h; it will not contain the state produced by #if TEST.

A PCH file will be produced only if the header stop point and the code preceding it (mainly, the header files themselves) meet certain requirements:

 The header stop point must appear at file scope -- it may not be within an unclosed scope established by a header file. For example, a PCH file will not be created in this case:

```
// xxx.h
class A {
// xxx.C
#include "xxx.h"
int i; };
```

• The header stop point may not be inside a declaration started within a header file, nor (in C++) may it be part of a declaration list of a linkage specification. For example, in the following case the header stop point is int, but since it is not the start of a new declaration, no PCH file will be created:

```
// yyy.h
static
// yyy.C
#include "yyy.h"
int i;
```

- Similarly, the header stop point may not be inside a #if block or a #define started within a header file.
- The processing preceding the header stop must not have produced any errors. (Note: warnings and other diagnostics will not be reproduced when the PCH file is reused.)
- No references to predefined macros __DATE__ or __TIME__ may have appeared.
- No use of the #line preprocessing directive may have appeared.
- #pragma no_pch (see below) must not have appeared.
- The code preceding the header stop point must have introduced a sufficient number of declarations to
 justify the overhead associated with precompiled headers. The minimum number of declarations required
 is 1.

When the host system does not support memory mapping, so that everything to be saved in the precompiled header file is assigned to preallocated memory (MS-Windows), two additional restrictions apply:

- The total memory needed at the header stop point cannot exceed the size of the block of preallocated memory.
- No single program entity saved can exceed 16384, the preallocation unit.

When a precompiled header file is produced, it contains, in addition to the snapshot of the compiler state, some information that can be checked to determine under what circumstances it can be reused. This includes:

- The compiler version, including the date and time the compiler was built.
- The current directory (i.e., the directory in which the compilation is occurring).
- The command line options.
- The initial sequence of preprocessing directives from the primary source file, including #include directives.
- The date and time of the header files specified in #include directives.

This information comprises the PCH prefix. The prefix information of a given source file can be compared to the prefix information of a PCH file to determine whether the latter is applicable to the current compilation.

As an illustration, consider two source files:

When a.cc is compiled with --pch, a precompiled header file named a.pch is created. Then, when b.cc is compiled (or when a.cc is recompiled), the prefix section of a.pch is read in for comparison with the current source file. If the command line options are identical, if xxx.h has not been modified, and so forth, then, instead of opening xxx.h and processing it line by line, the C++ compiler reads in the rest of a.pch and thereby establishes the state for the rest of the compilation.

It may be that more than one PCH file is applicable to a given compilation. If so, the largest (i.e., the one representing the most preprocessing directives from the primary source file) is used. For instance, consider a primary source file that begins with

```
#include "xxx.h"
#include "yyy.h"
#include "zzz.h"
```

If there is one PCH file for xxx.h and a second for xxx.h and yyy.h, the latter will be selected (assuming both are applicable to the current compilation). Moreover, after the PCH file for the first two headers is read in and the third is compiled, a new PCH file for all three headers may be created.

When a precompiled header file is created, it takes the name of the primary source file, with the suffix replaced by an implementation-specified suffix (pch by default). Unless --pch-dir is specified (see below), it is created in the directory of the primary source file.

When a precompiled header file is created or used, a message such as

"test.cc": creating precompiled header file "test.pch"

is issued. The user may suppress the message by using the command line option --no-pch-messages.

When the option --pch-verbose is used the C++ compiler will display a message for each precompiled header file that is considered that cannot be used giving the reason that it cannot be used.

In automatic mode (i.e., when --pch is used) the C++ compiler will deem a precompiled header file obsolete and delete it under the following circumstances:

- if the precompiled header file is based on at least one out-of-date header file but is otherwise applicable for the current compilation; or
- if the precompiled header file has the same base name as the source file being compiled (e.g., xxx.pch and xxx.cc) but is not applicable for the current compilation (e.g., because of different command line options).

This handles some common cases; other PCH file clean-up must be dealt with by other means (e.g., by the user).

Support for precompiled header processing is not available when multiple source files are specified in a single compilation: an error will be issued and the compilation aborted if the command line includes a request for precompiled header processing and specifies more than one primary source file.

2.9.2. Manual Precompiled Header Processing

Command line option --create-pch=file-name specifies that a precompiled header file of the specified name should be created.

Command line option --use-pch=file-name specifies that the indicated precompiled header file should be used for this compilation; if it is invalid (i.e., if its prefix does not match the prefix for the current primary source file), a warning will be issued and the PCH file will not be used.

When either of these options is used in conjunction with --pch-dir, the indicated file name (which may be a path name) is tacked on to the directory name, unless the file name is an absolute path name.

The options --create-pch, --use-pch, and --pch may not be used together. If more than one of these options is specified, only the last one will apply. Nevertheless, most of the description of automatic PCH processing applies to one or the other of these modes -- header stop points are determined the same way, PCH file applicability is determined the same way, and so forth.

2.9.3. Other Ways to Control Precompiled Headers

There are several ways in which the user can control and/or tune how precompiled headers are created and used.

#pragma hdrstop may be inserted in the primary source file at a point prior to the first token that does
not belong to a preprocessing directive. It enables you to specify where the set of header files subject
to precompilation ends. For example,

```
#include "xxx.h"
#include "yyy.h"
#pragma hdrstop
#include "zzz.h"
```

Here, the precompiled header file will include processing state for xxx.h and yyy.h but not zzz.h. (This is useful if the user decides that the information added by what follows the **#pragma hdrstop** does not justify the creation of another PCH file.)

- #pragma no_pch may be used to suppress precompiled header processing for a given source file.
- Command line option --pch-dir=directory-name is used to specify the directory in which to search for and/or create a PCH file.

Moreover, when the host system does not support memory mapping and preallocated memory is used instead, then one of the command line options --pch, --create-pch, or --use-pch, if it appears at all, must be the *first* option on the command line.

2.9.4. Performance Issues

The relative overhead incurred in writing out and reading back in a precompiled header file is quite small for reasonably large header files.

In general, it does not cost much to write a precompiled header file out even if it does not end up being used, and if it *is* used it almost always produces a significant speedup in compilation. The problem is that

the precompiled header files can be quite large (from a minimum of about 250K bytes to several megabytes or more), and so one probably does not want many of them sitting around.

Thus, despite the faster recompilations, precompiled header processing is not likely to be justified for an arbitrary set of files with nonuniform initial sequences of preprocessing directives. Rather, the greatest benefit occurs when a number of source files can share the same PCH file. The more sharing, the less disk space is consumed. With sharing, the disadvantage of large precompiled header files can be minimized, without giving up the advantage of a significant speedup in compilation times.

Consequently, to take full advantage of header file precompilation, users should expect to reorder the #include sections of their source files and/or to group #include directives within a commonly used header file.

Below is an example of how this can be done. A common idiom is this:

```
#include "comnfile.h"
#pragma hdrstop
#include ...
```

where <code>comnfile.h</code> pulls in, directly and indirectly, a few dozen header files; the <code>#pragma hdrstop</code> is inserted to get better sharing with fewer PCH files. The PCH file produced for <code>comnfile.h</code> can be a bit over a megabyte in size. Another idiom, used by the source files involved in declaration processing, is this:

```
#include "comnfile.h"
#include "decl_hdrs.h"
#pragma hdrstop
#include ...
```

decl_hdrs.h pulls in another dozen header files, and a second, somewhat larger, PCH file is created. In all, the source files of a particular program can share just a few precompiled header files. If disk space were at a premium, you could decide to make comnfile.h pull in all the header files used -- then, a single PCH file could be used in building the program.

Different environments and different projects will have different needs, but in general, users should be aware that making the best use of the precompiled header support will require some experimentation and probably some minor changes to source code.

Chapter 3. Assembly Language

This chapter describes the most important aspects of the TASKING assembly language for ARM and contains a detailed description of all built-in assembly functions and assembler directives. For a complete overview of the architecture you are using and a description of the assembly instruction set, refer to the target's core reference manual (for example the *ARM Architecture Reference Manual* ARM DDI 0100I [2005, ARM Limited]).

3.1. Assembly Syntax

An assembly program consists of statements. A statement may optionally be followed by a comment. Any source statement can be extended to more lines by including the line continuation character (\(\)) as the last character on the line. The length of a source statement (first line and continuation lines) is only limited by the amount of available memory.

Mnemonics, directives and other keywords are case insensitive. Labels, symbols, directive arguments, and literal strings are case sensitive.

The syntax of an assembly statement is:

```
[label[:]] [instruction | directive | macro_call] [;comment]
```

label

A label is a special symbol which is assigned the value and type of the current program location counter. A label can consist of letters, digits and underscore characters (_). The first character cannot be a digit. The label can also be a *number*. A label which is prefixed by whitespace (spaces or tabs) has to be followed by a colon (:). The size of an identifier is only limited by the amount of available memory.

number is a number ranging from 1 to 255. This type of label is called a *numeric label* or *local label*. To refer to a numeric label, you must put an **n** (next) or **p** (previous) immediately after the label. This is required because the same label number may be used repeatedly.

Examples:

```
LAB1: ; This label is followed by a colon and ; can be prefixed by whitespace

LAB1 ; This label has to start at the beginning ; of a line

1: b 1p ; This is an endless loop ; using numeric labels
```

instruction An instruction consists of a mnemonic and zero, one or more operands. It must

not start in the first column.

All instructions of the ARM Unified Assembler Language (UAL) are supported. With assembler option **--old-syntax** you can specify to use the pre-UAL syntax.

VFP instructions are only supported in the UAL syntax.

Operands are described in Section 3.3, *Operands of an Assembly Instruction*. The instructions are described in the target's core Architecture Reference Manual.

The instruction can also be a so-called 'generic instruction'. Generic instructions are pseudo instructions (no instructions from the instruction set). Depending on the situation in which a generic instruction is used, the assembler replaces the generic instruction with appropriate real assembly instruction(s). For a complete

list, see Section 3.11, Generic Instructions.

directive With directives you can control the assembler from within the assembly source.

Except for preprocessing directives, these must not start in the first column.

Directives are described in Section 3.9, Assembler Directives.

macro_call A call to a previously defined macro. It must not start in the first column. See

Section 3.10, Macro Operations.

comment Comment, preceded by a ; (semicolon).

You can use empty lines or lines with only comments.

3.2. Assembler Significant Characters

You can use all ASCII characters in the assembly source both in strings and in comments. Also the extended characters from the ISO 8859-1 (Latin-1) set are allowed.

Some characters have a special meaning to the assembler. Special characters associated with expression evaluation are described in Section 3.6.3, *Expression Operators*. Other special assembler characters are:

Character	Description
;	Start of a comment
١	Line continuation character or macro operator: argument concatenation
?	Macro operator: return decimal value of a symbol
%	Macro operator: return hex value of a symbol
۸	Macro operator: override local label
"	Macro string delimiter or quoted string .DEFINE expansion character
1	String constants delimiter
@	Start of a built-in assembly function
\$	Location counter substitution
#	Immediate addressing
++	String concatenation operator

Character	Description
[]	Load and store addressing mode

3.3. Operands of an Assembly Instruction

In an instruction, the mnemonic is followed by zero, one or more operands. An operand has one of the following types:

Operand	Description
symbol	A symbolic name as described in Section 3.4, <i>Symbol Names</i> . Symbols can also occur in expressions.
register	Any valid register as listed in Section 3.5, Registers.
expression	Any valid expression as described in Section 3.6, Assembly Expressions.
address	A combination of expression, register and symbol.

Addressing modes

The ARM assembly language has several addressing modes. These are described in detail in the target's core Architecture Reference Manual.

3.4. Symbol Names

User-defined symbols

A user-defined *symbol* can consist of letters, digits and underscore characters (_). The first character cannot be a digit. The size of an identifier is only limited by the amount of available memory. The case of these characters is significant. You can define a symbol by means of a label declaration or an equate or set directive.

Predefined preprocessor symbols

These symbols start and end with two underscore characters, __symbol__, and you can use them in your assembly source to create conditional assembly. See Section 3.4.1, Predefined Preprocessor Symbols.

Labels

Symbols used for memory locations are referred to as labels. It is allowed to use reserved symbols as labels as long as the label is followed by a colon or starts at the first column.

Reserved symbols

Symbol names and other identifiers beginning with a period (.) are reserved for the system (for example for directives or section names). Instructions and registers are also reserved. The case of these built-in symbols is insignificant.

Examples

Valid symbol names:

```
loop_1
ENTRY
a_B_c
_aBC
```

Invalid symbol names:

```
1_loop  ; starts with a number
.DEFINE  ; reserved directive name
```

3.4.1. Predefined Preprocessor Symbols

The TASKING assembler knows the predefined symbols as defined in the table below. The symbols are useful to create conditional assembly.

Symbol	Description
ASARM	Expands to 1 for the ARM toolset, otherwise unrecognized as macro.
BUILD	Identifies the build number of the compiler, composed of decimal digits for the build number, three digits for the major branch number and three digits for the minor branch number. For example, if you use build 1.22.1 of the assembler,BUILD expands to 1022001. If there is no branch number, the branch digits expand to zero. For example, build 127 results in 127000000.
REVISION	Expands to the revision number of the compiler. Digits are represented as they are; characters (for prototypes, alphas, betas) are represented by -1. Examples: v1.0r1 -> 1, v1.0rb -> -1
TASKING	Identifies the assembler as a TASKING assembler. Expands to 1 if a TASKING assembler is used.
VERSION	Identifies the version number of the assembler. For example, if you use version 2.1r1 of the assembler,VERSION expands to 2001 (dot and revision number are omitted, minor version number in 3 digits).

Example

```
.if @defined('__ASARM___')
  ; this part is only for the asarm assembler
...
.endif
```

3.5. Registers

The following register names, either upper or lower case, should not be used for user-defined symbol names in an assembly language source file:

```
R0 .. R15 (general purpose registers)
IP (alias for R12)
SP (alias for R13)
LR (alias for R14)
PC (alias for R15)
```

3.6. Assembly Expressions

An expression is a combination of symbols, constants, operators, and parentheses which represent a value that is used as an operand of an assembler instruction (or directive).

Expressions can contain user-defined labels (and their associated integer or floating-point values), and any combination of integers, floating-point numbers, or ASCII literal strings.

Expressions follow the conventional rules of algebra and boolean arithmetic.

Expressions that can be evaluated at assembly time are called *absolute expressions*. Expressions where the result is unknown until all sections have been combined and located, are called *relocatable* or *relative expressions*.

When any operand of an expression is relocatable, the entire expression is relocatable. Relocatable expressions are emitted in the object file and evaluated by the linker. Relocatable expressions can only contain integral functions; floating-point functions and numbers are not supported by the ELF/DWARF object format.

The assembler evaluates expressions with 64-bit precision in two's complement.

The syntax of an *expression* can be any of the following:

- · numeric constant
- string
- symbol
- expression binary operator expression
- unary_operator expression
- (expression)
- · function call

All types of expressions are explained in separate sections.

3.6.1. Numeric Constants

Numeric constants can be used in expressions. If there is no prefix, by default the assembler assumes the number is a decimal number. Prefixes can be used in either lower or upper case.

Base	Description	Example
Binary	A 0b prefix followed by binary digits (0,1). Or use a b suffix.	0B1101 11001010b
Hexadecimal	A 0x prefix followed by hexadecimal digits (0-9, A-F, a-f). Or use a h suffix.	0x12FF 0x45 0fa10h
Decimal integer	Decimal digits (0-9).	12 1245
Decimal floating-point	Decimal digits (0-9), includes a decimal point, or an 'E' or 'e' followed by the exponent.	6E10 .6 3.14 2.7e10

3.6.2. Strings

ASCII characters, enclosed in single (') or double (") quotes constitute an ASCII string. Strings between double quotes allow symbol substitution by a <code>.DEFINE</code> directive, whereas strings between single quotes are always literal strings. Both types of strings can contain escape characters.

Strings constants in expressions are evaluated to a number (each character is replaced by its ASCII value). Strings in expressions can have a size of up to 8 characters or less depending on the operand of an instruction or directive; any subsequent characters in the string are ignored. In this case the assembler issues a warning. An exception to this rule is when a string is used in a .DB assembler directive; in that case all characters result in a constant value of the specified size. Null strings have a value of 0.

Examples

```
'ABCD'
                    ; (0x41424344)
111791
                   ; to enclose a quote double it
"A\"BC"
                  ; or to enclose a quote escape it
'AB'+1
                    ; (0x4143) string used in expression
                   ; null string
.DW 'abcdef'
                   ; (0x64636261) 'ef' are ignored
                    ; warning: string value truncated
'ab'++'cd'
                    ; you can concatenate
                    ; two strings with the '++' operator.
                    ; This results in 'abcd'
```

3.6.3. Expression Operators

The next table shows the assembler operators. They are ordered according to their precedence. Operators of the same precedence are evaluated left to right. Parenthetical expressions have the highest priority (innermost first).

Valid operands include numeric constants, literal ASCII strings and symbols.

Most assembler operators can be used with both integer and floating-point values. If one operand has an integer value and the other operand has a floating-point value, the integer is converted to a floating-point value before the operator is applied. The result is a floating-point value.

Туре	Operator	Name	Description
	()	parenthesis	Expressions enclosed by parenthesis are evaluated first.
Unary	+	plus	Returns the value of its operand.
	-	minus	Returns the negative of its operand.
	~	one's complement	Integer only. Returns the one's complement of its operand. It cannot be used with a floating-point operand.
	!	logical negate	Returns 1 if the operands' value is 0; otherwise 0. For example, if buf is 0 then !buf is 1. If buf has a value of 1000 then !buf is 0.
Arithmetic	*	multiplication	Yields the product of its operands.
	/	division	Yields the quotient of the division of the first operand by the second. For integer operands, the divide operation produces a truncated integer result.
	%	modulo	Integer only. This operator yields the remainder from the division of the first operand by the second.
	+	addition	Yields the sum of its operands.
	-	subtraction	Yields the difference of its operands.
Shift	<<	shift left	Integer only. Causes the left operand to be shifted to the left (and zero-filled) by the number of bits specified by the right operand.
	>>	shift right	Integer only. Causes the left operand to be shifted to the right by the number of bits specified by the right operand. The sign bit will be extended.

Туре	Operator	Name	Description
Relational	<	less than	Returns an integer 1 if the indicated condition is
	<=	less than or equal	TRUE or an integer 0 if the indicated condition is
	>	greater than	
	>=	greater than or equal	For example, if D has a value of 3 and E has a value of 5, then the result of the expression D <e 1,="" and<="" is="" td=""></e>
	==	equal	the result of the expression D>E is 0.
	!=	not equal	Use tests for equality involving floating-point values with caution, since rounding errors could cause unexpected results.
Bit and Bitwise	&	AND	Integer only. Yields the bitwise AND function of its operand.
		OR	Integer only. Yields the bitwise OR function of its operand.
	٨	exclusive OR	Integer only. Yields the bitwise exclusive OR function of its operands.
Logical	&&	logical AND	Returns an integer 1 if both operands are non-zero; otherwise, it returns an integer 0.
	II	logical OR	Returns an integer 1 if either of the operands is non-zero; otherwise, it returns an integer 1

The relational operators and logical operators are intended primarily for use with the conditional assembly .if directive, but can be used in any expression.

3.7. Working with Sections

Sections are absolute or relocatable blocks of contiguous memory that can contain code or data. Some sections contain code or data that your program declared and uses directly, while other sections are created by the compiler or linker and contain debug information or code or data to initialize your application. These sections can be named in such a way that different modules can implement different parts of these sections. These sections are located in memory by the linker (using the linker script language, LSL) so that concerns about memory placement are postponed until after the assembly process.

All instructions and directives which generate data or code must be within an active section. The assembler emits a warning if code or data starts without a section definition. The compiler automatically generates sections. If you program in assembly you have to define sections yourself.

For more information about locating sections see Section 8.7.8, *The Section Layout Definition: Locating Sections*.

Section definition

Sections are defined with the <code>.SECTION/.ENDSEC</code> directive and have a name. The names have a special meaning to the locating process and have to start with a predefined name, optionally extended by a dot '.' and a user defined name. Optionally, you can specify the <code>at()</code> attribute to locate a section at a specific address.

```
.SECTION name[,at(address)]
; instructions etc.
.ENDSEC
```

See the description of the .SECTION directive for more information.

Examples

```
.SECTION .data ; Declare a .data section ; ...
.ENDSEC

.SECTION .data.abs, at(0x0) ; Declare a .data.abs section at ; an absolute address ; ...
.ENDSEC
```

3.8. Built-in Assembly Functions

The TASKING assembler has several built-in functions to support data conversion, string comparison, and math computations. You can use functions as terms in any expression.

Syntax of an assembly function

```
@function_name([argument[,argument]...])
```

Functions start with the '@' character and have zero or more arguments, and are always followed by opening and closing parentheses. White space (a blank or tab) is not allowed between the function name and the opening parenthesis and between the (comma-separated) arguments.

The names of assembly functions are case insensitive.

Overview of assembly functions

Function	Description
@ALUPCREL(expr,group[,check])	PC-relative ADD/SUB with operand split
@ARG('symbol' expr)	Test whether macro argument is present
@BIGENDIAN()	Test if assembler generates code for big-endian mode
@CNT()	Return number of macro arguments
@CPU('architecture')	Test if current CPU matches architecture
@DEFINED('symbol' symbol)	Test whether symbol exists
@LSB(expr)	Least significant byte of the expression
@LSH(expr)	Least significant half word of the absolute expression
@LSW(expr)	Least significant word of the expression
@MSB(expr)	Most significant byte of the expression
@MSH(expr)	Most significant half word of the absolute expression

Function	Description
@MSW(expr)	Most significant word of the expression
@PRE_UAL()	Test if the assembler runs in pre-UAL syntax mode or in UAL syntax mode by default (option old-syntax)
@STRCAT(str1,str2)	Concatenate str1 and str2
@STRCMP(str1,str2)	Compare str1 with str2
@STRLEN(string)	Return length of string
@STRPOS(str1,str2[,start])	Return position of str2 in str1
@STRSUB(str,expr1,expr2)	Return substring
@THUMB()	Test if the assembler runs in Thumb mode or in ARM mode by default (option thumb)

Detailed Description of Built-in Assembly Functions

@ALUPCREL(expression,group[,check])

This function is used internally by the assembler with the generic instructions ADR, ADRL and ADRLL. This function returns the PC-relative address of the *expression* for use in these generic instructions. *group* is 0 for ADR, 1 for ADRL or 2 for ADRLL.

With check you can specify to check for overflow (1 means true, 0 means false). If check is omitted, the default is 1.

Example:

```
; The instruction "ADRAL R1,label" expands to ADRAL R1,PC,@ALUPCREL(label,0,1)
```

@ARG('symbol' | expression)

Returns integer 1 if the macro argument represented by symbol or expression is present, 0 otherwise.

You can specify the argument with a *symbol* name (the name of a macro argument enclosed in single quotes) or with *expression* (the ordinal number of the argument in the macro formal argument list). If you use this function when macro expansion is not active, the assembler issues a warning.

Example:

```
.IF @ARG('TWIDDLE') ;is argument twiddle present?
.IF @ARG(1) ;is first argument present?
```

@BIGENDIAN()

Returns 1 if the assembler generates code for big-endian mode, returns 0 if the assembler generates code for little-endian mode (this is the default).

@CNT()

Returns the number of macro arguments of the current macro expansion as an integer. If you use this function when macro expansion is not active, the assembler issues a warning.

Example:

```
ARGCOUNT .SET @CNT(); reserve argument count
```

@CPU('architecture')

Returns 1 if *architecture* corresponds to the architecture that was specified with the option **--cpu**=*architecture*; 0 otherwise. See also assembler option **--cpu** (Select architecture).

Example:

```
.IF @CPU('ARMv4') ; true if you specified option --cpu=ARMv4 ...; code for the ARMv4 ...; code for the ARMv4 ...; code for the ARMv6-M ...; code for the ARMv6-M ...; code for other architectures .ENDIF
```

@DEFINED('symbol' | symbol)

Returns 1 if symbol has been defined, 0 otherwise. If symbol is quoted, it is looked up as a .DEFINE symbol; if it is not quoted, it is looked up as an ordinary symbol, macro or label.

Example:

```
.IF @DEFINED('ANGLE') ; is symbol ANGLE defined?
.IF @DEFINED(ANGLE) ; does label ANGLE exist?
```

@LSB(expression)

Returns the *least* significant byte of the result of the *expression*. The result of the expression is calculated as 16 bits.

Example:

```
.DB @LSB(0x1234) ; stores 0x34
.DB @MSB(0x1234) ; stores 0x12
```

@LSH(expression)

Returns the *least* significant half word (bits 0..15) of the result of the absolute *expression*. The result of the expression is calculated as a word (32 bits).

@LSW(expression)

Returns the *least* significant word (bits 0..31) of the result of the *expression*. The result of the expression is calculated as a double-word (64 bits).

Example:

```
.DW @LSW(0x12345678) ; stores 0x5678
.DW @MSW(0x123456) ; stores 0x0012
```

@MSB(expression)

Returns the *most* significant byte of the result of the *expression*. The result of the expression is calculated as 16 bits.

@MSH(expression)

Returns the *most* significant half word (bits 16..31) of the result of the absolute *expression*. The result of the expression is calculated as a word (32 bits). @MSH(expression) is equivalent to ((expression>>16) & 0xffff).

@MSW(expression)

Returns the *most* significant word of the result of the *expression*. The result of the expression is calculated as a double-word (64 bits).

@PRE_UAL()

Returns 1 if the assembler runs in pre-UAL syntax mode by default, or 0 if the assembler runs in UAL syntax mode (default). This function reflects the setting of the assembler option --old-syntax.

Example:

```
.IF @PRE_UAL() ; true if you specified option --old-syntax
...; old code
.ELSE
...; new code, UAL syntax
.ENDIF
```

@STRCAT(string1,string2)

Concatenates *string1* and *string2* and returns them as a single string. You must enclose *string1* and *string2* either with single quotes or with double quotes.

Example:

```
.DEFINE ID "@STRCAT('TAS','KING')" ; ID = 'TASKING'
```

@STRCMP(string1,string2)

Compares *string1* with *string2* by comparing the characters in the string. The function returns the difference between the characters at the first position where they disagree, or zero when the strings are equal:

```
<0 if string1 < string2
0 if string1 == string2
>0 if string1 > string2
Example:
    .IF (@STRCMP(STR,'MAIN')) == 0 ; does STR equal 'MAIN'?
```

@STRLEN(string)

Returns the length of string as an integer.

Example:

```
SLEN .SET @STRLEN('string') ; SLEN = 6
```

@STRPOS(string1,string2[,start])

Returns the position of *string1* in *string1* as an integer. If *string2* does not occur in *string1*, the last string position + 1 is returned.

With *start* you can specify the starting position of the search. If you do not specify start, the search is started from the beginning of *string1*.

Example:

```
ID .set @STRPOS('TASKING','ASK') ; ID = 1
ID .set @STRPOS('TASKING','BUG') ; ID = 7
```

@STRSUB(string,expression1,expression2)

Returns the substring from *string* as a string. *expression1* is the starting position within *string*, and *expression2* is the length of the desired string. The assembler issues an error if either *expression1* or *expression2* exceeds the length of string. Note that the first position in a string is position 0.

Example:

```
.DEFINE ID "@STRSUB('TASKING',3,4)" ;ID = 'KING'
```

@THUMB()

Returns 1 if the assembler runs in Thumb mode by default or 0 if the assembler runs in ARM mode (default). This function reflects the setting of the assembler option --thumb. So, it does not depend on the .CODE16, .CODE32, .ARM or .THUMB directive.

If you are in a .CODE 32 part and you specified --thumb, @THUMB() still returns 1.

3.9. Assembler Directives

An assembler directive is simply a message to the assembler. Assembler directives are not translated into machine instructions. There are three main groups of assembler directives.

Assembler directives that tell the assembler how to go about translating instructions into machine code.
This is the most typical form of assembly directives. Typically they tell the assembler where to put a
program in memory, what space to allocate for variables, and allow you to initialize memory with data.
When the assembly source is assembled, a location counter in the assembler keeps track of where
the code and data is to go in memory.

The following directives fall under this group:

- · Assembly control directives
- · Symbol definition and section directives
- · Data definition / Storage allocation directives
- High Level Language (HLL) directives
- Directives that are interpreted by the macro preprocessor. These directives tell the macro preprocessor
 how to manipulate your assembly code before it is actually being assembled. You can use these
 directives to write macros and to write conditional source code. Parts of the code that do not match the
 condition, will not be assembled at all. Unlike other directives, preprocessor directives can start in the
 first column.
- Some directives act as assembler options and most of them indeed do have an equivalent assembler (command line) option. The advantage of using a directive is that with such a directive you can overrule the assembler option for a particular part of the code. Directives of this kind are called *controls*. A typical example is to tell the assembler with an option to generate a list file while with the directives .NOLIST and .LIST you overrule this option for a part of the code that you do not want to appear in the list file. Directives of this kind sometimes are called *controls*.

Each assembler directive has its own syntax. Some assembler directives can be preceded with a label. If you do not precede an assembler directive with a label, you must use white space instead (spaces or tabs). You can use assembler directives in the assembly code as pseudo instructions. The assembler recognizes both upper and lower case for directives.

3.9.1. Overview of Assembler Directives

The following tables provide an overview of all assembler directives. For a detailed description of these directives, refer to Section 3.9.2, *Detailed Description of Assembler Directives*.

Overview of assembly control directives

Directive	Description
.END	Indicates the end of an assembly module
.INCLUDE	Include file
.MESSAGE	Programmer generated message

Overview of symbol definition and section directives

Directive	Description
.EQU	Set permanent value to a symbol
.EXTERN	Import global section symbol
.GLOBAL	Declare global section symbol
.SECTION, .ENDSEC	Start a new section
.SET	Set temporary value to a symbol
.SIZE	Set size of symbol in the ELF symbol table
.SOURCE	Specify name of original C source file
.TYPE	Set symbol type in the ELF symbol table
.WEAK	Mark a symbol as 'weak'

Overview of data definition / storage allocation directives

Directive	Description
.ALIGN	Align location counter
.BS, .BSB, .BSH, .BSW, .BSD	Define block storage (initialized)
.DB	Define byte
.DH	Define half word (16 bits)
.DW	Define word (32 bits)
.DD	Define double-word (64 bits)
.DOUBLE	Define a 64-bit floating-point constant
.DS, .DSB, .DSH, .DSW, .DSD	Define storage
.FLOAT	Define a 32-bit floating-point constant
.OFFSET	Move location counter forwards

Overview of macro preprocessor directives

Directive	Description
.DEFINE	Define substitution string
.BREAK	Break out of current macro expansion
.REPEAT, .ENDREP	Repeat sequence of source lines
.FOR, .ENDFOR	Repeat sequence of source lines n times
.IF, .ELIF, .ELSE	Conditional assembly directive
.ENDIF	End of conditional assembly directive
.MACRO, .ENDM	Define macro
.UNDEF	Undefine . DEFINE symbol or macro

Overview of listing control directives

Directive	Description	
.LIST, .NOLIST	Print / do not print source lines to list file	
.PAGE	Set top of page/size of page	
.TITLE	Set program title in header of assembly list file	

Overview of HLL directives

Directive	Description	
.CALLS	Pass call tree information and/or stack usage information	
.MISRAC	Pass MISRA-C information	

Overview of ARM specific directives

Directive	Description
.CODE16, .CODE32	Treat instructions as Thumb or ARM instructions using pre-UAL syntax
.THUMB, .ARM	Treat instructions as Thumb or ARM instructions using UAL syntax
.LTORG	Assemble current literal pool immediately

3.9.2. Detailed Description of Assembler Directives

.ALIGN

Syntax

```
.ALIGN expression
```

Description

With the . ALIGN directive you instruct the assembler to align the location counter. By default the assembler aligns on one byte.

When the assembler encounters the .ALIGN directive, it advances the location counter to an address that is aligned as specified by *expression* and places the next instruction or directive on that address. The alignment is in minimal addressable units (MAUs). The assembler fills the 'gap' with NOP instructions for code sections or with zeros for data sections. If the location counter is already aligned on the specified alignment, it remains unchanged. The location of absolute sections will not be changed.

The *expression* must be a power of two: 2, 4, 8, 16, ... If you specify another value, the assembler changes the alignment to the next higher power of two and issues a warning.

The assembler aligns sections automatically to the largest alignment value occurring in that section.

A label is not allowed before this directive.

Example

```
.SECTION .text
.ALIGN 4 ; the assembler aligns
instruction ; this instruction at 4 MAUs and
; fills the 'gap' with NOP instructions.

.SECTION .text
.ALIGN 3 ; WRONG: not a power of two, the
instruction ; assembler aligns this instruction at
; 4 MAUs and issues a warning.
```

.BREAK

Syntax

.BREAK

Description

The .BREAK directive causes immediate termination of a macro expansion, a .FOR loop expansion or a .REPEAT loop expansion. In case of nested loops or macros, the .BREAK directive returns to the previous level of expansion.

The . BREAK directive is, for example, useful in combination with the . IF directive to terminate expansion when error conditions are detected.

The assembler does not allow a label with this directive.

Example

```
.FOR MYVAR IN 10 TO 20
...;
...; assembly source lines
...;
.IF MYVAR > 15
.BREAK
.ENDIF
.ENDFOR
```

.BS, .BSB, .BSH, .BSW, .BSD

Syntax

```
[label] .BS count[,value]
[label] .BSB count[,value]
[label] .BSH count[,value]
[label] .BSW count[,value]
[label] .BSD count[,value]
```

Description

With the .BS directive the assembler reserves a block of memory. The reserved block of memory is initialized to the value of *value*, or zero if omitted.

With *count* you specify the number of minimum addressable units (MAUs) you want to reserve, and how much the location counter will advance. The expression must be an integer greater than zero and cannot contain any forward references to address labels (labels that have not yet been defined).

With value you can specify a value to initialize the block with. Only the least significant MAU of value is used. If you omit value, the default is zero.

If you specify the optional *label*, it gets the value of the location counter at the start of the directive processing.

You cannot initialize of a block of memory in sections with prefix .sbss or .bss. In those sections, the assembler issues a warning and only reserves space, just as with .DS.

The .BSB, .BSH, .BSW and .BSD directives are variants of the .BS directive. The difference is the number of bits that are reserved for the *count* argument:

Directive	Reserved bits
.BSB	8
.BSH	16
.BSW	32
.BSD	64

Example

The .BSB directive is for example useful to define and initialize an array that is only partially filled:

```
.section .sdata
.DB 84,101,115,116 ; initialize 4 bytes
.BSB 96,0xFF ; reserve another 96 bytes, initialized with 0xFF
```

Related Information

- .DB (Define Memory)
- .DS (Define Storage)

.CALLS

Syntax

```
.CALLS 'caller','callee'

or
.CALLS 'caller','',stack_usage[,...]
```

Description

The first syntax creates a call graph reference between *caller* and *callee*. The linker needs this information to build a call graph. *caller* and *callee* are names of functions.

The second syntax specifies stack information. When *callee* is an empty name, this means we define the stack usage of the function itself. The value specified is the stack usage in bytes at the time of the call including the return address. A function can use multiple stacks.

This information is used by the linker to compute the used stack within the application. The information is found in the generated linker map file within the Memory Usage.

This directive is generated by the C compiler. Use the <code>.CALLS</code> directive in hand-coded assembly when the assembly code calls a C function. If you manually add <code>.CALLS</code> directives, make sure they connect to the compiler generated <code>.CALLS</code> directives: the name of the caller must also be named as a callee in another directive.

A label is not allowed before this directive.

Example

```
.CALLS 'main', 'nfunc'
```

Indicates that the function main calls the function nfunc.

```
.CALLS 'main','',8
```

The function main uses 8 bytes on the stack.

.CODE16, .CODE32, .THUMB, .ARM

Syntax

- .CODE16
- .CODE32
- .THUMB
- .ARM

Description

With the .CODE16 directive you instruct the assembler to interpret subsequent instructions as 16-bit Thumb instructions using the pre-UAL syntax until it encounters another mode directive or till it reaches the end of the active section. This directive causes an implicit alignment of two bytes. The assembler issues an error message if .CODE16 is used in combination with option --cpu=ARMv4.

The .THUMB directive is the same as the .CODE16 directive except that the UAL syntax is expected.

With the .CODE32 directive you instruct the assembler to interpret subsequent instructions as 32-bit ARM instructions using the pre-UAL syntax until it encounters another mode directive or till it reaches the end of the active section. This directive causes an implicit alignment of four bytes. The assembler issues an error message if .CODE32 is used in combination with option --cpu=ARMv7M.

The .ARM directive is the same as the .CODE32 directive except that the UAL syntax is expected.

These directives are useful when you have files that contain both ARM and Thumb instructions. The directive must appear before the instruction change and between a .SECTION/.ENDSEC. The default instruction set at the start of a section depends on the use of assembler option --thumb.

Example

```
.section .text
.code32
  ;following instructions are ARM instructions
  ;
.endsec
```

Related Information

Assembler option --thumb (Treat input as Thumb instructions)

.DB, .DH, .DW, .DD

Syntax

```
[label] .DB argument[,argument]...
[label] .DH argument[,argument]...
[label] .DW argument[,argument]...
[label] .DD argument[,argument]...
```

Description

With these directive you can define memory. With each directive the assembler allocates and initializes one or more bytes of memory for each argument.

If you specify the optional *label*, it gets the value of the location counter at the start of the directive processing.

An *argument* can be a single- or multiple-character string constant, an expression or empty. Multiple arguments must be separated by commas with no intervening spaces. Empty arguments are stored as 0 (zero).

The following table shows the number of bits initialized.

Directive	Bits
.DB	8
.DH	16
.DW	32
.DD	64

The value of the arguments must be in range with the size of the directive; floating-point numbers are not allowed. If the evaluated argument is too large to be represented in a half word / word / double-word, the assembler issues a warning and truncates the value.

String constants

Single-character strings are stored in a byte whose lower seven bits represent the ASCII value of the character, for example:

```
.DB 'R' i = 0x52
```

Multiple-character strings are stored in consecutive byte addresses, as shown below. The standard C language escape characters like '\n' are permitted.

```
.DB 'AB',,'C' ; = 0x41420043 (second argument is empty)
```

Example

When a string is supplied as argument of a directive that initializes multiple bytes, each character in the string is stored in consecutive bytes whose lower seven bits represent the ASCII value of the character. For example:

```
<code>HTBL: .DH 'ABC',,'D' ; results in 0x424100004400 , the 'C' is truncated WTBL: .DW 'ABC' ; results in 0x43424100</code>
```

Related Information

- .BS (Block Storage)
- .DS (Define Storage)

.DEFINE

Syntax

```
.DEFINE symbol string
```

Description

With the .DEFINE directive you define a substitution string that you can use on all following source lines. The assembler searches all succeeding lines for an occurrence of *symbol*, and replaces it with *string*. If the *symbol* occurs in a double quoted string it is also replaced. Strings between single quotes are not expanded.

This directive is useful for providing better documentation in the source program. A *symbol* can consist of letters, digits and underscore characters (_), and the first character cannot be a digit.

Macros represent a special case. .DEFINE directive translations will be applied to the macro definition as it is encountered. When the macro is expanded, any active .DEFINE directive translations will again be applied.

The assembler issues a warning if you redefine an existing symbol.

A label is not allowed before this directive.

Example

Suppose you defined the symbol LEN with the substitution string "32":

```
.DEFINE LEN "32"
```

Then you can use the symbol LEN for example as follows:

```
.DS LEN
.MESSAGE "The length is: LEN"
```

The assembler preprocessor replaces LEN with "32" and assembles the following lines:

```
.DS 32
.MESSAGE "The length is: 32"
```

Related Information

```
. UNDEF (Undefine a .DEFINE symbol)
.MACRO, .ENDM (Define a macro)
```

.DS, .DSB, .DSH, .DSW, .DSD

Syntax

```
[label] .DS expression
[label] .DSB expression
[label] .DSH expression
[label] .DSW expression
[label] .DSD expression
```

Description

With the .DS directive the assembler reserves a block in memory. The reserved block of memory is not initialized to any value.

With the *expression* you specify the number of MAUs (Minimal Addressable Units) that you want to reserve, and how much the location counter will advance. The expression must evaluate to an integer greater than zero and cannot contain any forward references (symbols that have not yet been defined).

If you specify the optional *label*, it gets the value of the location counter at the start of the directive processing.

The .DSB, .DSH, .DSW and .DSD directives are variants of the .DS directive. The difference is the number of bits that are reserved per expression argument:

Directive	Reserved bits
.DSB	8
.DSH	16
.DSW	32
.DSD	64

Example

```
.section .bss
RES: .DS 5+3 ; allocate 8 bytes
```

Related Information

```
.BS (Block Storage)
```

.DB (Define Memory)

.END

Syntax

. END

Description

With the optional . ${\tt END}$ directive you tell the assembler that the end of the module is reached. If the assembler finds assembly source lines beyond the . ${\tt END}$ directive, it ignores those lines and issues a warning.

You cannot use the .END directive in a macro expansion.

The assembler does not allow a label with this directive.

Example

.EQU

Syntax

symbol .EQU expression

Description

With the .EQU directive you assign the value of *expression* to *symbol* permanently. The expression can be relative or absolute. Once defined, you cannot redefine the symbol. With the .GLOBAL directive you can declare the symbol global.

Example

To assign the value 0x400 permanently to the symbol MYSYMBOL:

MYSYMBOL .EQU 0x4000

You cannot redefine the symbol MYSYMBOL after this.

Related Information

. SET (Set temporary value to a symbol)

.EXTERN

Syntax

```
.EXTERN symbol[,symbol]...
```

Description

With the . EXTERN directive you define an *external* symbol. It means that the specified symbol is referenced in the current module, but is not defined within the current module. This symbol must either have been defined outside of any module or declared as globally accessible within another module with the .global directive.

If you do not use the .EXTERN directive and the symbol is not defined within the current module, the assembler issues a warning and inserts the .EXTERN directive.

A label is not allowed with this directive.

Example

```
.EXTERN AA,CC,DD ;defined elsewhere
```

Related Information

.GLOBAL (Declare global section symbol)

.FLOAT, .DOUBLE

Syntax

```
[label].FLOAT expression[,expression]...
[label].DOUBLE expression[,expression]...
```

Description

With the .FLOAT or .DOUBLE directive the assembler allocates and initializes a floating-point number (32 bits) or a double (64 bits) in memory for each argument.

An expression can be:

- · a floating-point expression
- NULL (indicated by two adjacent commas: ,,)

You can represent a constant as a signed whole number with fraction or with the 'e' format as used in the C language. For example, 12.457 and +0.27E-13 are legal floating-point constants.

If the evaluated argument is too large to be represented in a single word / double-word, the assembler issues an error and truncates the value.

If you specify *label*, it gets the value of the location counter at the start of the directive processing.

Example

```
FLT: .FLOAT 12.457,+0.27E-13
DBL: .DOUBLE 12.457,+0.27E-13
```

Related Information

.DS (Define Storage)

.FOR, .ENDFOR

Syntax

Description

With the .FOR/.ENDFOR directive you can repeat a block of assembly source lines with an iterator. As shown by the syntax, you can use the .FOR/.ENDFOR in two ways.

- 1. In the first method, the block of source statements is repeated as many times as the number of arguments following IN. If you use the symbol *var* in the assembly lines between . FOR and . ENDFOR, for each repetition the symbol *var* is substituted by a subsequent expression from the argument list. If the argument is a null, then the block is repeated with each occurrence of the symbol *var* removed. If an argument includes an embedded blank or other assembler-significant character, it must be enclosed with single quotes.
- 2. In the second method, the block of source statements is repeated using the symbol *var* as a counter. The counter passes all integer values from *start* to *end* with a *step*. If you do not specify *step*, the counter is increased by one for every repetition.

If you specify label, it gets the value of the location counter at the start of the directive processing.

Example

In the following example the block of source statements is repeated 4 times (there are four arguments). With the .DB directive you allocate and initialize a byte of memory for each repetition of the loop (a word for the .DW directive). Effectively, the preprocessor duplicates the .DB and .DW directives four times in the assembly source.

```
.FOR VAR1 IN 1,2+3,4,12
.DB VAR1
.DW (VAR1*VAR1)
.ENDFOR
```

In the following example the loop is repeated 16 times. With the .DW directive you allocate and initialize four bytes of memory for each repetition of the loop. Effectively, the preprocessor duplicates the .DW directive 16 times in the assembled file, and substitutes VAR2 with the subsequent numbers.

```
.FOR VAR2 IN 1 to 0x10
.DW (VAR1*VAR1)
.ENDFOR
```

Related Information

.REPEAT, .ENDREP (Repeat sequence of source lines)

.GLOBAL

Syntax

```
.GLOBAL symbol[,symbol]...
```

Description

All symbols or labels defined in the current section or module are local to the module by default. You can change this default behavior with assembler option --symbol-scope=global.

With the .GLOBAL directive you declare one of more symbols as global. It means that the specified symbols are defined within the current section or module, and that those definitions should be accessible by all modules.

To access a symbol, defined with .GLOBAL, from another module, use the .EXTERN directive.

Only program labels and symbols defined with . EQU can be made global.

If the symbols that appear in the operand field are not used in the module, the assembler gives a warning.

The assembler does not allow a label with this directive.

Example

```
LOOPA .EQU 1 ; definition of symbol LOOPA .GLOBAL LOOPA ; LOOPA will be globally ; accessible by other modules
```

Related Information

. EXTERN (Import global section symbol)

.IF, .ELIF, .ELSE, .ENDIF

Syntax

```
.IF expression
.
.
[.ELIF expression] ; the .ELIF directive is optional
.
.
[.ELSE] ; the .ELSE directive is optional
.
.
.
.ENDIF
```

Description

With the .IF/.ENDIF directives you can create a part of conditional assembly code. The assembler assembles only the code that matches a specified condition.

The *expression* must evaluate to an absolute integer and cannot contain forward references. If *expression* evaluates to zero, the IF-condition is considered FALSE, any non-zero result of *expression* is considered as TRUE.

If the optional .ELSE and/or .ELIF directives are not present, then the source statements following the .IF directive and up to the next .ENDIF directive will be included as part of the source file being assembled only if the *expression* had a non-zero result.

If the *expression* has a value of zero, the source file will be assembled as if those statements between the .IF and the .ENDIF directives were never encountered.

If the .ELSE directive is present and expression has a nonzero result, then the statements between the .IF and .ELSE directives will be assembled, and the statement between the .ELSE and .ENDIF directives will be skipped. Alternatively, if expression has a value of zero, then the statements between the .IF and .ELSE directives will be skipped, and the statements between the .ELSE and .ENDIF directives will be assembled.

You can nest .IF directives to any level. The .ELSE and .ELIF directive always refer to the nearest previous .IF directive.

A label is not allowed with this directive.

Example

Suppose you have an assemble source file with specific code for a test version, for a demo version and for the final version. Within the assembly source you define this code conditionally as follows:

```
.IF TEST
...; code for the test version
.ELIF DEMO
...; code for the demo version
.ELSE
```

```
\dots; code for the final version <code>.ENDIF</code>
```

Before assembling the file you can set the values of the symbols <code>TEST</code> and <code>DEMO</code> in the assembly source before the <code>.IF</code> directive is reached. For example, to assemble the demo version:

```
TEST .SET 0
DEMO .SET 1
```

Related Information

Assembler option --define (Define preprocessor macro)

.INCLUDE

Syntax

```
.INCLUDE "filename" | <filename>
```

Description

With the .INCLUDE directive you include another file at the exact location where the .INCLUDE occurs. This happens before the resulting file is assembled. The .INCLUDE directive works similarly to the #include statement in C. The source from the include file is assembled as if it followed the point of the .INCLUDE directive. When the end of the included file is reached, assembly of the original file continues.

The string specifies the filename of the file to be included. The filename must be compatible with the operating system (forward/backward slashes) and can contain a directory specification. If you omit a filename extension, the assembler assumes the extension, asm.

If an absolute pathname is specified, the assembler searches for that file. If a relative path is specified or just a filename, the order in which the assembler searches for include files is:

1. The current directory if you use the "filename" construction.

The current directory is not searched if you use the *<filename>* syntax.

- 2. The path that is specified with the assembler option --include-directory.
- 3. The path that is specified in the environment variable ASARMINC when the product was installed.
- 4. The default include directory in the installation directory.

The assembler does not allow a label with this directive.

The state of the assembler is not changed when an include file is processed. The lines of the include file are inserted just as if they belong to the file where it is included.

Example

Suppose that your assembly source file test.src contains the following line:

```
.INCLUDE "c:\myincludes\myinc.inc"
```

The assembler issues an error if it cannot find the file at the specified location.

```
.INCLUDE "myinc.inc"
```

The assembler searches the file myinc.inc according to the rules described above.

Related Information

Assembler option --include-directory (Add directory to include file search path)

.LIST, .NOLIST

Syntax

```
.NOLIST
.
. ; assembly source lines
.
.LIST
```

Description

If you generate a list file with the assembler option --list-file, you can use the directives .LIST and .NOLIST to specify which source lines the assembler must write to the list file. Without the assembler option --list-file these directives have no effect. The directives take effect starting at the next line.

The assembler prints all source lines to the list file, until it encounters a .NOLIST directive. The assembler does not print the .NOLIST directive and subsequent source lines. When the assembler encounters the .LIST directive, it resumes printing to the list file.

It is possible to nest the .LIST/.NOLIST directives.

Example

Suppose you assemble the following assembly code with the assembler option --list-file:

```
.SECTION .text
...; source line 1
.NOLIST
...; source line 2
.LIST
...; source line 3
.ENDSEC
```

The assembler generates a list file with the following lines:

```
.SECTION .text
...; source line 1
...; source line 3
.ENDSEC
```

Related Information

Assembler option --list-file (Generate list file)

.LTORG

Syntax

.LTORG

Description

With this directive you force the assembler to generate a literal pool (data pocket) at the current location.

All literals from the LDR= pseudo-instructions (except those which could be translated to MOV or MVN instructions) between the previous literal pool and the current location will be assembled in a new literal pool using .DW directives.

By default, the assembler generates a literal pool at the end of a code section, i.e. the .ENDSEC directive at the end of a code section causes an implicit .LTORG directive. However, the default literal pool may be out-of-reach of one or more LDR= pseudo-instructions in the section. In that case the assembler issues an error message and you should insert .LTORG directives at proper locations in the section.

Example

```
.section .text
;
LDR r1,=0x12345678
; code
.ltorg ; literal pool contains the literal &0x12345678
;
;
.endsec ; default literal pool is empty
```

Related Information

LDR= ARM generic instruction

LDR= Thumb generic instruction

.MACRO, .ENDM

Syntax

```
macro_name .MACRO [argument[,argument]...]
    ...
    macro_definition_statements
    ...
    .ENDM
```

Description

With the . MACRO directive you define a macro. Macros provide a shorthand method for handling a repeated pattern of code or group of instructions. You can define the pattern as a macro, and then call the macro at the points in the program where the pattern would repeat.

The definition of a macro consists of three parts:

- Header, which assigns a name to the macro and defines the arguments (.MACRO directive).
- · Body, which contains the code or instructions to be inserted when the macro is called.
- Terminator, which indicates the end of the macro definition (.ENDM directive).

The arguments are symbolic names that the macro processor replaces with the literal arguments when the macro is expanded (called). Each formal *argument* must follow the same rules as symbol names: the name can consist of letters, digits and underscore characters (_). The first character cannot be a digit. Argument names cannot start with a percent sign (%).

Macro definitions can be nested but the nested macro will not be defined until the primary macro is expanded.

You can use the following operators in macro definition statements:

Operator	Name	Description
\	Macro argument concatenation	Concatenates a macro argument with adjacent alphanumeric characters.
?	Return decimal value of symbol	Substitutes the <i>?symbol</i> sequence with a character string that represents the decimal value of the symbol.
%	Return hex value of symbol	Substitutes the %symbol sequence with a character string that represents the hexadecimal value of the symbol.
"	Macro string delimiter	Allows the use of macro arguments as literal strings.
۸	Macro local label override	Prevents name mangling on labels in macros.

Example

The macro definition:

```
macro_a .MACRO arg1,arg2 ;header
   .db arg1 ;body
```

```
.dw (arg1*arg2)
.ENDM
```

;terminator

The macro call:

```
.section far
macro_a 2,3
```

The macro expands as follows:

```
.db 2 .dw (2*3)
```

Related Information

Section 3.10, Macro Operations

.DEFINE (Define a substitution string)

.MESSAGE

Syntax

```
.MESSAGE type [{str|exp}[,{str|exp}]...]
```

Description

With the .MESSAGE directive you tell the assembler to print a message to stderr during the assembling process.

With type you can specify the following types of messages:

I	Information message. Error and warning counts are not affected and the assembler continues the assembling process.
W	Warning message. Increments the warning count and the assembler continues the assembling process.
E	Error message. Increments the error count and the assembler continues the assembling process.
F	Fatal error message. The assembler immediately aborts the assembling process and generates no object file or list file.

An arbitrary number of strings and expressions, in any order but separated by commas with no intervening white space, can be specified to describe the nature of the generated message. If you use expressions, the assembler outputs the result. The assembler outputs a space between each argument.

The error and warning counts will not be affected. The .MESSAGE directive is for example useful in combination with conditional assembly to indicate which part is assembled. The assembling process proceeds normally after the message has been printed.

This directive has no effect on the exit code of the assembler.

A label is not allowed with this directive.

Example

```
.MESSAGE I 'Generating tables'

ID .EQU 4
.MESSAGE E 'The value of ID is',ID
.DEFINE LONG "SHORT"
.MESSAGE I 'This is a LONG string'
.MESSAGE I "This is a LONG string"
```

Within single quotes, the defined symbol LONG is not expanded. Within double quotes the symbol LONG is expanded so the actual message is printed as:

```
This is a LONG string
This is a SHORT string
```

.MISRAC

Syntax

.MISRAC string

Description

The C compiler can generate the .MISRAC directive to pass the compiler's MISRA-C settings to the object file. The linker performs checks on these settings and can generate a report. It is not recommended to use this directive in hand-coded assembly.

Example

```
.MISRAC 'MISRA-C:2004,64,e2,0b,e,e11,27,6,ef83,e1,ef,66,cb75,af1,eff,e7, e7f,8d,63,87ff7,6ff3,4'
```

Related Information

Section 4.6, C Code Checking: MISRA-C

C compiler option --misrac

.OFFSET

Syntax

```
.OFFSET expression
```

Description

With the .OFFSET directive you tell the assembler to give the location counter a new offset relative to the start of the section.

When the assembler encounters the .OFFSET directive, it moves the location counter forwards to the specified address, relative to the start of the section, and places the next instruction on that address. If you specify an address equal to or lower than the current position of the location counter, the assembler issues an error.

A label is not allowed with this directive.

Example

Related Information

```
.SECTION (Start a new section)
```

.PAGE

Syntax

```
.PAGE [pagewidth[,pagelength[,blanktop[,blankbtm[,blankleft]]]]
```

Default

```
.PAGE 132,72,0,0,0
```

Description

If you generate a list file with the assembler option --list-file, you can use the directive . PAGE to format the generated list file.

The arguments may be any positive absolute integer expression, and must be separated by commas.

pagewidth	Number of columns per line. The default is 132, the minimum is 40.
pagelength	Total number of lines per page. The default is 72, the minimum is 10. As a special case, a page length of 0 turns off page breaks.
blanktop	Number of blank lines at the top of the page. The default is 0, the minimum is 0 and the maximum must be a value so that ($blanktop + blankbtm$) $\leq (pagelength - 10)$.
blankbtm	Number of blank lines at the bottom of the page. The default is 0, the minimum is 0 and the maximum must be a value so that ($blanktop + blankbtm$) $\leq (pagelength - 10)$.
blankleft	Number of blank columns at the left of the page. The default is 0, the minimum is 0, and the maximum must maintain the relationship: blankleft < pagewidth.

If you use the . PAGE directive without arguments, it causes a 'formfeed': the next source line is printed on the next page in the list file. The . PAGE directive itself is not printed.

You can omit an argument by using two adjacent commas. If the remaining arguments after an argument are all empty, you can omit them.

Example

```
.PAGE ; formfeed, the next source line is printed ; on the next page in the list file.

.PAGE 96 ; set page width to 96. Note that you can ; omit the last four arguments.

.PAGE ,,3,3 ; use 3 line top/bottom margins.
```

Related Information

.TITLE (Set program title in header of assembler list file)

Assembler option --list-file

.REPEAT, .ENDREP

Syntax

```
[label] .REPEAT expression .... .ENDREP
```

Description

With the .REPEAT/.ENDREP directive you can repeat a sequence of assembly source lines. With *expression* you specify the number of times the loop is repeated. If the *expression* evaluates to a number less than or equal to 0, the sequence of lines will not be included in the assembler output. The *expression* result must be an absolute integer and cannot contain any forward references (symbols that have not already been defined). The .REPEAT directive may be nested to any level.

If you specify label, it gets the value of the location counter at the start of the directive processing.

Example

In this example the loop is repeated 3 times. Effectively, the preprocessor repeats the source lines (.DB 10) three times, then the assembler assembles the result:

```
.REPEAT 3
.DB 10 ; assembly source lines
.ENDFOR
```

Related Information

. FOR , . ENDFOR (Repeat sequence of source lines *n* times)

.SECTION, .ENDSEC

Syntax

```
.SECTION name[,at( address)]
....
.ENDSEC
```

Description

With the .SECTION directive you define a new section. Each time you use the .SECTION directive, a new section is created. It is possible to create multiple sections with exactly the same name.

If you define a section, you must always specify the section *name*. The names have a special meaning to the locating process and have to start with a predefined name, optionally extended by a dot '.' and a user defined name. The predefined section name also determines the type of the section (code, data or debug). Optionally, you can specify the at () attribute to locate a section at a specific address.

You can use the following predefined section names:

Section name	Description	Section type
.text	Code sections	code
.data	Initialized data	data
.sdata	Initialized data in read-write small data area	data
.bss	Uninitialized data (cleared)	data
.sbss	Uninitialized data in read-write small data area (cleared)	data
.rodata	ROM data (constants)	data
.debug	Debug sections	debug

Sections of a specified type are located by the linker in a memory space. The space names are defined in a so-called 'linker script file' (files with the extension .1s1) delivered with the product in the directory <code>installation-dir\include.ls1</code>.

Example

```
.SECTION .data ; Declare a .data section
.SECTION .data.abs, at(0x0) ; Declare a .data.abs section at ; an absolute address
```

Related Information

.OFFSET (Move location counter forwards)

.SET

Syntax

```
symbol .SET expression
.SET symbol expression
```

Description

With the . SET directive you assign the value of *expression* to symbol *temporarily*. If a symbol was defined with the . SET directive, you can redefine that symbol in another part of the assembly source, using the . SET directive again. Symbols that you define with the . SET directive are always local: you cannot define the symbol global with the . GLOBAL directive.

The . SET directive is useful in establishing temporary or reusable counters within macros. *expression* must be absolute and cannot include a symbol that is not yet defined (no forward references are allowed).

Example

```
COUNT .SET 0 ; Initialize count. Later on you can ; assign other values to the symbol
```

Related Information

. EQU (Set permanent value to a symbol)

.SIZE

Syntax

```
.SIZE symbol, expression
```

Description

With the .SIZE directive you set the size of the specified symbol to the value represented by expression.

The .SIZE directive may occur anywhere in the source file unless the specified symbol is a function. In this case, the .SIZE directive must occur after the function has been defined.

Example

```
.section .text
.global main
.arm
.align 4
; Function main
main: .type func
;
.SIZE main,$-main
.endsec
```

Related Information

```
.TYPE (Set symbol type)
```

.SOURCE

Syntax

.SOURCE string

Description

With the .SOURCE directive you specify the name of the original C source module. This directive is generated by the C compiler. You do not need this directive in hand-written assembly.

Example

.SOURCE "main.c"

.TITLE

Syntax

```
.TITLE ["string"]
```

Default

.TITLE ""

Description

If you generate a list file with the assembler option --list-file, you can use the <code>.TITLE</code> directive to specify the program title which is printed at the top of each page in the assembler list file.

If you use the .TITLE directive without the argument, the title becomes empty. This is also the default. The specified title is valid until the assembler encounters a new .TITLE directive.

The .TITLE directive itself will not be printed in the source listing.

If the page width is too small for the title to fit in the header, it will be truncated.

Example

```
.TITLE "This is the title"
```

Related Information

. PAGE (Format the assembler list file)

Assembler option --list-file

.TYPE

Syntax

```
symbol .TYPE typeid
```

Description

With the .TYPE directive you set a *symbol*'s type to the specified value in the ELF symbol table. Valid symbol types are:

FUNC The symbol is associated with a function or other executable code.

OBJECT The symbol is associated with an object such as a variable, an array, or a structure.

FILE The symbol name represents the filename of the compilation unit.

Labels in code sections have the default type FUNC. Labels in data sections have the default type OBJECT.

Example

Afunc: .type func

Related Information

.SIZE (Set symbol size)

.UNDEF

Syntax

.UNDEF symbol

Description

With the .UNDEF directive you can undefine a substitution string that was previously defined with the .DEFINE directive. The substitution string associated with *symbol* is released, and *symbol* will no longer represent a valid .DEFINE substitution or macro.

The assembler issues a warning if you redefine an existing symbol.

The assembler does not allow a label with this directive.

Example

The following example undefines the LEN substitution string that was previously defined with the . \mathtt{DEFINE} directive:

.UNDEF LEN

Related Information

.DEFINE (Define a substitution string)

.MACRO, .ENDM (Define a macro)

.WEAK

Syntax

```
.WEAK symbol[,symbol]...
```

Description

With the .WEAK directive you mark one or more symbols as 'weak'. The *symbol* can be defined in the same module with the .GLOBAL directive or the .EXTERN directive. If the symbol does not already exist, it will be created.

A 'weak' external reference is resolved by the linker when a global (or weak) definition is found in one of the object files. However, a weak reference will not cause the extraction of a module from a library to resolve the reference.

You can overrule a weak definition with a .GLOBAL definition in another module. The linker will not complain about the duplicate definition, and ignore the weak definition.

Only program labels and symbols defined with . EQU can be made weak.

Example

```
LOOPA .EQU 1 ; definition of symbol LOOPA .GLOBAL LOOPA ; LOOPA will be globally ; accessible by other modules .WEAK LOOPA ; mark symbol LOOPA as weak
```

Related Information

```
. EXTERN (Import global section symbol)
```

.GLOBAL (Declare global section symbol)

3.10. Macro Operations

Macros provide a shorthand method for inserting a repeated pattern of code or group of instructions. You can define the pattern as a macro, and then call the macro at the points in the program where the pattern would repeat.

Some patterns contain variable entries which change for each repetition of the pattern. Others are subject to conditional assembly.

When a macro is called, the assembler executes the macro and replaces the call by the resulting in-line source statements. 'In-line' means that all replacements act as if they are on the same line as the macro call. The generated statements may contain substitutable arguments. The statements produced by a macro can be any processor instruction, almost any assembler directive, or any previously-defined macro. Source statements resulting from a macro call are subject to the same conditions and restrictions as any other statements.

Macros can be nested. The assembler processes nested macros when the outer macro is expanded.

3.10.1. Defining a Macro

The first step in using a macro is to define it.

The definition of a macro consists of three parts:

- Header, which assigns a name to the macro and defines the arguments (.MACRO directive).
- Body, which contains the code or instructions to be inserted when the macro is called.
- Terminator, which indicates the end of the macro definition (.ENDM directive).

A macro definition takes the following form:

```
macro_name .MACRO [argument[,argument]...]
...
macro_definition_statements
...
.ENDM
```

For more information on the definition see the description of the .MACRO directive.

3.10.2. Calling a Macro

To invoke a macro, construct a source statement with the following format:

```
[label] macro_name [argument[,argument]...] [; comment]
where.
```

label An optional label that corresponds to the value of the location counter

at the start of the macro expansion.

macro_name The name of the macro. This may not start in the first column.

argument One or more optional, substitutable arguments. Multiple arguments

must be separated by commas.

comment An optional comment.

The following applies to macro arguments:

Each argument must correspond one-to-one with the formal arguments of the macro definition. If the
macro call does not contain the same number of arguments as the macro definition, the assembler
issues a warning.

- If an argument has an embedded comma or space, you must surround the argument by single quotes
 (').
- You can declare a macro call argument as null in three ways:
 - · enter delimiting commas in succession with no intervening spaces

```
macroname ARG1, ARG3; the second argument is a null argument
```

 terminate the argument list with a comma, the arguments that normally would follow, are now considered null

```
macroname ARG1, ; the second and all following arguments are null
```

- · declare the argument as a null string
- No character is substituted in the generated statements that reference a null argument.

3.10.3. Using Operators for Macro Arguments

The assembler recognizes certain text operators within macro definitions which allow text substitution of arguments during macro expansion. You can use these operators for text concatenation, numeric conversion, and string handling.

Operator	Name	Description
\	Macro argument concatenation	Concatenates a macro argument with adjacent alphanumeric characters.
?	Return decimal value of symbol	Substitutes the ?symbol sequence with a character string that represents the decimal value of the symbol.
%	Return hex value of symbol	Substitutes the <i>%symbol</i> sequence with a character string that represents the hexadecimal value of the symbol.
"	Macro string delimiter	Allows the use of macro arguments as literal strings.
۸	Macro local label override	Prevents name mangling on labels in macros.

**Example: Argument Concatenation Operator - **

Consider the following macro definition:

```
MAC_A .MACRO reg,val
    sub    r\reg,r\reg,#val
    .ENDM
```

The macro is called as follows:

```
MAC A 2,1
```

The macro expands as follows:

```
sub r2, r2, #1
```

The macro preprocessor substitutes the character '2' for the argument reg, and the character '1' for the argument reg. The concatenation operator (\) indicates to the macro preprocessor that the substitution characters for the arguments are to be concatenated with the characters 'r'.

Without the '\' operator the macro would expand as:

```
sub rreg, rreg, #1
```

which results in an assembler error (invalid operand).

Example: Decimal Value Operator - ?

Instead of substituting the formal arguments with the actual macro call arguments, you can also use the value of the macro call arguments.

Consider the following source code that calls the macro $\mathtt{MAC}_\mathtt{A}$ after the argument \mathtt{AVAL} has been set to 1.

```
AVAL .SET 1
MAC A 2,AVAL
```

If you want to replace the argument val with the value of AVAL rather than with the literal string 'AVAL', you can use the ? operator and modify the macro as follows:

```
MAC_A .MACRO reg,val
    sub    r\reg,r\reg,#?val
    .ENDM
```

Example: Hex Value Operator - %

The percent sign (%) is similar to the standard decimal value operator (?) except that it returns the hexadecimal value of a symbol.

Consider the following macro definition:

```
GEN_LAB .MACRO LAB, VAL, STMT LAB\$VAL STMT .ENDM
```

The macro is called after NUM has been set to 10:

```
NUM .SET 10
GEN_LAB HEX,NUM,NOP
```

The macro expands as follows:

```
HEXA NOP
```

The VAL argument is replaced by the character 'A' which represents the hexadecimal value 10 of the argument VAL.

Example: Argument String Operator - "

To generate a literal string, enclosed by single quotes ('), you must use the argument string operator (") in the macro definition.

Consider the following macro definition:

```
STR_MAC .MACRO STRING
.DB "STRING"
.ENDM
```

The macro is called as follows:

```
STR_MAC ABCD
```

The macro expands as follows:

```
.DB 'ABCD'
```

Within double quotes .DEFINE directive definitions can be expanded. Take care when using constructions with single quotes and double quotes to avoid inappropriate expansions. Since .DEFINE expansion occurs before macro substitution, any .DEFINE symbols are replaced first within a macro argument string:

```
.DEFINE LONG 'short'

STR_MAC .MACRO STRING

.MESSAGE I 'This is a LONG STRING'

.MESSAGE I "This is a LONG STRING"

.ENDM
```

If the macro is called as follows:

```
STR_MAC sentence
```

it expands as:

```
.MESSAGE I 'This is a LONG STRING'
.MESSAGE I 'This is a short sentence'
```

Macro Local Label Override Operator - ^

If you use labels in macros, the assembler normally generates another unique name for the labels (such as LOCAL_M_L000001).

The macro ^-operator prevents name mangling on macro local labels.

Consider the following macro definition:

```
INIT .MACRO addr
LOCAL: ldr r0,^addr
.ENDM
```

The macro is called as follows:

```
LOCAL:

INIT LOCAL

The macro expands as:
```

```
LOCAL_M_L000001: ldr r0,LOCAL
```

If you would not have used the ^ operator, the macro preprocessor would choose another name for LOCAL because the label already exists. The macro would expand like:

```
LOCAL M L000001: ldr r0,LOCAL M L000001
```

3.11. Generic Instructions

The assembler supports so-called 'generic instructions'. Generic instructions are pseudo instructions (no instructions from the instruction set). Depending on the situation in which a generic instruction is used, the assembler replaces the generic instruction with appropriate real assembly instruction(s).

3.11.1. ARM Generic Instructions

The ARM assembler recognizes the following generic instructions in ARM mode:

ADR, ADRL, ADRLL ARM generics

Load a PC-relative address into a register. The address is specified as a target label. The assembler generates one (ADR), two (ADRL) or three (ADRLL) generic DPR instruction (called ADR) and one, two or three PC-relative relocation types for the target label. The linker evaluates the relocation types (calculate the PC-relative offset) and generates one, two or three add or sub instructions each with an 8-bit immediate operand plus a 4-bit rotation. If the offset cannot be encoded the linker generates an error message.

Instruction	Replacement
ADR cond Rd, label	ADR <i>cond Rd</i> , PC, @ALUPCREL(<i>label</i> ,0,1)
ADRLcond Rd,label	ADR <i>cond Rd</i> , PC, @ALUPCREL(<i>label</i> ,0,0) ADR <i>cond Rd</i> , <i>Rd</i> , @ALUPCREL(<i>label</i> ,1,1)
	ADR <i>cond Rd</i> , PC, @ALUPCREL(<i>label</i> ,0,0) ADR <i>cond Rd</i> , <i>Rd</i> , @ALUPCREL(<i>label</i> ,1,0) ADR <i>cond Rd</i> , <i>Rd</i> , @ALUPCREL(<i>label</i> ,2,1)

BX for ARMv4

The ARMv4 architecture does not support the BX instruction in hardware. If the option --cpu=ARMv4 or --cpu=ARMv4T was specified, the assembler will emit a relocation type at the location of the BX instruction. The linker will replace the BX instruction by a MOV instruction if the option --cpu=ARMv4 was specified.

Instruction	Replacement	Remarks
BXcond Rm	MOV cond PC,Rm	Only if architecture is ARMv4

3.11.2. ARM and Thumb-2 32-bit Generic Instructions

LDR= ARM and Thumb-2 generic

Load an address or a 32-bit constant value into a register. If the constant or its bitwise negation can be encoded, then the assembler will generate a MOV or a MVN instruction. Otherwise the assembler places the constant or the address in a literal pool and generates a PC-relative LDR instruction that loads the value from the literal pool.

Instruction	Replacement	Remarks
LDR <i>cond</i> Rd,=expr	MOV cond Rd, #expr	If expr can be encoded
	MVNcond Rd,#@LSW(~(expr))	If ~expr can be encoded
	LDRcond Rd,ltpool ;; code ltpool: .DW expr	If expr is external or PC-relative, or cannot be encoded

The PC-relative offset from the LDR instruction to the value in the literal pool must be positive and less than 4 kB. By default the assembler will place a literal pool at the end of each code section. If the default literal pool is out-of-range you will have to ensure that there is another literal pool within range by means of the .LTORG directive.

VLDR= ARM and Thumb-2 generic

Load a 32-bit or 64-bit floating-point constant value into a register. The assembler places the constant in a literal pool and generates a PC-relative VLDR instruction that loads the value from the literal pool.

Instruction	Replacement
VLDR <i>cond Sd</i> ,=expr	
	;; code
	ltpool:
	.FLOAT expr
VLDRcond Dd,=expr	VLDRcond Dd,ltpool
	;; code
	<pre>ltpool:</pre>
	.DOUBLE expr

MOV32 ARM and Thumb-2 generic

Load an address or a 32-bit constant value into a register.

Instruction	Replacement	Remarks
	MOVW <i>cond Rd</i> , #@LSH(<i>expr</i>) MOVT <i>cond Rd</i> , #@MSH(<i>expr</i>)	If expr is internal and absolute
	MOVWcond Rd, #expr MOVTcond Rd, #expr	If expr is external or relocatable

ARM and Thumb-2 generic DPR inversions for immediate operands

For data processing instructions (DPR) which operate on an immediate operand, the operand value must be encoded as an 8-bit value plus a 4-bit even rotation value. If a value does not fit in such an encoding, it could be possible that the negated value (-value) or the bitwise negated value (~value) does fit in such an encoding. In that case the assembler will replcace the DPR instruction by its inverse DPR instruction operating on the negated value.

Instruction	Replacement (if #-imm or #~imm can be encoded)
ADDcond Rd,Rn,#imm32	SUBcond Rd,Rn,#-(imm32)
ADDcondS Rd,Rn,#imm32	SUBcondS Rd,Rn,#-(imm32)
ADDWcond Rd,Rn,#imm12	SUBWcond Rd,Rn,#-(imm12)
SUBcond Rd,Rn,#imm32	ADDcond Rd,Rn,#-(imm32)
SUBcondS Rd,Rn,#imm32	ADDcondS Rd,Rn,#-(imm32)
SUBWcond Rd,Rn,#imm12	ADDWcond Rd,Rn,#-(imm12)
ADCcond Rd,Rn,#imm32	SBCcond Rd,Rn,#-(imm32)
ADCcondS Rd,Rn,#imm32	SBCcondS Rd,Rn,#-(imm32)
SBCcond Rd,Rn,#imm32	ADCcond Rd,Rn,#-(imm32)
SBCcondS Rd,Rn,#imm32	ADCcondS Rd,Rn,#-(imm32)
ANDcond Rd,Rn,#imm32	BICcond Rd,Rn,#@LSW(~(imm32))
ANDcondS Rd,Rn,#imm32	BICcondS Rd,Rn,#@LSW(~(imm32))

Instruction	Replacement (if #-imm or #~imm can be encoded)
BICcond Rd,Rn,#imm32	ANDcond Rd,Rn,#@LSW(~(imm32))
BICcondS Rd,Rn,#imm32	ANDcondS Rd,Rn,#@LSW(~(imm32))
CMNcond Rn,#imm32	CMPcond Rn,#-(imm)
CMPcond Rn,#imm32	CMNcond Rn,#-(imm)
MOV cond Rd,#imm32	MVNcond Rd,#@LSW(~(imm32))
MOV condS Rd,#imm32	MVNcondS Rd,#@LSW(~(imm32))
MVNcond Rd,#imm32	MOV cond Rd,#@LSW(~(imm32))
MVNcondS Rd,#imm32	MOV condS Rd,#@LSW(~(imm32))

Note that the built-in function @LSW() must be used on the bitwise negated immediate value because all values are interpreted by the assembler as 64-bit signed values. The @LSW() function returns the lowest 32 bits.

3.11.3. Thumb 16-bit Generic Instructions

The ARM assembler recognizes the following generic instructions in Thumb mode:

ADR Thumb 16-bit generic

Load a PC-relative address into a low register. The address is specified as a target label. The PC-relative offset must be less than 1 kB. The target label must be defined locally, must be word-aligned and must be in the same code section as the instruction. The assembler will not emit a relocation type for the target label. If the offset is out-of-range or the target label is external or in another section, then the assembler generates an error message.

LDR=Thumb 16-bit generic

Load an address or a 32-bit constant value into a low register. If the constant is in the range [0,255] the assembler will generate a MOV instruction. Otherwise the assembler places the constant or the address in a literal pool and generates a PC-relative LDR instruction that loads the value from the literal pool.

Instruction	Replacement	Remarks
LDR Rd,=expr	MOV Rd, #expr	If expr is in range
	LDR Rd, ltpool ;; code ltpool:	If <i>expr</i> is external or PC-relative, or not in range
	.DW expr	

The PC-relative offset from the LDR instruction to the value in the literal pool must be positive and less than 1 kB. By default the assembler will place a literal pool at the end of each code section. If the default literal pool is out-of-range you will have to ensure that there is another literal pool within range by means of the .LTORG directive.

Bcond inversion Thumb 16-bit generic

The PC-relative conditional branch instruction has a range of (-256,+255) bytes. The unconditional version has a range of (-2048,+2047) bytes. If the conditional branch target is out-of-range, the assembler will rewrite the conditional branch instruction with an inversed conditional branch and an unconditional branch.

Instruction	Replacement	Remarks
Bcond label	B label	If target label out-of-range
	~1: 	

ADD, SUB inversions Thumb 16-bit generic

For the following six instructions the assembler accepts negative values for the immediate operand. If a negative value is specified, the assembler inverts the instruction from ADD to SUB or vice versa. For example: ADD R1.#-4 will be rewritten as SUB R1.#4.

Instruction	Replacement
ADD Rd,Rn,#imm	SUB Rd,Rn,#-(imm)
ADD Rd,#imm	SUB Rd,#-(imm)
ADD SP,#imm	SUB SP,#-(imm)
SUB Rd,Rn,#imm	ADD Rd,Rn,#-(imm)
SUB Rd,#imm	ADD Rd,#-(imm)
SUB SP,#imm	ADD SP,#-(imm)

Chapter 4. Using the C Compiler

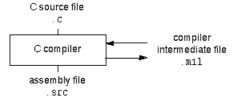
This chapter describes the compilation process and explains how to call the C compiler.

The TASKING VX-toolset for ARM under Eclipse can use the internal builder (default) or the TASKING makefile generator (external builder) to build your entire embedded project, from C source till the final ELF/DWARF object file which serves as input for the debugger.

Although in Eclipse you cannot run the C compiler separately from the other tools, this section discusses the options that you can specify for the C compiler.

On the command line it is possible to call the C compiler separately from the other tools. However, it is recommended to use the control program for command line invocations of the toolset (see Section 10.1, *Control Program*). With the control program it is possible to call the entire toolset with only one command line.

The C compiler takes the following files for input and output:



This chapter first describes the compilation process which consists of a *frontend* and a *backend* part. Next it is described how to call the C compiler and how to use its options. An extensive list of all options and their descriptions is included in Section 12.1, C Compiler Options. Finally, a few important basic tasks are described, such as including the C startup code and performing various optimizations.

4.1. Compilation Process

During the compilation of a C program, the C compiler runs through a number of phases that are divided into two parts: *frontend* and *backend*.

The backend part is not called for each C statement, but starts after a complete C module or set of modules has been processed by the frontend (in memory). This allows better optimization.

The C compiler requires only one pass over the input file which results in relative fast compilation.

Frontend phases

1. The preprocessor phase:

The preprocessor includes files and substitutes macros by C source. It uses only string manipulations on the C source. The syntax for the preprocessor is independent of the C syntax but is also described in the ISO/IEC 9899:1999(E) standard.

2. The scanner phase:

The scanner converts the preprocessor output to a stream of tokens.

3. The parser phase:

The tokens are fed to a parser for the C grammar. The parser performs a syntactic and semantic analysis of the program, and generates an intermediate representation of the program. This code is called MIL (Medium level Intermediate Language).

4. The frontend optimization phase:

Target processor independent optimizations are performed by transforming the intermediate code.

Backend phases

1. Instruction selector phase:

This phase reads the MIL input and translates it into Low level Intermediate Language (LIL). The LIL objects correspond to a processor instruction, with an opcode, operands and information used within the C compiler.

2. Peephole optimizer/instruction scheduler/software pipelining phase:

This phase replaces instruction sequences by equivalent but faster and/or shorter sequences, rearranges instructions and deletes unnecessary instructions.

3. Register allocator phase:

This phase chooses a physical register to use for each virtual register.

4. The backend optimization phase:

Performs target processor independent and dependent optimizations which operate on the Low level Intermediate Language.

5. The code generation/formatter phase:

This phase reads through the LIL operations to generate assembly language output.

4.2. Calling the C Compiler

The TASKING VX-toolset for ARM under Eclipse can use the internal builder (default) or the TASKING makefile generator (external builder) to build your entire project. After you have built your project, the output files are available in a subdirectory of your project directory, depending on the active configuration you have set in the **C/C++ Build » Settings** page of the **Project » Properties** dialog.

Building a project under Eclipse

You have several ways of building your project:

• Build Selected File(s) (i). This compiles and assembles the selected file(s) without calling the linker.

- 1. In the C/C++ Projects view, select the files you want to compile.
- 2. Right-click in the C/C++ Projects view and select Build Selected File(s).
- Build Individual Project (¹

 ¹

 ¹

To build individual projects incrementally, select **Project** » **Build Project**.

- Rebuild Project (). This builds every file in the project whether or not a file has been modified since the last build. A rebuild is a clean followed by a build.
 - 1. Select Project » Clean...
 - 2. Enable the option Start a build immediately and click OK.
- Build Automatically. This performs a build of all projects whenever any project file is saved, such as your makefile.

This way of building is not recommended for C/C++ development, but to enable this feature select **Project** » **Build Automatically** and ensure there is a check mark beside the **Build Automatically** menu item.

Select a target processor (core)

Processor options affect the invocation of all tools in the toolset. In Eclipse you only need to set them once. Based on the target processor, the compiler includes a special function register file. This is a regular include file which enables you to use virtual registers that are located in memory.

1. From the **Project** menu, select **Properties**

The Properties dialog appears.

2. In the left pane, expand C/C++ Build and select Processor.

In the right pane the Processor page appears.

3. From the **Processor Selection** list, select a processor.

To access the C/C++ compiler options

From the Project menu, select Properties

The Properties dialog appears.

2. In the left pane, expand **C/C++ Build** and select **Settings**.

In the right pane the Settings appear.

- 3. On the Tool Settings tab, select **C/C++ Compiler**.
- 4. Select the sub-entries and set the options in the various pages.

Note that the C/C++ compiler options are used to create an object file from a C or C++ file. This means that the options you enter in the Assembler page are not used for intermediate assembly files, only for hand-coded assembly files.

You can find a detailed description of all C compiler options in Section 12.1, C Compiler Options.

Invocation syntax on the command line (Windows Command Prompt):

```
carm [ [option]... [file]... ]...
```

4.3. How the Compiler Searches Include Files

When you use include files (with the #include statement), you can specify their location in several ways. The compiler searches the specified locations in the following order:

1. If the #include statement contains an absolute pathname, the compiler looks for this file. If no path or a relative path is specified, the compiler looks in the same directory as the source file. This is only possible for include files that are enclosed in "".

This first step is not done for include files enclosed in <>.

- When the compiler did not find the include file, it looks in the directories that are specified in the C/C++
 Compiler » Include Paths page in the C/C++ Build » Settings » Tool Settings tab of the Project
 Properties dialog (equivalent to the -I command line option).
- 3. When the compiler did not find the include file (because it is not in the specified include directory or because no directory is specified), it looks in the path(s) specified in the environment variable CARMINC.
- 4. When the compiler still did not find the include file, it finally tries the default include directory relative to the installation directory (unless you specified option --no-stdinc).

Example

Suppose that the C source file test.c contains the following lines:

```
#include <stdio.h>
#include "myinc.h"
```

You can call the compiler as follows:

```
carm - Imyinclude test.c
```

First the compiler looks for the file stdio.h in the directory myinclude relative to the current directory. If it was not found, the compiler searches in the environment variable CARMINC and then in the default include directory.

The compiler now looks for the file myinc.h, in the directory where test.c is located. If the file is not there the compiler searches in the directory myinclude. If it was still not found, the compiler searches in the environment variable CARMINC and then in the default include directory.

4.4. Compiling for Debugging

Compiling your files is the first step to get your application ready to run on a target. However, during development of your application you first may want to debug your application.

To create an object file that can be used for debugging, you must instruct the compiler to include symbolic debug information in the source file.

To include symbolic debug information

1. From the Project menu, select Properties

The Properties dialog appears.

2. In the left pane, expand **C/C++ Build** and select **Settings**.

In the right pane the Settings appear.

- 3. On the Tool Settings tab, select C/C++ Compiler » Debugging.
- 4. Select **Default** in the **Generate symbolic debug information** box.

Debug and optimizations

Due to different compiler optimizations, it might be possible that certain debug information is optimized away. Therefore, if you encounter strange behavior during debugging it might be necessary to reduce the optimization level, so that the source code is still suitable for debugging. For more information on optimization see Section 4.5, *Compiler Optimizations*.

Invocation syntax on the command line (Windows Command Prompt)

The invocation syntax on the command line is:

```
carm -q file.c
```

4.5. Compiler Optimizations

The compiler has a number of optimizations which you can enable or disable.

1. From the **Project** menu, select **Properties**

The Properties dialog appears.

2. In the left pane, expand C/C++ Build and select Settings.

In the right pane the Settings appear.

- 3. On the Tool Settings tab, select **C/C++ Compiler » Optimization**.
- 4. Select an optimization level in the **Optimization level** box.

or:

In the **Optimization level** box select **Custom optimization** and enable the optimizations you want on the Custom optimization page.

Optimization levels

The TASKING C compiler offers four optimization levels and a custom level, at each level a specific set of optimizations is enabled.

- Level 0 No optimization: No optimizations are performed. The compiler tries to achieve a 1-to-1
 resemblance between source code and produced code. Expressions are evaluated in the order written
 in the source code, associative and commutative properties are not used.
- Level 1 Optimize: Enables optimizations that do not affect the debug-ability of the source code. Use
 this level when you encounter problems during debugging your source code with optimization level 2.
- Level 2 Optimize more (default): Enables more optimizations to reduce the memory footprint and/or execution time. This is the default optimization level.
- Level 3 Optimize most: This is the highest optimization level. Use this level when your program/hardware has become too slow to meet your real-time requirements.
- Custom optimization: you can enable/disable specific optimizations on the Custom optimization page.

Optimization pragmas

If you specify a certain optimization, all code in the module is subject to that optimization. Within the C source file you can overrule the C compiler options for optimizations with #pragma optimize flag and #pragma endoptimize. Nesting is allowed:

The compiler optimizes the code between the pragma pair as specified.

You can enable or disable the optimizations described in the following subsection. The command line option for each optimization is given in brackets.

4.5.1. Generic Optimizations (frontend)

Common subexpression elimination (CSE) (option -Oc/-OC)

The compiler detects repeated use of the same (sub-)expression. Such a "common" expression is replaced by a variable that is initialized with the value of the expression to avoid recomputation. This method is called common subexpression elimination (CSE).

Expression simplification (option -Oe/-OE)

Multiplication by 0 or 1 and additions or subtractions of 0 are removed. Such useless expressions may be introduced by macros or by the compiler itself (for example, array subscripting).

Constant propagation (option -Op/-OP)

A variable with a known value is replaced by that value.

Automatic function inlining (option -Oi/-OI)

Small functions that are not too often called, are inlined. This reduces execution time at the cost of code size.

Control flow simplification (option -Of/-OF)

A number of techniques to simplify the flow of the program by removing unnecessary code and reducing the number of jumps. For example:

- Switch optimization: A number of optimizations of a switch statement are performed, such as removing redundant case labels or even removing an entire switch.
- Jump chaining: A (conditional) jump to a label which is immediately followed by an unconditional jump
 may be replaced by a jump to the destination label of the second jump. This optimization speeds up
 execution.
- Conditional jump reversal: A conditional jump over an unconditional jump is transformed into one
 conditional jump with the jump condition reversed. This reduces both the code size and the execution
 time.
- Dead code elimination: Code that is never reached, is removed. The compiler generates a warning messages because this may indicate a coding error.

Subscript strength reduction (option -Os/-OS)

An array or pointer subscripted with a loop iterator variable (or a simple linear function of the iterator variable), is replaced by the dereference of a pointer that is updated whenever the iterator is updated.

Loop transformations (option -OI/-OL)

Transform a loop with the entry point at the bottom, to a loop with the entry point at the top. This enables constant propagation in the initial loop test and code motion of loop invariant code by the CSE optimization.

Forward store (option -Oo/-OO)

A temporary variable is used to cache multiple assignments (stores) to the same non-automatic variable.

4.5.2. Core Specific Optimizations (backend)

Coalescer (option -Oa/-OA)

The coalescer seeks for possibilities to reduce the number of moves (MOV instruction) by smart use of registers. This optimizes both speed as code size.

Interprocedural register optimization (option -Ob/-OB)

Register allocation is improved by taking note of register usage in functions called by a given function.

Peephole optimizations (option -Oy/-OY)

The generated assembly code is improved by replacing instruction sequences by equivalent but faster and/or shorter sequences, or by deleting unnecessary instructions.

Instruction Scheduler (option -Ok/-OK)

When two instructions need the same machine resource - like a bus, register or functional unit - at the same time, they suffer a *structural hazard*, which stalls the pipeline. This optimization tries to rearrange instructions to avoid structural hazards, for example by inserting another non-related instruction.

Loop unrolling (option -Ou/-OU)

To reduce the number of branches, short loops are eliminated by replacing them with a number of copies.

Software pipelining (option -Ow/-OW)

A number of techniques to optimize loops. For example, within a loop the most efficient order of instructions is chosen by the *pipeline scheduler* and it is examined what instructions can be executed parallel.

Generic assembly optimizations (option -Og/-OG)

A set of target independent optimizations that increase speed and decrease code size.

4.5.3. Optimize for Size or Speed

You can tell the compiler to focus on execution speed or code size during optimizations. You can do this by specifying a size/speed trade-off level from 0 (speed) to 4 (size). This trade-off does not turn optimization phases on or off. Instead, its level is a weight factor that is used in the different optimization phases to influence the heuristics. The higher the level, the more the compiler focusses on code size optimization. To choose a trade-off value read the description below about which optimizations are affected and the impact of the different trade-off values.

Note that the trade-off settings are directions and there is no guarantee that these are followed. The compiler may decide to generate different code if it assessed that this would improve the result.

To specify the size/speed trade-off optimization level:

1. From the Project menu, select Properties

The Properties dialog appears.

2. In the left pane, expand **C/C++ Build** and select **Settings**.

In the right pane the Settings appear.

- 3. On the Tool Settings tab, select **C/C++ Compiler** » **Optimization**.
- 4. Select a trade-off level in the Trade-off between speed and size box.

See also C compiler option --tradeoff (-t)

Instruction Selection

Trade-off levels 0, 1 and 2: the compiler selects the instructions with the smallest number of cycles.

Trade-off levels 3 and 4: the compiler selects the instructions with the smallest number of bytes.

Switch Jump Chain versus Jump Table

Instruction selection for the switch statements follows different trade-off rules. A switch statement can result in a jump chain or a jump table. The compiler makes the decision between those by measuring and weighing bytes and cycles. This weigh is controlled with the trade-off values:

Trade-off value	Time	Size
0	100%	0%
1	75%	25%
2	50%	50%
3	25%	75%
4	0%	100%

Loop Optimization

For a top-loop, the loop is entered at the top of the loop. A bottom-loop is entered at the bottom. Every loop has a test and a jump at the bottom of the loop, otherwise it is not possible to create a loop. Some top-loops also have a conditional jump before the loop. This is only necessary when the number of loop iterations is unknown. The number of iterations might be zero, in this case the conditional jump jumps over the loop.

Bottom loops always have an unconditional jump to the loop test at the bottom of the loop.

Trade-off value	Try to rewrite top-loops to bottom-loops	Optimize loops for size/speed
0	no	speed
1	yes	speed

	Try to rewrite top-loops to bottom-loops	Optimize loops for size/speed
2	yes	speed
3	yes	size
4	yes	size

Example:

```
int a;
void i( int 1, int m )
{
    int i;
    for ( i = m; i < 1; i++ )
        {
            a++;
        }
      return;
}</pre>
```

Coded as a bottom loop (compiled with --tradeoff=4) is:

```
ldr
              r2,.L4
       b
              .L2
                          ;; unconditional jump to loop test at bottom
.L3:
        ldr
             r3,[r2,#0]
        add
             r1,r1,#1
        add
              r3,r3,#1
        str
              r3,[r2,#0]
.L2:
                          ;; loop entry point
              r1,r0
        cmp
       blt
              .L3
```

Coded as a top loop (compiled with --tradeoff=0) is:

```
cmp
              r1,r0
                          ;; test for at least one loop iteration
                          ;; can be omitted when number of iterations is known
        ldr
        ldr
             r3,[r2,#0]
       bge
             .L2
        sub
             r0,r0,r1
.L3:
                          ;; loop entry point
        subs r0,r0,\#1
        add
             r0,r0,#1
       bgt
              .L3
.L2:
        str
            r3,[r2,#0]
```

Automatic Function Inlining

Trade-off levels 0, 1 and 2: the compiler inlines functions as long as the function will not grow more than the percentage specified with option --inline-max-incr.

Trade-off levels 3 and 4: no automatic inlining.

The following inlining is independent of the trade-off level:

- Functions that are smaller or equal to the threshold specified with the option --inline-max-size are always inlined.
- Static functions that are called only once, are always inlined.

4.6. C Code Checking: MISRA-C

The C programming language is a standard for high level language programming in embedded systems, yet it is considered somewhat unsuitable for programming safety-related applications. Through enhanced code checking and strict enforcement of best practice programming rules, TASKING MISRA-C code checking helps you to produce more robust code.

MISRA-C specifies a subset of the C programming language which is intended to be suitable for embedded automotive systems. It consists of a set of rules, defined in *MISRA-C:2004*, *Guidelines for the Use of the C Language in Critical Systems* (Motor Industry Research Association (MIRA), 2004).

The compiler also supports MISRA-C:1998, the first version of MISRA-C. You can select this version with the following C compiler option:

```
--misrac-version=1998
```

For a complete overview of all MISRA-C rules, see Chapter 18, MISRA-C Rules.

Implementation issues

The MISRA-C implementation in the compiler supports nearly all rules. Only a few rules are not supported because they address documentation, run-time behavior, or other issues that cannot be checked by static source code inspection, or because they require an application-wide overview.

During compilation of the code, violations of the enabled MISRA-C rules are indicated with error messages and the build process is halted.

MISRA-C rules are divided in required rules and advisory rules. If rules are violated, errors are generated causing the compiler to stop. With the following options warnings, instead of errors, are generated for either or both the required rules and the advisory rules:

```
--misrac-required-warnings
--misrac-advisory-warnings
```

Note that not all MISRA-C violations will be reported when other errors are detected in the input source. For instance, when there is a syntax error, all semantic checks will be skipped, including some of the MISRA-C checks. Also note that some checks cannot be performed when the optimizations are switched off.

Quality Assurance report

To ensure compliance to the MISRA-C rules throughout the entire project, the TASKING linker can generate a MISRA-C Quality Assurance report. This report lists the various modules in the project with the respective MISRA-C settings at the time of compilation. You can use this in your company's quality assurance system to provide proof that company rules for best practice programming have been applied in the particular project.

To apply MISRA-C code checking to your application

1. From the Project menu, select Properties

The Properties dialog appears.

In the left pane, expand C/C++ Build and select Settings.

In the right pane the Settings appear.

- 3. On the Tool Settings tab, select C/C++ Compiler » MISRA-C.
- 4. Select the MISRA-C version (2004 or 1998).
- 5. In the **MISRA-C checking** box select a MISRA-C configuration. Select a predefined configuration for conformance with the required rules in the MISRA-C guidelines.
- 6. (Optional) In the Custom 2004 or Custom 1998 entry, specify the individual rules.

On the command line you can use the option --misrac.

```
carm --misrac={all | number [-number],...]
```

4.7. C Compiler Error Messages

The C compiler reports the following types of error messages in the Problems view of Eclipse.

F (Fatal errors)

After a fatal error the compiler immediately aborts compilation.

E (Errors)

Errors are reported, but the compiler continues compilation. No output files are produced unless you have set the C compiler option --keep-output-files (the resulting output file may be incomplete).

W (Warnings)

Warning messages do not result into an erroneous assembly output file. They are meant to draw your attention to assumptions of the compiler for a situation which may not be correct. You can control warnings in the C/C++ Build » Settings » Tool Settings » C/C++ Compiler » Diagnostics page of the Project » Properties menu (C compiler option --no-warnings).

I (Information)

Information messages are always preceded by an error message. Information messages give extra information about the error.

S (System errors)

System errors occur when internal consistency checks fail and should never occur. When you still receive the system error message

```
S9##: internal consistency check failed - please report
```

please report the error number and as many details as possible about the context in which the error occurred.

Display detailed information on diagnostics

1. From the Window menu, select Show View » Other » General » Problems.

The Problems view is added to the current perspective.

2. In the Problems view right-click on a message.

A popup menu appears.

3. Select Detailed Diagnostics Info.

A dialog box appears with additional information.

On the command line you can use the C compiler option --diag to see an explanation of a diagnostic message:

```
carm --diag=[format:]{all | number,...]
```

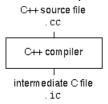
Chapter 5. Using the C++ Compiler

This chapter describes the compilation process and explains how to call the C++ compiler. You should be familiar with the C++ language and with the ISO C language.

The C++ compiler can be seen as a preprocessor or front end which accepts C++ source files or sources using C++ language features. The output generated by the C++ compiler (**cparm**) is intermediate C, which can be translated with the C compiler (**carm**).

The C++ compiler is part of a complete toolset, the TASKING VX-toolset for ARM. For details about the C compiler see Chapter 4, *Using the C Compiler*.

The C++ compiler takes the following files for input and output:



Although in Eclipse you cannot run the C++ compiler separately from the other tools, this section discusses the options that you can specify for the C++ compiler.

On the command line it is possible to call the C++ compiler separately from the other tools. However, it is recommended to use the control program for command line invocations of the toolset (see Section 10.1, Control Program). With the control program it is possible to call the entire toolset with only one command line. Eclipse also uses the control program to call the C++ compiler. Files with the extensions .cc, .cpp or .cxx are seen as C++ source files and passed to the C++ compiler.

The C++ compiler accepts the C++ language of the ISO/IEC 14882:1998 C++ standard, with some minor exceptions documented in Chapter 2, C++ Language. It also accepts embedded C++ language extensions.

The C++ compiler does no optimization. Its goal is to produce quickly a complete and clean parsed form of the source program, and to diagnose errors. It does complete error checking, produces clear error messages (including the position of the error within the source line), and avoids cascading of errors. It also tries to avoid seeming overly finicky to a knowledgeable C or C++ programmer.

5.1. Calling the C++ Compiler

Under Eclipse you cannot run the C++ compiler separately. However, you can set options specific for the C++ compiler. After you have built your project, the output files are available in a subdirectory of your project directory, depending on the active configuration you have set in the C/C++ Build » Settings page of the Project » Properties dialog.

Building a project under Eclipse

You have several ways of building your project:

• Build Selected File(s) (i). This compiles and assembles the selected file(s) without calling the linker.

- 1. In the C/C++ Projects view, select the files you want to compile.
- 2. Right-click in the C/C++ Projects view and select **Build Selected File(s)**.
- Build Individual Project (¹⁰⁰).

To build individual projects incrementally, select Project » Build Project.

- Rebuild Project (). This builds every file in the project whether or not a file has been modified since the last build. A rebuild is a clean followed by a build.
 - 1. Select Project » Clean...
 - 2. Enable the option Start a build immediately and click OK.
- Build Automatically. This performs a build of all projects whenever any project file is saved, such as your makefile.

This way of building is not recommended for C/C++ development, but to enable this feature select **Project » Build Automatically** and ensure there is a check mark beside the **Build Automatically** menu item.

Select a target processor (core)

Processor options affect the invocation of all tools in the toolset. In Eclipse you only need to set them once. Based on the target processor, the compiler includes a special function register file. This is a regular include file which enables you to use virtual registers that are located in memory.

1. From the **Project** menu, select **Properties**

The Properties dialog appears.

In the left pane, expand C/C++ Build and select Processor.

In the right pane the Processor page appears.

3. From the **Processor Selection** list, select a processor.

To access the C/C++ compiler options

1. From the **Project** menu, select **Properties**

The Properties dialog appears.

2. In the left pane, expand C/C++ Build and select Settings.

In the right pane the Settings appear.

- 3. On the Tool Settings tab, select **C/C++ Compiler**.
- 4. Select the sub-entries and set the options in the various pages.

Note that C++ compiler options are only enabled if you have added a C++ file to your project, a file with the extension .cc, .cpp or .cxx.

Note that the C/C++ compiler options are used to create an object file from a C or C++ file. This means that the options you enter in the Assembler page are not used for intermediate assembly files, only for hand-coded assembly files.

You can find a detailed description of all C++ compiler options in Section 12.2, C++ Compiler Options.

Invocation syntax on the command line (Windows Command Prompt):

```
cparm [ [option]... [file]... ]...
```

5.2. How the C++ Compiler Searches Include Files

When you use include files (with the #include statement), you can specify their location in several ways. The C++ compiler searches the specified locations in the following order:

1. If the #include statement contains an absolute pathname, the C++ compiler looks for this file. If no path or a relative path is specified, the C++ compiler looks in the same directory as the source file. This is only possible for include files that are enclosed in "".

This first step is not done for include files enclosed in <>.

- 2. When the C++ compiler did not find the include file, it looks in the directories that are specified in the C/C++ Compiler » Include Paths page in the C/C++ Build » Settings » Tool Settings tab of the Project Properties dialog (equivalent to the --include-directory (-I) command line option).
- When the C++ compiler did not find the include file (because it is not in the specified include directory
 or because no directory is specified), it looks in the path(s) specified in the environment variable
 CPARMINC.
- 4. When the C++ compiler still did not find the include file, it finally tries the default include.cpp and include directory relative to the installation directory.
- 5. If the include file is still not found, the directories specified in the --sys-include option are searched.

If the include directory is specified as -, e.g., -I-, the option indicates the point in the list of -I or --include-directory options at which the search for file names enclosed in < . . . > should begin. That is, the search for < . . . > names should only consider directories named in -I or --include-directory options following the -I-, and the directories of items 3 and 4 above. -I- also removes the directory containing the current input file (item 1 above) from the search path for file names enclosed in " . . . ".

An include directory specified with the **--sys-include** option is considered a "system" include directory. Warnings are suppressed when processing files found in system include directories.

If the filename has no suffix it will be searched for by appending each of a set of include file suffixes. When searching in a given directory all of the suffixes are tried in that directory before moving on to the next search directory. The default set of suffixes is, no extension and .stdh. The default can be overridden using the --incl-suffixes command line option. A null file suffix cannot be used unless it is present in the suffix list (that is, the C++ compiler will always attempt to add a suffix from the suffix list when the filename has no suffix).

Example

Suppose that the C++ source file test.cc contains the following lines:

```
#include <stdio.h>
#include "myinc.h"
```

You can call the C++ compiler as follows:

```
cparm -Imyinclude test.cc
```

First the C++ compiler looks for the file stdio.h in the directory myinclude relative to the current directory. If it was not found, the C++ compiler searches in the environment variable CPARMINC and then in the default include directory.

The C++ compiler now looks for the file myinc.h, in the directory where test.cc is located. If the file is not there the C++ compiler searches in the directory myinclude. If it was still not found, the C++ compiler searches in the environment variable CPARMINC and then in the default include.cpp and include directories.

5.3. C++ Compiler Error Messages

The C++ compiler reports the following types of error messages in the Problems view of Eclipse.

F (Fatal errors)

Catastrophic errors, also called 'fatal errors', indicate problems of such severity that the compilation cannot continue. For example: command-line errors, internal errors, and missing include files. If multiple source files are being compiled, any source files after the current one will not be compiled.

E (Errors)

Errors indicate violations of the syntax or semantic rules of the C++ language. Compilation continues, but object code is not generated.

W (Warnings)

Warnings indicate something valid but questionable. Compilation continues and object code is generated (if no errors are detected). You can control warnings in the C/C++ Build » Settings » Tool Settings » C/C++ Compiler » Diagnostics page of the Project » Properties menu (C++ compiler option --no-warnings).

R (Remarks)

Remarks indicate something that is valid and probably intended, but which a careful programmer may want to check. These diagnostics are not issued by default. Compilation continues and object code is generated (if no errors are detected). To enable remarks, enable the option Issue remarks on C++ code in the C/C++ Build » Settings » Tool Settings » C/C++ Compiler » Diagnostics page of the Project » Properties menu (C++ compiler option --remarks).

S (Internal errors)

Internal compiler errors are caused by failed internal consistency checks and should never occur. However, if such a 'SYSTEM' error appears, please report the occurrence to Altium. Please include a small C++ program causing the error.

Message format

By default, diagnostics are written in a form like the following:

```
cparm E0020: ["test.cc" 3] identifier "name" is undefined
```

With the command line option --error-file=file you can redirect messages to a file instead of stderr.

Note that the message identifies the file and line involved. Long messages are wrapped to additional lines when necessary.

With the option C/C++ Build » Settings » Tool Settings » Global Options » Treat warnings as errors (option --warnings-as-errors) you can change the severity of warning messages to errors.

For some messages, a list of entities is useful; they are listed following the initial error message:

```
cparm E0308: ["test.cc" 4] more than one instance of overloaded
    function "f" matches the argument list:
        function "f(int)"
        function "f(float)"
        argument types are: (double)
```

In some cases, some additional context information is provided; specifically, such context information is useful when the C++ compiler issues a diagnostic while doing a template instantiation or while generating a constructor, destructor, or assignment operator function. For example:

Without the context information, it is very hard to figure out what the error refers to.

Termination Messages

The C++ compiler writes sign-off messages to stderr (the Problems view in Eclipse) if errors are detected. For example, one of the following forms of message

```
n errors detected in the compilation of "file".
```

1 catastrophic error detected in the compilation of "file".

n errors and 1 catastrophic error detected in the compilation of "file".

is written to indicate the detection of errors in the compilation. No message is written if no errors were detected. The following message

Error limit reached.

is written when the count of errors reaches the error limit (see the option --error-limit); compilation is then terminated. The message

Compilation terminated.

is written at the end of a compilation that was prematurely terminated because of a catastrophic error. The message

Compilation aborted

is written at the end of a compilation that was prematurely terminated because of an internal error. Such an error indicates an internal problem in the compiler. If such an internal error appears, please report the occurrence to Altium. Please include a small C++ program causing the error.

Chapter 6. Profiling

Profiling is the process of collecting statistical data about a running application. With these data you can analyze which functions are called, how often they are called and what their execution time is. This chapter describes the TASKING profiling method with code instrumentation techniques and static profiling.

6.1. What is Profiling?

Profiling is a collection of methods to gather data about your application which helps you to identify code fragments where execution consumes the greatest amount of time.

TASKING supplies a number of profiler tools each dedicated to solve a particular type of performance tuning problem. Performance problems can be solved by:

- Identifying time-consuming algorithms and rewrite the code using a more time-efficient algorithm.
- Identifying time-consuming functions and select the appropriate compiler optimizations for these functions (for example, enable loop unrolling or function inlining).
- Identifying time consuming loops and add the appropriate pragmas to enable the compiler to further optimize these loops.

A profiler helps you to find and identify the time consuming constructs and provides you this way with valuable information to optimize your application.

TASKING employs various schemes for collecting profiling data, depending on the capabilities of the target system and different information needs.

6.1.1. Four Methods of Profiling

There are several methods of profiling: recording by an instruction set simulator, profiling using the debugger, profiling with code instrumentation techniques (dynamic profiling) and profiling by the C compiler at compile time (static profiling). Each method has its advantages and disadvantages.

Profiling by an instruction set simulator

One way to gather profiling information is built into the instruction set simulator (ISS). The ISS records the time consumed by each instruction that is executed. The debugger then retrieves this information and correlates the time spent for individual instructions to C source statements.

Advantages

- it gives (cycle) accurate information with extreme fine granularity
- the executed code is identical to the non-profiled code

Disadvantages

· the method requires an ISS as execution environment

Profiling with the debugger (intrusive profiling)

The second method of profiling is built into the debugger. You specify which functions you want to profile. The debugger places breakpoints on the function entry and all its exit addresses and measures the time spent in the function and its callees.

<u>Advantages</u>

• the executed code is identical to the non-profiled code

Disadvantage

each time a profiling breakpoint is hit the target is stopped and control is passed to the debugger.
 Although the debugger restarts the application immediately, the applications performance is significantly reduced.

Profiling using code instrumentation techniques (Dynamic Profiling)

The TASKING C compiler has an option to add code to your application which takes care of the profiling process. This is called code instrumentation. The gathered profiling data is first stored in the target's memory and will be written to a file when the application finishes execution or when the function __prof_cleanup() is called.

Advantages

- it can give a complete call graph of the application annotated with the time spent in each function and basic block
- this profiling method is execution environment independent
- the application is profiled while it executes on its aimed target taking real-life input

Disadvantage

 instrumentation code creates a significant run-time overhead, and instrumentation code and gathered data take up target memory

This method provides a valuable complement to the other two methods and is described into more detail below.

Profiling estimation by the C compiler (Static Profiling)

The TASKING C compiler has an option to generate static profile information through various heuristics and estimates. The profiling data produced this way at compile time is stored in an XML file, which can be processed and displayed using the same tools used for dynamic (run-time) profiling.

Advantages

- it can give a give a quick estimation of the time spent in each function and basic block
- this profiling method is execution environment independent
- the application is profiled at compile time

• it requires no extra code instrumentation, so no extra run-time overhead

Disadvantage

it is an estimation by the compiler and therefore less accurate than dynamic profiling

This method also is described into more detail below.

6.2. Profiling using Code Instrumentation (Dynamic Profiling)

Profiling can be used to determine which parts of a program take most of the execution time.

Once the collected data are presented, it may reveal which pieces of your code execute slower than expected and which functions contribute most to the overall execution time of a program. It gives you also information about which functions are called more or less often than expected. This information not only reveal design flaws or bugs that had otherwise been unnoticed, it also reveals parts of the program which can be effectively optimized.

Important considerations

The code instrumentation method adds code to your original application which is needed to gather the profiling data. Therefore, the code size of your application increases. Furthermore, during the profiling process, the gathered data is initially stored into dynamically allocated memory of the target. The heap of your application should be large enough to store this data. Since code instrumentation is done by the compiler, assembly functions used in your program do not show up in the profile.

The profiling information is collected during the actual execution of the program. Therefore, the input of the program influences the results. If a part/function of the program is not activated while the program is profiled, no profile data is generated for that part/function.

Overview of steps to perform

To obtain a profile using code instrumentation, perform the following steps:

- 1. Compile and link your program with profiling enabled
- 2. Execute the program to generate the profile data
- 3. Display the profile

First you need a completed project. If you are not using your own project, use the profiling example as described below.

1. From the File menu, select Import...

The Import dialog appears.

- 2. Select TASKING C/C++ » TASKING ARM Example Projects and click Next.
- 3. In the **Example projects** box, disable all projects except profiling.
- 4. Click Finish.

The profiling project should now be visible in the C/C++ view.

6.2.1. Step 1: Build your Application for Profiling

The first step is to add the code that takes care of the profiling, to your application. This is done with C compiler options:

1. From the Project menu, select Properties

The Properties for profiling dialog box appears.

2. In the left pane, expand C/C++ Build and select Settings.

In the right pane the Settings appear.

- 3. On the Tool Settings tab, expand the C/C++ Compiler entry and select Debugging.
- 4. Enable one or more of the following **Generate profiling information** options (the sample profiling project already has profiling options enabled).
 - for block counters (not in combination with Call graph or Function timers)
 - to build a call graph (not in combination with Block counters)
 - · for function counters
 - for function timers (not in combination with Block counters/Function counters)

Note that the more detailed information you request, the larger the overhead in terms of execution time, code size and heap space needed. The option Generate symbolic debug information (--debug) does not affect profiling, execution time or code size.

Block counters (not in combination with Call graph or Function timers)

This will instrument the code to perform basic block counting. As the program runs, it will count how many time it executed each branch of each if statement, each iteration of a for loop, and so on. Note that though you can combine Block counters with Function counters, this has no effect because Function counters is only a subset of Block counters.

Call graph (not in combination with Block counters)

This will instrument the code to reconstruct the run-time call graph. As the program runs it associates the caller with the gathered profiling data.

Function counters

This will instrument the code to perform function call counting. This is a subset of the basic Block counters.

Function timers (not in combination with Block counters/Function counters)

This will instrument the code to measure the time spent in a function. This includes the time spent in all called functions (callees).

For the command line, see the C compiler option --profile (-p).

Profiling is only possible with optimization levels 0, 1 and 2. So:

- 5. Open the Optimization page and set the Optimization level to 2 Optimize more.
- 6. Click **OK** to apply the new option settings and rebuild the project ().

6.2.1.1. Profiling Modules and C Libraries

Profiling individual modules

It is possible to profile individual C modules. In this case only limited profiling data is gathered for the functions in the modules compiled without the profiling option. When you use the suboption **Call graph**, the profiling data reveals which profiled functions are called by non-profiled functions. The profiling data does not show how often and from where the non-profiled functions themselves are called. Though this does not affect the flat profile, it might reduce the usefulness of the call graph.

Profiling C library functions

Eclipse and/or the control program will link your program with the standard version of the C library. Functions from this library which are used in your application, will not be profiled. If you do want to incorporate the library functions in the profile, you must set the appropriate C compiler options in the C library makefiles and rebuild the library.

6.2.1.2. Linking Profiling Libraries

When building your application, the application must be linked against the corresponding profile library. Eclipse (or the control program) automatically select the correct library based on the profiling options you specified. However, if you compile, assemble and link your application manually, make sure you specify the correct library.

See Section 8.3, *Linking with Libraries* for an overview of the (profiling) libraries.

6.2.2. Step 2: Execute the Application

Once you have compiled and linked the application for profiling, it must be executed to generate the profiling data. Run the program as usual: the program should run normally taking the same input as usual and producing the same output as usual. The application will run somewhat slower than normal because of the extra time spent on collecting the profiling data.

Eclipse has already made a default simulator debug configuration for your project. Follow the steps below to run the application on the TASKING simulator, using the debugger. (In fact, you can run the application also on a target board.)

1. From the Run menu, select Debug Configurations...

The Debug Configurations dialog appears.

- Select the simulator debug configuration (TASKING Embedded C/C++ Application » profiling.simulator).
- 3. Click the **Debug** button to start the debugger and launch the profiling application.

Eclipse will open the TASKING Debug perspective (as specified in the configuration) and asks for confirmation.

4. Click **Yes** to open the TASKING Debug perspective.

The TASKING Debug perspective opens while the application has stopped before it enters main()

5. In the Debug view, click on the (Resume) button.

A file system simulation (FSS) view appears in which the application outputs the results.

When the program has finished, the collected profiling data is saved (for details see 'After execution' below).

Startup code

The startup code initializes the profiling functions by calling the function <u>__prof_init()</u>. Eclipse will automatically make the required modifications to the startup code. Or, when you use the control program, this extracts the correct startup code from the C library.

If you use your own startup code, you must manually insert a call to the function __prof_init just before the call to main and its stack setup.

An application can have multiple entry points, such as main() and other functions that are called by interrupt. This does not affect the profiling process.

Small heap problem

When the program does not run as usual, this is typically caused by a shortage of heap space. In this case a message is issued (when running with file system simulation, it is displayed on the Debug console). To solve this problem, increase the size of the heap. Information about the heap is stored in the linker script file (.lsl) file which is automatically added when a project is created.

- 1. In the C/C++ view, expand the project tree and double-click on the file profiling.1s1 to open it.
 - In the editor view, the LSL file is opened, showing a number of tabs at the bottom.
- 2. Open the **Stack/Heap** tab and enter a larger value for **heap**.
- 3. Save the file.

Presumable incorrect call graph

The call graph is based on the *compiled* source code. Due to compiler optimizations the call graph may therefor seem incorrect at first sight. For example, the compiler can replace a function call immediately followed by a return instruction by a jump to the callee, thereby merging the callee function with the caller function. In this case the time spent in the callee function is not recorded separately anymore, but added

to the time spent in the caller function (which, as said before, now holds the callee function). This represents exactly the structure of your source in assembly but may differ from the structure in the initial C source.

After execution

When the program has finished (returning from main()), the exit code calls the function __prof_cleanup(void). This function writes the gathered profiling data to a file on the host system using the debugger's file system simulation features. If your program does not return from main(), you can force this by inserting a call to the function __prof_cleanup() in your application source code. Please note the double underscores when calling from C code!

The resulting profiling data file is named amon.prf.

If your program does not run under control of the debugger and therefore cannot use the file system simulation (FSS) functionality to write a file to the host system, you must implement a way to pass the profiling data gathered on the target to the host. Adapt the function _prof_cleanup() in the profiling libraries or the underlying I/O functions for this purpose.

6.2.3. Step 3: Displaying Profiling Results

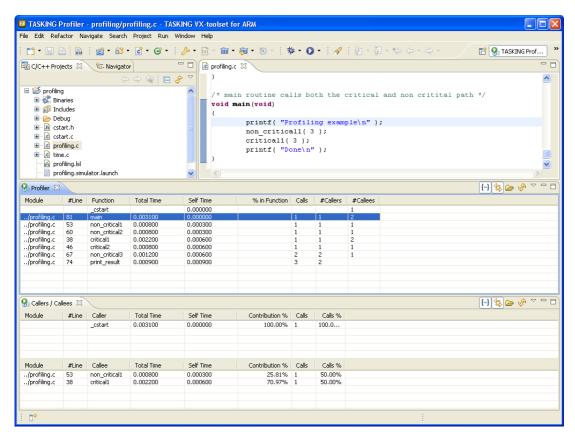
After the function <code>__prof_cleanup()</code> has been executed, the result of the profiler can be displayed in the TASKING Profiler perspective. The profiling data in the file <code>amon.prf</code> is then converted to an XML file. This file is read and its information is displayed. To view the profiling information, open the TASKING Profiler perspective:

1. From the Window menu, select Open Perspective » Other...

The Select Perspective dialog appears.

2. Select the **TASKING Profiler** perspective and click **OK**.

The TASKING Profiler perspective opens.



The TASKING Profiler perspective

The TASKING Profiler perspective contains the following Views:

Profiler view	Shows the profiling information of all functions in all C source modules belonging to your application.
Callara / Callaga	The first table in this view, the college table above the functions that called the

Callers / Callees T

The first table in this view, the *callers* table, shows the functions that called the focus function.

The second table in this view, the *callees* table, shows the functions that are called by the focus function.

- Clicking on a function (or on its table row) makes it the focus function.
- Double-clicking on a function, opens the appropriate C source module in the Editor view at the location
 of the function definition.
- To sort the rows in the table, click on one of the column headers.

The profiling information

Based on the profiling options you have set before compiling your application, some profiling data may be present and some may be not. The columns in the tables represent the following information:

Module The C source module in which the function resides.

#Line The line number of the function definition in the C source module.

Function The function for which profiling data is gathered and (if present) the code blocks in each

function. To show or hide the block counts, in the Profiler view click the **Menu** button (\bigtriangledown)

and select Show Block Counts.

Total Time The total amount of time in seconds that was spent in this function and all of its

sub-functions.

Self Time The amount of time in seconds that was spent in the function itself. This excludes the

time spent in the sub-functions.

% in This is the relative amount of time spent in this function. These should add up to 100%.

Function Similar to self time.

Calls Number of times the function has been executed.

#Callers Number of functions by which the function was called.

#Callees Number of functions that was actually called from this function.

Contribution In the caller table: shows for which part (in percent) the caller contributes to the time spent

% in the focus function.

In the callee table: shows how much time the focus function has spent relatively in each

of its callees.

Calls % In the caller table: shows how often each callee was called as a percentage of all calls

from the focus function.

In the callee table: shows how often the focus function was called from a particular caller

as a percentage of all calls to the focus function.

Toolbar icons

Icon	Action	Description
{···}	Show/Hide Block Counts	Toggle. If enabled, shows profiling information for block counters.
₩	Link with Editor	Toggle. If enabled, updates the profiling information according to the active source file.
≥	Select Profiling File(s)	Opens a dialog where you can specify profiling files for display.
S. S	Refresh Profiler Data	Updates the views with the latest profiling information.

Viewing previously recorded profiling results, combining results

Each time you run your application, new profiling information is gathered and stored in the file amon.prf. You can store previous results by renaming the file amon.prf (keep the extension .prf); this prevents

the existing amon.prf from being overwritten by the new amon.prf. At any time, you can reload these profiling results in the profiler. You can even load multiple .prf files into the Profiler to view the combined results.

First, open the TASKING Profiler perspective if it is not open anymore:

- 1. In the Profiler view, click on the (Select Profiling File(s)) button.
 - The Select Profiling File(s) dialog appears.
- 2. In the Projects box, select the project for which you want to see profiling information.
- 3. In the **Profiling Type** group box, select **Dynamic Profiling**.
- 4. In the **Profiling Files** group box, disable the option **Use default**.
- 5. Click the **Add...** button, select the .prf files you want to load and click **Open** to confirm your choice.
- Make sure the correct symbol file is selected, in this example profiling.abs.
- 7. Click **OK** to finish.

6.3. Profiling at Compile Time (Static Profiling)

Just as with dynamic profiling, static profiling can be used to determine which parts of a program take most of the execution time. It can provide a good alternative if you do not want that your code is affected by extra code.

Overview of steps to perform

To obtain a profile using code instrumentation, perform the following steps:

- 1. Compile and link your program with static profiling enabled
- 2. Display the profile

First you need a completed project. If you are not using your own project, use the profiling example as described in Section 6.2, *Profiling using Code Instrumentation (Dynamic Profiling)*.

6.3.1. Step 1: Build your Application with Static Profiling

The first step is to tell the C compiler to make an estimation of the profiling information of your application. This is done with C compiler options:

1. From the **Project** menu, select **Properties**

The Properties for profiling dialog box appears.

2. In the left pane, expand C/C++ Build and select Settings.

In the right pane the Settings appear.

- 3. On the Tool Settings tab, expand the C/C++ Compiler entry and select Debugging.
- 4. Enable Static profiling.

For the command line, see the C compiler option --profile (-p).

Profiling is only possible with optimization levels 0, 1 and 2, So:

- 5. Open the Optimization page and set the Optimization level to 2 Optimize more.
- 6. Click **OK** to apply the new option settings and rebuild the project ().

6.3.2. Step 2: Displaying Static Profiling Results

After your project has been built with static profiling, the result of the profiler can be displayed in the TASKING Profiler perspective. The profiling data of each individual file (.sxml), is combined in the XML file profiling.xprof. This file is read and its information is displayed. To view the profiling information, open the TASKING Profiler perspective:

1. From the Window menu, select Open Perspective » Other...

The Select Perspective dialog appears.

2. Select the **TASKING Profiler** perspective and click **OK**.

The TASKING Profiler perspective opens. This perspective is explained in Section 6.2.3, Step 3: Displaying Profiling Results

To display static profiling information in the Profiler view

1. In the Profiler view, click on the (Select Profiling File(s)) button.

The Select Profiling File(s) dialog appears.

- 2. In the Projects box, select the project for which you want to see profiling information.
- 3. In the **Profiling Type** group box, select **Static Profiling**.
- 4. In the Static Profiling File group box, enable the option Use default.

By default, the file *project*.xprof is used (profiling.xprof). If you want to specify another file, disable the option **Use default** and use the edit field and/or Browse button to specify a static profiling file (.xprof).

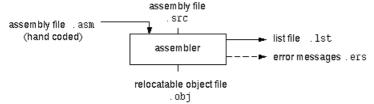
5. Click **OK** to finish.

Chapter 7. Using the Assembler

This chapter describes the assembly process and explains how to call the assembler.

The assembler converts hand-written or compiler-generated assembly language programs into machine language, resulting in object files in the ELF/DWARF object format.

The assembler takes the following files for input and output:



The following information is described:

- The assembly process.
- How to call the assembler and how to use its options. An extensive list of all options and their descriptions is included in Section 12.3, Assembler Options.
- · How to generate a list file.
- · Types of assembler messages.

7.1. Assembly Process

The assembler generates relocatable output files with the extension .obj. These files serve as input for the linker.

Phases of the assembly process

- Parsing of the source file: preprocessing of assembler directives and checking of the syntax of instructions
- Generation of the relocatable object file and optionally a list file

The assembler integrates file inclusion and macro facilities. See Section 3.10, *Macro Operations* for more information.

7.2. Calling the Assembler

The TASKING VX-toolset for ARM under Eclipse can use the internal builder (default) or the TASKING makefile generator (external builder) to build your entire project. After you have built your project, the output files are available in a subdirectory of your project directory, depending on the active configuration you have set in the **C/C++ Build » Settings** page of the **Project » Properties** dialog.

Building a project under Eclipse

You have several ways of building your project:

- Build Selected File(s) (i). This compiles and assembles the selected file(s) without calling the linker.
 - 1. In the C/C++ Projects view, select the files you want to compile.
 - 2. Right-click in the C/C++ Projects view and select **Build Selected File(s)**.
- Build Individual Project (¹

To build individual projects incrementally, select **Project** » **Build Project**.

- Rebuild Project (). This builds every file in the project whether or not a file has been modified since the last build. A rebuild is a clean followed by a build.
 - 1. Select Project » Clean...
 - 2. Enable the option Start a build immediately and click OK.
- Build Automatically. This performs a build of all projects whenever any project file is saved, such as your makefile.

This way of building is not recommended for C/C++ development, but to enable this feature select **Project » Build Automatically** and ensure there is a check mark beside the **Build Automatically** menu item.

Select a target processor (core)

Processor options affect the invocation of all tools in the toolset. In Eclipse you only need to set them once. Based on the target processor, the compiler includes a special function register file. This is a regular include file which enables you to use virtual registers that are located in memory.

From the Project menu, select Properties

The Properties dialog appears.

2. In the left pane, expand C/C++ Build and select Processor.

In the right pane the Processor page appears.

3. From the **Processor Selection** list, select a processor.

To access the assembler options

1. From the Project menu, select Properties

The Properties dialog appears.

2. In the left pane, expand C/C++ Build and select Settings.

In the right pane the Settings appear.

- 3. On the Tool Settings tab, select **Assembler**.
- 4. Select the sub-entries and set the options in the various pages.

Note that the options you enter in the Assembler page are only used for hand-coded assembly files, not for the assembly files generated by the compiler.

You can find a detailed description of all assembler options in Section 12.3, Assembler Options.

Invocation syntax on the command line (Windows Command Prompt):

```
asarm [ [option]... [file]... ]...
```

The input file must be an assembly source file (.asm or .src).

7.3. How the Assembler Searches Include Files

When you use include files (with the . INCLUDE directive), you can specify their location in several ways. The assembler searches the specified locations in the following order:

- 1. If the .INCLUDE directive contains an absolute path name, the assembler looks for this file. If no path or a relative path is specified, the assembler looks in the same directory as the source file.
- When the assembler did not find the include file, it looks in the directories that are specified in the
 Assembler » Include Paths page in the C/C++ Build » Settings » Tool Settings tab of the Project
 Properties dialog (equivalent to the -I command line option).
- 3. When the assembler did not find the include file (because it is not in the specified include directory or because no directory is specified), it looks in the path(s) specified in the environment variable ASARMING.
- 4. When the assembler still did not find the include file, it finally tries the default include directory relative to the installation directory.

Example

Suppose that the assembly source file test.asm contains the following lines:

```
.INCLUDE 'myinc.inc'
```

You can call the assembler as follows:

```
asarm -Imyinclude test.asm
```

First the assembler looks for the file myinc.asm, in the directory where test.asm is located. If the file is not there the assembler searches in the directory myinclude. If it was still not found, the assembler searches in the environment variableASARMINC and then in the default include directory.

7.4. Generating a List File

The list file is an additional output file that contains information about the generated code. You can customize the amount and form of information.

If the assembler generates errors or warnings, these are reported in the list file just below the source line that caused the error or warning.

To generate a list file

1. From the Project menu, select Properties

The Properties dialog appears.

2. In the left pane, expand C/C++ Build and select Settings.

In the right pane the Settings appear.

- 3. On the Tool Settings tab, select Assembler » List File.
- Enable the option Generate list file.
- 5. (Optional) Enable the options to include that information in the list file.

Example on the command line (Windows Command Prompt)

The following command generates the list file test.lst:

```
asarm -1 test.asm
```

See Section 14.1, Assembler List File Format, for an explanation of the format of the list file.

7.5. Assembler Error Messages

The assembler reports the following types of error messages in the Problems view of Eclipse.

F (Fatal errors)

After a fatal error the assembler immediately aborts the assembly process.

E (Errors)

Errors are reported, but the assembler continues assembling. No output files are produced unless you have set the assembler option --keep-output-files (the resulting output file may be incomplete).

W (Warnings)

Warning messages do not result into an erroneous assembly output file. They are meant to draw your attention to assumptions of the assembler for a situation which may not be correct. You can control warnings in the C/C++ Build » Settings » Tool Settings » Assembler » Diagnostics page of the Project » Properties menu (assembler option --no-warnings).

Display detailed information on diagnostics

1. From the Window menu, select Show View » Other » General » Problems.

The Problems view is added to the current perspective.

2. In the Problems view right-click on a message.

A popup menu appears.

3. Select **Detailed Diagnostics Info**.

A dialog box appears with additional information.

On the command line you can use the assembler option --diag to see an explanation of a diagnostic message:

```
asarm --diag=[format:]{all | number,...]
```

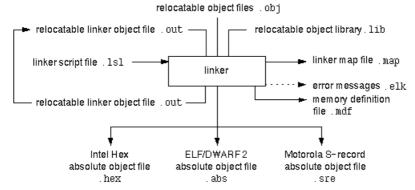
Chapter 8. Using the Linker

This chapter describes the linking process, how to call the linker and how to control the linker with a script file.

The TASKING linker is a combined linker/locator. The linker phase combines relocatable object files (.obj files, generated by the assembler), and libraries into a single relocatable linker object file (.out). The locator phase assigns absolute addresses to the linker object file and creates an absolute object file which you can load into a target processor. From this point the term linker is used for the combined linker/locator.

The linker can simultaneously link and locate all programs for all cores available on a target board. The target board may be of arbitrary complexity. A simple target board may contain one standard processor with some external memory that executes one task. A complex target board may contain multiple standard processors and DSPs combined with configurable IP-cores loaded in an FPGA. Each core may execute a different program, and external memory may be shared by multiple cores.

The linker takes the following files for input and output:



This chapter first describes the linking process. Then it describes how to call the linker and how to use its options. An extensive list of all options and their descriptions is included in Section 12.4, *Linker Options*.

To control the link process, you can write a script for the linker. This chapter shortly describes the purpose and basic principles of the Linker Script Language (LSL) on the basis of an example. A complete description of the LSL is included in Linker Script Language.

8.1. Linking Process

The linker combines and transforms relocatable object files (.obj) into a single absolute object file. This process consists of two phases: the linking phase and the locating phase.

In the first phase the linker combines the supplied relocatable object files and libraries into a single relocatable object file. In the second phase, the linker assigns absolute addresses to the object file so it can actually be loaded into a target.

Terms used in the linking process

Term	Definition
Absolute object file	Object code in which addresses have fixed absolute values, ready to load into a target.
Address	A specification of a location in an address space.
Address space	The set of possible addresses. A core can support multiple spaces, for example in a Harvard architecture the addresses that identify the location of an instruction refer to <i>code</i> space, whereas addresses that identify the location of a data object refer to a <i>data</i> space.
Architecture	A description of the characteristics of a core that are of interest for the linker. This encompasses the address space(s) and the internal bus structure. Given this information the linker can convert logical addresses into physical addresses.
Copy table	A section created by the linker. This section contains data that specifies how the startup code initializes the data sections. For each section the copy table contains the following fields:
	action: defines whether a section is copied or zeroed
	destination: defines the section's address in RAM
	source: defines the sections address in ROM
	• length: defines the size of the section in MAUs of the destination space
Core	An instance of an architecture.
Derivative	The design of a processor. A description of one or more cores including internal memory and any number of buses.
Library	Collection of relocatable object files. Usually each object file in a library contains one symbol definition (for example, a function).
Logical address	An address as encoded in an instruction word, an address generated by a core (CPU).
LSL file	The set of linker script files that are passed to the linker.
MAU	Minimum Addressable Unit. For a given processor the number of bits between an address and the next address. This is not necessarily a byte or a word.
Object code	The binary machine language representation of the C source.
Physical address	An address generated by the memory system.
Processor	An instance of a derivative. Usually implemented as a (custom) chip, but can also be implemented in an FPGA, in which case the derivative can be designed by the developer.
Relocatable object file	Object code in which addresses are represented by symbols and thus relocatable.
Relocation	The process of assigning absolute addresses.

Term	Definition
Relocation information	Information about how the linker must modify the machine code instructions when it relocates addresses.
Section	A group of instructions and/or data objects that occupy a contiguous range of addresses.
Section attributes	Attributes that define how the section should be linked or located.
Target	The hardware board on which an application is executing. A board contains at least one processor. However, a complex target may contain multiple processors and external memory and may be shared between processors.
Unresolved reference	A reference to a symbol for which the linker did not find a definition yet.

8.1.1. Phase 1: Linking

The linker takes one or more relocatable object files and/or libraries as input. A relocatable object file, as generated by the assembler, contains the following information:

- Header information: Overall information about the file, such as the code size, name of the source file it was assembled from, and creation date.
- Object code: Binary code and data, divided into various named sections. Sections are contiguous
 chunks of code that have to be placed in specific parts of the memory. The program addresses start
 at zero for each section in the object file.
- Symbols: Some symbols are exported defined within the file for use in other files. Other symbols are
 imported used in the file but not defined (external symbols). Generally these symbols are names of
 routines or names of data objects.
- Relocation information: A list of places with symbolic references that the linker has to replace with
 actual addresses. When in the code an external symbol (a symbol defined in another file or in a library)
 is referenced, the assembler does not know the symbol's size and address. Instead, the assembler
 generates a call to a preliminary relocatable address (usually 0000), while stating the symbol name.
- Debug information: Other information about the object code that is used by a debugger. The assembler
 optionally generates this information and can consist of line numbers, C source code, local symbols
 and descriptions of data structures.

The linker resolves the external references between the supplied relocatable object files and/or libraries and combines the files into a single relocatable linker object file.

The linker starts its task by scanning all specified relocatable object files and libraries. If the linker encounters an unresolved symbol, it remembers its name and continues scanning. The symbol may be defined elsewhere in the same file, or in one of the other files or libraries that you specified to the linker. If the symbol is defined in a library, the linker extracts the object file with the symbol definition from the library. This way the linker collects all definitions and references of all of the symbols.

Next, the linker combines sections with the same section name and attributes into single sections. The linker also substitutes (external) symbol references by (relocatable) numerical addresses where possible.

At the end of the linking phase, the linker either writes the results to a file (a single relocatable object file) or keeps the results in memory for further processing during the locating phase.

The resulting file of the linking phase is a single relocatable object file (.out). If this file contains unresolved references, you can link this file with other relocatable object files (.obj) or libraries (.lib) to resolve the remaining unresolved references.

With the linker command line option --link-only, you can tell the linker to only perform this linking phase and skip the locating phase. The linker complains if any unresolved references are left.

8.1.2. Phase 2: Locating

In the locating phase, the linker assigns absolute addresses to the object code, placing each section in a specific part of the target memory. The linker also replaces references to symbols by the actual address of those symbols. The resulting file is an absolute object file which you can actually load into a target memory. Optionally, when the resulting file should be loaded into a ROM device the linker creates a so-called copy table section which is used by the startup code to initialize the data sections.

Code modification

When the linker assigns absolute addresses to the object code, it needs to modify this code according to certain rules or *relocation expressions* to reflect the new addresses. These relocation expressions are stored in the relocatable object file. Consider the following snippet of x86 code that moves the contents of variable a to variable b via the eax register:

```
A1 3412 0000 mov a, %eax (a defined at 0x1234, byte reversed)
A3 0000 0000 mov %eax,b (b is imported so the instruction refers to 0x0000 since its location is unknown)
```

Now assume that the linker links this code so that the section in which a is located is relocated by 0x10000 bytes, and b turns out to be at 0x9A12. The linker modifies the code to be:

```
A1 3412 0100 mov a, %eax (0x10000 added to the address)
A3 129A 0000 mov %eax,b (0x9A12 patched in for b)
```

These adjustments affect instructions, but keep in mind that any pointers in the data part of a relocatable object file have to be modified as well.

Output formats

The linker can produce its output in different file formats. The default ELF/DWARF format (.abs) contains an image of the executable code and data, and can contain additional debug information. The Intel-Hex format (.hex) and Motorola S-record format (.sre) only contain an image of the executable code and data. You can specify a format with the options --output (-o) and --chip-output (-c).

Controlling the linker

Via a so-called *linker script file* you can gain complete control over the linker. The script language is called the *Linker Script Language* (LSL). Using LSL you can define:

The memory installed in the embedded target system:

To assign locations to code and data sections, the linker must know what memory devices are actually installed in the embedded target system. For each physical memory device the linker must know its start-address, its size, and whether the memory is read-write accessible (RAM) or read-only accessible (ROM).

How and where code and data should be placed in the physical memory:

Embedded systems can have complex memory systems. If for example on-chip and off-chip memory devices are available, the code and data located in internal memory is typically accessed faster and with dissipating less power. To improve the performance of an application, specific code and data sections should be located in on-chip memory. By writing your own LSL file, you gain full control over the locating process.

• The underlying hardware architecture of the target processor.

To perform its task the linker must have a model of the underlying hardware architecture of the processor you are using. For example the linker must know how to translate an address used within the object file (a logical address) into an offset in a particular memory device (a physical address). In most linkers this model is hard coded in the executable and can not be modified. For the TASKING linker this hardware model is described in the linker script file. This solution is chosen to support configurable cores that are used in system-on-chip designs.

When you want to write your own linker script file, you can use the standard linker script files with architecture descriptions delivered with the product.

See also Section 8.7, Controlling the Linker with a Script.

8.2. Calling the Linker

In Eclipse you can set options specific for the linker. After you have built your project, the output files are available in a subdirectory of your project directory, depending on the active configuration you have set in the **C/C++ Build** » **Settings** page of the **Project** » **Properties** dialog.

Building a project under Eclipse

You have several ways of building your project:

Build Individual Project (¹

 ¹

 ¹

To build individual projects incrementally, select Project » Build Project.

- Rebuild Project (^{w)}. This builds every file in the project whether or not a file has been modified since the last build. A rebuild is a clean followed by a build.
 - 1. Select Project » Clean...
 - 2. Enable the option Start a build immediately and click OK.
- Build Automatically. This performs a build of all projects whenever any project file is saved, such as your makefile.

This way of building is not recommended, but to enable this feature select **Project » Build Automatically** and ensure there is a check mark beside the **Build Automatically** menu item.

To access the linker options

1. From the **Project** menu, select **Properties**

The Properties dialog appears.

2. In the left pane, expand C/C++ Build and select Settings.

In the right pane the Settings appear.

- 3. On the Tool Settings tab, select Linker.
- 4. Select the sub-entries and set the options in the various pages.

You can find a detailed description of all linker options in Section 12.4, Linker Options.

Invocation syntax on the command line (Windows Command Prompt):

```
lkarm [ [option]... [file]... ]...
```

When you are linking multiple files, either relocatable object files (.obj) or libraries (.lib), it is important to specify the files in the right order. This is explained in Section 8.3, *Linking with Libraries*.

Example:

```
lkarm -darm.lsl test.obj
```

This links and locates the file test.obj and generates the file test.abs.

8.3. Linking with Libraries

There are two kinds of libraries: system libraries and user libraries.

System library

System libraries are stored in the directories:

```
<ARM installation path>\lib\v4T\le
<ARM installation path>\lib\v4T\be
<ARM installation path>\lib\v5T\le
<ARM installation path>\lib\v5T\be
<ARM installation path>\lib\v6M\le
<ARM installation path>\lib\v6M\le
<ARM installation path>\lib\v6M\be
<ARM installation path>\lib\v7M\le
<ARM installation path>\lib\v7M\be
```

An overview of the system libraries is given in the following table:

Libraries	Description	
carm[s].lib cthumb[s].lib	C libraries for ARM and Thumb instructions repectively Optional letter: s = single precision floating-point (compiler optionno-double)	
fparm.lib fpthumb.lib	Floating-point libraries for ARM and Thumb	
rtarm.lib rtthumb.lib	Run-time library for ARM and Thumb	
pbarm.lib / pbthumb.lib pcarm.lib / pcthumb.lib pctarm.lib / pctthumb.lib pdarm.lib / pdthumb.lib ptarm.lib / ptthumb.lib	Profiling libraries for ARM and Thumb pb = block/function counter pc = call graph pct = call graph and timing pd = dummy pt = function timing	
cparm[s][x].lib cpthumb[s][x].lib	C++ libraries for ARM and Thumb Optional letter: s = single precision floating-point x = exception handling	
stlarmx.lib stlthumbx.lib	STLport C++ libraries (exception handling variants only) Optional letter: s = single precision floating-point	
str*xstdlibarm.lib str*xstdlibthumb.lib	STMicroelectronics STR71x, STR73x, STR75x, STR91x software libraries	

To link the default C (system) libraries

1. From the **Project** menu, select **Properties**

The Properties dialog appears.

2. In the left pane, expand C/C++ Build and select Settings.

In the right pane the Settings appear.

- 3. On the Tool Settings tab, select Linker » Libraries.
- 4. Enable the option Link default libraries.

When you want to link system libraries from the command line, you must specify this with the option --library (-I). For example, to specify the system library carm.lib, type:

lkarm --library=carm test.obj

User library

You can create your own libraries. Section 10.4, *Archiver* describes how you can use the archiver to create your own library with object modules.

To link user libraries

1. From the **Project** menu, select **Properties**

The Properties dialog appears.

2. In the left pane, expand C/C++ Build and select Settings.

In the right pane the Settings appear.

- 3. On the Tool Settings tab, select Linker » Libraries.
- 4. Add your libraries to the **Libraries** box.

When you want to link user libraries from the command line, you must specify their filenames on the command line:

```
lkarm start.obj mylib.lib
```

If the library resides in a sub-directory, specify that directory with the library name:

```
lkarm start.obj mylibs\mylib.lib
```

If you do not specify a directory, the linker searches the library in the current directory only.

Library order

The order in which libraries appear on the command line is important. By default the linker processes object files and libraries in the order in which they appear at the command line. Therefore, when you use a weak symbol construction, like printf, in an object file or your own library, you must position this object/library before the C library.

With the option --first-library-first you can tell the linker to scan the libraries from left to right, and extract symbols from the first library where the linker finds it. This can be useful when you want to use newer versions of a library routine:

```
lkarm --first-library-first a.lib test.obj b.lib
```

If the file test.obj calls a function which is both present in a.lib and b.lib, normally the function in b.lib would be extracted. With this option the linker first tries to extract the symbol from the first library a.lib.

Note that routines in b.lib that call other routines that are present in both a.lib and b.lib are now also resolved from a.lib.

8.3.1. How the Linker Searches Libraries

System libraries

You can specify the location of system libraries in several ways. The linker searches the specified locations in the following order:

- The linker first looks in the Library search path that are specified in the Linker » Libraries page in the C/C++ Build » Settings » Tool Settings tab of the Project Properties dialog (equivalent to the -L command line option). If you specify the -L option without a pathname, the linker stops searching after this step.
- 2. When the linker did not find the library (because it is not in the specified library directory or because no directory is specified), it looks in the path(s) specified in the environment variables LIBARM.
- 3. When the linker did not find the library, it tries the default lib directory relative to the installation directory (or a processor specific sub-directory).

User library

If you use your own library, the linker searches the library in the current directory only.

8.3.2. How the Linker Extracts Objects from Libraries

A library built with the TASKING archiver **ararm** always contains an index part at the beginning of the library. The linker scans this index while searching for unresolved externals. However, to keep the index as small as possible, only the defined symbols of the library members are recorded in this area.

When the linker finds a symbol that matches an unresolved external, the corresponding object file is extracted from the library and is processed. After processing the object file, the remaining library index is searched. If after a complete search of the library unresolved externals are introduced, the library index will be scanned again. After all files and libraries are processed, and there are still unresolved externals and you did not specify the linker option --no-rescan, all libraries are rescanned again. This way you do not have to worry about the library order on the command line and the order of the object files in the libraries. However, this rescanning does not work for 'weak symbols'. If you use a weak symbol construction, like printf, in an object file or your own library, you must position this object/library before the C library.

The option--verbose (-v) shows how libraries have been searched and which objects have been extracted.

Resolving symbols

If you are linking from libraries, only the objects that contain symbols to which you refer, are extracted from the library. This implies that if you invoke the linker like:

```
lkarm mylib.lib
```

nothing is linked and no output file will be produced, because there are no unresolved symbols when the linker searches through mylib.lib.

It is possible to force a symbol as external (unresolved symbol) with the option --extern (-e):

```
lkarm --extern=main mylib.lib
```

In this case the linker searches for the symbol main in the library and (if found) extracts the object that contains main.

If this module contains new unresolved symbols, the linker looks again in mylib.lib. This process repeats until no new unresolved symbols are found.

8.4. Incremental Linking

With the TASKING linker it is possible to link incrementally. Incremental linking means that you link some, but not all .obj modules to a relocatable object file .out. In this case the linker does not perform the locating phase. With the second invocation, you specify both new .obj files as the .out file you had created with the first invocation.

Incremental linking is only possible on the command line.

```
lkarm -darm.lsl --incremental test1.obj -otest.out
lkarm -darm.lsl test2.obj test.out
```

This links the file test1.obj and generates the file test.out. This file is used again and linked together with test2.obj to create the file test.abs (the default name if no output filename is given in the default ELF/DWARF format).

With incremental linking it is normal to have unresolved references in the output file until all .obj files are linked and the final .out or .abs file has been reached. The option --incremental linking also suppresses warnings and errors because of unresolved symbols.

8.5. Importing Binary Files

With the TASKING linker it is possible to add a binary file to your absolute output file. In an embedded application you usually do not have a file system where you can get your data from. With the linker option --import-object you can add raw data to your application. This makes it possible for example to display images on a device or play audio. The linker puts the raw data from the binary file in a section. The section is aligned on a 4-byte boundary. The section name is derived from the filename, in which dots are replaced by an underscore. So, when importing a file called my . mp 3, a section with the name my mp 3 is created. In your application you can refer to the created section by using linker labels.

For example:

```
#include <stdio.h>
extern char    _lc_ub_my_mp3; /* linker labels */
extern char    _lc_ue_my_mp3;
char*    mp3 = &_lc_ub_my_mp3;

void main(void)
{
    int size = &_lc_ue_my_mp3 - &_lc_ub_my_mp3;
    int i;
    for (i=0;i<size;i++)
        putchar(mp3[i]);
}</pre>
```

If you want to use the export functionality of Eclipse, the binary file has to be part of your project.

8.6. Linker Optimizations

During the linking and locating phase, the linker looks for opportunities to optimize the object code. Both code size and execution speed can be optimized.

To enable or disable optimizations

1. From the Project menu, select Properties

The Properties dialog appears.

2. In the left pane, expand C/C++ Build and select Settings.

In the right pane the Settings appear.

- 3. On the Tool Settings tab, select Linker » Optimization.
- 4. Enable one or more optimizations.

You can enable or disable the optimizations described below. The command line option for each optimization is given in brackets.

Delete unreferenced sections (option -Oc/-OC)

This optimization removes unused sections from the resulting object file.

First fit decreasing (option -OI/-OL)

When the physical memory is fragmented or when address spaces are nested it may be possible that a given application cannot be located although the size of the available physical memory is larger than the sum of the section sizes. Enable the first-fit-decreasing optimization when this occurs and re-link your application.

The linker's default behavior is to place sections in the order that is specified in the LSL file (that is, working from low to high memory addresses or vice versa). This also applies to sections within an unrestricted group. If a memory range is partially filled and a section must be located that is larger than the remainder of this range, then the section and all subsequent sections are placed in a next memory range. As a result of this gaps occur at the end of a memory range.

When the first-fit-decreasing optimization is enabled the linker will first place the largest sections in the smallest memory ranges that can contain the section. Small sections are located last and can likely fit in the remaining gaps.

Compress copy table (option -Ot/-OT)

The startup code initializes the application's data areas. The information about which memory addresses should be zeroed and which memory ranges should be copied from ROM to RAM is stored in the copy table.

When this optimization is enabled the linker will try to locate sections in such a way that the copy table is as small as possible thereby reducing the application's ROM image.

Delete duplicate code (option -Ox/-OX)

Delete duplicate constant data (option -Oy/-OY)

These two optimizations remove code and constant data that is defined more than once, from the resulting object file.

8.7. Controlling the Linker with a Script

With the options on the command line you can control the linker's behavior to a certain degree. From Eclipse it is also possible to determine where your sections will be located, how much memory is available, which sorts of memory are available, and so on. Eclipse passes these locating directions to the linker via a script file. If you want even more control over the locating process you can supply your own script.

The language for the script is called the *Linker Script Language*, or shortly LSL. You can specify the script file to the linker, which reads it and locates your application exactly as defined in the script. If you do not specify your own script file, the linker always reads a standard script file which is supplied with the toolset.

8.7.1. Purpose of the Linker Script Language

The Linker Script Language (LSL) serves three purposes:

- It provides the linker with a definition of the target's core architecture. This definition is supplied with the toolset.
- 2. It provides the linker with a specification of the memory attached to the target processor.
- 3. It provides the linker with information on how your application should be located in memory. This gives you, for example, the possibility to create overlaying sections.

The linker accepts multiple LSL files. You can use the specifications of the core architectures that Altium has supplied in the include.lsl directory. Do not change these files.

If you use a different memory layout than described in the LSL file supplied for the target core, you must specify this in a separate LSL file and pass both the LSL file that describes the core architecture and your LSL file that contains the memory specification to the linker. Next you may want to specify how sections should be located and overlaid. You can do this in the same file or in another LSL file.

LSL has its own syntax. In addition, you can use the standard C preprocessor keywords, such as #include and #define, because the linker sends the script file first to the C preprocessor before it starts interpreting the script.

The complete LSL syntax is described in Linker Script Language.

8.7.2. Eclipse and LSL

In Eclipse you can specify the size of the stack and heap; the physical memory attached to the processor; identify that particular address ranges are reserved; and specify which sections are located where in memory. Eclipse translates your input into an LSL file that is stored in the project directory under the name <code>project_name.lsl</code> and passes this file to the linker. If you want to learn more about LSL you can inspect the generated file <code>project_name.lsl</code>.

To add a generated Linker Script File to your project

 From the File menu, select File » New » Other... » TASKING C/C++ » TASKING VX-toolset for ARM C/C++ Project.

The New C/C++ Project wizard appears.

2. Fill in the project settings in each dialog and click **Next** > until the following dialog appears.



3. Enable the option Add Linker script file to the project and click Finish.

Eclipse creates your project and the file "project_name. 1s1" in the project directory.

If you do not add the linker script file here, you can always add it later with File » New » Other... » TASKING C/C++ » Linker Script File (LSL)

To change the Linker Script File in Eclipse

1. Double-click on the file *project_name*.lsl.

The project LSL file opens in the editor area with several tabs.

```
🔯 myproject.lsl 💢
  memory xrom
  {
      mau = 8;
      type = rom;
      size = ROM SIZE;
      map ( size = ROM SIZE, dest offset = 0, dest = bus:ARM:
  )
  memory xram
      mau = 8;
      type = ram;
      size = RAM SIZE;
      map ( size = __RAM_SIZE, dest offset = __ROM_SIZE, dest =
  }
  <
Memory Sections Stack/Heap myproject.lsl
```

2. You can edit the LSL file directly in the *project_name*.lsl tab or make changes to the other tabs (Memory, Sections, Stack/Heap).

The LSL file is updated automatically according to the changes you make in the tabs. A * appears in front of the name of the LSL file to indicate that the file has changes.

3. Click 🗟 or select **File** » **Save** to save the changes.

You can guickly navigate through the LSL file by using the Outline view (Window » Show View » Outline).

8.7.3. Structure of a Linker Script File

A script file consists of several definitions. The definitions can appear in any order.

The architecture definition (required)

In essence an *architecture definition* describes how the linker should convert logical addresses into physical addresses for a given type of core. If the core supports multiple address spaces, then for each space the linker must know how to perform this conversion. In this context a physical address is an offset on a given internal or external bus. Additionally the architecture definition contains information about items such as the (hardware) stack and the vector table.

This specification is normally written by Altium. Altium supplies LSL files in the include.lsl directory.

The architecture definition of the LSL file should not be changed by you unless you also modify the core's hardware architecture. If the LSL file describes a multi-core system an architecture definition must be available for each different type of core.

The linker uses the architecture name in the LSL file to identify the target. For example, the default library search path can be different for each core architecture.

The derivative definition

The *derivative definition* describes the configuration of the internal (on-chip) bus and memory system. Basically it tells the linker how to convert offsets on the buses specified in the architecture definition into offsets in internal memory. Microcontrollers and DSPs often have internal memory and I/O sub-systems apart from one or more cores. The design of such a chip is called a *derivative*.

When you want to use multiple cores of the same type, you must instantiate the cores in a derivative definition, since the linker automatically instantiates only a single core for an unused architecture.

The processor definition

The *processor definition* describes an instance of a derivative. A processor definition is only needed in a multi-processor embedded system. It allows you to define multiple processors of the same type.

If for a derivative 'A' no processor is defined in the LSL file, the linker automatically creates a processor named 'A' of derivative 'A'. This is why for single-processor applications it is enough to specify the derivative in the LSL file.

The memory and bus definitions (optional)

Memory and bus definitions are used within the context of a derivative definition to specify internal memory and on-chip buses. In the context of a board specification the memory and bus definitions are used to define external (off-chip) memory and buses. Given the above definitions the linker can convert a logical address into an offset into an on-chip or off-chip memory device.

The board specification

The processor definition and memory and bus definitions together form a board specification. LSL provides language constructs to easily describe single-core and heterogeneous or homogeneous multi-core systems. The board specification describes all characteristics of your target board's system buses, memory devices, I/O sub-systems, and cores that are of interest to the linker. Based on the information provided in the board specification the linker can for each core:

- · convert a logical address to an offset within a memory device
- locate sections in physical memory
- maintain an overall view of the used and free physical memory within the whole system while locating

The section layout definition (optional)

The optional section layout definition enables you to exactly control where input sections are located. Features are provided such as: the ability to place sections at a given address, to place sections in a given order, and to overlay code and/or data sections.

Example: Skeleton of a Linker Script File

A linker script file that defines a derivative "X" based on the ARM architecture, its external memory and how sections are located in memory, may have the following skeleton:

```
architecture ARM
    // Specification of the ARM core architecture.
    // Written by Altium.
derivative X // derivative name is arbitrary
    // Specification of the derivative.
    // Written by Altium.
   core ARM
                  // always specify the core
      architecture = ARM;
   bus local_bus // local bus
       // maps to bus "local_bus" in "ARM" core
    // internal memory
}
processor spe // processor name is arbitrary
   derivative = X;
   // You can omit this part, except if you use a
    // multi-core system.
}
memory ext_name
   // external memory definition
section_layout spe:ARM:linear // section layout
    // section placement statements
   // sections are located in address space 'linear'
   // of core 'ARM' of processor 'spe'
}
```

Overview of LSL files delivered by Altium

Altium supplies the following LSL files in the directory include.lsl.

LSL file	Description
arm_arch.lsl	Defines the base architecture (ARM) for all cores.
arm.lsl	Default LSL file. It includes the file arm_arch.lsl.
<pre>lpc*.lsl mac*.lsl stm*.lsl str*.lsl</pre>	Template file with a specification of the external memory attached to the target processor. Used for specific processors.
template.lsl	This file is used by Eclipse as a template for the project LSL file. It includes the file arm_arch.lsl and contains a default specification of the external memory attached to the target processor.

When you select to add a linker script file when you create a project in Eclipse, Eclipse makes a copy of the file template.lsl and names it "project_name.lsl". On the command line, the linker uses the file arm.lsl, unless you specify another file with the linker option --isi-file (-d).

8.7.4. The Architecture Definition

Although you will probably not need to program the architecture definition (unless you are building your own processor core) it helps to understand the Linker Script Language and how the definitions are interrelated.

Within an *architecture definition* the characteristics of a target processor core that are important for the linking process are defined. These include:

- space definitions: the logical address spaces and their properties
- bus definitions: the I/O buses of the core architecture
- mappings: the address translations between logical address spaces, the connections between logical address spaces and buses and the address translations between buses

Address spaces

A logical address space is a memory range for which the core has a separate way to encode an address into instructions. Most microcontrollers and DSPs support multiple address spaces. For example, separate spaces for code and data. Normally, the size of an address space is 2^N , with N the number of bits used to encode the addresses.

The relation of an address space with another address space can be one of the following:

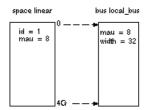
- one space is a subset of the other. These are often used for "small" absolute, and relative addressing.
- the addresses in the two address spaces represent different locations so they do not overlap. This
 means the core must have separate sets of address lines for the address spaces. For example, in
 Harvard architectures we can identify at least a code and a data memory space.

Address spaces (even nested) can have different minimal addressable units (MAU), alignment restrictions, and page sizes. All address spaces have a number that identifies the logical space (id). The following table lists the different address spaces for the architecture ARM as defined in arm_arch.lsl.

Space	ld	MAU	Description
linear	1	8	Linear address space.

The ARM architecture in LSL notation

The best way to program the architecture definition, is to start with a drawing. The following figure shows a part of the ARM architecture:



The figure shows one address space called linear. The address space has attributes like a number that identifies the logical space (id), a MAU and an alignment. In LSL notation the definition of this address space looks as follows:

```
space linear
{
    id = 1;
    mau = 8;

    map (size=4G, dest=bus:local_bus);
}
```

The keyword map corresponds with the arrows in the drawing. You can map:

- address space => address space (not shown in the drawing)
- address space => bus
- memory => bus (not shown in the drawing)
- bus => bus (not shown in the drawing)

Next the internal buses, named local_bus must be defined in LSL:

```
bus local_bus
{
    mau = 8;
    width = 32; // there are 32 data lines on the bus
}
```

This completes the LSL code in the architecture definition. Note that all code above goes into the architecture definition, thus between:

```
architecture ARM
{
    // All code above goes here.
}
```

8.7.5. The Derivative Definition

Although you will probably not need to program the derivative definition (unless you are using multiple cores) it helps to understand the Linker Script Language and how the definitions are interrelated.

A *derivative* is the design of a processor, as implemented on a chip (or FPGA). It comprises one or more cores and on-chip memory. The derivative definition includes:

- · core definition: an instance of a core architecture
- bus definition: the I/O buses of the core architecture
- memory definitions: internal (or on-chip) memory

Core

Each derivative must have at least one core and each core must have a specification of its core architecture. This core architecture must be defined somewhere in the LSL file(s).

```
core ARM
{
    architecture = ARM;
}
```

Bus

Each derivative can contain a bus definition for connecting external memory. In this example, the bus local_bus maps to the bus local_bus defined in the architecture definition of core ARM:

```
bus local_bus
{
    mau = 8;
    width = 32;
    map (dest=bus:ARM:local_bus, dest_offset=0, size=4G);
}
```

Memory

Memory is usually described in a separate memory definition, but you can specify on-chip memory for a derivative. For example:

```
memory internal_code_rom
{
    mau = 8;
```

This completes the LSL code in the derivative definition. Note that all code above goes into the derivative definition, thus between:

8.7.6. The Processor Definition

The processor definition is only needed when you write an LSL file for a multi-processor embedded system. The processor definition explicitly instantiates a derivative, allowing multiple processors of the same type.

```
processor name
{
    derivative = derivative_name;
}
```

If no processor definition is available that instantiates a derivative, a processor is created with the same name as the derivative.

8.7.7. The Memory Definition

Once the core architecture is defined in LSL, you may want to extend the processor with external (or off-chip) memory. You need to specify the location and size of the physical external memory devices in the target system.

The principle is the same as defining the core's architecture but now you need to fill the memory definition:

Suppose your embedded system has 512kB of external ROM, named simrom, 512kB of external RAM, named simram and 32kB of external NVRAM, named my_nvram (see figure above.) All memories are connected to the bus local_bus. In LSL this looks like follows:

```
memory simrom
    mau = 8;
    type = rom;
    size = 512k;
    map ( size = 512k, dest_offset=0, dest=bus:X:local_bus);
memory simram
   mau = 8;
   type = ram;
    size = 512k;
    map ( size = 512k, dest_offset=512k, dest=bus:X:local_bus);
memory my_nvram
   mau = 8;
   size = 32k;
    type = ram;
    map ( size = 32k, dest_offset=1M, dest=bus:X:local_bus);
}
```

If you use a different memory layout than described in the LSL file supplied for the target core, you can specify this in Eclipse or you can specify this in a separate LSL file and pass both the LSL file that describes the core architecture and your LSL file that contains the memory specification to the linker.

To add memory using Eclipse

1. Double-click on the file *project*.lsl.

The project LSL file opens in the editor area with several tabs.

2. Open the **Memory** tab and click on the **Add** button.

A new line is added to the list of Memory.

3. Click in each field to change the type, name (for example my_nvram) and sizes.

The LSL file is updated automatically according to the changes you make.

4. Click 📓 or select **File** » **Save** to save the changes.

A 🔒 in front of a memory chip means that you cannot change this memory, because it is defined is a system LSL file.

8.7.8. The Section Layout Definition: Locating Sections

Once you have defined the internal core architecture and optional memory, you can actually define where your application must be located in the physical memory.

During compilation, the compiler divides the application into sections. Sections have a name, an indication (section type) in which address space it should be located and attributes like writable or read-only.

In the section layout definition you can exactly define how input sections are placed in address spaces, relative to each other, and what their absolute run-time and load-time addresses will be.

Example: section propagation through the toolset

To illustrate section placement, the following example of a C program (bat.c) is used. The program saves the number of times it has been executed in battery back-upped memory, and prints the number.

```
#define BATTERY_BACKUP_TAG 0xa5f0
#include <stdio.h>
int uninitialized_data;
int initialized_data = 1;
#pragma section "non_volatile"
int battery backup tag;
int battery_backup_invok;
#pragma endsection
void main (void)
    if (battery_backup_tag != BATTERY_BACKUP_TAG )
        // battery back-upped memory area contains invalid data
        // initialize the memory
        battery backup tag = BATTERY BACKUP TAG;
        battery_backup_invok = 0;
   printf( "This application has been invoked %d times\n",
             battery_backup_invok++);
}
```

The compiler assigns names and attributes to sections. With the #pragma section and #pragma endsection the compiler's default section naming convention is overruled and a section with the name non_volatile appended is defined. In this section the battery back-upped data is stored.

As a result of the #pragma section "non_volatile", the data objects between the pragma pair are placed in a section with the name ".bss.non_volatile". Note that ".bss" sections are cleared at startup. However, battery back-upped sections should not be cleared and therefore we will change this section attribute using the LSL.

Section placement

The number of invocations of the example program should be saved in non-volatile (battery back-upped) memory. This is the memory my_nvram from the example in Section 8.7.7, *The Memory Definition*.

To control the locating of sections, you need to write one or more section definitions in the LSL file. At least one for each address space where you want to change the default behavior of the linker. In our example, we need to locate sections in the address space linear:

```
section_layout ::linear
{
    // Section placement statements
}
```

To locate sections, you must create a group in which you select sections from your program. For the battery back-up example, we need to define one group, which contains the section .bss.non_volatile. All other sections are located using the defaults specified in the architecture definition. Section .bss.non_volatile should be placed in non-volatile ram. To achieve this, the run address refers to our non-volatile memory called my_nvram. Furthermore, the section should not be cleared and therefore the attribute s (scratch) is assigned to the group:

```
group ( ordered, run_addr = mem:my_nvram, attributes = rws )
{
    select ".bss.non_volatile";
}
```

Section placement from Eclipse

1. Double-click on the file *project*.lsl.

The project LSL file opens in the editor area with several tabs.

2. Open the **Sections** tab and click on the **Add...** button.

The Add New LSL Element dialog appears.

3. In the New element box, select Section Layout and click Finish.

A new section layout 🖫 appears. In the Section layout properties you can specify its characteristics. Note that you can add 'tags', which is just arbitrary text that can be added to a statement.

- 4. In the **Space** field of the Section layout properties, enter **linear**.
- 5. Click on the linear section layout and click on the Add... button.
- In the New element box, select Group and in the Parent box select section_layout ::linear. Click Finish.

An empty group element [-] is added to the section layout. In the Group properties you can specify its characteristics.

7. Click in the **Run address** field of the group and enter mem:my_nvram.

- 8. In the Group properties part, select **Ordered** and set the **Attributes r**, **w** and **s**.
- Click the Add... button, select Select Section(s) and in the Parent box select the corresponding group. Click Finish.

A default select section element with the name "section_name" is added to the group. In the Section selection properties you can specify its characteristics.

10. Click on the section_name and change it to .bss.non_valatile.

The LSL file is updated automatically according to the changes you make.

11. Click 📓 or select **File** » **Save** to save the changes.

This completes the LSL file for the sample architecture and sample program. You can now invoke the linker with this file and the sample program to obtain an application that works for this architecture.

For a complete description of the Linker Script Language, refer to Chapter 16, *Linker Script Language (LSL)*.

8.8. Linker Labels

The linker creates labels that you can use to refer to from within the application software. Some of these labels are real labels at the beginning or the end of a section. Other labels have a second function, these labels are used to address generated data in the locating phase. The data is only generated if the label is used.

Linker labels are labels starting with _1c_. The linker assigns addresses to the following labels when they are referenced:

Label	Description
_lc_ub_ <i>name</i>	Begin of section <i>name</i> . Also used to mark the begin of the stack or heap or copy table.
_lc_b_name	
_lc_ue_ <i>name</i>	End of section <i>name</i> . Also used to mark the end of the stack or heap.
_lc_e_name	
_lc_cb_ <i>name</i>	Start address of an overlay section in ROM.
_lc_ce_ <i>name</i>	End address of an overlay section in ROM.
_lc_gb_name	Begin of group <i>name</i> . This label appears in the output file even if no reference to the label exists in the input file.
_lc_ge_name	End of group <i>name</i> . This label appears in the output file even if no reference to the label exists in the input file.

The linker only allocates space for the stack and/or heap when a reference to either of the section labels exists in one of the input object files.

If you want to use linker labels in your C source for sections that have a dot (.) in the name, you have to replace all dots by underscores.

Example: refer to a label with section name with dots from C

Suppose a section has the name .text. When you want to refer to the begin of this section you have to replace all dots in the section name by underscores:

Example: refer to the stack

Suppose in an LSL file a stack section is defined with the name "stack" (with the keyword stack). You can refer to the begin and end of the stack from your C source as follows:

From assembly you can refer to the end of the stack with:

```
.extern _lc_ue_stack ; end of user stack
```

8.9. Generating a Map File

The map file is an additional output file that contains information about the location of sections and symbols. You can customize the type of information that should be included in the map file.

To generate a map file

1. From the Project menu, select Properties

The Properties dialog appears.

2. In the left pane, expand C/C++ Build and select Settings.

In the right pane the Settings appear.

- 3. On the Tool Settings tab, select Linker » Map File.
- 4. Enable the option Generate XML map file format (.mapxml) for map file viewer.
- (Optional) Enable the option Generate map file (.map).
- 6. (Optional) Enable the options to include that information in the map file.

Example on the command line (Windows Command Prompt)

The following command generates the map file test.map:

```
lkarm --map-file test.obj
```

With this command the map file test.map is created.

See Section 14.2, Linker Map File Format, for an explanation of the format of the map file.

8.10. Linker Error Messages

The linker reports the following types of error messages in the Problems view of Eclipse.

F (Fatal errors)

After a fatal error the linker immediately aborts the link/locate process.

E (Errors)

Errors are reported, but the linker continues linking and locating. No output files are produced unless you have set the linker option--keep-output-files.

W (Warnings)

Warning messages do not result into an erroneous output file. They are meant to draw your attention to assumptions of the linker for a situation which may not be correct. You can control warnings in the C/C++ Build » Settings » Tool Settings » Linker » Diagnostics page of the Project » Properties menu (linker option --no-warnings).

I (Information)

Verbose information messages do not indicate an error but tell something about a process or the state of the linker. To see verbose information, use the linker option--verbose.

S (System errors)

System errors occur when internal consistency checks fail and should never occur. When you still receive the system error message

```
S6##: message
```

please report the error number and as many details as possible about the context in which the error occurred.

Display detailed information on diagnostics

1. From the Window menu, select Show View » Other » General » Problems.

The Problems view is added to the current perspective.

2. In the Problems view right-click on a message.

A popup menu appears.

3. Select **Detailed Diagnostics Info**.

A dialog box appears with additional information.

On the command line you can use the linker option --diag to see an explanation of a diagnostic message:

```
lkarm --diag=[format:]{all | number,...]
```

Chapter 9. Run-time Environment

This chapter describes the startup code used by the TASKING VX-toolset for ARM C Compiler, the vector table, the stack layout and the heap.

9.1. Startup Code

You need the run-time startup code to build an executable application. The default startup code consists of the following components:

- Initialization code. This code is executed when the program is initiated and before the function main() is called.
- Exit code. This controls the close down of the application after the program's main function terminates.

The startup code is part of the C library, and the source is present in the file cstart.asm (ARM and Thumb), or cstart_thumb2.asm (Thumb2 specific) in the directory lib\src. This code is generic code. It uses linker generated symbols which you can give target specific or application specific values. These symbols are defined in the linker script file (include.lsl\arm_arch.lsl) and you can specify their values in Eclipse or on the command line with linker option --define. If the default run-time startup code does not match your configuration, you need to make a copy of the startup file, modify it and add it to your project.

The entry point of the startup code (reset handler) is label _START. This global label should not be removed, since the linker uses it in the linker script file. It is also used as the default start address of the application.

Initialization code

The following initialization actions are executed before the application starts:

- Load the 'real' program address. This assures that the reset handler is immune for any ROM/RAM re-mapping.
- Initialize the stack pointers for each processor mode. The stack pointers are loaded in memory by the stack address located at a linker generate symbol (for example _lc_ub_stack). These symbols are defined in the linker script file. See Section 9.3, Stack and Heap, for detailed information on the stack.
- Call a user function which initializes hardware. The startup code calls the function __init_hardware.
 This function has an empty implementation in the run-time library, which you should change if certain hardware initializations, such as ROM/RAM re-mapping or MMU configuration, are required before calling the main application.
- Copy initialized sections from ROM to RAM, using a linker generated table (also known as the 'copy table') and clear uninitialized data sections in RAM.
- Initialize or copy the vector table. The startup code calls the function __init_vector_table. This
 function has a default implementation in the run-time library, which copies the vector table from ROM
 to RAM if necessary. You should only change it in very specific situations. For example, in case position

dependent vectors are used (B instructions instead of LDR PC) and the vector table must be generated in RAM (or copied from ROM to RAM with patched offsets in the B instructions).

- (cstart.asm only) Switch to the user-defined application mode as defined through the symbol
 _APPLICATION_MODE_ in the LSL file. This symbol is used to set the value of the CPSR status register
 before calling the function main.
- Load register r10 with the end of the user/system stack. This is needed in case stack overflow checking
 is enabled.
- (cstart.asm only) Switch to Thumb code if you specified command line option --thumb.
- Initialize profiling if profiling is enabled. For an extensive description of profiling refer to Chapter 6, *Profiling*.
- Initialize the argc and argv arguments.
- Call the entry point of your application with a call to function main().

Exit code

When the C application 'returns', which is not likely to happen in an embedded environment, the program ends with a call to the library function <code>exit()</code>.

Macro preprocessor symbols

A number of macro preprocessor symbols are used in the startup code. These are enabled when you use a particular option or you can enable or disable them using the assembler option --define with the following syntax:

--define=symbol[=value]

In the startup file (cstart.asm and cstart_thumb2.asm) the following macro preprocessor symbols are used:

Define	Description	
PROF_ENABLE	If defined, initialize profiling.	
POSIX	If defined, call posix_main instead of main.	

The following table shows the linker labels and other labels used in the startup code.

Define	Description
_START	Start label, mentioned in LSL file (arm_arch.lsl)
_Next	Real program address.
main	Start label user C program.
exit	Start label of exit() function.
_lc_ub_stack	User/system mode stack pointer.
_lc_ue_stack	End of stack symbol, required by debugger.

Define	Description
_lc_ub_stack_und	Undefined mode stack pointer. (*)
_lc_ub_stack_svc	Supervisor mode stack pointer. (*)
_lc_ub_stack_abt	Abort mode stack pointer. (*)
_lc_ub_stack_irq	IRQ mode stack pointer. (*)
_lc_ub_stack_fiq	FIQ mode stack pointer. (*)
_lc_ub_table	ROM to RAM copy table.
get_argcv	Start label of argc/argv initialization routine.
argcvbuf	Buffer for holding the argc/argv arguments.
_APPLICATION_MODE_	Contains the processor mode, and the IRQ/FIQ interrupts mode.*
init_hardware	Start label of hardware initialization routine.
init_vector_table	Start label of vector table initialization.

(*) The labels marked with a * are available in cstart.asm only.

9.2. Reset Handler and Vector Table

Reset handler

As explained in the previous section the entry point of the startup code (reset handler) is label _START. The reset handler can have a fixed ROM address (run address). If the reset handler is called from the vector table, you do not need the specify a fixed address. In this case the linker determines the address and patches the vector table. There are however situations were you have to specify a fixed ROM address:

- If _START is the entry point upon reset. Typically you would set the ROM address to the address which
 is mapped at address 0x00000000. Your initialization code remaps this address during startup. Note
 that the reset handler in the run-time library is immune to this remapping because the first instruction
 in the startup code sets the program counter to the actual ROM address.
- When the reset handler is called from the vector table with a branch instruction (B _START) and the linker has located the reset handler at an address that is out-of-range of the branch instruction. When you specify a fixed ROM address you can make sure that the reset handler can be called from the vector table. Note however that you can prevent out-of-range branches by using a position independent vector table, which loads the handler addresses into the program counter by means of a PC-relative load from a literal pool.

Reset handler on fixed ROM address (all architectures)

To force the reset handler on a fixed ROM address, you need to define the symbol __START. This symbol is used in the linker script file arm_arch.lsl. By default, __START is not defined.

To define a symbol for the linker script file

From the Project menu, select Properties

The Properties dialog appears.

2. In the left pane, expand C/C++ Build and select Settings.

In the right pane the Settings appear.

Select Linker » Script File.

The Defined symbols box shows the symbols that are currently defined.

- 4. To define a new symbol, click on the **Add** button in the **Defined symbols** box.
- 5. Type the symbol definition (for example, __START=0x0).

The following table contains an overview of the defines you can set. The defines are used in arm_arch.lsl.

Define	Description
START	Reset handler ROM address
PROCESSOR_MODE	Main application execution mode. Default value is 0x1F (SYS mode).
IRQ_BIT	If 0, IRQ interrupts are enabled. The default value is 0x80 (IRQ disabled).
FIQ_BIT	If 0, FIQ interrupts are enabled. The default value is 0x40 (FIQ disabled).
NO_AUTO_VECTORS	If defined, the vector table will not be generated.
NR_OF_VECTORS	Number of vectors (default 16).
PIC_VECTORS	If defined, position independent vectors are used.
FIQ_HANDLER_INLINE	If defined, the FIQ handler is located directly at the FIQ vector (position dependent vector table only).
VECTOR_TABLE_ROM_ADDR	Address of the vector table in ROM (default 0x0000000).
VECTOR_TABLE_RAM_SPACE	If defined, space must be reserved for a copy of the vector table in RAM.
VECTOR_TABLE_RAM_ADDR	Address of the copy of the vector table in RAM (default 0x00000000).
VECTOR_TABLE_RAM_COPY	If defined, the linker provides copy address symbols so that the startup code can copy the vector table from ROM to RAM.

Main application execution mode (all architectures except M-profile)

With the symbol ___PROCESSOR_MODE you can define the execution mode in which the processor should run when your application's main program is called. Based on this setting, together with the interrupt status (FIQ interrupts enabled/disabled, IRQ interrupts enabled/disabled), the linker will generate a symbol

(_APPLICATION_MODE_) which value is used in the startup code in the run-time library to set the value
of the CPSR status register before calling your main function. Available values:

Value	Description
0x10	USR mode
0x11	FIQ mode
0x12	IRQ mode
0x13	SVC mode
0x17	ABT mode
0x1B	UND mode
0x1F	SYS mode (default)

Interrupt Status (all architectures except M-profile)

It is common use to start with interrupts disabled ($__{IRQ_BIT=0x80}$ and $__{FIQ_BIT=0x40}$) and enable interrupt during run-time after installing all exception handlers and initializing all peripherals. To enable interrupts during run-time, use the $__{setcpsr}()$ intrinsic:

```
__setcpsr (0x00, 0x80); /* Enable IRQ interrupts */
__setcpsr (0x00, 0x40); /* Enable FIQ interrupts */
```

If you want to start with interrupts enabled, set the define the symbols __IRQ_BIT=0 and/or __FIQ_BIT=0.

Vector table

By default the linker can generate a vector table, unless you define the symbol __NO_AUTO_VECTORS.

The linker will look for specific symbols designating the start of a handler function. These symbols are generated by the compiler when one of the following function qualifiers is used:

Function type qualifier	Vector symbol
interrupt_und	_vector_1
interrupt_svc	_vector_2 (*)
interrupt_iabt	_vector_3
interrupt_dabt	_vector_4
interrupt_irq	_vector_6
interrupt_fiq	_vector_7
interrupt(n)	_vector_n

(*) For M-profile architecture the __interrupt_swi qualifier is mapped to _vector_11. Function qualifier __interrupt_swi is equal to __interrupt_svc.

Note that the reset handler is designated by the symbol _START instead of _vector_0. The fifth vector, with symbol _vector_5 is reserved. You should use the same vector symbols in hand-coded assembly handlers. You may first want to generate an idle handler in C with the compiler and than use the result

as a starting point for your assembly implementation. If the linker does not find the symbol for a handler, it will generate a loop for the corresponding vector, i.e. a jump to itself.

Note that if you have more than one handler for the same exception, for example for different IRQ's or for different run-time phases of your application, and you are using the __interrupt_type function qualifier of the compiler, you will need to specify the __novector attribute in order to prevent the compiler from generating the _vector_nr symbol multiple times, as this would lead to a link error.

Vector table size (M-profile architectures)

The vector table size for M-profile architectures is calculated as 4 times the number of vectors. The default number of vectors is 16, but you can specify another value by defining the symbol __NR_OF_VECTORS.

Vector table versions (all architectures except M-profile)

You can select between two versions of the vector table: position dependent or position independent.

The position dependent table contains branch instructions to the handlers. The handlers must be located in-range of the branch instructions. The size of the table is 32 bytes. This is the default.

The *position independent* table contains PC-relative load instructions of the PC. The handler addresses are in a literal pool (data pocket) following the vector table. There are no range restrictions. The size of the table and pool together is 64 bytes.

A position independent table is recommended if the table is copied from ROM to RAM at run-time or if the ROM table is re-mapped to address 0x00000000 after startup.

To select a position independent vector table, define the symbol PIC VECTORS.

FIQ handler at FIQ vector (all architectures except M-profile)

If you selected a position dependent vector table (this is the default), it is possible to locate the FIQ handler directly at the FIQ vector, since the FIQ vector is the last vector in the table. To do this, define the symbol __FIQ_HANDLER_INLINE. Doing so saves a branch instruction when servicing a fast interrupt. The generated vector table or the space reserved for the table will be 28 bytes instead of 32.

This option is not available for a position independent vector table. Note that you need to use the __at() attribute to specify the actual position of the FIQ handler.

Vector table ROM address (all architectures)

The ROM address of the vector table is usually address 0x00000000. You have to specify an address if the vector table will be copied from ROM to RAM (address 0x00000000 is mapped to RAM) or if the hardware uses high vectors at address 0xFFFF0000. If you forced the reset handler on address 0x000000000 then you also have to specify a vector table ROM address to prevent overlapping address ranges.

By default, the symbol __VECTOR_TABLE_ROM_ADDR is defined as 0x00000000.

Reserve RAM space for copy of vector table (all architectures except M-profile)

You can ask the linker to reserve space in RAM memory for a copy of the vector table at run-time at a certain address in memory. Typically this would be the address which will be the mapping of address 0x00000000 after ROM/RAM re-mapping. If you reserve space for a copy you can also let the startup code copy the table automatically from ROM to RAM, but only if position independent vectors are used.

By default, the symbol ___VECTOR_TABLE_RAM_SPACE is not defined.

Vector table RAM address (all architectures except M-profile)

With the define ___VECTOR_TABLE_RAM_ADDR you can set the address in RAM of the copy of the vector table (default 0x00000000).

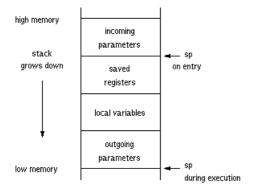
Copy of vector table in RAM (all architectures except M-profile)

If you define the symbol ___VECTOR_TABLE_RAM_COPY, the linker will provide copy address symbols that will be used by the startup code to copy the vector table from ROM to RAM.

Refer to the run-time library implementation of the __init_vector_table routine in lib\src\initvectortable.asm or initvectortable thumb.asm for more information.

9.3. Stack and Heap

The stack is used for local automatic variables and function parameters. The following diagram shows the structure of a stack frame.



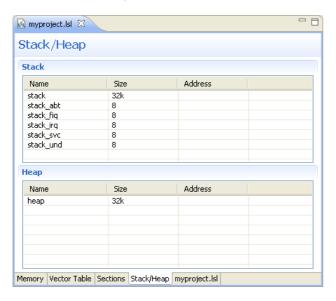
All ARM architectures, except for M-profile architectures, have separate stack pointers for each processor mode. M-profile architectures have one stack pointer. These stack pointers should be initialized at run-time. This is taken care of by the startup code in the run-time library, by means of linker-generated symbols defined in the LSL file. See Section 9.1, Startup Code, for a list of these symbols.

You can define the values of these symbols in Eclipse as follows.

1. Double-click on the file *project*.lsl.

The project LSL file opens in the editor area with several tabs.

- 2. Open the Stack/Heap tab.
- 3. Make your changes.



You can specify the size and location of the stacks.

The stack size is defined in the linker script file (arm_arch.lsl in directory include.lsl) with macros:

Define	Description
STACK	Size of user stack.
STACK_ABT	Abort mode stack size. (*)
STACK_FIQ	FIQ mode stack size. (*)
STACK_IRQ	IRQ mode stack size. (*)
STACK_SVC	Supervisor mode stack size. (*)
STACK_UND	Undefined mode stack size. (*)
STACK_FIXED	Defined if you do not expand the user stack if space is left.
STACKADDR	User stack start address.

(*) The defines marked with a * are not used for M-profile architectures.

Heap allocation

The heap is only needed when you use one or more of the dynamic memory management library functions: malloc(), calloc(), free() and realloc(). The heap is a reserved area in memory. Only if you use one of the memory allocation functions listed above, the linker automatically allocates a heap, as specified in the linker script file with the keyword heap.

A special section called heap is used for the allocation of the heap area. The size of the heap is defined in the linker script file ($arm_arch.lsl$ in directory include.lsl) with the macro $__HEAP$, which results in a section called heap. The linker defined labels $_lc_ub_heap$ and $_lc_ue_heap$ (begin and end of heap) are used by the library function sbrk(), which is called by malloc() when memory is needed from the heap.

The following heap macros are used in arm_arch.lsl:

Define	Description
HEAP	Size of heap.
HEAP_FIXED	Defined if you do not expand the heap if space is left.
HEAPADDR	Heap start address.

Chapter 10. Using the Utilities

The TASKING VX-toolset for ARM comes with a number of utilities:

A control program. The control program invokes all tools in the toolset and lets you quickly generate an absolute object file from C and/or assembly source input files. Eclipse uses the control program to call the compiler, assembler and linker.

Matter A utility program to maintain, update, and reconstruct groups of programs. The make utility

looks whether files are out of date, rebuilds them and determines which other files as a consequence also need to be rebuilt.

amk The make utility which is used in Eclipse. It supports parallelism which utilizes the multiple cores found on modern host hardware.

An archiver. With this utility you create and maintain library files with relocatable object modules (.obj) generated by the assembler.

10.1. Control Program

The control program is a tool that invokes all tools in the toolset for you. It provides a quick and easy way to generate the final absolute object file out of your C/C++ sources without the need to invoke the compiler, assembler and linker manually.

Eclipse uses the control program to call the C++ compiler, C compiler, assembler and linker, but you can call the control program from the command line. The invocation syntax is:

```
ccarm [ [option]... [file]... ]...
```

Recognized input files

- Files with a .cc, .cxx or .cpp suffix are interpreted as C++ source programs and are passed to the C++ compiler.
- Arguments with a .c suffix are interpreted as C source programs and are passed to the compiler.
- Files with a .asm suffix are interpreted as hand-written assembly source files which have to be passed to the assembler.
- Files with a .src suffix are interpreted as compiled assembly source files. They are directly passed to the assembler.
- Files with a .lib suffix are interpreted as library files and are passed to the linker.
- Files with a .obj suffix are interpreted as object files and are passed to the linker.
- Files with a .out suffix are interpreted as linked object files and are passed to the locating phase of the linker. The linker accepts only one .out file in the invocation.
- Files with a .1s1 suffix are interpreted as linker script files and are passed to the linker.

Options

The control program accepts several command line options. If you specify an unknown option to the control program, the control program looks if it is an option for a specific tool. If so, it passes the option directly to the tool. However, it is recommended to use the control program options --pass-* (-Wcp, -Wc, -Wa, -WI) to pass arguments directly to tools.

For a complete list and description of all control program options, see Section 12.5, *Control Program Options*.

Example with verbose output

```
ccarm --verbose test.c
```

The control program calls all tools in the toolset and generates the absolute object file test.abs. With option --verbose (-v) you can see how the control program calls the tools:

The control program produces unique filenames for intermediate steps in the compilation process (such as cc3248a.src and cc3248b.obj in the example above) which are removed afterwards, unless you specify command line option --keep-temporary-files (-t).

Example with argument passing to a tool

```
ccarm --pass-compiler=-Oc test.c
```

The option **-Oc** is directly passed to the compiler.

10.2. Make Utility mkarm

If you are working with large quantities of files, or if you need to build several targets, it is rather time-consuming to call the individual tools to compile, assemble, link and locate all your files.

You save already a lot of typing if you use the control program and define an options file. You can even create a batch file or script that invokes the control program for each target you want to create. But with these methods all files are completely compiled, assembled and linked to obtain the target file, even if you changed just one C source. This may demand a lot of (CPU) time on your host.

The make utility **mkarm** is a tool to maintain, update, and reconstruct groups of programs. The make utility looks which files are out-of-date and only recreates these files to obtain the updated target.

Make process

In order to build a target, the make utility needs the following input:

- the target it should build, specified as argument on the command line
- the rules to build the target, stored in a file usually called makefile

In addition, the make utility also reads the file mkarm.mk which contains predefined rules and macros. See Section 10.2.2, Writing a Makefile.

The makefile contains the relationships among your files (called *dependencies*) and the commands that are necessary to create each of the files (called *rules*). Typically, the absolute object file (.abs) is updated when one of its dependencies has changed. The absolute file depends on .obj files and libraries that must be linked together. The .obj files on their turn depend on .src files that must be assembled and finally, .src files depend on the C source files (.c) that must be compiled. In the makefile this looks like:

You can use any command that is valid on the command line as a rule in the makefile. So, rules are not restricted to invocation of the toolset.

Example

To build the target test.abs, call **mkarm** with one of the following lines:

```
mkarm test.abs

mkarm -fmymake.mak test.abs
```

By default the make utility reads the file makefile so you do not need to specify it on the command line. If you want to use another name for the makefile, use the option -f.

If you do not specify a target, **mkarm** uses the first target defined in the makefile. In this example it would build test.src instead of test.abs.

Based on the sample invocation, the make utility now tries to build test.abs based on the makefile and performs the following steps:

- 1. From the makefile the make utility reads that test.abs depends on test.obj.
- 2. If test.obj does not exist or is out-of-date, the make utility first tries to build this file and reads from the makefile that test.obj depends on test.src.
- 3. If test.src does exist, the make utility now creates test.obj by executing the rule for it: asarm test.src.
- 4. There are no other files necessary to create test.abs so the make utility now can use test.obj to create test.abs by executing the rule: lkarm test.obj -o test.abs ...

The make utility has now built test.abs but it only used the assembler to update test.obj and the linker to create test.abs.

If you compare this to the control program:

```
ccarm test.c
```

This invocation has the same effect but now all files are recompiled (assembled, linked and located).

10.2.1. Calling the Make Utility

You can only call the make utility from the command line. The invocation syntax is:

```
mkarm [ [option]... [target]... [macro=def]... ]
```

For example:

mkarm test.abs

target You can specify any target that is defined in the makefile. A target can also be one

of the intermediate files specified in the makefile.

macro=def Macro definition. This definition remains fixed for the **mkarm** invocation. It overrides

any regular definitions for the specified macro within the makefiles and from the environment. It is inherited by subordinate **mkarm**'s but act as an environment variable for these. That is, depending on the **-e** setting, it may be overridden by a makefile

definition.

option For a complete list and description of all make utility options, see Section 12.6, Make

Utility Options.

Exit status

The make utility returns an exit status of 1 when it halts as a result of an error. Otherwise it returns an exit status of 0.

10.2.2. Writing a Makefile

In addition to the standard makefile makefile, the make utility always reads the makefile mkarm.mk before other inputs. This system makefile contains implicit rules and predefined macros that you can use in the makefile makefile.

With the option -r (Do not read the mkarm.mk file) you can prevent the make utility from reading mkarm.mk.

The default name of the makefile is makefile in the current directory. If you want to use another makefile, use the option -f.

The makefile can contain a mixture of:

- · targets and dependencies
- rules
- · macro definitions or functions
- · conditional processing
- comment lines
- include lines
- export lines

To continue a line on the next line, terminate it with a backslash (1):

```
# this comment line is continued\
on the next line
```

If a line must end with a backslash, add an empty macro:

```
# this comment line ends with a backslash \$(EMPTY)
# this is a new line
```

10.2.2.1. Targets and Dependencies

The basis of the makefile is a set of targets, dependencies and rules. A target entry in the makefile has the following format:

```
target ...: [dependency ...] [; rule] [rule] ...
```

Target lines must always start at the beginning of a line, leading white spaces (tabs or spaces) are not allowed. A target line consists of one or more targets, a semicolon and a set of files which are required to build the target (*dependencies*). The target itself can be one or more filenames or symbolic names:

```
all: demo.abs final.abs

demo.abs final.abs: test.obj demo.obj final.obj
```

You can now can specify the target you want to build to the make utility. The following three invocations all have the same effect:

```
mkarm mkarm all mkarm demo.abs final.abs
```

If you do *not* specify a target, the first target in the makefile (in this example all) is built. The target all depends on demo.abs and final.abs so the second and third invocation have the same effect and the files demo.abs and final.abs are built.

You can normally use colons to denote drive letters. The following works as intended:

```
c:foo.obj : a:foo.c
```

If a target is defined in more than one target line, the dependencies are added to form the target's complete dependency list:

```
all: demo.abs  # These two lines are equivalent with:
all: final.abs  # all: demo.abs final.abs
```

Special targets

There are a number of special targets. Their names begin with a period.

Target	Description
.DEFAULT	If you call the make utility with a target that has no definition in the makefile, this target is built.
.DONE	When the make utility has finished building the specified targets, it continues with the rules following this target.
. IGNORE	Non-zero error codes returned from commands are ignored. Encountering this in a makefile is the same as specifying the option -i on the command line.
.INIT	The rules following this target are executed before any other targets are built.
.PRECIOUS	Dependency files mentioned for this target are never removed. Normally, if a command in a rule returns an error or when the target construction is interrupted, the make utility removes that target file. You can use the option -p on the command line to make all targets precious.
.SILENT	Commands are not echoed before executing them. Encountering this in a makefile is the same as specifying the option -s on the command line.

Target	Description
SUFFIXES	This target specifies a list of file extensions. Instead of building a completely specified target, you now can build a target that has a certain file extension. Implicit rules to build files with a number of extensions are included in the system makefile mkarm.mk. If you specify this target with dependencies, these are added to the existing .SUFFIXES target in mkarm.mk. If you specify this target without dependencies, the existing list is cleared.

10.2.2.2. Makefile Rules

A line with leading white space (tabs or spaces) is considered as a rule and associated with the most recently preceding dependency line. A *rule* is a line with commands that are executed to build the associated target. A target-dependency line can be followed by one or more rules.

You can precede a rule with one or more of the following characters:

- @ does not echo the command line, except if **-n** is used.
- the make utility ignores the exit code of the command. Normally the make utility stops if a non-zero exit code is returned. This is the same as specifying the option **-i** on the command line or specifying the special . IGNORE target.
- + The make utility uses a shell or Windows command prompt (cmd.exe) to execute the command. If the '+' is not followed by a shell line, but the command is an MS-DOS command or if redirection is used (<, |, >), the shell line is passed to cmd.exe anyway.

You can force **mkarm** to execute multiple command lines in one shell environment. This is accomplished with the token combination ';\'. For example:

```
cd c:\Tasking\bin ;\
mkarm -V
```

Note that the ';' must always directly be followed by the '\' token. Whitespace is not removed when it is at the end of the previous command line or when it is in front of the next command line. The use of the ';' as an operator for a command (like a semicolon ';' separated list with each item on one line) and the '\' as a layout tool is not supported, unless they are separated with whitespace.

Inline temporary files

The make utility can generate inline temporary files. If a line contains <<LABEL (no whitespaces!) then all subsequent lines are placed in a temporary file until the line LABEL is encountered. Next, <<LABEL is replaced by the name of the temporary file. For example:

```
lkarm -o $@ -f <<EOF
    $(separate "\n" $(match .obj $!))
$(separate "\n" $(match .lib $!))</pre>
```

```
$(LKFLAGS)
```

The three lines between <<EOF and EOF are written to a temporary file (for example mkce4c0a.tmp), and the rule is rewritten as: lkarm -o \$@ -f mkce4c0a.tmp.

Suffix targets

Instead of specifying a specific target, you can also define a general target. A general target specifies the rules to generate a file with extension .ex1 to a file with extension .ex2. For example:

```
.SUFFIXES: .c
.c.obj : ccarm -c $<
```

Read this as: to build a file with extension .obj out of a file with extension .c, call the control program with -c \$<. \$< is a predefined macro that is replaced with the name of the current dependency file. The special target .SUFFIXES: is followed by a list of file extensions of the files that are required to build the target.

Implicit rules

Implicit rules are stored in the system makefile <code>mkarm.mk</code> and are intimately tied to the <code>.SUFFIXES</code> special target. Each dependency that follows the <code>.SUFFIXES</code> target, defines an extension to a filename which must be used to build another file. The implicit rules then define how to actually build one file from another. These files share a common basename, but have different extensions.

If the specified target on the command line is not defined in the makefile or has not rules in the makefile, the make utility looks if there is an implicit rule to build the target.

Example:

```
LIB = -lcarm -lfparm -lrtarm # macro

prog.abs: prog.obj sub.obj
    lkarm prog.obj sub.obj $(LIB) -o prog.abs

prog.obj: prog.c inc.h
    carm prog.c
    asarm prog.src

sub.obj: sub.c inc.h
    carm sub.c
    asarm sub.src
```

This makefile says that prog.abs depends on two files prog.obj and sub.obj, and that they in turn depend on their corresponding source files (prog.c and sub.c) along with the common file inc.h.

The following makefile uses implicit rules (from mkarm.mk) to perform the same job.

```
LDFLAGS = -lcarm -lfparm -lrtarm # macro used by implicit rules prog.abs: prog.obj sub.obj # implicit rule used
```

```
prog.obj: prog.c inc.h  # implicit rule used
sub.obj: sub.c inc.h  # implicit rule used
```

10.2.2.3. Macro Definitions

A *macro* is a symbol name that is replaced with its definition before the makefile is executed. Although the macro name can consist of lower case or upper case characters, upper case is an accepted convention. The general form of a macro definition is:

```
MACRO = text
MACRO += and more text
```

Spaces around the equal sign are not significant. With the += operator you can add a string to an existing macro. An extra space is inserted before the added string automatically.

To use a macro, you must access its contents:

```
$(MACRO)  # you can read this as
${MACRO}  # the contents of macro MACRO
```

If the macro name is a single character, the parentheses are optional. Note that the expansion is done recursively, so the body of a macro may contain other macros. These macros are expanded when the macro is actually used, not at the point of definition:

```
FOOD = $(EAT) and $(DRINK)
EAT = meat and/or vegetables
DRINK = water
export FOOD
```

The macro FOOD is expanded as meat and/or vegetables and water at the moment it is used in the export line, and the environment variable FOOD is set accordingly.

Predefined macros

Macro	Description
MAKE	Holds the value mkarm . Any line which uses MAKE, temporarily overrides the option -n (Show commands without executing), just for the duration of the one line. This way you can test nested calls to MAKE with the option -n.
MAKEFLAGS	Holds the set of options provided to mkarm (except for the options -f and -d). If this macro is exported to set the environment variable MAKEFLAGS, the set of options is processed before any command line options. You can pass this macro explicitly to nested mkarm 's, but it is also available to these invocations as an environment variable.
PRODDIR	Holds the name of the directory where mkarm is installed. You can use this macro to refer to files belonging to the product, for example a library source file. DOPRINT = \$(PRODDIR)/lib/src/_doprint.c
	When mkarm is installed in the directory c:/Tasking/bin this line expands to: DOPRINT = c:/Tasking/lib/src/_doprint.c
	BOTKINI - C-, Tubking, Tib, bic, _dopine.c

Macro	Description
	Holds the default list of commands which are local to the SHELL. If a rule is an invocation of one of these commands, a SHELL is automatically spawned to handle it.
\$	This macro translates to a dollar sign. Thus you can use "\$\$" in the makefile to represent a single "\$".

Dynamically maintained macros

There are several dynamically maintained macros that are useful as abbreviations within rules. It is best not to define them explicitly.

Macro	Description
\$*	The basename of the current target.
\$<	The name of the current dependency file.
\$@	The name of the current target.
\$?	The names of dependents which are younger than the target.
\$!	The names of all dependents.

The \$< and \$* macros are normally used for implicit rules. They may be unreliable when used within explicit target command lines. All macros may be suffixed with \mathbf{F} to specify the Filename components (e.g. $\{*F\}$, $\{@F\}$). Likewise, the macros $\{*, *C\}$ and $\{*M\}$ may be suffixed by \mathbf{D} to specify the Directory component.

The result of the \$* macro is always without double quotes ("), regardless of the original target having double quotes (") around it or not.

The result of using the suffix **F** (Filename component) or **D** (Directory component) is also always without double quotes ("), regardless of the original contents having double quotes (") around it or not.

10.2.2.4. Makefile Functions

A function not only expands but also performs a certain operation. Functions syntactically look like macros but have embedded spaces in the macro name, e.g. '\$(match arg1 arg2 arg3)'. All functions are built-in and currently there are five of them: match, separate, protect, exist and nexist.

match

The match function yields all arguments which match a certain suffix:

```
$(match .obj prog.obj sub.obj mylib.lib)
yields:
prog.obj sub.obj
```

separate

The separate function concatenates its arguments using the first argument as the separator. If the first argument is enclosed in double quotes then '\n' is interpreted as a newline character, '\t' is interpreted as a tab, '\ooo' is interpreted as an octal value (where, ooo is one to three octal digits), and spaces are taken literally. For example:

```
$(separate "\n" prog.obj sub.obj)
results in:
prog.obj
sub.obj
```

Function arguments may be macros or functions themselves. So,

```
$(separate "\n" $(match .obj $!))
```

yields all object files the current target depends on, separated by a newline string.

protect

The protect function adds one level of quoting. This function has one argument which can contain white space. If the argument contains any white space, single quotes, double quotes, or backslashes, it is enclosed in double quotes. In addition, any double quote or backslash is escaped with a backslash.

Example:

```
echo $(protect I'll show you the "protect" function)
yields:
echo "I'll show you the \"protect\" function"
```

exist

The exist function expands to its second argument if the first argument is an existing file or directory.

Example:

```
$(exist test.c ccarm test.c)
When the file test.c exists, it yields:
ccarm test.c
```

When the file test.c does not exist nothing is expanded.

nexist

The nexist function is the opposite of the exist function. It expands to its second argument if the first argument is not an existing file or directory.

Example:

```
$(nexist test.src ccarm test.c)
```

10.2.2.5. Conditional Processing

Lines containing ifdef, ifndef, else or endif are used for conditional processing of the makefile. They are used in the following way:

```
ifdef macro-name
if-lines
else
else-lines
endif
```

The *if-lines* and *else-lines* may contain any number of lines or text of any kind, even other <code>ifdef</code>, <code>ifndef</code>, <code>else</code> and <code>endif</code> lines, or no lines at all. The <code>else</code> line may be omitted, along with the *else-lines* following it.

First the *macro-name* after the ifdef command is checked for definition. If the macro is defined then the *if-lines* are interpreted and the *else-lines* are discarded (if present). Otherwise the *if-lines* are discarded; and if there is an else line, the *else-lines* are interpreted; but if there is no else line, then no lines are interpreted.

When you use the ifndef line instead of ifdef, the macro is tested for not being defined. These conditional lines can be nested up to 6 levels deep.

You can also add tests based on strings. With ifeq the result is true if the two strings match, with ifneq the result is true if the two strings do not match. They are used in the following way:

```
ifeq(string1,string2)
if-lines
else
else-lines
endif
```

10.2.2.6. Comment, Include and Export Lines

Comment lines

Anything after a "#" is considered as a comment, and is ignored. If the "#" is inside a quoted string, it is not treated as a comment. Completely blank lines are ignored.

Include lines

An *include line* is used to include the text of another makefile (like including a .h file in a C source). Macros in the name of the included file are expanded before the file is included. You can include several files. Include files may be nested.

include makefile2 makefile3

Export lines

An *export line* is used to export a macro definition to the environment of any command executed by the make utility.

```
GREETING = Hello
export GREETING
```

This example creates the environment variable GREETING with the value Hello. The macro is exported at the moment the export line is read so the macro definition has to precede the export line.

10.3. Make Utility amk

amk is the make utility Eclipse uses to maintain, update, and reconstruct groups of programs. But you can also use it on the command line. Its features are a little different from mkarm. The main difference compared to mkarm and other make utilities, is that amk features parallelism which utilizes the multiple cores found on modern host hardware, hardening for path names with embedded white space and it has an (internal) interface to provide progress information for updating a progress bar. It does not use an external command shell (/bin/sh, cmd.exe) but executes commands directly.

The primary purpose of any make utility is to speed up the edit-build-test cycle. To avoid having to build everything from scratch even when only one source file changes, it is necessary to describe dependencies between source files and output files and the commands needed for updating the output files. This is done in a so called "makefile".

10.3.1. Makefile Rules

A makefile dependency rule is a single line of the form:

```
[target ...] : [prerequisite ...]
```

where target and prerequisite are path names to files. Example:

```
test.obj : test.c
```

This states that target test.obj depends on prerequisite test.c. So, whenever the latter is modified the first must be updated. Dependencies accumulate: prerequisites and targets can be mentioned in multiple dependency rules (circular dependencies are not allowed however). The command(s) for updating a target when any of its prerequisites have been modified must be specified with leading white space after any of the dependency rule(s) for the target in question. Example:

```
test.obj :
   ccarm test.c  # leading white space
```

Command rules may contain dependencies too. Combining the above for example yields:

```
test.obj : test.c
  ccarm test.c
```

White space around the colon is not required. When a path name contains special characters such as ':', '#' (start of comment), '=' (macro assignment) or any white space, then the path name must be enclosed in single or double quotes. Quoted strings can contain anything except the quote character itself and a newline. Two strings without white space in between are interpreted as one, so it is possible to embed single and double quotes themselves by switching the quote character.

When a target does not exist, its modification time is assumed to be very old. So, **amk** will try to make it. When a prerequisite does not exist possibly after having tried to make it, it is assumed to be very new. So, the update commands for the current target will be executed in that case. **amk** will only try to make targets which are specified on the command line. The default target is the first target in the makefile which does not start with a dot.

10.3.2. Makefile Directives

Directives inside makefiles are executed while reading the makefile. When a line starts with the word "include" or "-include" then the remaining arguments on that line are considered filenames whose contents are to be inserted at the current line. "-include" will silently skip files which are not present. You can include several files. Include files may be nested.

Example:

include makefile2 makefile3

10.3.3. Macro Definitions

A *macro* is a symbol name that is replaced with its definition before the makefile is executed. Although the macro name can consist of lower case or upper case characters, upper case is an accepted convention. When a line does not start with white space and contains the assignment operator '=', ':=' or '+=' then the line is interpreted as a macro definition. White space around the assignment operator and white space at the end of the line is discarded. Single character macro evaluation happens by prefixing the name with '\$'. To evaluate macros with names longer than one character put the name between parentheses '()' or curly braces '\{\}'. Macro names may contain anything, even white space or other macro evaluations. Example:

```
DINNER = $(FOOD) and $(BEVERAGE)
FOOD = pizza
BEVERAGE = sparkling water
FOOD += with cheese
```

With the += operator you can add a string to an existing macro. An extra space is inserted before the added string automatically.

Macros are evaluated recursively. Whenever \$(DINNER) or \${DINNER} is mentioned after the above, it will be replaced by the text "pizza with cheese and sparkling water". The left hand side in a macro definition is evaluated before the definition takes place. Right hand side evaluation depends on the assignment operator:

- Evaluate the macro at the moment it is used.
- := Evaluate the replacement text before defining the macro.

Subsequent '+=' assignments will inherit the evaluation behavior from the previous assignment. If there is none, then '+=' is the same as '='. The default value for any macro is taken from the environment. Macro definitions inside the makefile overrule environment variables. Macro definitions on the **amk** command line will be evaluated first and overrule definitions inside the makefile.

Predefined macros

Macro	Description
\$	This macro translates to a dollar sign. Thus you can use "\$\$" in the makefile to represent a single "\$".
@	The name of the current target. When a rule has multiple targets, then it is the name of the target that caused the rule commands to be run.
<	The name of the first prerequisite.
MAKE	The amk path name (quoted if necessary). Optionally followed by the options -n and -s .
ORIGIN	The name of the directory where amk is installed (quoted if necessary).
SUBDIR	The argument of option -G . If you have nested makes with -G options, the paths are combined. This macro is defined in the environment (i.e. default macro value).

The @ and < macros may be suffixed by 'D' to specify the directory component or by 'F' to specify the filename component. (@D) evaluates to the directory name holding the file (@F). (@D) /(@F) is equivalent to @D. Note that on MS-Windows most programs accept forward slashes, even for UNC path names.

The result of the predefined macros @ and < and 'D' and 'F' variants is not quoted, so it may be necessary to put quotes around it.

Macro string substitution

When the macro name in an evaluation is followed by a colon and equal sign as in

```
$(MACRO:string1=string2)
```

then **amk** will replace string1 at the end of every word in (MACRO) by string2 during evaluation. When (MACRO) contains quoted path names, the quote character must be mentioned in both the original string and the replacement string¹. For example:

```
$(MACRO:.obj"=.d")
```

10.3.4. Makefile Parsing

amk reads and interprets a makefile in the following order:

- 1. When the last character on a line is a backslash () (i.e. without trailing white space) then that line and the next line will be concatenated, removing the backslash and newline.
- The unquoted '#' character indicates start of comment and may be placed anywhere on a line. It will be removed in this phase.

```
# this comment line is continued\
on the next line
```

¹Internally, **amk** tokenizes the evaluated text, but performs substitution on the original input text to preserve compatibility here with existing make implementations and POSIX.

- 3. Trailing white space is removed.
- 4. When a line starts with white space then it is interpreted as a command for updating a target.
- 5. Otherwise, when a line contains the unquoted text '=', '+=' or ':=' operator, then it will be interpreted as a macro definition.
- 6. Otherwise, all macros on the line are evaluated before considering the next steps.
- 7. When the resulting line contains an unquoted ':' the line is interpreted as a dependency rule.
- 8. When the first token on the line is "include" or "-include" (which by now must start on the first column of the line), **amk** will execute the directive.
- 9. Otherwise, the line must be empty.

Macros in commands for updating a target are evaluated right before the actual execution takes place (or would take place when you use the **-n** option).

10.3.5. Makefile Command Processing

A line with leading white space (tabs or spaces) is considered as a command for updating a target. When you use the option **-j** or **-J**, **amk** will execute the commands for updating different targets in parallel. In that case standard input will not be available and standard output and error output will be merged and displayed on standard output only after the commands have finished for a target.

You can precede a command by one or more of the following characters:

- @ Do not show the command. By default, commands are shown prior to their output.
- Continue upon error. This means that **amk** ignores a non-zero exit code of the command.
- + Execute the command, even when you use option -n (dry run).
- Execute the command on the foreground with standard input, standard output and error output available.

Built-in commands

Command	Description
true	This command does nothing. Arguments are ignored.
false	This command does nothing, except failing with exit code 1. Arguments are ignored.
echo <i>arg</i>	Display a line of text.
text arg	Display a line of text in the progress bar of Eclipse.
argfile <i>file arg</i>	Create an argument file suitable for the option-file (-f) option of all the other tools. The first argfile argument is the name of the file to be created. Subsequent arguments specify the contents. An existing argument file is not modified unless necessary. So, the argument file itself can be used to create a dependency to options of the command for updating a target.

10.3.6. Calling the amk Make Utility

The invocation syntax of amk is:

```
amk [option]... [target]... [macro=def]...
```

For example:

amk test.abs

target You can specify any target that is defined in the makefile. A target can also be one

of the intermediate files specified in the makefile.

macro=def Macro definition. This definition remains fixed for the **amk** invocation. It overrides any

regular definitions for the specified macro within the makefiles and from the

environment. It is not inherited by subordinate amk's

option For a complete list and description of all **amk** make utility options, see Section 12.7,

Parallel Make Utility Options.

Exit status

The make utility returns an exit status of 1 when it halts as a result of an error. Otherwise it returns an exit status of 0.

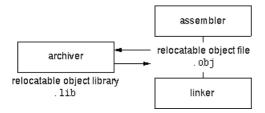
10.4. Archiver

The archiver **ararm** is a program to build and maintain your own library files. A library file is a file with extension .lib and contains one or more object files (.obj) that may be used by the linker.

The archiver has five main functions:

- Deleting an object module from the library
- Moving an object module to another position in the library file
- · Replacing an object module in the library or add a new object module
- . Showing a table of contents of the library file
- Extracting an object module from the library

The archiver takes the following files for input and output:



The linker optionally includes object modules from a library if that module resolves an external symbol definition in one of the modules that are read before.

10.4.1. Calling the Archiver

You can create a library in Eclipse, which calls the archiver or you can call the archiver on the command line.

To create a library in Eclipse

Instead of creating an ARM absolute ELF file, you can choose to create a library. You do this when you create a new project with the New C/C++ Project wizard.

 From the File menu, select New » Other... » TASKING C/C++ » TASKING VX-toolset for ARM C/C++ Project.

The New C/C++ Project wizard appears.

- 2. Enter a project name.
- 3. In the Project types box, select TASKING ARM Library and clickNext >.
- 4. Follow the rest of the wizard and click Finish.
- 5. Add the files to your project.

6. Build the project as usual. For example, select Project » Build Project (🗐).

Eclipse builds the library. Instead of calling the linker, Eclipse now calls the archiver.

Command line invocation

You can call the archiver from the command line. The invocation syntax is:

ararm key_option [sub_option...] library [object_file]

key_option With a key option you specify the main task which the archiver should perform. You

must always specify a key option.

sub option Sub-options specify into more detail how the archiver should perform the task that is

specified with the key option. It is not obligatory to specify sub-options.

library The name of the library file on which the archiver performs the specified action. You

must always specify a library name, except for the options -? and -V. When the library is not in the current directory, specify the complete path (either absolute or relative) to

the library.

object_file The name of an object file. You must always specify an object file name when you

add, extract, replace or remove an object file from the library.

Options of the archiver utility

The following archiver options are available:

Description	Option	Sub-option
Main functions (key options)	·	
Replace or add an object module	-r	-a -b -c -u -v
Extract an object module from the library	-x	-v
Delete object module from library	-d	-v
Move object module to another position	-m	-a -b -v
Print a table of contents of the library	-t	-s0 -s1
Print object module to standard output	-p	
Sub-options		
Append or move new modules after existing module name	-a name	
Append or move new modules before existing module name -b na		
Create library without notification if library does not exis	-с	
Preserve last-modified date from the library	-0	
Print symbols in library modules	-s{0 1}	
Replace only newer modules -u		
Verbose	-v	
Miscellaneous		•

Description	Option	Sub-option
Display options	-?	
Display version header	-V	
Read options from file	-f file	
Suppress warnings above level n	-wn	

For a complete list and description of all archiver options, see Section 12.8, Archiver Options.

10.4.2. Archiver Examples

Create a new library

If you add modules to a library that does not yet exist, the library is created. To create a new library with the name mylib.lib and add the object modules cstart.obj and calc.obj to it:

```
ararm -r mylib.lib cstart.obj calc.obj
```

Add a new module to an existing library

If you add a new module to an existing library, the module is added at the end of the module. (If the module already exists in the library, it is replaced.)

```
ararm -r mylib.lib mod3.obj
```

Print a list of object modules in the library

To inspect the contents of the library:

```
ararm -t mylib.lib
```

The library has the following contents:

```
cstart.obj
calc.obj
mod3.obj
```

Move an object module to another position

To move mod3.obj to the beginning of the library, position it just before cstart.obj:

```
ararm -mb cstart.obj mylib.lib mod3.obj
```

Delete an object module from the library

To delete the object module cstart.obj from the library mylib.lib:

```
ararm -d mylib.lib cstart.obj
```

Extract all modules from the library

Extract all modules from the library mylib.lib:

ararm -x mylib.lib

Chapter 11. Using the Debugger

This chapter describes the debugger and how you can run and debug a C or C++ application. This chapter only describes the TASKING specific parts.

11.1. Reading the Eclipse Documentation

Before you start with this chapter, it is recommended to read the Eclipse documentation first. It provides general information about the debugging process. This chapter guides you through a number of examples using the TASKING debugger with simulation as target.

You can find the Eclipse documentation as follows:

- 1. Start Eclipse.
- 2. From the **Help** menu, select **Help Contents**.

The help screen overlays the Eclipse Workbench.

- 3. In the left pane, select C/C++ Development User Guide.
- 4. Open the Getting Started entry and select Debugging projects.

This Eclipse tutorial provides an overview of the debugging process. Be aware that the Eclipse example does not use the TASKING tools and TASKING debugger.

11.2. Creating a Customized Debug Configuration

Before you can debug a project, you need a Debug launch configuration. Such a configuration, identified by a name, contains all information about the debug project: which debugger is used, which project is used, which binary debug file is used, which perspective is used, ... and so forth.

When you created your project, a default launch configuration for the TASKING simulator is available. If you used the Target Board Configuration wizard, also a default debug launch configuration for your target board is available. At any time you can change this configuration or create a custom debug configuration.

To debug or run a project, you need at least one opened and active project in your workbench. In this chapter, it is assumed that the myproject is opened and active in your workbench.

Customize your debug configuration

To change or create your own debug configuration follow the steps below.

1. From the Run menu, select Debug Configurations...

The Debug Configurations dialog appears.

2. In the left pane, select the configuration you want to change, for example, **TASKING Embedded C/C++ Application** » myproject.simulator.

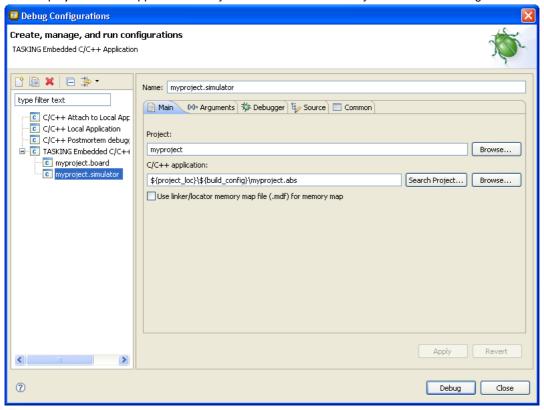
Or: click the **New launch configuration** button (\square) to add a new configuration.

The next dialog appears.

The dialog shows several tabs.

Main tab

On the **Main** tab, you can set the properties for the debug configuration such as a name for the configuration and the project and the application binary file which are used when you choose this configuration.



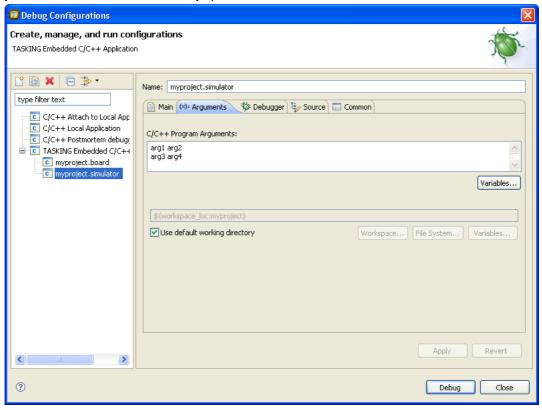
- Name is the name of the configuration. By default, this is the name of the project, optionally appended with simulator or board. You can give your configuration any name you want to distinguish it from the project name.
- In the Project field, you can choose the project for which you want to make a debug configuration.
 Because the project myproject is the active project, this project is filled in automatically. Click the Browse... button to select a different project. Only the opened projects in your workbench are listed.
- In the C/C++ Application field, you can choose the binary file to debug. The file myproject. abs is automatically selected from the active project.

You can use the option Use linker/locator memory map file (.mdf) for memory map to find errors
in your application that cause access to non-existent memory or cause an attempt to write to read-only
memory. When building your project, the linker/locator creates a memory description file (.mdf) file
which describes the memory regions of the target you selected in your project properties. The debugger
uses this file to initialize the debugging target.

This option is only useful in combination with a simulator as debug target. The debugger may fail to start if you use this option in combination with other debugging targets than a simulator.

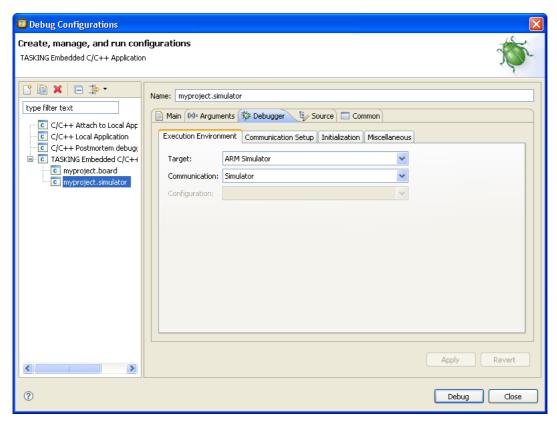
Arguments tab

If your application's main() function takes arguments, you can pass them in this tab. Arguments are conventionally passed in the argv[] array. Because this array is allocated in target memory, make sure you have allocated sufficient memory space for it.



Debugger tab

On the **Debugger** tab you can set the debugger options. You can choose which debugger should be used and with what options it should work. The Debugger tab itself contains several tabs.



- On the Execution Environment tab you can select on which target the application should be debugged.
 An application may run on an external evaluation board, or on a simulator using your own PC. For the evaluation board these settings should be the same as you specified in the Target Board Configuration wizard.
- On the Communication Setup tab you can select the type of communication (RS-232, TCP/IP, CAN) for execution environments. This tab is grayed out for the simulator.
- On the **Initialization** tab enable one or more of the following options:

Initial download of program

If enabled, the target application is downloaded onto the target. If disabled, only the debug information in the file is loaded, which may be useful when the application has already been downloaded (or flashed) earlier. If downloading fails, the debugger will shut down.

Verify download of program

If enabled, the debugger verifies whether the code and data has been downloaded successfully. This takes some extra time but may be useful if the connection to the target is unreliable.

Program flash when downloading

If enabled, also flash devices are programmed (if necessary). Flash programming will not work when you use a simulator.

Reset target

If enabled, the target is immediately reset after downloading has completed.

Goto main

If enabled, only the C startup code is processed when the debugger is launched. The application stops executing when it reaches the first C instruction in the function main(). Usually you enable this option in combination with the option **Reset Target**.

· Break on exit

If enabled, the target halts automatically when the exit() function is called.

· Reduce target state polling

If you have set a breakpoint, the debugger checks the status of the target every *number* of seconds to find out if the breakpoint is hit. In this field you can change the polling frequency.

• On the **Miscellaneous** tab you can specify several file locations.

Debugger location

The location of the debugger itself. This should not be changed.

FSS root directory

The initial directory used by file system simulation (FSS) calls. See the description of the FSS view.

ORTI file and KSM module

If you wish to use the debugger's special facilities for OSEK kernels, specify the name of your ORTI file and that of your KSM module (shared library) in the appropriate edit boxes. See also the description of the RTOS view.

· GDI log file and Debug instrument log file

You can use the options GDI log file and Debug instrument log file (if applicable) to control the generation of internal log files. These are primarily intended for use by or at the request of Altium support personnel.

Set TCP port to

The debugger may use the TCP/IP protocol for internal purposes, for which it needs to reserve a TCP port number. In the unlikely case that the default number conflicts with a program already running, you can change the TCP port.

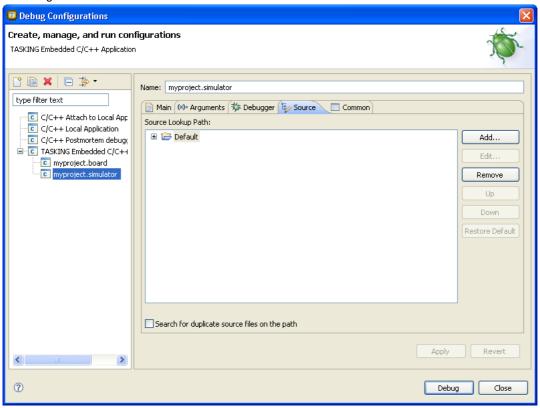
Cache target access

Except when using a simulator, the debugger's performance is generally strongly dependent on the throughput and latency of the connection to the target. Depending on the situation, enabling this

option may result in a noticeable improvement, as the debugger will then avoid re-reading registers and memory while the target remains halted. However, be aware that this may cause the debugger to show the wrong data if tasks with a higher priority or external sources can influence the halted target's state.

Source tab

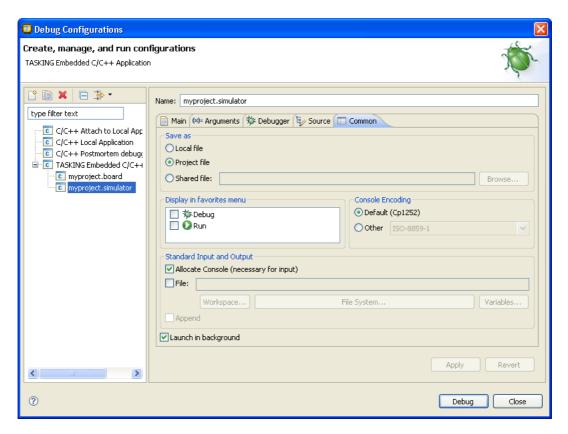
On the **Source** tab, you can add additional source code locations in which the debugger should search for debug data.



Usually, the default source code location is correct.

Common tab

On the **Common** tab you can set additional launch configuration settings.



11.3. Troubleshooting

If the debugger does not launch properly, this is likely due to mistakes in the settings of the execution environment or to an improper connection between the host computer and the execution environment. Always read the notes for your particular execution environment.

Some common problems you may check for, are:

Problem	Solution
Wrong device name in the launch configuration	Make sure the specified device name is correct.
Invalid baud rate	Specify baud rate that matches the baud rate the execution environment is configured to expect.
No power to the execution environment.	Make sure the execution environment or attached probe is powered.
Wrong type of RS-232 cable.	Make sure you are using the correct type of RS-232 cable.
Cable connected to the wrong port on the execution environment or host.	Some target machines and hosts have several ports. Make sure you connect the cable to the correct port.

Problem	Solution
Conflict between communication ports.	A device driver or background application may use the same communications port on the host system as the debugger. Disable any service that uses the same port-number or choose a different port-number if possible.
Port already in use by another user.	The port may already be in use by another user on some UNIX hosts, or being allocated by a login process. Some target machines and hosts have several ports. Make sure you connect the cable to the correct port.

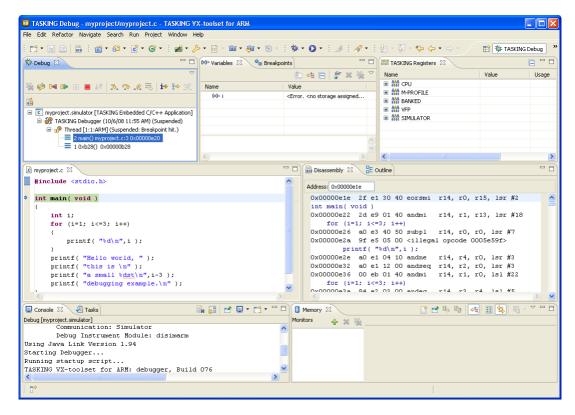
11.4. TASKING Debug Perspective

After you have launched the debugger, you are either asked if the TASKING Debug perspective should be opened or it is opened automatically. The Debug perspective consists of several views.

To open views in the Debug perspective:

- 1. Make sure the Debug perspective is opened
- 2. From the Window menu, select Show View »
- 3. Select a view from the menu or choose Other... for more views.

By default, the Debug perspective is opened with the following views:



11.4.1. Debug View

The Debug view shows the target information in a tree hierarchy shown below with a sample of the possible icons:

Icon	Session item	Description
C	Launch instance	Launch configuration name and launch type
69	Debugger instance	Debugger name and state
n9 🌬 🚳	Thread instance	Thread number and state
≡⊭	Stack frame instance	Stack frame number, function, file name, and file line number

The number beside the thread label is a reference counter, not a thread identification number (TID).

Stack display

During debugging (running) the actual stack is displayed as it increases or decreases during program execution. By default, all views present information that is related to the current stack item (variables, memory, source code etc.). To obtain the information from other stack items, click on the item you want.

The Debug view displays stack frames as child elements. It displays the reason for the suspension beside the thread, (such as end of stepping range, breakpoint hit, and signal received). When a program exits, the exit code is displayed.

The Debug view contains numerous functions for controlling the individual stepping of your programs and controlling the debug session. You can perform actions such as terminating the session and stopping the program. All functions are available from the right-click menu, though commonly used functions are also available from the toolbar in the Debug view.

Controlling debug sessions

Icon	Action	Description
*	Remove all	Removes all terminated launches.
\$	Restart	Restarts the application. The target system is not reset.
•	Reset target system	Resets the target system and restarts the application.
•	Resume	Resumes the application after it was suspended (manually, breakpoint, signal).
00	Suspend	Suspends the application (pause). Use the Resume button to continue.
Q,	Relaunch	Right-click menu. Restarts the selected debug session when it was terminated. If the debug session is still running, a new debug session is launched.
™	Reload current application	Reloads the current application without restarting the debug session. The application does restart of course.
	Terminate	Ends the selected debug session and/or process. Use Relaunch to restart this debug session, or start another debug session.
l _e	Terminate all	Right-click menu. As terminate. Ends all debug sessions.
	Terminate and remove	Right-click menu. Ends the debug session and removes it from the Debug view.
	Terminate and Relaunch	Right-click menu. Ends the debug session and relaunches it. This is the same as choosing Terminate end then Relaunch.
14	Disconnect	Detaches the debugger from the selected process (useful for debugging attached processes)

Stepping through the application

Icon	Action	Description
3	Step into	Steps to the next source line or instruction
⊕	Step over	Steps over a called function. The function is executed and the application suspends at the next instruction after the call.
_€	Step return	Executes the current function. The application suspends at the next instruction after the return of the function.

Icon	Action	Description
i⇒	Instruction stepping	Toggle. If enabled, the stepping functions are performed on instruction level instead of on C source line level.
8⇔	Interrupt aware stepping	Toggle. If enabled, the stepping functions do not step into an interrupt when it occurs.

Miscellaneous

Icon	Action	Description
	Copy Stack	Right-click menu. Copies the stack as text to the windows clipboard. You can paste the copied selection as text in, for example, a text editor.
С	Edit <i>project</i>	Right-click menu. Opens the debug configuration dialog to let you edit the current debug configuration.
E-	Edit Source Lookup	Right-click menu. Opens the Edit Source Lookup Path window to let you edit the search path for locating source files.

11.4.2. Breakpoints View

You can add, disable and remove breakpoints by clicking in the marker bar (left margin) of the Editor view. This is explained in the Getting Started manual.

Description

Types of breakpoints

To access the breakpoints dialog, add a breakpoint as follows:

1. Click the Add TASKING Breakpoint button (button (button (button (button) .

The Breakpoints dialog appears.

Each tab lets you set a breakpoint of a special type. You can set the following types of breakpoints:

File breakpoint

The target halts when it reaches the specified line of the specified source file. Note that it is possible that a source line corresponds to multiple addresses, for example when a header file has been included into two different source files or when inlining has occurred. If so, the breakpoint will be associated with all those addresses.

Function

The target halts when it reaches the first line of the specified function. If no source file has been specified and there are multiple functions with the given name, the target halts on all of those. Note that function breakpoints generally will not work on inlined instances of a function.

Address

The target halts when it reaches the specified instruction address.

Stack

The target halts when it reaches the specified stack level.

Data

The target halts when the given variable is read or written to, as specified.

Instruction

The target halts when the given number of instructions has been executed.

Cycle

The target halts when the given number of clock cycles has elapsed.

Timer

The target halts when the given amount of time elapsed.

In addition to the type of the breakpoint, you can specify the condition that must be met to halt the program.

In the **Condition** field, type a condition. The condition is an expression which evaluates to 'true' (non-zero) or 'false' (zero). The program only halts on the breakpoint if the condition evaluates to 'true'.

In the **Ignore count** field, you can specify the number of times the breakpoint is ignored before the program halts. For example, if you want the program to halt only in the fifth iteration of a while-loop, type '4': the first four iterations are ignored.

11.4.3. File System Simulation (FSS) View

Description

The File System Simulation (FSS) view is automatically opened when the target requests FSS input or generates FSS output. The virtual terminal that the FSS view represents, follows the VT100 standard. If you right-click in the view area of the FSS view, a menu is presented which gives access to some self-explanatory functions.

VT100 characteristics

The queens example demonstrates some of the VT100 features. (You can find the queens example in the <ARM installation path>\examples directory from where you can import it into your workspace.) Per debugging session, you can have more than one FSS view, each of which is associated with a positive integer. By default, the view "FSS #1" is associated with the standard streams stdin, stdout, stderr and stdaux. Other views can be accessed by opening a file named "terminal window <number>", as shown in the example below.

```
FILE * f3 = fopen("terminal window 3", "rw");
fprintf(f3, "Hello, window 3.\n");
fclose(f3);
```

You can set the initial working directory of the target application in the Debug configuration dialog (see also Section 11.2, Creating a Customized Debug Configuration):

- 1. On the **Debugger** tab, select the **Miscellaneous** sub-tab.
- 2. In the **FSS root directory** field, specify the FSS root directory.

The FSS implementation is designed to work without user intervention. Nevertheless, there are some aspects that you need to be aware of.

First, the interaction between the C library code (in the files dbg*.c and dbg*.h; see Section 13.1.5, dbg.h) and the debugger takes place via a breakpoint, which incidentally is not shown in the Breakpoints view. Depending on the situation this may be a hardware breakpoint, which may be in short supply.

Secondly, proper operation requires certain code in the C library to have debug information. This debug information should normally be present but might get lost when this information is stripped later in the development process.

11.4.4. Disassembly View

The Disassembly view shows target memory disassembled into instructions and / or data. If possible, the associated C / C++ source code is shown as well. The **Address** field shows the address of the current selected line of code.

To view the contents of a specific memory location, type the address in the **Address** field. If the address is invalid, the field turns red.

11.4.5. Expressions View

The Expressions view allows you to evaluate and watch regular C expressions.

To add an expression:

Click **OK** to add the expression.

1. Right-click in the Expressions View and select **Add Watch Expression**.

The Add Watch Expression dialog appears.

2. Enter an expression you want to watch during debugging, for example, the variable name "i"

If you have added one or more expressions to watch, the right-click menu provides options to **Remove** and **Edit** or **Enable** and **Disable** added expressions.

- You can access target registers directly using #NAME. For example "arr[#R0 << 3]" or "#TIMER3 = m++". If a register is memory-mapped, you can also take its address, for example, "&#ADCIN".
- Expressions may contain target function calls like for example "g1 + invert(&g2)". Be aware that this will not work if the compiler has optimized the code in such a way that the original function code

does not actually exist anymore. This may be the case, for example, as a result of inlining. Also, be aware that the function and its callees use the same stack(s) as your application, which may cause problems if there is too little stack space. Finally, any breakpoints present affect the invoked code in the normal way.

11.4.6. Memory View

Use the Memory view to inspect and change process memory. The Memory view supports the same addressing as the C and C++ languages. You can address memory using expressions such as:

- 0x0847d3c
- (&y) + 1024
- *ptr

Monitors

To monitor process memory, you need to add a *monitor*.

- In the Debug view, select a debug session. Selecting a thread or stack frame automatically selects the associated session.
- 2. Click the **Add Memory Monitor** button in the Memory Monitors pane.

The Monitor Memory dialog appears.

3. Type the address or expression that specifies the memory section you want to monitor and click **OK**.

The monitor appears in the monitor list and the Memory Renderings pane displays the contents of memory locations beginning at the specified address.

To remove a monitor:

- In the Monitors pane, right-click on a monitor.
- From the popup menu, select Remove Memory Monitor.

Renderings

You can inspect the memory in so-called *renderings*. A rendering specifies how the output is displayed: hexadecimal, ASCII, signed integer or unsigned integer. You can add or remove renderings per monitor. Though you cannot change a rendering, you can add or remove them:

Click the Add Rendering button in the Memory Renderings pane.

The Add Memory Rendering dialog appears.

Select the rendering you want (Hex, ASCII, Signed Integer or Unsigned Integer) and click OK.

To remove a rendering:

1. Right-click on a memory address in the rendering.

2. From the popup menu, select Remove Rendering.

Changing memory contents

In a rendering you can change the memory contents. Simply type a new value.

Warning: Changing process memory can cause a program to crash.

The right-click popup menu gives some more options for changing the memory contents or to change the layout of the memory representation.

11.4.7. Compare Application View

You can use the Compare Application view to check if the downloaded application matches the application in memory. Differences may occur, for example, if you changed memory addresses in the Memory view.

• To check for differences, click the Compare button.

11.4.8. Heap View

With the Heap view you can inspect the status of the heap memory. This can be illustrated with the following example:

```
string = (char *) malloc(100);
strcpy ( string, "abcdefgh" );
free (string);
```

If you step through these lines during debugging, the Heap view shows the situation after each line has been executed. Before any of these lines has been executed, there is no memory allocated and the Heap view is empty.

- After the first line the Heap view shows that memory is occupied, the description tells where the block starts, how large it is (100 MAUs) and what its content is (0x0, 0x0, ...).
- After the second line, "abcdefgh" has been copied to the allocated block of memory. The description field of the Heap view again shows the actual contents of the memory block (0x61, 0x62,...).
- The third line frees the memory. The Heap view is empty again because after this line no memory is allocated anymore.

11.4.9. Logging View

Use the Logging view to control the generation of internal log files. This view is intended mainly for use by or at the request of Altium support personnel.

11.4.10. RTOS View

The debugger has special support for debugging real-time operating systems (RTOSs). This support is implemented in an RTOS-specific shared library called a *kernel support module* (KSM) or *RTOS-aware debugging module* (RADM). Specifically, the TASKING VX-toolset for ARM ships with a KSM supporting

the OSEK standard. You have to create your own OSEK Run Time Interface (ORTI) and specify this file on the **Miscellaneous** sub tab while configuring a customized debug configuration (see also Section 11.2, Creating a Customized Debug Configuration):

1. From the Run menu, select Debug Configurations...

The Debug Configurations dialog appears.

2. In the left pane, select the configuration you want to change, for example, **TASKING Embedded C/C++ Application** » **myproject.simulator**.

Or: click the **New launch configuration** button () to add a new configuration.

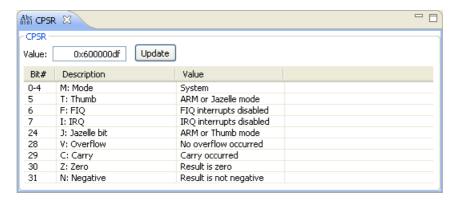
- 3. On the **Debugger** tab, select the **Miscellaneous** tab
- 4. In the **ORTI file** field, specify the name of your own ORTI file.

The debugger supports ORTI specifications v2.0 and v2.1.

11.4.11. TASKING Registers View

When first opened, the TASKING Registers view shows a number of *register groups*, which together contain all known registers. You can expand each group to see which registers they contain and examine the register's values while stepping through your application. This view has a number of features:

- While you step through the application, the registers involved in the step turn yellow.
- You can change each register's value.
- You can copy registers and/or groups to the windows clipboard: select the groups and/or individual
 registers, right-click on a register(group) and from the popup menu choose Copy Registers. You can
 paste the copied selection as text in, for example, a text editor.
- You can change the way the register value is displayed: right-click on a register(group) and from the popup menu choose the desired display mode (Natural, Hexadecimal, Decimal, Binary, Octal)
- For registers that are depicted with the icon 🔐, the menu entry **Symbolic Representation** is available in their right-click popup menu. This opens a new view which shows the internal fields of the register. (Alternatively, you can double-click on a register). For example, the CPSR register from the CPU group may be shown as follows:



In this view you can set the individual values in the register, either by selecting a value from a drop-down box or by simply entering a value depending on the chosen field. To update the register with the new values, click the **Update** button.

You can fully organize the register groups as you like: right-click on a register and from the popup menu
use the menu items Add Register Group..., Edit Register Group... or Remove Register Group. This
way you not only can choose which groups should be visible in the Register view, you can also create
your own groups to which you add the registers of your interest.

To restore the original groups: right-click on a register and from the popup menu choose **Restore Register Groups**. Be aware: groups you have created will be removed, groups you have edited are restored to their original and groups you have deleted are placed back!

Viewing a register group in a separate view

For a better overview, you can open a register group in a separate view. To do so, double-click on the register group name. A new Register view is opened, showing all registers from the group. You can consider this view as a sub view of the Register view with roughly the same features.

11.4.12. Trace View

If tracing is enabled, the Trace view shows the code was most recently executed. For example, while you step through the application, the Trace view shows the executed code of each step. To enable tracing:

From the Run menu, select Trace.

A check mark appears when tracing is enabled.

The view has three tabs, Source, Instruction and Raw, each of which represents the trace in a different way. However, not all target environments will support all three of these. The view is updated automatically each time the target halts.

11.5. Programming a Flash Device

With the TASKING debugger you can download an application file to flash memory. Before you download the file, you must specify the type of flash devices you use in your system and the address range(s) used by these devices.

To program a flash device the debugger needs to download a flash programming monitor to the target to execute the flash programming algorithm (target-target communication). This method uses temporary target memory to store the flash programming monitor and you have to specify a temporary data workspace for interaction between the debugger and the flash programming monitor.

Two types of flash devices can exist: on-chip flash devices and external flash devices.

Setup an on-chip flash device

When you specify a target configuration board using the Target Board Configuration wizard (Project Target Board Configuration), as explained in the *Getting Started with the TASKING VX-toolset for ARM* manual, any on-chip flash devices are setup automatically.

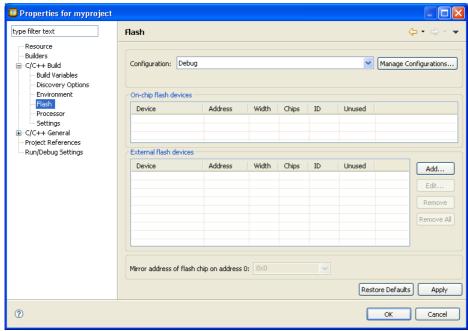
Setup an external flash device

From the Project menu, select Properties

The Properties for project dialog appears.

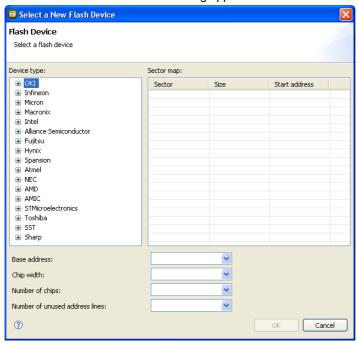
2. In the left pane, expand C/C++ Build and select Flash.

The Flash pane appears.



3. Click Add... to specify an external flash device.

The Select a New Flash Device dialog appears.



4. In the **Device type** box, expand the name of the manufacturer of the device and select a device.

The Sector map displays the memory layout of the flash device(s). Each sector has a size and

- 5. In the **Base address** field enter the start address of the memory range that will be covered by the flash device.
- 6. In the **Chip width** field select the width of the flash device.
- 7. In the **Number of chips** field, enter the number of flash devices that are located in parallel. For example, if you have two 8-bit devices in parallel attached to a 16-bit data bus, enter 2.
- Fill in the Number of unused address lines field, if necessary.

The flash memory is added to the linker script file automatically with the tag "flash=flash-id".

To program a flash device

1. From the Run menu, select Debug Configurations...

The Debug Configurations dialog appears.

2. In the left pane, select the configuration you want to change, for example, **TASKING Embedded C/C++ Application** » **myproject.board**.

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- 3. On the **Debugger** tab, select the **Initialization** tab
- 4. Enable the option Program flash when downloading.

The Flash settings group box becomes active.

- 5. In the **Monitor file** field, specify the filename of the flash programming monitor, usually an Intel Hex or S-Record file.
- 6. In the **Sector buffer size** field, specify the buffer size for buffering a flash sector.
- 7. Specify the data **Workspace address** used by the flash programming monitor. This address may not conflict with the addresses of the flash devices.
- 8. Click **Debug** to program the flash device and start debugging.

Chapter 12. Tool Options

This chapter provides a detailed description of the options for the compiler, assembler, linker, control program, make utility and the archiver.

Tool options in Eclipse (Menu entry)

For each tool option that you can set from within Eclipse, a **Menu entry** description is available. In Eclipse you can customize the tools and tool options in the following dialog:

1. From the Project menu, select Properties

The Properties dialog appears.

In the left pane, expand C/C++ Build and select Settings.

In the right pane the Settings appear.

3. Open the **Tool Settings** tab.

You can set all tool options here.

Unless stated otherwise, all **Menu entry** descriptions expect that you have this Tool Settings tab open.

12.1. C Compiler Options

This section lists all C compiler options.

Options in Eclipse versus options on the command line

Most command line options have an equivalent option in Eclipse but some options are only available on the command line. Eclipse invokes the compiler via the control program. Therefore, it uses the syntax of the control program to pass options and files to the C compiler. If there is no equivalent option in Eclipse, you can specify a command line option in Eclipse as follows:

1. From the **Project** menu, select **Properties**

The Properties dialog appears.

2. In the left pane, expand C/C++ Build and select Settings.

In the right pane the Settings appear.

- 3. On the Tool Settings tab, select C/C++ Compiler » Miscellaneous.
- 4. In the **Additional options** field, enter one or more command line options.

Because Eclipse uses the control program, you have to precede the option with **-Wc** to pass the option via the control program directly to the C compiler.

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Be aware that some command line options are not useful in Eclipse or just do not have any effect. For example, the option -n sends output to stdout instead of a file and has no effect in Eclipse.

Short and long option names

Options can have both short and long names. Short option names always begin with a single minus (-) character, long option names always begin with two minus (--) characters. You can abbreviate long option names as long as it forms a unique name. You can mix short and long option names on the command line.

Options can have flags or suboptions. To switch a flag 'on', use a lowercase letter or a +longflag. To switch a flag off, use an uppercase letter or a -longflag. Separate longflags with commas. The following two invocations are equivalent:

```
carm -Oac test.c
carm --optimize=+coalesce,+cse test.c
```

When you do not specify an option, a default value may become active.

C compiler option: --align-composites

Menu entry

- 1. Select C/C++ Compiler » Code Generation.
- 2. Select the Alignment for composite types: Natural alignment or Optimal alignment.

Command line syntax

```
--align-composites=alignment
```

You can specify the following alignments:

n Natural alignment (default)

Optimal alignment

Description

With this option you can set the alignment for composite types (structs, unions and arrays).

Natural alignment (n) uses the natural alignment of the most-aligned member of the composite type.

Optimal alignment (o) sets the alignment to 8, 16, or 32 bits depending on the size of the composite type.

Related information

C compiler option: --call (-m)

Menu entry

- Select C/C++ Compiler » Code Generation.
- 2. Set the option Select call mode to Use PC-relative calls (default) or to Use 32-bit indirect calls.

Command line syntax

```
\label{eq:call} \begin{split} &--\text{call=}\{\text{far}\,|\,\text{near}\}\\ &-\text{m}\{\text{f}\,|\,\text{n}\} \end{split}
```

Description

To address the memory of the ARM, you can use two different call modes:

far 32-bit indirect calls. Though you can address the full range of memory, the

address is first loaded into a register after which the call is executed.

near 26-bit PC-relative call. The PC-relative call is directly coded into the B instruction.

This way of calling results in higher execution speed. However, not the full range

of memory can be addressed with near calls.

If you compile your C source with near calls but the called address cannot be reached with a near call, the *linker* will generate an error.

It is recommended to use the near addressing mode unless your application needs calls to addresses that fall outside a 256 MB region.

Related information

_

C compiler option: --check

Menu entry

-

Command line syntax

--check

Description

With this option you can check the source code for syntax errors, without generating code. This saves time in developing your application because the code will not actually be compiled.

The compiler reports any warnings and/or errors.

This option is available on the command line only.

Related information

Assembler option --check (Check syntax)

C compiler option: --cpu (-C)

Menu entry

- 1. Expand C/C++ Build and select Processor.
- 2. From the Processor Selection list, make a selection by Architecture, Core or Manufacturer.

Command line syntax

```
--cpu=architecture
```

-Carchitecture

You can specify the following architectures:

ARMv4 Compile for ARMv4 architecture
ARMv4T Compile for ARMv4T architecture
ARMv5T Compile for ARMv5T architecture
ARMv5TE Compile for ARMv5TE architecture

ARMv6M Compile for ARMv6-M architecture profile
ARMv7M Compile for ARMv7-M architecture profile

XS Compile for XScale core

Description

With this option you specify the ARM architecture for which you create your application. The ARM target supports more than one architecture and therefore you need to specify for which architecture the compiler should compile. The architecture determines which instructions are valid and which are not.

The effect of this option is that the compiler uses the appropriate instruction set. You choose one of the following architectures: ARMv4, ARMv4T, ARMv5T, ARMv5TE, ARMv6-M, ARMv7-M or XScale.

When you call the compiler from the command line, make sure you specify the same core type to the assembler to avoid conflicts!

Example

To compile the file test.c for the ARMv4 processor type, enter the following on the command line:

```
carm --cpu=ARMv4 test.c
```

The compiler compiles for the chosen processor type.

Related information

Assembler option --cpu (Select architecture)

C compiler option: --debug-info (-g)

Menu entry

- 1. Select C/C++ Compiler » Debugging.
- To generate symbolic debug information, select Default, Call-frame only or Full.
 To disable the generation of debug information, select None.

Command line syntax

```
--debug-info[=suboption]
-g[suboption]
```

You can set the following suboptions:

small	1 / c	Emit small set of debug information.
default	2 / d	Emit default symbolic debug information.
all	3 / a	Emit full symbolic debug information.

Default: --debug-info (same as --debug-info=default)

Description

With this option you tell the compiler to add directives to the output file for including symbolic information. This facilitates high level debugging but increases the size of the resulting assembler file (and thus the size of the object file). For the final application, compile your C files without debug information.

Small set of debug information

With this suboption only DWARF call frame information and type information are generated. This enables you to inspect parameters of nested functions. The type information improves debugging. You can perform a stack trace, but stepping is not possible because debug information on function bodies is not generated. You can use this suboption, for example, to compact libraries.

Default debug information

This provides all debug information you need to debug your application. It meets the debugging requirements in most cases without resulting in oversized assembler/object files.

Full debug information

With this information extra debug information is generated. In extraordinary cases you may use this debug information (for instance, if you use your own debugger which makes use of this information). With this suboption, the resulting assembler/object file increases significantly.

Related information

C compiler option: --define (-D)

Menu entry

1. Select C/C++ Compiler » Preprocessing.

The Defined symbols box shows the symbols that are currently defined.

- 2. To define a new symbol, click on the **Add** button in the **Defined symbols** box.
- 3. Type the symbol definition (for example, demo=1)

Use the Edit and Delete button to change a macro definition or to remove a macro from the list.

Command line syntax

```
--define=macro_name[=macro_definition]
-Dmacro_name[=macro_definition]
```

Description

With this option you can define a macro and specify it to the preprocessor. If you only specify a macro name (no macro definition), the macro expands as '1'.

You can specify as many macros as you like. Simply use the **Add** button to add new macro definitions.

On the command line, use the option **--define** (**-D**) multiple times. If the command line exceeds the limit of the operating system, you can define the macros in an option file which you then must specify to the compiler with the option **--option-file** (**-f**) *file*.

Defining macros with this option (instead of in the C source) is, for example, useful to compile conditional C source as shown in the example below.

Example

Consider the following C program with conditional code to compile a demo program and a real program:

```
void main( void )
{
#if DEMO
    demo_func();    /* compile for the demo program */
#else
    real_func();    /* compile for the real program */
#endif
}
```

You can now use a macro definition to set the DEMO flag:

```
carm --define=DEMO test.c
carm --define=DEMO=1 test.c
```

Note that both invocations have the same effect.

The next example shows how to define a macro with arguments. Note that the macro name and definition are placed between double quotes because otherwise the spaces would indicate a new option.

```
carm --define="MAX(A,B)=((A) > (B) ? (A) : (B))" test.c
```

Related information

C compiler option --undefine (Remove preprocessor macro)

C compiler option --option-file (Specify an option file)

C compiler option: --dep-file

Menu entry

-

Command line syntax

```
--dep-file[=file]
```

Description

With this option you tell the compiler to generate dependency lines that can be used in a Makefile. In contrast to the option --preprocess=+make, the dependency information will be generated in addition to the normal output file.

By default, the information is written to a file with extension .d (one for every input file). When you specify a filename, all dependencies will be combined in the specified file.

Example

```
carm --dep-file=test.dep test.c
```

The compiler compiles the file test.c, which results in the output file test.src, and generates dependency lines in the file test.dep.

Related information

C compiler option --preprocess=+make (Generate dependencies for make)

C compiler option: --diag

Menu entry

1. From the Window menu, select Show View » Other » Basic » Problems.

The Problems view is added to the current perspective.

2. In the Problems view right-click on a message.

A popup menu appears.

3. Select Detailed Diagnostics Info.

A dialog box appears with additional information.

Command line syntax

```
--diag=[format:]{all | nr,...}
```

You can set the following output formats:

html HTML output.

rtf Rich Text Format.

text ASCII text.

Default format: text

Description

With this option you can ask for an extended description of error messages in the format you choose. The output is directed to stdout (normally your screen) and in the format you specify. You can specify the following formats: **html**, **rtf** or **text** (default). To create a file with the descriptions, you must redirect the output.

With the suboption **all**, the descriptions of all error messages are given. If you want the description of one or more selected error messages, you can specify the error message numbers, separated by commas.

Example

To display an explanation of message number 282, enter:

```
carm --diag=282
```

This results in the following message and explanation:

```
E282: unterminated comment
```

Make sure that every comment starting with /* has a matching */. Nested comments are not possible.

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To write an explanation of all errors and warnings in HTML format to file cerrors.html, use redirection and enter:

carm --diag=html:all > cerrors.html

Related information

Section 4.7, C Compiler Error Messages

C compiler option: --endianness

Menu entry

- 1. Select Global Options.
- 2. Specify the Endianness:Little-endian mode or Big-endian mode.

Command line syntax

--endianness=endianness

-B

--big-endian

You can specify the following endianness:

big b Big endian

little I Little endian (default)

Description

By default, the compiler generates code for a little-endian target (least significant byte of a word at lowest byte address). With **--endianness=big** the compiler generates code for a big-endian target (most significant byte of a word at lowest byte address). **-B** is an alias for option **--endianness=big**.

Related information

_

C compiler option: --error-file

Menu entry

-

Command line syntax

```
--error-file[=file]
```

Description

With this option the compiler redirects error messages to a file. If you do not specify a filename, the error file will be named after the input file with extension .err.

Example

To write errors to errors.err instead of stderr, enter:

```
carm --error-file=errors.err test.c
```

Related information

C compiler option: --fpu

Menu entry

- 1. Select C/C++ Compiler » Language.
- 2. Select an option from the Floating-point unit (FPU) support field.

Command line syntax

```
--fpu=fpu
```

You can specify the following arguments:

VFPv2 Compile for VFPv2 architecture
VFPv3 Compile for VFPv2 architecture

none Compile for software FPU library (default)

Description

With this option you define the kind of FPU support with which you create your application.

Related information

C compiler option: --global-type-checking

Menu entry

- 1. Select C/C++ Compiler » Diagnostics.
- 2. Enable the option Perform global type checking on C code.

Command line syntax

--global-type-checking

Description

The C compiler already performs type checking within each module. Use this option when you want the linker to perform type checking between modules.

Related information

C compiler option: --help (-?)

Menu entry

_

-?

Command line syntax

```
--help[=item]
```

You can specify the following arguments:

intrinsics	i	Show the list of intrinsic functions
options	0	Show extended option descriptions
pragmas	p	Show the list of supported pragmas
typedefs	t	Show the list of predefined typedefs

Description

Displays an overview of all command line options. With an argument you can specify which extended information is shown.

Example

The following invocations all display a list of the available command line options:

```
carm -?
carm --help
carm
```

The following invocation displays a list of the available pragmas:

```
carm --help=pragmas
```

Related information

C compiler option: --include-directory (-I)

Menu entry

Select C/C++ Compiler » Include Paths.

The Include paths box shows the directories that are added to the search path for include files.

- 2. To define a new directory for the search path, click on the **Add** button in the **Include paths** box.
- 3. Type or select a path.

Use the Edit and Delete button to change a path or to remove a path from the list.

Command line syntax

```
--include-directory=path,...
-Ipath,...
```

Description

With this option you can specify the path where your include files are located. A relative path will be relative to the current directory,

The order in which the compiler searches for include files is:

- 1. The pathname in the C source file and the directory of the C source (only for #include files that are enclosed in "")
- 2. The path that is specified with this option.
- 3. The path that is specified in the environment variable CARMINC when the product was installed.
- 4. The default directory \$(PRODDIR)\include (unless you specified option --no-stdinc).

Example

Suppose that the C source file test.c contains the following lines:

```
#include <stdio.h>
#include "myinc.h"
```

You can call the compiler as follows:

```
carm --include-directory=myinclude test.c
```

First the compiler looks for the file stdio.h in the directory myinclude relative to the current directory. If it was not found, the compiler searches in the environment variable and then in the default include directory.

The compiler now looks for the file myinc.h in the directory where test.c is located. If the file is not there the compiler searches in the directory myinclude. If it was still not found, the compiler searches in the environment variable and then in the default include directory.

Related information

C compiler option --include-file (Include file at the start of a compilation)

C compiler option --no-stdinc (Skip standard include files directory)

C compiler option: --include-file (-H)

Menu entry

Select C/C++ Compiler » Preprocessing.

The Pre-include files box shows the files that are currently included before the compilation starts.

- 2. To define a new file, click on the **Add** button in the **Pre-include files** box.
- 3. Type the full path and file name or select a file.
- 4. (Optional) Enable the option Include default register definition header file before source.

Use the **Edit** and **Delete** button to change a file name or to remove a file from the list.

Command line syntax

```
--include-file=file,...
-Hfile,...
```

Description

With this option you include one or more extra files at the beginning of each C source file, before other includes. This is the same as specifying #include "file" at the beginning of each of your C sources.

Example

```
carm --include-file=stdio.h test1.c test2.c
```

The file stdio.h is included at the beginning of both test1.c and test2.c.

Related information

C compiler option --include-directory (Add directory to include file search path)

C compiler option: --inline

Menu entry

- 1. Select C/C++ Compiler » Optimization.
- 2. Enable the option Always inline function calls.

Command line syntax

--inline

Description

With this option you instruct the compiler to inline calls to functions without the __noinline function qualifier whenever possible. This option has the same effect as a #pragma inline at the start of the source file.

Related information

Section 1.8.2, Inlining Functions: inline

C compiler option: --inline-max-incr / --inline-max-size

Menu entry

- 1. Select C/C++ Compiler » Optimization.
- 2. In the **Maximum size increment when inlining** field, enter a value (default 25).
- 3. In the Maximum size for functions to always inline field, enter a value (default 25).

Command line syntax

```
--inline-max-incr=percentage (default: 25)
--inline-max-size=threshold (default: 25)
```

Description

With these options you can control the automatic function inlining optimization process of the compiler. These options have only effect when you have enabled the inlining optimization (option --optimize=+inline or Optimize most).

Regardless of the optimization process, the compiler always inlines all functions that have the function qualifier inline.

With the option **--inline-max-size** you can specify the maximum size of functions that the compiler inlines as part of the optimization process. The compiler always inlines all functions that are smaller than the specified *threshold*. The threshold is measured in compiler internal units and the compiler uses this measure to decide which functions are small enough to inline. The default threshold is 25.

After the compiler has inlined all functions that have the function qualifier inline and all functions that are smaller than the specified threshold, the compiler looks whether it can inline more functions without increasing the code size too much. With the option --inline-max-incr you can specify how much the code size is allowed to increase. By default, this is 25% which means that the compiler continues inlining functions until the resulting code size is 25% larger than the original size.

Example

```
carm --inline-max-incr=40 --inline-max-size=15 test.c
```

The compiler first inlines all functions with the function qualifier inline and all functions that are smaller than the specified threshold of 15. If the code size has still not increased with 40%, the compiler decides which other functions it can inline.

Related information

C compiler option --optimize=+inline (Optimization: automatic function inlining)

Section 1.8.2, Inlining Functions: inline

C compiler option: --interwork

Menu entry

- 1. Select C/C++ Compiler » Code Generation.
- 2. Enable the option Compile for ARM/Thumb interworking.

Command line syntax

--interwork

Description

With this option the compiler generates code which supports calls between functions with the ARM and Thumb instruction set.

Use this option if your program consists of both ARM and Thumb functions.

By default this option is disabled, since it produces slightly larger code.

Related information

C compiler option --thumb (Use Thumb instruction set)

C compiler option: --iso (-c)

Menu entry

- Select C/C++ Compiler » Language.
- From the Comply to C standard list, select ISO C99 or ISO C90.

Command line syntax

```
--iso={90|99}
-c{90|99}
Default: --iso=99
```

Description

With this option you select the ISO C standard. C90 is also referred to as the "ANSI C standard". C99 refers to the newer ISO/IEC 9899:1999 (E) standard. C99 is the default.

Example

To select the ISO C90 standard on the command line:

```
carm --iso=90 test.c
```

Related information

C compiler option --language (Language extensions)

C compiler option: --keep-output-files (-k)

Menu entry

Eclipse always removes the .src file when errors occur during compilation.

Command line syntax

```
--keep-output-files
```

-k

Description

If an error occurs during compilation, the resulting .src file may be incomplete or incorrect. With this option you keep the generated output file (.src) when an error occurs.

By default the compiler removes the generated output file (.src) when an error occurs. This is useful when you use the make utility. If the erroneous files are not removed, the make utility may process corrupt files on a subsequent invocation.

Use this option when you still want to inspect the generated assembly source. Even if it is incomplete or incorrect.

Example

```
carm --keep-output-files test.c
```

When an error occurs during compilation, the generated output file test.src will not be removed.

Related information

C compiler option --warnings-as-errors (Treat warnings as errors)

C compiler option: --language (-A)

Menu entry

- Select C/C++ Compiler » Language.
- 2. Enable or disable one or more of the following options:
 - · Allow GNU C extensions
 - Allow // comments in ISO C90 mode
 - · Check assignment of string literal to non-const string pointer

Command line syntax

```
--language=[flags]
-A[flags]
```

You can set the following flags:

+/-gcc	g/G	enable a number of gcc extensions
+/-comments	p/P	// comments in ISO C90 mode
+/-strings	x/X	relaxed const check for string literals

Default: -AGpx

Default (without flags): -AGPX

Description

With this option you control the language extensions the compiler can accept. By default the ARM compiler allows all language extensions, except for **gcc** extensions.

The option --language (-A) without flags disables all language extensions.

GNU C extensions

The --language=+gcc (-Ag) option enables the following gcc language extensions:

- The identifier __FUNCTION__ expands to the current function name.
- Alternative syntax for variadic macros.
- · Alternative syntax for designated initializers.
- · Allow zero sized arrays.
- Allow empty struct/union.

- · Allow empty initializer list.
- Allow initialization of static objects by compound literals.
- The middle operand of a ? : operator may be omitted.
- Allow a compound statement inside braces as expression.
- Allow arithmetic on void pointers and function pointers.
- Allow a range of values after a single case label.
- Additional preprocessor directive #warning.
- Allow comma operator, conditional operator and cast as Ivalue.
- An inline function without "static" or "extern" will be global.
- An "extern inline" function will not be compiled on its own.
- An __attribute__ directly following a struct/union definition relates to that tag instead of to the
 objects in the declaration.

For a more complete description of these extensions, you can refer to the UNIX gcc info pages (**info gcc**).

Comments in ISO C90 mode

With --language=+comments (-Ap) you tell the compiler to allow C++ style comments (//) in ISO C90 mode (option --iso=90). In ISO C99 mode this style of comments is always accepted.

Check assignment of string literal to non-const string pointer

With --language=+strings (-Ax) you disable warnings about discarded const qualifiers when a string literal is assigned to a non-const pointer.

```
char *p;
void main( void ) { p = "hello"; }
```

Example

```
carm --language=-comments,+strings --iso=90 test.c
carm -APx -c90 test.c
```

The compiler compiles in ISO C90 mode, accepts assignments of a constant string to a non-constant string pointer and does not allow C++ style comments.

Related information

C compiler option --iso (ISO C standard)

C compiler option: --make-target

Menu entry

_

Command line syntax

--make-target=name

Description

With this option you can overrule the default target name in the make dependencies generated by the options --preprocess=+make (-Em) and --dep-file. The default target name is the basename of the input file, with extension .obj.

Example

```
carm --preprocess=+make --make-target=mytarget.obj test.c
```

The compiler generates dependency lines with the default target name mytarget.obj instead of test.obj.

Related information

C compiler option --preprocess=+make (Generate dependencies for make)

C compiler option --dep-file (Generate dependencies in a file)

C compiler option: --mil / --mil-split

Menu entry

-

Command line syntax

```
--mil
--mil-split[=file,...]
```

Description

With option --mil the C compiler skips the code generator phase and writes the optimized intermediate representation (MIL) to a file with the suffix .mil. The C compiler accepts .mil. files as input files on the command line.

Option --mil-split does the same as option --mil, but in addition, the C compiler splits the MIL representation and writes it to separate files with suffix .ms. One file is written for each input file or MIL library specified on the command line. The .ms files are only updated on a change. The C compiler accepts .ms files as input files on the command line.

With option --mil-split you can perform application-wide optimizations during the frontend phase by specifying all modules at once, and still invoke the backend phase one module at a time to reduce the total compilation time.

Optionally, you can specify another filename for the .ms file the C compiler generates. Without an argument, the basename of the C source file is used to create the .ms filename. Note that if you specify a filename, you have to specify one filename for every input file.

Related information

Section 4.1, Compilation Process

Control program option --mil-link / --mil-split

C compiler option: --misrac

Menu entry

- Select C/C++ Compiler » MISRA-C.
- 2. Make a selection from the MISRA-C checking list.
- If you selected Custom, expand the Custom 2004 or Custom 1998 entry and enable one or more individual rules.

Command line syntax

```
--misrac={all | nr[-nr]},...
```

Description

With this option you specify to the compiler which MISRA-C rules must be checked. With the option **--misrac=all** the compiler checks for all supported MISRA-C rules.

Example

```
carm --misrac=9-13 test.c
```

The compiler generates an error for each MISRA-C rule 9, 10, 11, 12 or 13 violation in file test.c.

Related information

Section 4.6, C Code Checking: MISRA-C

C compiler option --misrac-advisory-warnings

C compiler option --misrac-required-warnings

Linker option --misrac-report

C compiler option: --misrac-advisory-warnings / --misrac-required-warnings

Menu entry

- 1. Select C/C++ Compiler » MISRA-C.
- 2. Make a selection from the MISRA-C checking list.
- Enable one or both options Warnings instead of errors for required rules and Warnings instead of errors for advisory rules.

Command line syntax

- --misrac-advisory-warnings
- --misrac-required-warnings

Description

Normally, if an advisory rule or required rule is violated, the compiler generates an error. As a consequence, no output file is generated. With this option, the compiler generates a warning instead of an error.

Related information

Section 4.6, C Code Checking: MISRA-C

C compiler option --misrac

Linker option --misrac-report

C compiler option: --misrac-version

Menu entry

- 1. Select C/C++ Compiler » MISRA-C.
- 2. Select the MISRA-C version: 2004 or 1998.

Command line syntax

--misrac-version={1998|2004}

Default: 2004

Description

MISRA-C rules exist in two versions: MISRA-C:1998 and MISRA-C:2004. By default, the C source is checked against the MISRA-C:2004 rules. With this option you can specify to check against the MISRA-C:1998 rules.

Related information

Section 4.6, C Code Checking: MISRA-C

C compiler option --misrac

C compiler option: --no-double (-F)

Menu entry

- 1. Select C/C++ Compiler » Language.
- 2. Enable the option **Treat double as float**.

Command line syntax

```
--no-double
```

-F

Description

With this option you tell the compiler to treat variables of the type double as float. Because the float type takes less space, execution speed increases and code size decreases, both at the cost of less precision.

Example

```
carm --no-double test.c
```

The file test.c is compiled where variables of the type double are treated as float.

Related information

C compiler option: --no-stdinc

Menu entry

- 1. Select C/C++ Compiler » Miscellaneous.
- 2. Add the option **--no-stdinc** to the **Additional options** field.

Command line syntax

--no-stdinc

Description

With this option you tell the compiler not to look in the default include directory relative to the installation directory, when searching for include files. This way the compiler only searches in the include file search paths you specified.

Related information

C compiler option --include-directory (Add directory to include file search path)

Section 4.3, How the Compiler Searches Include Files

C compiler option: --no-warnings (-w)

Menu entry

1. Select C/C++ Compiler » Diagnostics.

The Suppress C compiler warnings box shows the warnings that are currently suppressed.

- 2. To suppress a warning, click on the **Add** button in the **Suppress warnings** box.
- 3. Enter the numbers, separated by commas, of the warnings you want to suppress (for example 537,538). Or you can use the **Add** button multiple times.
- 4. To suppress all warnings, enable the option **Suppress all warnings**.

Use the Edit and Delete button to change a warning number or to remove a number from the list.

Command line syntax

```
--no-warnings[=number,...]
-w[number,...]
```

Description

With this option you can suppresses all warning messages or specific warning messages.

On the command line this option works as follows:

- If you do not specify this option, all warnings are reported.
- If you specify this option but without numbers, all warnings are suppressed.
- If you specify this option with a number, only the specified warning is suppressed. You can specify the option --no-warnings=number multiple times.

Example

To suppress warnings 537 and 538, enter:

```
carm test.c --no-warnings=537,538
```

Related information

C compiler option --warnings-as-errors (Treat warnings as errors)

Pragma warning

C compiler option: --optimize (-O)

Menu entry

- 1. Select C/C++ Compiler » Optimization.
- 2. Select an optimization level in the **Optimization level** box.

Command line syntax

```
--optimize[=flags]
```

-Oflags

You can set the following flags:

+/-coalesce	a/A	Coalescer: remove unnecessary moves
+/-ipro	b/B	Interprocedural register optimizations
+/-cse	c/C	Common subexpression elimination
+/-expression	e/E	Expression simplification
+/-flow	f/F	Control flow simplification
+/-glo	g/G	Generic assembly code optimizations
+/-inline	i/l	Automatic function inlining
+/-schedule	k/K	Instruction scheduler
+/-loop	I/L	Loop transformations
+/-forward	o/O	Forward store
+/-propagate	p/P	Constant propagation
+/-subscript	s/S	Subscript strength reduction
+/-unroll	u/U	Unroll small loops
+/-pipeline	w/W	Software pipelining
+/-peephole	y/Y	Peephole optimizations

Use the following options for predefined sets of flags:

optimize=0	-00	No optimization
		Alias for -OABCEFGIKLOPSUWY

No optimizations are performed. The compiler tries to achieve an optimal resemblance between source code and produced code. Expressions are evaluated in the same order as written in the source code, associative and commutative properties are not used.

--optimize=1 -O1 Optimize
Alias for -OabcefglKLOPSUWy

Enables optimizations that do not affect the debug ability of the source code. Use this level when you encounter problems during debugging your source code with optimization level 2.

```
--optimize=2 -O2 Optimize more (default)
Alias for -OabcefglklopsUwy
```

Enables more optimizations to reduce code size and/or execution time. This is the default optimization level.

```
--optimize=3 -O3 Optimize most
Alias for -Oabcefgiklopsuwy
```

This is the highest optimization level. Use this level to decrease execution time to meet your real-time requirements.

```
Default: --optimize=2
```

Description

With this option you can control the level of optimization. If you do not use this option, the default optimization level is *Optimize more* (option **--optimize=2** or **--optimize**).

When you use this option to specify a set of optimizations, you can overrule these settings in your C source file with #pragma optimize flag/#pragma endoptimize.

In addition to the option **--optimize**, you can specify the option **--tradeoff** (-t). With this option you specify whether the used optimizations should optimize for more speed (regardless of code size) or for smaller code size (regardless of speed).

Example

The following invocations are equivalent and result all in the default optimization set:

Related information

C compiler option --tradeoff (Trade off between speed and size)

```
Pragma optimize/endoptimize
```

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Section 4.5, Compiler Optimizations

C compiler option: --option-file (-f)

Menu entry

- 1. Select C/C++ Compiler » Miscellaneous.
- 2. Add the option --option-file to the Additional options field.

Be aware that the options in the option file are added to the C compiler options you have set in the other pages. Only in extraordinary cases you may want to use them in combination.

Command line syntax

```
--option-file=file,...
-f file,...
```

Description

This option is primarily intended for command line use. Instead of typing all options on the command line, you can create an option file which contains all options and flags you want to specify. With this option you specify the option file to the compiler.

Use an option file when the command line would exceed the limits of the operating system, or just to store options and save typing.

You can specify the option --option-file multiple times.

Format of an option file

- Multiple arguments on one line in the option file are allowed.
- To include whitespace in an argument, surround the argument with single or double quotes.
- If you want to use single quotes as part of the argument, surround the argument by double quotes and vise versa:

```
"This has a single quote ' embedded"

'This has a double quote " embedded'

'This has a double quote " and a single quote '"' embedded"
```

When a text line reaches its length limit, use a \ to continue the line. Whitespace between quotes is
preserved.

```
"This is a continuation \ line" -> "This is a continuation line"
```

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• It is possible to nest command line files up to 25 levels.

Example

Suppose the file myoptions contains the following lines:

```
--debug-info
--define=DEMO=1
test.c
```

Specify the option file to the compiler:

```
carm --option-file=myoptions
```

This is equivalent to the following command line:

```
carm --debug-info --define=DEMO=1 test.c
```

Related information

C compiler option: --output (-o)

Menu entry

Eclipse names the output file always after the C source file.

Command line syntax

```
--output=file
-o file
```

Description

With this option you can specify another filename for the output file of the compiler. Without this option the basename of the C source file is used with extension .src.

Example

To create the file output.src instead of test.src, enter:

```
carm --output=output.src test.c
```

Related information

C compiler option: --preprocess (-E)

Menu entry

- Select C/C++ Compiler » Preprocessing.
- 2. Enable the option Store preprocessor output in <file>.pre.
- 3. (Optional) Enable the option Keep comments in preprocessor output.
- 4. (Optional) Enable the option **Keep #line info in preprocessor output**.

Command line syntax

```
--preprocess[=flags]
-E[flags]
```

You can set the following flags:

+/-comments c/C keep comments

+/-make m/M generate dependencies for make+/-noline p/P strip #line source position information

Default: -ECMP

Description

With this option you tell the compiler to preprocess the C source. Under Eclipse the compiler sends the preprocessed output to the file <code>name</code>. <code>pre</code> (where <code>name</code> is the name of the C source file to compile). Eclipse also compiles the C source.

On the command line, the compiler sends the preprocessed file to stdout. To capture the information in a file, specify an output file with the option **--output**.

With --preprocess=+comments you tell the preprocessor to keep the comments from the C source file in the preprocessed output.

With --preprocess=+make the compiler will generate dependency lines that can be used in a Makefile. The preprocessor output is discarded. The default target name is the basename of the input file, with the extension .obj. With the option --make-target you can specify a target name which overrules the default target name.

With **--preprocess=+noline** you tell the preprocessor to strip the #line source position information (lines starting with #line). These lines are normally processed by the assembler and not needed in the preprocessed output. When you leave these lines out, the output is easier to read.

Example

```
carm --preprocess=+comments,-make,-noline test.c --output=test.pre
```

The compiler preprocesses the file <code>test.c</code> and sends the output to the file <code>test.pre</code>. Comments are included but no dependencies are generated and the line source position information is not stripped from the output file.

Related information

C compiler option --dep-file (Generate dependencies in a file)

C compiler option --make-target (Specify target name for -Em output)

C compiler option: --profile (-p)

Menu entry

- Select C/C++ Compiler » Debugging.
- 2. Enable or disable Static profiling.
- Enable or disable one or more of the following Generate profiling information options (dynamic profiling):
 - for block counters (not in combination with Call graph or Function timers)
 - · to build a call graph
 - · for function counters
 - · for function timers

Note that the more detailed information you request, the larger the overhead in terms of execution time, code size and heap space needed. The option **--debug** does not affect profiling, execution time or code size.

Command line syntax

```
--profile[=flag,...]
-p[flags]
```

Use the following option for a predefined set of flags:

profile=g	-pg	Profiling with call graph and function timers.
		Alias for: -pBcFSt

You can set the following flags:

+/-block	b/B	block counters
+/-callgraph	c/C	call graph

+/-function f/F function counters

+/-static s/S static profile generation

+/-time t/T function timers

Default (without flags): -pBCfST

Description

Profiling is the process of collecting statistical data about a running application. With these data you can analyze which functions are called, how often they are called and what their execution time is.

Several methods of profiling exist. One method is *code instrumentation* which adds code to your application that takes care of the profiling process when the application is executed. Another method is *static profiling*.

For an extensive description of profiling refer to Chapter 6, *Profiling*.

You can obtain the following profiling data (see flags above):

Block counters (not in combination with Call graph or Function timers)

This will instrument the code to perform basic block counting. As the program runs, it counts the number of executions of each branch in an if statement, each iteration of a for loop, and so on. Note that though you can combine Block counters with Function counters, this has no effect because Function counters is only a subset of Block counters.

Call graph (not in combination with Block counters)

This will instrument the code to reconstruct the run-time call graph. As the program runs it associates the caller with the gathered profiling data.

Function counters

This will instrument the code to perform function call counting. This is a subset of the basic Block counters.

Function timers (not in combination with Block counters/Function counters)

This will instrument the code to measure the time spent in a function. This includes the time spent in all sub functions (callees).

Static profiling

With this option you do not need to run the application to get profiling results. The compiler generates profiling information at compile time, without adding extra code to your application.

If you use one or more profiling options that use code instrumentation, you must link the corresponding libraries too! Refer to Section 8.3, *Linking with Libraries*, for an overview of the (profiling) libraries. In Eclipse the correct libraries are linked automatically.

Example

To generate block count information for the module test.c during execution, compile as follows:

```
carm --profile=+block test.c
```

In this case you must link the library libpb.a.

Related information

Chapter 6, Profiling

C compiler option: --rename-sections (-R)

Menu entry

- 1. Select C/C++ Compiler » Miscellaneous.
- 2. Add the option --rename-sections to the Additional options field.

Command line syntax

```
--rename-sections=[name=]\{suffix \mid -f \mid -m \mid -fm\}
-R[name=]\{suffix \mid -f \mid -m \mid -fm\}
```

Description

In case a module must be loaded at a fixed address, or a data section needs a special place in memory, you can use this option to generate different section names. You can then use this unique section name in the linker script file for locating. Because sections have reserved names, the compiler will not actually change the section name, but will add a suffix to the name.

With the section *name* you select which sections are renamed. With *suffix* you specify the suffix part which will be attached to the existing name. The following name values have special meaning:

With the suboption **-f**, the compiler uses the function name (only for code).

With the suboption **-m**, the compiler uses the name of the current module.

With the suboption **-fm** (or **-mf**), the compiler uses the name of the current module for data sections and the function name for code sections.

If you do not specify a section name, all sections will receive the specified suffix.

Example

To change all sections named .data into .data.NEW, enter:

```
carm --rename-sections=.data=NEW test.c
```

To add the name of the current module as suffix to all data sections, resulting in .data.test, enter:

```
carm --rename-sections=.data=-m test.c
```

Related information

Assembler directive .SECTION

C compiler option: --runtime (-r)

Menu entry

- 1. Select C/C++ Compiler » Debugging.
- 2. Enable or disable one or more of the following run-time error checking options:
 - · Generate code for bounds checking
 - Generate code to detect unhandled case in a switch
 - · Generate code for malloc consistency checks
 - Generate code for stack overflow checks (allowed for USR and SYS mode only)
 - · Generate code for division by zero checks

Command line syntax

```
--runtime[=flag,...]
-r[flags]
```

You can set the following flags:

+/-bounds	b/B	bounds checking
+/-case	c/C	report unhandled case in a switch
+/-malloc	m/M	malloc consistency checks
+/-stack	s/S	check for stack overflow
+/-zero	z/Z	check for divide by zero

Default (without flags): -rbcm

Description

This option controls a number of run-time checks to detect errors during program execution. Some of these checks require additional code to be inserted in the generated code, and may therefore slow down the program execution. The following checks are available:

Bounds checking

Every pointer update and dereference will be checked to detect out-of-bounds accesses, null pointers and uninitialized automatic pointer variables. This check will increase the code size and slow down the program considerably. In addition, some heap memory is allocated to store the bounds information. You may enable bounds checking for individual modules or even parts of modules only (see #pragma runtime).

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Report unhandled case in a switch

Report an unhandled case value in a switch without a default part. This check will add one function call to every switch without a default part, but it will have little impact on the execution speed.

Malloc consistency checks

This option enables the use of wrappers around the functions malloc/realloc/free that will check for common dynamic memory allocation errors like:

- buffer overflow
- · write to freed memory
- · multiple calls to free
- · passing invalid pointer to free

Enabling this check will extract some additional code from the library, but it will not enlarge your application code. The dynamic memory usage will increase by a couple of bytes per allocation.

Stack overflow check

The compiler generates extra code within the function prolog that will check the available stack size before allocating. This is only useful when the processor runs in USR or SYS mode.

Division by zero check

The compiler generates a call to specific run-time functions for additional division by zero checks. If this situation occurs, an abort signal is issued. Without this check, a division by zero could lead to unpredictable results.

Related information

Pragma runtime

C compiler option: --signed-bitfields

Menu entry

- 1. Select C/C++ Compiler » Language.
- 2. Enable the option Treat "int" bit-fields as signed.

Command line syntax

--signed-bitfields

Description

For bit-fields it depends on the implementation whether a plain int is treated as signed int or unsigned int. By default an int bit-field is treated as unsigned int. This offers the best performance. With this option you tell the compiler to treat int bit-fields as signed int. In this case, you can still add the keyword unsigned to treat a particular int bit-field as unsigned.

Related information

C++ compiler option --signed-bitfields

Section 1.1, Data Types

C compiler option: --source (-s)

Menu entry

- 1. Select C/C++ Compiler » Miscellaneous.
- Enable the option Merge C source code with generated assembly.

Command line syntax

--source

-s

Description

With this option you tell the compiler to merge C source code with generated assembly code in the output file. The C source lines are included as comments.

Related information

Pragmas source/nosource

C compiler option: --static

Menu entry

-

Command line syntax

--static

Description

With this option, the compiler treats external definitions at file scope (except for main) as if they were declared static. As a result, unused functions will be eliminated, and the alias checking algorithm assumes that objects with static storage cannot be referenced from functions outside the current module.

This option only makes sense when you specify all modules of an application on the command line.

Example

carm --static module1.c module2.c module3.c ...

Related information

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C compiler option: --stdout (-n)

Menu entry

_

Command line syntax

--stdout

-n

Description

With this option you tell the compiler to send the output to stdout (usually your screen). No files are created. This option is for example useful to quickly inspect the output or to redirect the output to other tools.

Related information

C compiler option: --thumb

Menu entry

- 1. Select C/C++ Compiler » Code Generation.
- 2. Enable the option **Use Thumb instruction set**.

Command line syntax

--thumb

Description

With this option you tell the compiler to generate 16-bit Thumb instructions.

Related information

C compiler option --interwork (Generate interworking code)

C compiler option: --tradeoff (-t)

Menu entry

- Select C/C++ Compiler » Optimization.
- Select a trade-off level in the Trade-off between speed and size box.

Command line syntax

```
--tradeoff=\{0 | 1 | 2 | 3 | 4\}
-t\{0 | 1 | 2 | 3 | 4\}
Default: --tradeoff=0
```

Description

If the compiler uses certain optimizations (option **--optimize**), you can use this option to specify whether the used optimizations should optimize for more speed (regardless of code size) or for smaller code size (regardless of speed).

By default the compiler optimizes for speed (--tradeoff=0).

If you have not specified the option **--optimize**, the compiler uses the default *Optimize more* optimization. In this case it is still useful to specify a trade-off level.

Example

To set the trade-off level for the used optimizations:

```
carm --tradeoff=4 --thumb test.c
```

The compiler uses the default Optimize more optimization level and optimizes for code size.

Related information

C compiler option --optimize (Specify optimization level)

Section 4.5.3, Optimize for Size or Speed

C compiler option: --uchar (-u)

Menu entry

- 1. Select C/C++ Compiler » Language.
- 2. Enable the option Treat "char" variables as unsigned.

Command line syntax

--uchar

-u

Description

By default char is the same as specifying signed char. With this option char is the same as unsigned char.

Related information

Section 1.1, Data Types

C compiler option: --unaligned-access

Menu entry

- 1. Select C/C++ Compiler » Miscellaneous.
- 2. Add the option --unaligned-access to the Additional options field.

Command line syntax

--unaligned-access

Description

With this option you tell the compiler to generate more efficient instructions to access unaligned 16-bit or larger data. Halfword or word load and store instructions are used instead of byte instructions.

This option is only useful for cores that have support for unaligned access.

Related information

C compiler option: --undefine (-U)

Menu entry

1. Select C/C++ Compiler » Preprocessing

The Defined symbols box shows the symbols that are currently defined.

To remove a defined symbol, select the symbol in the **Defined symbols** box and click on the **Delete** button.

Command line syntax

```
--undefine=macro_name
```

Description

With this option you can undefine an earlier defined macro as with #undef. This option is for example useful to undefine predefined macros.

The following predefined ISO C standard macros cannot be undefined:

F.T.T.E	current source fliename
LINE	current source line number (int type
TIME	hh:mm:ss
DATE	Mmm dd yyyy
STDC	level of ANSI standard

Example

```
To undefine the predefined macro __TASKING__:

carm --undefine=__TASKING__ test.c
```

Related information

C compiler option --define (Define preprocessor macro)

Section 1.6, Predefined Preprocessor Macros

⁻Umacro_name

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C compiler option: --version (-V)

Menu entry

_

Command line syntax

--version

-v

Description

Display version information. The compiler ignores all other options or input files.

Related information

C compiler option: --warnings-as-errors

Menu entry

- 1. Select Global Options.
- 2. Enable the option Treat warnings as errors.

Command line syntax

```
--warnings-as-errors[=number,...]
```

Description

If the compiler encounters an error, it stops compiling. When you use this option without arguments, you tell the compiler to treat all warnings as errors. This means that the exit status of the compiler will be non-zero after one or more compiler warnings. As a consequence, the compiler now also stops after encountering a warning.

You can also limit this option to specific warnings by specifying a comma-separated list of warning numbers.

Related information

C compiler option --no-warnings (Suppress some or all warnings)

12.2. C++ Compiler Options

This section lists all C++ compiler options.

Options in Eclipse versus options on the command line

Most command line options have an equivalent option in Eclipse but some options are only available on the command line. Eclipse invokes the C++ compiler via the control program. Therefore, it uses the syntax of the control program to pass options and files to the C++ compiler. If there is no equivalent option in Eclipse, you can specify a command line option in Eclipse as follows:

1. From the **Project** menu, select **Properties**

The Properties dialog appears.

In the left pane, expand C/C++ Build and select Settings.

In the right pane the Settings appear.

- On the Tool Settings tab, select C/C++ Compiler » Miscellaneous.
- In the Additional options field, enter one or more command line options.

Because Eclipse uses the control program, you have to precede the option with **-Wcp** to pass the option via the control program directly to the C++ compiler.

Short and long option names

Options can have both short and long names. Short option names always begin with a single minus (-) character, long option names always begin with two minus (--) characters. You can abbreviate long option names as long as it forms a unique name. You can mix short and long option names on the command line.

If an option requires an argument, the argument may be separated from the keyword by white space, or the keyword may be immediately followed by =option. When the second form is used there may not be any white space on either side of the equal sign.

Options can have flags or suboptions. To switch a flag 'on', use a lowercase letter or a +longflag. To switch a flag off, use an uppercase letter or a -longflag. Separate longflags with commas. The following two invocations are equivalent:

```
cparm -Ecp test.cc
cparm --preprocess=+comments,+noline test.cc
```

When you do not specify an option, a default value may become active.

The priority of the options is left-to-right: when two options conflict, the first (most left) one takes effect. The **-D** and **-U** options are not considered conflicting options, so they are processed left-to-right for each source file. You can overrule the default output file name with the **--output-file** option.

C++ compiler option: --alternative-tokens

Menu entry

_

Command line syntax

--alternative-tokens

Description

Enable recognition of alternative tokens. This controls recognition of the digraph tokens in C++, and controls recognition of the operator keywords (e.g., not, and, bitand, etc.).

Example

To enable operator keywords (e.g., "not", "and") and digraphs, enter:

```
cparm --alternative-tokens test.cc
```

Related information

C++ compiler option: --anachronisms

Menu entry

- Select C/C++ Compiler » Language.
- 2. Enable the option C++ anachronisms.

Command line syntax

--anachronisms

Description

Enable C++ anachronisms. This option also enables **--nonconst-ref-anachronism**. But you can turn this off individually with option **--no-nonconst-ref-anachronism**.

Related information

C++ compiler option --nonconst-ref-anachronism (Nonconst reference anachronism)

Section 2.2.3, Anachronisms Accepted

C++ compiler option: --base-assign-op-is-default

Menu entry

_

Command line syntax

--base-assign-op-is-default

Description

Enable the anachronism of accepting a copy assignment operator that has an input parameter that is a reference to a base class as a default copy assignment operator for the derived class.

Related information

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C++ compiler option: --building-runtime

Menu entry

_

Command line syntax

--building-runtime

Description

Special option for building the C++ run-time library. Used to indicate that the C++ run-time library is being compiled. This causes additional macros to be predefined that are used to pass configuration information from the C++ compiler to the run-time.

Related information

C++ compiler option: --c++0x

Menu entry

_

Command line syntax

--c++0x

Description

Enable the C++ extensions that are defined by the latest C++ working paper.

Related information

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C++ compiler option: --check

Menu entry

_

Command line syntax

--check

Description

With this option you can check the source code for syntax errors, without generating code. This saves time in developing your application because the code will not actually be compiled.

The C++ compiler reports any warnings and/or errors.

This option is available on the command line only.

Related information

C compiler option --check (Check syntax)

Assembler option --check (Check syntax)

C++ compiler option: --context-limit

Menu entry

_

Command line syntax

```
--context-limit=number
```

Default: --context-limit=10

Description

Set the context limit to *number*. The context limit is the maximum number of template instantiation context entries to be displayed as part of a diagnostic message. If the number of context entries exceeds the limit, the first and last *N* context entries are displayed, where *N* is half of the context limit. A value of zero is used to indicate that there is no limit.

Example

To set the context limit to 5, enter:

```
cparm --context-limit=5 test.cc
```

Related information

_

C++ compiler option: --cpu (-C)

Menu entry

- 1. Expand C/C++ Build and select Processor.
- 2. From the Processor Selection list, make a selection by Architecture, Core or Manufacturer.

Command line syntax

--cpu=architecture

-Carchitecture

You can specify the following architectures:

ARMv4 Compile for ARMv4 architecture
ARMv4T Compile for ARMv4T architecture
ARMv5T Compile for ARMv5T architecture
ARMv5TE Compile for ARMv5TE architecture

ARMv6M Compile for ARMv6-M architecture profile
ARMv7M Compile for ARMv7-M architecture profile

XS Compile for XScale core

Description

With this option you specify the ARM architecture for which you create your application. The ARM target supports more than one architecture and therefore you need to specify for which architecture the compiler should compile. The architecture determines which instructions are valid and which are not.

The effect of this option is that the C++ compiler uses the appropriate instruction set. You choose one of the following architectures: ARMv4, ARMv4T, ARMv5T, ARMv5TE, ARMv6-M, ARMv7-M or XScale.

The macro CPU is set to the name of the architecture.

Example

To compile the file test.cc for the ARMv4 architecture, enter the following on the command line:

```
cparm --cpu=ARMv4 test.cc
```

Related information

C compiler option --cpu (Select architecture)

C++ compiler option: --create-pch

Menu entry

- 1. Select C/C++ Compiler » Precompiled C++ Headers.
- 2. Enter a filename in the Create precompiled header file field.

Command line syntax

--create-pch=filename

Description

If other conditions are satisfied, create a precompiled header file with the specified name. If **--pch** (automatic PCH mode) or **--use-pch** appears on the command line following this option, its effect is erased.

Example

To create a precompiled header file with the name test.pch, enter:

```
cparm --create-pch=test.pch test.cc
```

Related information

C++ compiler option --pch (Automatic PCH mode)

C++ compiler option --use-pch (Use precompiled header file)

Section 2.9, Precompiled Headers

C++ compiler option: --define (-D)

Menu entry

1. Select C/C++ Compiler » Preprocessing.

The Defined symbols box shows the symbols that are currently defined.

- 2. To define a new symbol, click on the **Add** button in the **Defined symbols** box.
- 3. Type the symbol definition (for example, demo=1)

Use the Edit and Delete button to change a macro definition or to remove a macro from the list.

Command line syntax

```
--define=macro_name[(parm-list)][=macro_definition]
-Dmacro_name(parm-list)][=macro_definition]
```

Description

With this option you can define a macro and specify it to the preprocessor. If you only specify a macro name (no macro definition), the macro expands as '1'.

Function-style macros can be defined by appending a macro parameter list to macro_name.

You can specify as many macros as you like. Simply use the Add button to add new macro definitions.

On the command line, you can use the option --define (-D) multiple times. If the command line exceeds the limit of the operating system, you can define the macros in an option file which you then must specify to the C++ compiler with the option --option-file (-f) file.

The definition can be tested by the preprocessor with #if, #ifdef and #ifndef, for conditional compilations.

Example

Consider the following program with conditional code to compile a demo program and a real program:

```
void main( void )
{
#if DEMO
    demo_func();    /* compile for the demo program */
#else
    real_func();    /* compile for the real program */
#endif
}
```

You can now use a macro definition to set the DEMO flag:

```
cparm --define=DEMO test.cc
cparm --define=DEMO=1 test.cc
```

Note that both invocations have the same effect.

The next example shows how to define a macro with arguments. Note that the macro name and definition are placed between double quotes because otherwise the spaces would indicate a new option.

```
cparm --define="MAX(A,B)=((A) > (B) ? (A) : (B))" test.cc
```

Related information

C++ compiler option --undefine (Remove preprocessor macro)

C++ compiler option --option-file (Specify an option file)

C++ compiler option: --dep-file

Menu entry

-

Command line syntax

```
--dep-file[=file]
```

Description

With this option you tell the C++ compiler to generate dependency lines that can be used in a Makefile. In contrast to the option --preprocess=+make, the dependency information will be generated in addition to the normal output file.

By default, the information is written to a file with extension .d (one for every input file). When you specify a filename, all dependencies will be combined in the specified file.

Example

```
cparm --dep-file=test.dep test.cc
```

The compiler compiles the file test.cc, which results in the output file test.ic, and generates dependency lines in the file test.dep.

Related information

C++ compiler option --preprocess=+make (Generate dependencies for make)

C++ compiler option: --dollar

Menu entry

_

Command line syntax

--dollar

Default format: No dollar signs are allowed in identifiers.

Description

Accept dollar signs in identifiers. Names like A\$VAR are allowed.

Related information

C++ compiler option: --embedded-c++

Menu entry

- Select C/C++ Compiler » Language.
- 2. Enable the option Check for embedded C++ compliance.

Command line syntax

--embedded-c++

Description

Enable the diagnostics of non-compliance with the "Embedded C++" subset (from which templates, exceptions, namespaces, new-style casts, RTTI, multiple inheritance, virtual base classes, and mutable are excluded).

Related information

C++ compiler option: --endianness

Menu entry

- 1. Select Global Options.
- 2. Specify the Endianness:Little-endian mode or Big-endian mode.

Command line syntax

--endianness=endianness

-B

--big-endian

You can specify the following endianness:

b Big endian

little I Little endian (default)

Description

By default, the C++ compiler generates code for a little-endian target (least significant byte of a word at lowest byte address). With **--endianness=big** the C++ compiler generates code for a big-endian target (most significant byte of a word at lowest byte address). **-B** is an alias for option **--endianness=big**.

The macro __BIG_ENDIAN__ is defined when this option is specified, otherwise the macro __LITTLE_ENDIAN__ is defined.

C++ compiler option: --error-file

Menu entry

_

Command line syntax

```
--error-file[=file]
```

Description

With this option the C++ compiler redirects error messages to a file. If you do not specify a filename, the error file will be named after the input file with extension .ecp.

Example

To write errors to errors.ecp instead of stderr, enter:

```
cparm --error-file=errors.ecp test.cc
```

Related information

C++ compiler option: --error-limit (-e)

Menu entry

_

Command line syntax

```
\verb|--error-limit=| number|
```

-enumber

Default: --error-limit=100

Description

Set the error limit to *number*. The C++ compiler will abandon compilation after this number of errors (remarks and warnings are not counted). By default, the limit is 100.

Example

When you want compilation to stop when 10 errors occurred, enter:

```
cparm --error-limit=10 test.cc
```

Related information

C++ compiler option: --exceptions (-x)

Menu entry

- 1. Select C/C++ Compiler » Language.
- 2. Enable the option Support for C++ exception handling.

Command line syntax

--exceptions

 $-\mathbf{x}$

Description

With this option you enable support for exception handling in the C++ compiler.

The macro __EXCEPTIONS is defined when exception handling support is enabled.

Related information

C++ compiler option: --exported-template-file

Menu entry

_

Command line syntax

--exported-template-file=file

Description

This option specifies the name to be used for the exported template file used for processing of exported templates.

This option is supplied for use by the control program that invokes the C++ compiler and is not intended to be used by end-users.

Related information

C++ compiler option: --extended-variadic-macros

Menu entry

_

Command line syntax

--extended-variadic-macros

Default: macros with a variable number of arguments are not allowed.

Description

Allow macros with a variable number of arguments (implies **--variadic-macros**) and allow the naming of the variable argument list.

Related information

C++ compiler option --variadic-macros (Allow variadic macros)

C++ compiler option: --force-vtbl

Menu entry

- 1. Select C/C++ Compiler » Miscellaneous.
- 2. Enable the option Force definition of virtual function tables (C++).

Command line syntax

--force-vtbl

Description

Force definition of virtual function tables in cases where the heuristic used by the C++ compiler to decide on definition of virtual function tables provides no guidance.

Related information

C++ compiler option --suppress-vtbl (Suppress definition of virtual function tables)

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C++ compiler option: --friend-injection

Menu entry

_

Command line syntax

--friend-injection

Default: friend names are not injected.

Description

Controls whether the name of a class or function that is declared only in friend declarations is visible when using the normal lookup mechanisms. When friend names are injected, they are visible to such lookups. When friend names are not injected (as required by the standard), function names are visible only when using argument-dependent lookup, and class names are never visible.

Related information

C++ compiler option --no-arg-dep-lookup (Disable argument dependent lookup)

C++ compiler option: --g++

Menu entry

- 1. Select C/C++ Compiler » Language.
- 2. Enable the option Allow GNU C++ extensions.

Command line syntax

--g++

Description

Enable GNU C++ compiler language extensions.

Related information

Section 2.3, GNU Extensions

C++ compiler option: --gnu-version

Menu entry

_

Command line syntax

```
--gnu-version=version
```

Default: 30300 (version 3.3.0)

Description

It depends on the GNU C++ compiler version if a particular GNU extension is supported or not. With this option you set the GNU C++ compiler version that should be emulated in GNU C++ mode. Version x.y.z of the GNU C++ compiler is represented by the value x*10000+y*100+z.

Example

To specify version 3.4.1 of the GNU C++ compiler, enter:

```
cparm --g++ --gnu-version=30401 test.cc
```

Related information

Section 2.3, GNU Extensions

C++ compiler option: --guiding-decls

Menu entry

_

Command line syntax

```
--guiding-decls
```

Description

Enable recognition of "guiding declarations" of template functions. A guiding declaration is a function declaration that matches an instance of a function template but has no explicit definition (since its definition derives from the function template). For example:

```
template <class T> void f(T) { ... }
void f(int);
```

When regarded as a guiding declaration, f(int) is an instance of the template; otherwise, it is an independent function for which a definition must be supplied.

Related information

C++ compiler option --old-specializations (Old-style template specializations)

C++ compiler option: --help (-?)

Menu entry

_

-?

Command line syntax

```
--help[=item]
```

You can specify the following arguments:

options

Show extended option descriptions

Description

Displays an overview of all command line options. When you specify an argument you can list extended information such as a list of option descriptions.

Example

The following invocations all display a list of the available command line options:

```
cparm -?
cparm --help
cparm
```

The following invocation displays an extended list of the available options:

```
cparm --help=options
```

Related information

_

C++ compiler option: --implicit-extern-c-type-conversion

Menu entry

_

Command line syntax

--implicit-extern-c-type-conversion

Description

Enable the implicit type conversion between pointers to extern "C" and extern "C++" function types.

Related information

C++ compiler option: --implicit-include

Menu entry

- 1. Select C/C++ Compiler » Miscellaneous.
- 2. Enable the option **Implicit inclusion of source files for finding templates**.

Command line syntax

--implicit-include

Description

Enable implicit inclusion of source files as a method of finding definitions of template entities to be instantiated.

Related information

C++ compiler option --instantiate (Instantiation mode)

Section 2.5, Template Instantiation

C++ compiler option: --incl-suffixes

Menu entry

_

Command line syntax

```
--incl-suffixes=suffixes
```

Default: no extension and .stdh.

Description

Specifies the list of suffixes to be used when searching for an include file whose name was specified without a suffix. If a null suffix is to be allowed, it must be included in the suffix list. *suffixes* is a colon-separated list of suffixes (e.g., "::stdh").

Example

To allow only the suffixes .h and .stdh as include file extensions, enter:

```
cparm --incl-suffixes=h:stdh test.cc
```

Related information

C++ compiler option --include-file (Include file at the start of a compilation)

C++ compiler option: --include-directory (-I)

Menu entry

1. Select C/C++ Compiler » Include Paths.

The Include paths box shows the directories that are added to the search path for include files.

- 2. To define a new directory for the search path, click on the **Add** button in the **Include paths** box.
- 3. Type or select a path.

Use the Edit and Delete button to change a path or to remove a path from the list.

Command line syntax

```
--include-directory=path,...
-Ipath,...
```

Description

Add path to the list of directories searched for #include files whose names do not have an absolute pathname. You can specify multiple directories separated by commas.

Example

To add the directory /proj/include to the include file search path, enter:

```
cparm --include-directory=/proj/include test.cc
```

Related information

C++ compiler option --include-file (Include file at the start of a compilation)

C++ compiler option --sys-include (Add directory to system include file search path)

C++ compiler option: --include-file (-H)

Menu entry

1. Select C/C++ Compiler » Preprocessing.

The Pre-include files box shows the files that are currently included before the compilation starts.

- 2. To define a new file, click on the **Add** button in the **Include files at start of compilation** box.
- 3. Type the full path and file name or select a file.
- 4. (Optional) Enable the option Include default register definition header file before source.

Use the **Edit** and **Delete** button to change a file name or to remove a file from the list.

Command line syntax

```
--include-file=file
```

-**H**file

Description

Include the source code of the indicated file at the beginning of the compilation. This is the same as specifying #include "file" at the beginning of each of your C++ sources.

All files included with --include-file are processed after any of the files included with --include-macros-file.

The filename is searched for in the directories on the include search list.

Example

```
cparm --include-file=extra.h test1.cc test2.cc
```

The file extra.h is included at the beginning of both test1.cc and test2.cc.

Related information

C++ compiler option --include-directory (Add directory to include file search path)

C++ compiler option: --include-macros-file

Menu entry

_

Command line syntax

--include-macros-file=file

Description

Include the macros of the indicated file at the beginning of the compilation. Only the preprocessing directives from the file are evaluated. All of the actual code is discarded. The effect of this option is that any macro definitions from the specified file will be in effect when the primary source file is compiled. All of the macro-only files are processed before any of the normal includes (--include-file). Within each group, the files are processed in the order in which they were specified.

Related information

C++ compiler option --include-file (Include file at the start of a compilation)

C++ compiler option: --init-priority

Menu entry

_

Command line syntax

--init-priority=number

Default: 0

Description

Normally, the C++ compiler assigns no priority to the global initialization functions and the exact order is determined by the linker. This option sets the default priority for global initialization functions. Default value is "0". You can also set the default priority with the #pragma init_priority.

Values from 1 to 100 are for internal use only and should not be used. Values 101 to 65535 are available for user code. A lower number means a higher priority.

Example

cparm --init-priority=101 test.cc

Related information

_

C++ compiler option: --instantiate (-t)

Menu entry

- Select C/C++ Compiler » Miscellaneous.
- 2. Select an instantiation mode in the **Instantiation mode of external template entities** box.

Command line syntax

--instantiate=mode

-tmode

You can specify the following modes:

used

all

local

Default: --instantiate=used

Description

all

Control instantiation of external template entities. External template entities are external (that is, non-inline and non-static) template functions and template static data members. The instantiation mode determines the template entities for which code should be generated based on the template definition. Normally, when a file is compiled, template entities are instantiated wherever they are used (the linker will discard duplicate definitions). The overall instantiation mode can, however, be changed with this option. You can specify the following modes:

used	Instantiate those template entities that were used in the compilation. This will include
uoou	all static data members for which there are template definitions. This is the default.

all static data members for which there are template definitions. This is the deladit.

Instantiate all template entities declared or referenced in the compilation unit. For each fully instantiated template class, all of its member functions and static data members will be instantiated whether or not they were used. Non-member template

functions will be instantiated even if the only reference was a declaration.

local Similar to **--instantiate=used** except that the functions are given internal linkage.

This is intended to provide a very simple mechanism for those getting started with templates. The compiler will instantiate the functions that are used in each compilation unit as local functions, and the program will link and run correctly (barring problems due to multiple copies of local static variables). However, one may end up with many copies of the instantiated functions, so this is not suitable for production

use.

You cannot use --instantiate=local in conjunction with automatic template instantiation.

Related information

C++ compiler option --no-auto-instantiation (Disable automatic C++ instantiation)

Section 2.5, Template Instantiation

C++ compiler option: --io-streams

Menu entry

- 1. Select C/C++ Compiler » Language.
- 2. Enable the option **Support for C++ I/O streams**.

Command line syntax

--io-streams

Description

As I/O streams require substantial resources they are disabled by default. Use this option to enable I/O streams support in the C++ library.

This option also enables exception handling.

Related information

C++ compiler option: --late-tiebreaker

Menu entry

-

Command line syntax

--late-tiebreaker

Default: early tiebreaker processing.

Description

Select the way that tie-breakers (e.g., cv-qualifier differences) apply in overload resolution. In "early" tie-breaker processing, the tie-breakers are considered at the same time as other measures of the goodness of the match of an argument value and the corresponding parameter type (this is the standard approach).

In "late" tie-breaker processing, tie-breakers are ignored during the initial comparison, and considered only if two functions are otherwise equally good on all arguments; the tie-breakers can then be used to choose one function over another.

Related information

_

C++ compiler option: --list-file (-L)

Menu entry

-

Command line syntax

--list-file=file

-Lfile

Default: -1

Description

Generate raw listing information in the *file*. This information is likely to be used to generate a formatted listing. The raw listing file contains raw source lines, information on transitions into and out of include files, and diagnostics generated by the C++ compiler.

Each line of the listing file begins with a key character that identifies the type of line, as follows:

- **N** A normal line of source: the rest of the line is the text of the line.
- The expanded form of a normal line of source; the rest of the line is the text of the line. This line appears following the N line, and only if the line contains non-trivial modifications (comments are considered trivial modifications; macro expansions, line splices, and trigraphs are considered non-trivial modifications). Comments are replaced by a single space in the expanded-form line.
- A line of source skipped by an #if or the like; the rest of the line is text. Note that the #else, #elif, or #endif that ends a skip is marked with an N.
- An indication of a change in source position. The line has a format similar to the # line-identifying directive output by the C preprocessor, that is to say
 - L line_number "file-name" [key]

where key is, 1 for entry into an include file, or 2 for exit from an include file, and omitted otherwise.

The first line in the raw listing file is always an L line identifying the primary input file. L lines are also output for #line directives (key is omitted). L lines indicate the source position of the following source line in the raw listing file.

R, **W**, An indication of a diagnostic (**R** for remark, **W** for warning, **E** for error, and **C** for catastrophic **E**, or **C** error). The line has the form:

```
S "file-name" line_number column-number message-text
```

where *S* is R, W, E, or C, as explained above. Errors at the end of file indicate the last line of the primary source file and a column number of zero. Command line errors are catastrophes with an empty file name ("") and a line and column number of zero. Internal errors are catastrophes with position information as usual, and message-text beginning with (internal error). When a diagnostic displays a list (e.g., all the contending routines when there is ambiguity on an overloaded call), the initial diagnostic line is followed by one or more lines with the same overall format (code letter, file name, line number, column number, and message text), but in which the code letter is the lower case version of the code letter in the initial line. The source position in such lines is the same as that in the corresponding initial line.

Example

To write raw listing information to the file test.lst, enter:

cparm --list-file=test.lst test.cc

Related information

TASKING VX-toolset for ARM User Guide

C++ compiler option: --long-lifetime-temps

Menu entry

-

Command line syntax

--long-lifetime-temps

Description

Select the lifetime for temporaries: short means to end of full expression; long means to the earliest of end of scope, end of switch clause, or the next label. Short is the default.

Related information

C++ compiler option: --long-long

Menu entry

_

Command line syntax

--long-long

Description

Permit the use of long long in strict mode in dialects in which it is non-standard.

Related information

TASKING VX-toolset for ARM User Guide

C++ compiler option: --multibyte-chars

Menu entry

-

Command line syntax

--multibyte-chars

Default: multibyte character sequences are not allowed.

Description

Enable processing for multibyte character sequences in comments, string literals, and character constants. Multibyte encodings are used for character sets like the Japanese SJIS.

Related information

C++ compiler option: --namespaces

Menu entry

_

Command line syntax

- --namespaces
- --no-namespaces

Default: namespaces are supported.

Description

When you used option **--embedded-c++** namespaces are disabled. With option **--namespaces** you can enable support for namespaces in this case.

The macro ___NAMESPACES is defined when namespace support is enabled.

Related information

C++ compiler option --embedded-c++ (Embedded C++ compliancy tests)

C++ compiler option --using-std (Implicit use of the std namespace)

Section 2.4, Namespace Support

TASKING VX-toolset for ARM User Guide

C++ compiler option: --no-arg-dep-lookup

Menu entry

_

Command line syntax

--no-arg-dep-lookup

Default: argument dependent lookup of unqualified function names is performed.

Description

With this option you disable argument dependent lookup of unqualified function names.

Related information

C++ compiler option: --no-array-new-and-delete

Menu entry

_

Command line syntax

--no-array-new-and-delete

Default: array new and delete are supported.

Description

Disable support for array new and delete.

The macro __ARRAY_OPERATORS is defined when array new and delete is enabled.

Related information

TASKING VX-toolset for ARM User Guide

C++ compiler option: --no-auto-instantiation

Menu entry

_

Command line syntax

--no-auto-instantiation

Default: the C++ compiler automatically instantiates templates.

Description

With this option automatic instantiation of templates is disabled.

Related information

C++ compiler option --instantiate (Set instantiation mode)

Section 2.5, Template Instantiation

C++ compiler option: --no-bool

Menu entry

-

Command line syntax

--no-bool

Default: bool is recognized as a keyword.

Description

Disable recognition of the bool keyword.

The macro _BOOL is defined when bool is recognized as a keyword.

Related information

C++ compiler option: --no-class-name-injection

Menu entry

-

Command line syntax

--no-class-name-injection

Default: the name of a class is injected into the scope of the class (as required by the standard).

Description

Do not inject the name of a class into the scope of the class (as was true in earlier versions of the C++ language).

Related information

C++ compiler option: --no-const-string-literals

Menu entry

-

Command line syntax

--no-const-string-literals

Default: C++ string literals and wide string literals are const (as required by the standard).

Description

With this option C++ string literals and wide string literals are non-const (as was true in earlier versions of the C++ language).

Related information

C++ compiler option: --no-dep-name

Menu entry

_

Command line syntax

--no-dep-name

Default: dependent name processing is enabled.

Description

Disable dependent name processing; i.e., the special lookup of names used in templates as required by the C++ standard. This option implies the use of **--no-parse-templates**.

Related information

C++ compiler option --no-parse-templates (Disable parsing of nonclass templates)

C++ compiler option: --no-distinct-template-signatures

Menu entry

-

Command line syntax

--no-distinct-template-signatures

Description

Control whether the signatures for template functions can match those for non-template functions when the functions appear in different compilation units. By default a normal function cannot be used to satisfy the need for a template instance; e.g., a function "void f(int)" could not be used to satisfy the need for an instantiation of a template "void f(T)" with T set to int.

--no-distinct-template-signatures provides the older language behavior, under which a non-template function can match a template function. Also controls whether function templates may have template parameters that are not used in the function signature of the function template.

Related information

C++ compiler option: --no-double (-F)

Menu entry

- Select C/C++ Compiler » Language.
- 2. Enable the option Treat double as float.

Command line syntax

```
--no-double
```

-F

Description

With this option you tell the C++ compiler to treat variables of the type double as float. Because the float type takes less space, execution speed increases and code size decreases, both at the cost of less precision.

Example

```
cparm --no-double test.cc
```

The file test.cc is compiled where variables of the type double are treated as float.

Related information

C++ compiler option: --no-enum-overloading

Menu entry

_

Command line syntax

--no-enum-overloading

Description

Disable support for using operator functions to overload built-in operations on enum-typed operands.

Related information

C++ compiler option: --no-explicit

Menu entry

-

Command line syntax

--no-explicit

Default: the explicit specifier is allowed.

Description

Disable support for the explicit specifier on constructor declarations.

Related information

C++ compiler option: --no-export

Menu entry

_

Command line syntax

--no-export

Default: exported templates (declared with the keyword export) are allowed.

Description

Disable recognition of exported templates. This option requires that dependent name processing be done, and cannot be used with implicit inclusion of template definitions.

Related information

Section 2.5.5, Exported Templates

C++ compiler option: --no-extern-inline

Menu entry

_

Command line syntax

--no-extern-inline

Default: inline functions are allowed to have external linkage.

Description

Disable support for inline functions with external linkage in C++. When inline functions are allowed to have external linkage (as required by the standard), then extern and inline are compatible specifiers on a non-member function declaration; the default linkage when inline appears alone is external (that is, inline means extern inline on non-member functions); and an inline member function takes on the linkage of its class (which is usually external). However, when inline functions have only internal linkage (using --no-extern-inline), then extern and inline are incompatible; the default linkage when inline appears alone is internal (that is, inline means static inline on non-member functions); and inline member functions have internal linkage no matter what the linkage of their class.

Related information

Section 2.6, Extern Inline Functions

C++ compiler option: --no-for-init-diff-warning

Menu entry

_

Command line syntax

--no-for-init-diff-warning

Description

Disable a warning that is issued when programs compiled without the **--old-for-init** option would have had different behavior under the old rules.

Related information

C++ compiler option --old-for-init (Use old for scoping rules)

C++ compiler option: --no-implicit-typename

Menu entry

-

Command line syntax

--no-implicit-typename

Default: implicit typename determination is enabled.

Description

Disable implicit determination, from context, whether a template parameter dependent name is a type or nontype.

Related information

C++ compiler option --no-typename (Disable the typename keyword)

C++ compiler option: --no-inlining

Menu entry

- 1. Select C/C++ Compiler » Miscellaneous.
- 2. Disable the option Minimal inlining of function calls (C++).

Command line syntax

--no-inlining

Description

Disable minimal inlining of function calls.

Related information

C++ compiler option: --nonconst-ref-anachronism

Menu entry

-

Command line syntax

--nonconst-ref-anachronism

--no-nonconst-ref-anachronism

Default: --no-nonconst-ref-anachronism

Description

Enable or disable the anachronism of allowing a reference to nonconst to bind to a class rvalue of the right type. This anachronism is also enabled by the **--anachronisms** option.

Related information

C++ compiler option --anachronisms (Enable C++ anachronisms)

Section 2.2.3, Anachronisms Accepted

C++ compiler option: --nonstd-qualifier-deduction

Menu entry

_

Command line syntax

--nonstd-qualifier-deduction

Description

Controls whether non-standard template argument deduction should be performed in the qualifier portion of a qualified name. With this feature enabled, a template argument for the template parameter ${\tt T}$ can be deduced in contexts like ${\tt A}{\tt T}{\tt >}:{\tt B}$ or ${\tt T}:{\tt B}$. The standard deduction mechanism treats these as non-deduced contexts that use the values of template parameters that were either explicitly specified or deduced elsewhere.

Related information

C++ compiler option: --nonstd-using-decl

Menu entry

_

Command line syntax

--nonstd-using-decl

Default: non-standard using declarations are not allowed.

Description

Allow a non-member using declaration that specifies an unqualified name.

Related information

C++ compiler option: --no-parse-templates

Menu entry

_

Command line syntax

--no-parse-templates

Default: parsing of nonclass templates is enabled.

Description

Disable the parsing of nonclass templates in their generic form (i.e., even if they are not really instantiated). It is done by default if dependent name processing is enabled.

Related information

C++ compiler option --no-dep-name (Disable dependent name processing)

C++ compiler option: --no-pch-messages

Menu entry

_

Command line syntax

--no-pch-messages

Default: a message is displayed indicating that a precompiled header file was created or used in the current compilation. For example,

"test.cc": creating precompiled header file "test.pch"

Description

Disable the display of a message indicating that a precompiled header file was created or used in the current compilation.

Related information

C++ compiler option --pch (Automatic PCH mode)

C++ compiler option --use-pch (Use precompiled header file)

C++ compiler option --create-pch (Create precompiled header file)

C++ compiler option: --no-preprocessing-only

Menu entry

Eclipse always does a full compilation.

Command line syntax

--no-preprocessing-only

Description

You can use this option in conjunction with the options that normally cause the C++ compiler to do preprocessing only (e.g., --preprocess, etc.) to specify that a full compilation should be done (not just preprocessing). When used with the implicit inclusion option, this makes it possible to generate a preprocessed output file that includes any implicitly included files.

Example

cparm --preprocess --implicit-include --no-preprocessing-only test.cc

Related information

C++ compiler option --preprocess (Preprocessing only)

C++ compiler option --implicit-include (Implicit source file inclusion)

C++ compiler option: --no-stdinc

Menu entry

- 1. Select C/C++ Compiler » Miscellaneous.
- 2. Add the option --no-stdinc to the Additional options field.

Command line syntax

--no-stdinc

Description

With this option you tell the C++ compiler not to look in the default include directory relative to the installation directory, when searching for include files. This way the C++ compiler only searches in the include file search paths you specified.

Related information

Section 5.2, How the C++ Compiler Searches Include Files

C++ compiler option: --no-typename

Menu entry

_

Command line syntax

--no-typename

Default: typename is recognized as a keyword.

Description

Disable recognition of the typename keyword.

Related information

C++ compiler option --no-implicit-typename (Disable implicit typename determination)

C++ compiler option: --no-use-before-set-warnings (-j)

Menu entry

- 1. Select C/C++ Compiler » Diagnostics.
- 2. Enable the option Suppress C++ compiler "used before set" warnings.

Command line syntax

--no-use-before-set-warnings

-j

Description

Suppress warnings on local automatic variables that are used before their values are set.

Related information

C++ compiler option --no-warnings (Suppress all warnings)

C++ compiler option: --no-warnings (-w)

Menu entry

- 1. Select C/C++ Compiler » Diagnostics.
- 2. Enable the option **Suppress all warnings**.

Command line syntax

```
--no-warnings
```

-w

Description

With this option you suppress all warning messages. Error messages are still issued.

Related information

C++ compiler option --warnings-as-errors (Treat warnings as errors)

C++ compiler option: --old-for-init

Menu entry

_

Command line syntax

--old-for-init

Description

Control the scope of a declaration in a for-init-statement. The old (cfront-compatible) scoping rules mean the declaration is in the scope to which the for statement itself belongs; the default (standard-conforming) rules in effect wrap the entire for statement in its own implicitly generated scope.

Related information

C++ compiler option --no-for-init-diff-warning (Disable warning for old for-scoping)

C++ compiler option: --old-line-commands

Menu entry

_

Command line syntax

```
--old-line-commands
```

Description

When generating source output, put out #line directives in the form # nnn instead of #line nnn.

Example

To do preprocessing only, without comments and with old style line control information, enter:

```
cparm --preprocess --old-line-commands test.cc
```

Related information

C++ compiler option --preprocess (Preprocessing only)

C++ compiler option: --old-specializations

Menu entry

_

Command line syntax

--old-specializations

Description

Enable acceptance of old-style template specializations (that is, specializations that do not use the template<> syntax).

Related information

C++ compiler option: --option-file (-f)

Menu entry

-

Command line syntax

```
--option-file=file
-f file
```

Description

This option is primarily intended for command line use. Instead of typing all options on the command line, you can create an option file which contains all options and flags you want to specify. With this option you specify the option file to the C++ compiler.

Use an option file when the command line would exceed the limits of the operating system, or just to store options and save typing.

You can specify the option --option-file multiple times.

Format of an option file

- Multiple arguments on one line in the option file are allowed.
- To include whitespace in an argument, surround the argument with single or double quotes.
- If you want to use single quotes as part of the argument, surround the argument by double quotes and vise versa:

```
"This has a single quote ' embedded"

'This has a double quote " embedded'

'This has a double quote " and a single quote '"' embedded"
```

When a text line reaches its length limit, use a \ to continue the line. Whitespace between quotes is
preserved.

```
"This is a continuation \ line" -> "This is a continuation line"
```

• It is possible to nest command line files up to 25 levels.

Example

Suppose the file myoptions contains the following lines:

```
--embedded-c++
--define=DEMO=1
test.cc

Specify the option file to the C++ compiler:
cparm --option-file=myoptions

This is equivalent to the following command line:
cparm --embedded-c++ --define=DEMO=1 test.cc
```

Related information

C++ compiler option: --output (-o)

Menu entry

Eclipse names the output file always after the C++ source file.

Command line syntax

```
--output-file=file
-o file
```

Default: module name with .ic suffix.

Description

With this option you can specify another filename for the output file of the C++ compiler. Without this option the basename of the C++ source file is used with extension .ic.

You can also use this option in combination with the option --preprocess (-E) to redirect the preprocessing output to a file.

Example

To create the file output.ic instead of test.ic, enter:

```
cparm --output=output.ic test.cc
```

To use the file my.pre as the preprocessing output file, enter:

```
cparm --preprocess --output=my.pre test.cc
```

Related information

C++ compiler option --preprocess (Preprocessing)

C++ compiler option: --pch

Menu entry

- Select C/C++ Compiler » Precompiled C++ Headers.
- 2. Enable the option Automatically use/create precompiled header file.

Command line syntax

--pch

Description

Automatically use and/or create a precompiled header file. If --use-pch or --create-pch (manual PCH mode) appears on the command line following this option, its effect is erased.

Related information

C++ compiler option --use-pch (Use precompiled header file)

C++ compiler option --create-pch (Create precompiled header file)

C++ compiler option: --pch-dir

Menu entry

- 1. Select C/C++ Compiler » Precompiled C++ Headers.
- 2. Enter a path in the **Precompiled header file directory**.

Command line syntax

--pch-dir=directory-name

Description

Specify the directory in which to search for and/or create a precompiled header file. This option may be used with automatic PCH mode (--pch) or manual PCH mode (--create-pch or --use-pch).

Example

To use the directory c:\usr\include\pch to automatically create precompiled header files, enter:

```
cparm --pch-dir=c:\usr\include\pch --pch test.cc
```

Related information

C++ compiler option --pch (Automatic PCH mode)

C++ compiler option --use-pch (Use precompiled header file)

C++ compiler option --create-pch (Create precompiled header file)

C++ compiler option: --pch-verbose

Menu entry

_

Command line syntax

--pch-verbose

Description

In automatic PCH mode, for each precompiled header file that cannot be used for the current compilation, a message is displayed giving the reason that the file cannot be used.

Example

```
cparm --pch --pch-verbose test.cc
```

Related information

C++ compiler option --pch (Automatic PCH mode)

C++ compiler option: --pending-instantiations

Menu entry

_

Command line syntax

--pending-instantiations=n

where n is the maximum number of instantiations of a single template.

Default: 64

Description

Specifies the maximum number of instantiations of a given template that may be in process of being instantiated at a given time. This is used to detect runaway recursive instantiations. If n is zero, there is no limit.

Example

To specify a maximum of 32 pending instantiations, enter:

cparm --pending-instantiations=32 test.cc

Related information

Section 2.5, Template Instantiation

C++ compiler option: --preprocess (-E)

Menu entry

- Select C/C++ Compiler » Preprocessing.
- 2. Enable the option Store preprocessor output in <file>.pre.
- 3. (Optional) Enable the option Keep comments in preprocessor output.
- 4. (Optional) Enable the option **Keep #line info in preprocessor output**.

Command line syntax

```
--preprocess[=flags]
-E[flags]
```

You can set the following flags:

+/-comments c/C keep comments

+/-make m/M generate dependencies for make+/-noline p/P strip #line source position information

Default: -ECMP

Description

With this option you tell the C++ compiler to preprocess the C++ source. Under Eclipse the C++ compiler sends the preprocessed output to the file <code>name.pre</code> (where <code>name</code> is the name of the C++ source file to compile). Eclipse also compiles the C++ source.

On the command line, the C++ compiler sends the preprocessed file to stdout. To capture the information in a file, specify an output file with the option --output.

With --preprocess=+comments you tell the preprocessor to keep the comments from the C++ source file in the preprocessed output.

With **--preprocess=+make** the C++ compiler will generate dependency lines that can be used in a Makefile. The preprocessor output is discarded.

When implicit inclusion of templates is enabled, the output may indicate false (but safe) dependencies unless **--no-preprocessing-only** is also used.

With **--preprocess=+noline** you tell the preprocessor to strip the #line source position information (lines starting with #line). These lines are normally processed by the assembler and not needed in the preprocessed output. When you leave these lines out, the output is easier to read.

Example

```
cparm --preprocess=+comments,-make,-noline test.cc --output=test.pre
```

The C++ compiler preprocesses the file test.cc and sends the output to the file test.pre. Comments are included but no dependencies are generated and the line source position information is not stripped from the output file.

Related information

C++ compiler option --no-preprocessing-only (Force full compilation)

C++ compiler option --dep-file (Generate dependencies in a file)

C++ compiler option: --remarks (-r)

Menu entry

- 1. Select C/C++ Compiler » Diagnostics.
- 2. Enable the option Issue remarks on C++ code.

Command line syntax

--remarks

-r

Description

Issue remarks, which are diagnostic messages even milder than warnings.

Related information

Section 5.3, C++ Compiler Error Messages

C++ compiler option: --remove-unneeded-entities

Menu entry

-

Command line syntax

--remove-unneeded-entities

Description

Enable an optimization to remove types, variables, routines, and related constructs that are not really needed. Something may be referenced but unneeded if it is referenced only by something that is itself unneeded; certain entities, such as global variables and routines defined in the translation unit, are always considered to be needed.

Related information

C++ compiler option: --rtti

Menu entry

- 1. Select C/C++ Compiler » Language.
- 2. Enable the option Support for C++ RTTI (run-time type information).

Command line syntax

--rtti

Default: RTTI (run-time type information) features are disabled.

Description

Enable support for RTTI (run-time type information) features: dynamic_cast, typeid.

The macro __RTTI is defined when RTTI support is enabled.

Related information

C++ compiler option: --schar (-s)

Menu entry

- 1. Select C/C++ Compiler » Language.
- 2. Disable the option Treat "char" variables as unsigned.

Command line syntax

--schar

-s

Description

With this option char is the same as signed char.

When plain char is signed, the macro __SIGNED_CHARS__ is defined.

Related information

C++ compiler option --uchar (Plain char is unsigned)

Section 1.1, Data Types

C++ compiler option: --signed-bitfields

Menu entry

- 1. Select C/C++ Compiler » Language.
- Enable the option Treat "int" bit-fields as signed.

Command line syntax

--signed-bitfields

Description

For bit-fields it depends on the implementation whether a plain int is treated as signed int or unsigned int. By default an int bit-field is treated as unsigned int. This offers the best performance. With this option you tell the C++ compiler to treat int bit-fields as signed int. In this case, you can still add the keyword unsigned to treat a particular int bit-field as unsigned.

Related information

C compiler option --signed-bitfields

Section 1.1, Data Types

C++ compiler option: --special-subscript-cost

Menu entry

-

Command line syntax

```
--special-subscript-cost
```

Description

Enable a special nonstandard weighting of the conversion to the integral operand of the [] operator in overload resolution.

This is a compatibility feature that may be useful with some existing code. With this feature enabled, the following code compiles without error:

Related information

C++ compiler option: --strict (-A)

Menu entry

- Select C/C++ Compiler » Language.
- 2. Disable the option Allow non-ANSI/ISO C++ features.

Command line syntax

--strict

-A

Default: non-ANSI/ISO C++ features are enabled.

Description

Enable strict ANSI/ISO mode, which provides diagnostic messages when non-standard features are used, and disables features that conflict with ANSI/ISO C or C++. All ANSI/ISO violations are issued as errors.

Example

To enable strict ANSI mode, with error diagnostic messages, enter:

cparm --strict test.cc

Related information

C++ compiler option --strict-warnings (Strict ANSI/ISO mode with warnings)

C++ compiler option: --strict-warnings (-a)

Menu entry

_

Command line syntax

```
--strict-warnings
```

-a

Default: non-ANSI/ISO C++ features are enabled.

Description

This option is similar to the option --strict, but all violations are issued as warnings instead of errors.

Example

To enable strict ANSI mode, with warning diagnostic messages, enter:

```
cparm --strict-warnings test.cc
```

Related information

C++ compiler option --strict (Strict ANSI/ISO mode with errors)

C++ compiler option: --suppress-vtbl

Menu entry

- 1. Select C/C++ Compiler » Miscellaneous.
- Enable the option Suppress definition of virtual function tables (C++).

Command line syntax

--suppress-vtbl

Description

Suppress definition of virtual function tables in cases where the heuristic used by the C++ compiler to decide on definition of virtual function tables provides no guidance. The virtual function table for a class is defined in a compilation if the compilation contains a definition of the first non-inline non-pure virtual function of the class. For classes that contain no such function, the default behavior is to define the virtual function table (but to define it as a local static entity). The --suppress-vtbl option suppresses the definition of the virtual function tables for such classes, and the --force-vtbl option forces the definition of the virtual function table for such classes. --force-vtbl differs from the default behavior in that it does not force the definition to be local.

Related information

C++ compiler option --force-vtbl (Force definition of virtual function tables)

C++ compiler option: --sys-include

Menu entry

-

Command line syntax

```
--sys-include=directory, . . .
```

Description

Change the algorithm for searching system include files whose names do not have an absolute pathname to look in *directory*.

Example

To add the directory c:\proj\include to the system include file search path, enter:

```
cparm --sys-include=c:\proj\include test.cc
```

Related information

C++ compiler option --include-directory (Add directory to include file search path)

Section 5.2, How the C++ Compiler Searches Include Files

C++ compiler option: --template-directory

Menu entry

-

Command line syntax

```
--template-directory=directory,...
```

Description

Specifies a directory name to be placed on the exported template search path. The directories are used to find the definitions of exported templates (.et files) and are searched in the order in which they are specified on the command line. The current directory is always the first entry on the search path.

Example

To add the directory export to the exported template search path, enter:

```
cparm --template-directory=export test.cc
```

Related information

Section 2.5.5, Exported Templates

C++ compiler option: --thumb

Menu entry

- 1. Select C/C++ Compiler » Code Generation.
- 2. Enable the option **Use Thumb instruction set**.

Command line syntax

--thumb

Description

Generate code in Thumb mode. The Thumb instruction set is a subset of the ARM instruction set which is encoded using 16-bit instructions instead of 32-bit instructions.

The macro ___THUMB___ is defined when the Thumb mode is enabled.

Related information

C++ compiler option: --timing

Menu entry

_

Command line syntax

--timing

Default: no timing information is generated.

Description

Generate compilation timing information. This option causes the C++ compiler to display the amount of CPU time and elapsed time used by each phase of the compilation and a total for the entire compilation.

Example

```
cparm --timing test.cc
processed 180 lines at 8102 lines/min
```

Related information

C++ compiler option: --trace-includes

Menu entry

_

Command line syntax

--trace-includes

Description

Output a list of the names of files #included to the error output file. The source file is compiled normally (i.e. it is not just preprocessed) unless another option that causes preprocessing only is specified.

Example

```
cparm --trace-includes test.cc
iostream.h
string.h
```

Related information

C++ compiler option --preprocess (Preprocessing only)

C++ compiler option: --type-traits-helpers

Menu entry

-

Command line syntax

```
--type-traits-helpers
```

--no-type-traits-helpers

Default: in C++ mode type traits helpers are enabled by default. In GNU C++ mode, type traits helpers are never enabled by default.

Description

Enable or disable type traits helpers (like __is_union and __has_virtual_destructor). Type traits helpers are meant to ease the implementation of ISO/IEC TR 19768.

The macro __TYPE_TRAITS_ENABLED is defined when type traits pseudo-functions are enabled.

Related information

C++ compiler option: --uchar (-u)

Menu entry

- 1. Select C/C++ Compiler » Language.
- 2. Enable the option Treat "char" variables as unsigned.

Command line syntax

--uchar

-u

Description

By default char is the same as specifying signed char. With this option char is the same as unsigned char.

Related information

C++ compiler option --schar (Plain char is signed)

Section 1.1, Data Types

C++ compiler option: --undefine (-U)

Menu entry

1. Select C/C++ Compiler » Preprocessing

The Defined symbols box shows the symbols that are currently defined.

To remove a defined symbol, select the symbol in the **Defined symbols** box and click on the **Delete** button.

Command line syntax

```
--undefine=macro_name
-Umacro_name
```

Description

Remove any initial definition of *macro_name* as in #undef. --undefine options are processed after all --define options have been processed.

You cannot undefine a predefined macro as specified in Section 2.8, Predefined Macros, except for:

```
__STDC__
__cplusplus
__SIGNED_CHARS__
```

Example

To undefine the predefined macro __cplusplus:

```
cparm --undefine=__cplusplus test.cc
```

Related information

C++ compiler option --define (Define preprocessor macro)

Section 2.8, Predefined Macros

C++ compiler option: --use-pch

Menu entry

- 1. Select C/C++ Compiler » Precompiled C++ Headers.
- 2. Enter a filename in the **Use precompiled header file** field.

Command line syntax

--use-pch=filename

Description

Use a precompiled header file of the specified name as part of the current compilation. If **--pch** (automatic PCH mode) or **--create-pch** appears on the command line following this option, its effect is erased.

Example

To use the precompiled header file with the name test.pch, enter:

```
cparm --use-pch=test.pch test.cc
```

Related information

C++ compiler option --pch (Automatic PCH mode)

C++ compiler option --create-pch (Create precompiled header file)

Section 2.9, Precompiled Headers

C++ compiler option: --using-std

Menu entry

-

Command line syntax

--using-std

Default: implicit use of the std namespace is disabled.

Description

Enable implicit use of the std namespace when standard header files are included. Note that this does not do the equivalent of putting a "using namespace std;" in the program to allow old programs to be compiled with new header files; it has a special and localized meaning related to the TASKING versions of certain header files, and is unlikely to be of much use to end-users of the TASKING C++ compiler.

Related information

C++ compiler option --namespaces (Support for namespaces)

Section 2.4, Namespace Support

C++ compiler option: --variadic-macros

Menu entry

_

Command line syntax

--variadic-macros

Default: macros with a variable number of arguments are not allowed.

Description

Allow macros with a variable number of arguments.

Related information

C++ compiler option --extended-variadic-macros (Allow extended variadic macros)

C++ compiler option: --version (-V)

Menu entry

_

Command line syntax

--version

-v

Description

Display version information. The C++ compiler ignores all other options or input files.

C++ compiler option: --warnings-as-errors

Menu entry

- 1. Select Global Options.
- 2. Enable the option Treat warnings as errors.

Command line syntax

--warnings-as-errors

Description

If the C++ compiler encounters an error, it stops compiling. With this option you tell the C++ compiler to treat all warnings as errors. This means that the exit status of the C++ compiler will be non-zero after one or more compiler warnings. As a consequence, the C++ compiler now also stops after encountering a warning.

Related information

C++ compiler option --no-warnings (Suppress all warnings)

C++ compiler option: --wchar_t-keyword

Menu entry

- 1. Select C/C++ Compiler » Language.
- 2. Enable the option Allow the 'wchar_t' keyword (C++).

Command line syntax

```
--wchar_t-keyword
```

Default: wchar_t is not recognized as a keyword.

Description

Enable recognition of wchar_t as a keyword.

The macro _wchar_t is defined when wchar_t is recognized as a keyword.

Related information

C++ compiler option: --xref-file (-X)

Menu entry

-

Command line syntax

```
--xref-file=file
```

-Xfile

Description

Generate cross-reference information in a *file*. For each reference to an identifier in the source program, a line of the form

```
symbol_id name X file-name line-number column-number
```

is written, where X is

- **D** for definition;
- **d** for declaration (that is, a declaration that is not a definition);
- **M** for modification;
- A for address taken;
- U for used:
- **C** for changed (but actually meaning used and modified in a single operation, such as an increment):
- **R** for any other kind of reference, or
- **E** for an error in which the kind of reference is indeterminate.

symbol-id is a unique decimal number for the symbol. The fields of the above line are separated by tab characters.

Related information

12.3. Assembler Options

This section lists all assembler options.

Options in Eclipse versus options on the command line

Most command line options have an equivalent option in Eclipse but some options are only available on the command line. Eclipse invokes the assembler via the control program. Therefore, it uses the syntax of the control program to pass options and files to the assembler. If there is no equivalent option in Eclipse, you can specify a command line option in Eclipse as follows:

1. From the **Project** menu, select **Properties**

The Properties dialog appears.

2. In the left pane, expand C/C++ Build and select Settings.

In the right pane the Settings appear.

- On the Tool Settings tab, select Assembler » Miscellaneous.
- 4. In the **Additional options** field, enter one or more command line options.

Because Eclipse uses the control program, Eclipse automatically precedes the option with **-Wa** to pass the option via the control program directly to the assembler.

Note that the options you enter in the Assembler page are only used for hand-coded assembly files, not for the assembly files generated by the compiler.

Be aware that some command line options are not useful in Eclipse or just do not have any effect. For example, the option **-V** displays version header information and has no effect in Eclipse.

Short and long option names

Options can have both short and long names. Short option names always begin with a single minus (-) character, long option names always begin with two minus (--) characters. You can abbreviate long option names as long as it forms a unique name. You can mix short and long option names on the command line.

Options can have flags or suboptions. To switch a flag 'on', use a lowercase letter or a +longflag. To switch a flag off, use an uppercase letter or a -longflag. Separate longflags with commas. The following two invocations are equivalent:

```
asarm -l -LeM test.src
asarm --list-file --list-format=+symbol,-macro test.src
```

When you do not specify an option, a default value may become active.

Assembler option: --case-insensitive (-c)

Menu entry

- 1. Select Assembler » Symbols.
- 2. Enable the option Case insensitive identifiers.

Command line syntax

--case-insensitive

-c

Default: case sensitive

Description

With this option you tell the assembler not to distinguish between upper and lower case characters. By default the assembler considers upper and lower case characters as different characters.

Assembly source files that are generated by the compiler must always be assembled case sensitive. When you are writing your own assembly code, you may want to specify the case insensitive mode.

Example

When assembling case insensitive, the label Label Name is the same label as labelname.

asarm --case-insensitive test.src

Related information

_

Assembler option: --check

Menu entry

_

Command line syntax

--check

Description

With this option you can check the source code for syntax errors, without generating code. This saves time in developing your application.

The assembler reports any warnings and/or errors.

This option is available on the command line only.

Related information

C compiler option --check (Check syntax)

Assembler option: --cpu (-C)

Menu entry

- 1. Expand C/C++ Build and select Processor.
- 2. From the Processor Selection list, make a selection by Architecture, Core or Manufacturer.

Command line syntax

--cpu=architecture

-Carchitecture

You can specify the following architectures:

ARMv4 Assemble for ARMv4 architecture
ARMv4T Assemble for ARMv4T architecture
ARMv5T Assemble for ARMv5T architecture
ARMv5TE Assemble for ARMv5TE architecture

ARMv6M Assemble for ARMv6-M architecture profile
ARMv7M Assemble for ARMv7-M architecture profile

XS Assemble for XScale core

Description

With this option you specify the ARM architecture for which you create your application. The architecture determines which instructions are valid and which are not. If the architecture is ARMv4 the linker replaces BX instructions by MOV PC instructions. The default architecture is ARMv4T and the complete list of supported architectures is: ARMv4, ARMv4T, ARMv5TE, ARMv5TE, ARMv6-M, ARMv7-M or XScale.

Assembly code can check the value of the option by means of the built-in function @CPU(). Architecture ARMv4 does not support the Thumb instruction set. Architecture profile ARMv7-M only supports the Thumb-2 instruction set, i.e. it has no ARM execution state.

To avoid conflicts, make sure you specify the same architecture as you did for the compiler (Eclipse and the control program do this automatically).

Related information

Assembly function @CPU()

C compiler option --cpu (Select architecture)

Assembler option: --debug-info (-g)

Menu entry

- Select Assembler » Symbols.
- 2. Select an option from the Generate symbolic debug list.

Command line syntax

```
--debug-info[=flags]
-g[flags]
```

You can set the following flags:

+/-asm	a/A	Assembly source line information
+/-hII	h/H	Pass high level language debug information (HLL)
+/-local	I/L	Assembler local symbols debug information
+/-smart	s/S	Smart debug information

Default: --debug-info=+hll

Default (without flags): --debug-info=+smart

Description

With this option you tell the assembler which kind of debug information to emit in the object file.

You cannot specify **--debug-info=+asm,+hll**. Either the assembler generates assembly source line information, or it passes HLL debug information.

When you specify **--debug-info=+smart**, the assembler selects which flags to use. If high level language information is available in the source file, the assembler passes this information (same as **--debug-info=-asm,+hll,-local**). If not, the assembler generates assembly source line information (same as **--debug-info=+asm,-hll,+local**).

With --debug-info=AHLS the assembler does not generate any debug information.

Related information

Assembler option: --define (-D)

Menu entry

1. Select Assembler » Preprocessing.

The Defined symbols box right-below shows the symbols that are currently defined.

- 2. To define a new symbol, click on the **Add** button in the **Defined symbols** box.
- 3. Type the symbol definition (for example, demo=1)

Use the Edit and Delete button to change a macro definition or to remove a macro from the list.

Command line syntax

```
--define=macro_name[=macro_definition]
-Dmacro_name[=macro_definition]
```

Description

With this option you can define a macro and specify it to the assembler preprocessor. If you only specify a macro name (no macro definition), the macro expands as '1'.

You can specify as many macros as you like. Simply use the **Add** button to add new macro definitions.

On the command line, use the option --define (-D) multiple times. If the command line exceeds the limit of the operating system, you can define the macros in an option file which you then must specify to the assembler with the option --option-file (-f) file.

Defining macros with this option (instead of in the assembly source) is, for example, useful in combination with conditional assembly as shown in the example below.

This option has the same effect as defining symbols via the <code>.DEFINE</code>, <code>.SET</code>, and <code>.EQU</code> directives. (similar to <code>#define</code> in the C language). With the <code>.MACRO</code> directive you can define more complex macros.

Example

Consider the following assembly program with conditional code to assemble a demo program and a real program:

```
.IF DEMO == 1
... ; instructions for demo application
.ELSE
... ; instructions for the real application
.ENDIF
```

You can now use a macro definition to set the DEMO flag:

```
asarm --define=DEMO test.src
asarm --define=DEMO=1 test.src
```

Note that both invocations have the same effect.

Related information

Assembler option --option-file (Specify an option file)

Assembler option: --diag

Menu entry

1. From the Window menu, select Show View » Other » Basic » Problems.

The Problems view is added to the current perspective.

2. In the Problems view right-click on a message.

A popup menu appears.

3. Select **Detailed Diagnostics Info**.

A dialog box appears with additional information.

Command line syntax

```
--diag=[format:]{all | nr,...}
```

You can set the following output formats:

html HTML output.

rtf Rich Text Format.

text ASCII text.

Default format: text

Description

With this option you can ask for an extended description of error messages in the format you choose. The output is directed to stdout (normally your screen) and in the format you specify. You can specify the following formats: **html**, **rtf** or **text** (default). To create a file with the descriptions, you must redirect the output.

With the suboption **all**, the descriptions of all error messages are given. If you want the description of one or more selected error messages, you can specify the error message numbers, separated by commas.

Example

To display an explanation of message number 244, enter:

```
asarm --diag=244
```

This results in the following message and explanation:

```
W244: additional input files will be ignored
```

The assembler supports only a single input file. All other input files are ignored.

To write an explanation of all errors and warnings in HTML format to file aserrors.html, use redirection and enter:

asarm --diag=html:all > aserrors.html

Related information

Section 7.5, Assembler Error Messages

Assembler option: --emit-locals

Menu entry

- 1. Select Assembler » Symbols.
- 2. Enable or disable one or both of the following options:
 - · Emit local EQU symbols
 - Emit mapping symbols (\$a, \$t, \$d)
 - · Emit local non-EQU symbols

Command line syntax

```
--emit-locals[=flag,...]
```

You can set the following flags:

+/-equs e/E emit local EQU symbols

+/-mappings m/M emit mapping symbols (\$a, \$t, \$d)

+/-symbols s/S emit local non-EQU symbols

Default: --emit-locals=+mappings,+symbols

Description

With the option **--emit-locals=+equs** the assembler also emits local EQU symbols to the object file. Normally, only global symbols, mapping symbols and non-EQU local symbols are emitted. Having local symbols in the object file can be useful for debugging.

Mapping symbols are local symbols inside code sections which mark the start of a range of ARM instructions (\$a), a range of Thumb instructions (\$t), or a literal pool a.k.a. data pocket (\$d). Also, data sections start with a \$d symbol. The mapping symbol names are made unique with a'.' character suffix followed by a unique integer, for example: \$a.1, \$t.2 and \$d.3. This option only takes effect if local labels are emitted as well (default).

Related information

Assembler directive . EQU

Assembler option: --endianness

Menu entry

- Select Global Options.
- 2. Specify the Endianness:Little-endian mode or Big-endian mode.

Command line syntax

--endianness=endianness

-B

--big-endian

You can specify the following endianness:

big b Big endian

little I Little endian (default)

Description

By default, the assembler generates object files with instructions and data in little-endian format (least significant byte of a word at lowest byte address). With **--endianness=big** the assembler generates object files in big-endian format (most significant byte of a word at lowest byte address). **-B** is an alias for option **--endianness=big**.

The endianness is reflected in the list file.

Assembly code can check the setting of this option by means of the built-in assembly function <code>@BIGENDIAN()</code>.

Related information

Assembly function @BIGENDIAN()

Assembler option: --error-file

Menu entry

_

Command line syntax

```
--error-file[=file]
```

Description

With this option the assembler redirects error messages to a file. If you do not specify a filename, the error file will be named after the input file with extension .ers.

Example

To write errors to errors.ers instead of stderr, enter:

```
asarm --error-file=errors.ers test.src
```

Related information

Section 7.5, Assembler Error Messages

Assembler option: --error-limit

Menu entry

_

Command line syntax

--error-limit=number

Default: 42

Description

With this option you tell the assembler to only emit the specified maximum number of errors. When 0 (null) is specified, the assembler emits all errors. Without this option the maximum number of errors is 42.

Related information

Section 7.5, Assembler Error Messages

Assembler option: --help (-?)

Menu entry

_

Command line syntax

```
--help[=item]
--?
```

You can specify the following arguments:

options

Show extended option descriptions

Description

Displays an overview of all command line options. When you specify the argument **options** you can list detailed option descriptions.

Example

The following invocations all display a list of the available command line options:

```
asarm -?
asarm --help
asarm
```

To see a detailed description of the available options, enter:

```
asarm --help=options
```

Related information

Assembler option: --include-directory (-I)

Menu entry

Select Assembler » Include Paths.

The Include paths box shows the directories that are added to the search path for include files.

- 2. To define a new directory for the search path, click on the **Add** button in the **Include paths** box.
- 3. Type or select a path.

Use the Edit and Delete button to change a path or to remove a path from the list.

Command line syntax

```
--include-directory=path,...
-Ipath,...
```

Description

With this option you can specify the path where your include files are located. A relative path will be relative to the current directory,

The order in which the assembler searches for include files is:

- 1. The pathname in the assembly file and the directory of the assembly source.
- 2. The path that is specified with this option.
- 3. The path that is specified in the environment variable ASARMINC when the product was installed.
- 4. The default directory \$(PRODDIR)\include.

Example

Suppose that the assembly source file test.src contains the following lines:

```
.INCLUDE 'myinc.inc'
```

You can call the assembler as follows:

```
asarm --include-directory=c:\proj\include test.src
```

First the assembler looks for the file myinc.inc in the directory where test.src is located. If it does not find the file, it looks in the directory c:\proj\include (this option). If the file is still not found, the assembler searches in the environment variable and then in the default include directory.

Related information

Assembler option --include-file (Include file at the start of the input file)

Assembler option: --include-file (-H)

Menu entry

1. Select Assembler » Preprocessing.

The Pre-include files box shows the files that are currently included before the assembling starts.

- 2. To define a new file, click on the **Add** button in the **Pre-include files** box.
- 3. Type the full path and file name or select a file.

Use the Edit and Delete button to change a file name or to remove a file from the list.

Command line syntax

```
--include-file=file,...
-Hfile,...
```

Description

With this option (set at project level) you include one extra file at the beginning of the assembly source file. The specified include file is included before all other includes. This is the same as specifying .INCLUDE 'file' at the beginning of your assembly source.

Example

```
asarm --include-file=myinc.inc test.src
```

The file myinc.inc is included at the beginning of test.src before it is assembled.

Related information

Assembler option --include-directory (Add directory to include file search path)

Assembler option: --inversions

Menu entry

- 1. Select Assembler » Miscellaneous.
- 2. Enable the option Allow instruction inversions.

Command line syntax

--inversions

Description

With this option you tell the assembler to try to invert some data processing instructions with an immediate operand. Inversions are available for MOV/MVN, CMP/CMN, AND/BIC, ADC/SBC, and ADD/SUB.

Example

With this option enabled, you can write

```
add r1, r2, #-4
```

and the assembler will generate

```
sub r1,r2,#4
```

and instead of

```
mov r1,0xFFFFFFF
```

the assembler will generate

mvn r1,0

Related information

Assembler option: --keep-output-files (-k)

Menu entry

Eclipse always removes the object file when errors occur during assembling.

Command line syntax

--keep-output-files

-k

Description

If an error occurs during assembling, the resulting object file (.obj) may be incomplete or incorrect. With this option you keep the generated object file when an error occurs.

By default the assembler removes the generated object file when an error occurs. This is useful when you use the make utility. If the erroneous files are not removed, the make utility may process corrupt files on a subsequent invocation.

Use this option when you still want to use the generated object. For example when you know that a particular error does not result in a corrupt object file.

Related information

Assembler option --warnings-as-errors (Treat warnings as errors)

Assembler option: --list-file (-I)

Menu entry

- 1. Select Assembler » List File.
- 2. Enable the option Generate list file.
- 3. Enable or disable the types of information to be included.

Command line syntax

```
--list-file[=file]
-l[file]
```

Default: no list file is generated

Description

With this option you tell the assembler to generate a list file. A list file shows the generated object code and the relative addresses. Note that the assembler generates a relocatable object file with relative addresses.

With the optional *file* you can specify an alternative name for the list file. By default, the name of the list file is the basename of the source file with the extension .lst.

Related information

Assembler option --list-format (Format list file)

Assembler option: --list-format (-L)

Menu entry

- 1. Select Assembler » List File.
- 2. Enable the option Generate list file.
- 3. Enable or disable the types of information to be included.

Command line syntax

```
--list-format=flag,...
```

-Lflags

+/-section

+/-cycle-count

+/-define-expansion

You can set the following flags:

T/-36CIIOII	u/D	LIST SECTION directives (.SECTION)
+/-symbol	e/E	List symbol definition directives
+/-generic-expansion	g/G	List expansion of generic instructions
+/-generic	i/I	List generic instructions
+/-line	I/L	List C preprocessor #line directives
+/-macro	m/M	List macro definitions
+/-empty-line	n/N	List empty source lines (newline)
+/-conditional	p/P	List conditional assembly
+/-equate	q/Q	List equate and set directives (.EQU, .SET)
+/-relocations	r/R	List relocations characters 'r'
+/-hll	s/S	List HLL symbolic debug informations
+/-equate-values	v/V	List equate and set values
+/-wrap-lines	w/W	Wrap source lines
+/-macro-expansion	x/X	List macro expansions

Use the following options for predefined sets of flags:

--list-format=0 -L0 All options disabled

y/Y

z/Z

Alias for --list-format=DEGILMNPQRSVWXYZ

--list-format=1 -L1 All options enabled

Alias for --list-format=degilmnpqrsvwxyz

List cycle counts

List define expansions

d/D List section directives (SECTION)

Default: --list-format=dEGilMnPqrsVwXyZ

Description

With this option you specify which information you want to include in the list file.

On the command line you must use this option in combination with the option --list-file (-I).

Related information

Assembler option --list-file (Generate list file)

Assembler option --section-info=+list (Display section information in list file)

Assembler option: --no-warnings (-w)

Menu entry

1. Select Assembler » Diagnostics.

The Suppress warnings box shows the warnings that are currently suppressed.

- 2. To suppress a warning, click on the **Add** button in the **Suppress warnings** box.
- 3. Enter the numbers, separated by commas, of the warnings you want to suppress (for example 201, 202). Or you can use the **Add** button multiple times.
- 4. To suppress all warnings, enable the option **Suppress all warnings**.

Use the Edit and Delete button to change a warning number or to remove a number from the list.

Command line syntax

```
--no-warnings[=number,...]
-w[number,...]
```

Description

With this option you can suppresses all warning messages or specific warning messages.

On the command line this option works as follows:

- If you do not specify this option, all warnings are reported.
- If you specify this option but without numbers, all warnings are suppressed.
- If you specify this option with a number, only the specified warning is suppressed. You can specify the
 option --no-warnings=number multiple times.

Example

To suppress warnings 201 and 202, enter:

```
asarm test.src --no-warnings=201,202
```

Related information

Assembler option --warnings-as-errors (Treat warnings as errors)

Assembler option: --old-syntax

Menu entry

- 1. Select Assembler » Miscellaneous.
- 2. Disable the option **UAL syntax mode**.

Command line syntax

```
--old-syntax
```

Description

In UAL syntax mode the assembler will not accept instructions which use the pre-UAL syntax and will select encodings based on the UAL syntax in case both syntaxes are the same.

With this option you can change this default behavior. The assembler will run in pre-UAL mode. The built-in function @PRE_UAL() will return true, so you can use:

```
.IF @PRE_UAL()
   ; <old code>
.ELSE
   ; <new code>
.ENDIF
```

Related information

Assembly function @PRE_UAL()

Assembler option: --option-file (-f)

Menu entry

- Select Assembler » Miscellaneous.
- 2. Add the option --option-file to the Additional options field.

Be aware that the options in the option file are added to the assembler options you have set in the other pages. Only in extraordinary cases you may want to use them in combination.

Command line syntax

```
--option-file=file,...
-f file,...
```

Description

This option is primarily intended for command line use. Instead of typing all options on the command line, you can create an option file which contains all options and flags you want to specify. With this option you specify the option file to the assembler.

Use an option file when the command line would exceed the limits of the operating system, or just to store options and save typing.

Option files can also be generated on the fly, for example by the make utility. You can specify the option **--option-file** multiple times.

Format of an option file

- Multiple arguments on one line in the option file are allowed.
- To include whitespace in an argument, surround the argument with single or double quotes.
- If you want to use single quotes as part of the argument, surround the argument by double quotes and vise versa:

```
"This has a single quote ' embedded"

'This has a double quote " embedded'

'This has a double quote " and a single quote '"' embedded"
```

When a text line reaches its length limit, use a \ to continue the line. Whitespace between quotes is preserved.

```
"This is a continuation \ line" -> "This is a continuation line"
```

• It is possible to nest command line files up to 25 levels.

Example

Suppose the file myoptions contains the following lines:

```
--debug=+asm,-local
test.src
```

Specify the option file to the assembler:

```
asarm --option-file=myoptions
```

This is equivalent to the following command line:

```
asarm --debug=+asm,-local test.src
```

Related information

Assembler option: --output (-o)

Menu entry

Eclipse names the output file always after the input file.

Command line syntax

```
\verb|--output=| file|
```

-o file

Description

With this option you can specify another filename for the output file of the assembler. Without this option, the basename of the assembly source file is used with extension .obj.

Example

To create the file relobj.obj instead of asm.obj, enter:

```
asarm --output=relobj.obj asm.src
```

Related information

Assembler option: --page-length

Menu entry

- 1. Select Assembler » Miscellaneous.
- 2. Add the option **--page-length** to the **Additional options** field.

Command line syntax

--page-length=number

Default: 72

Description

If you generate a list file with the assembler option **--list-file**, this option sets the number of lines in a page in the list file. The default is 72, the minimum is 10. As a special case, a page length of 0 turns off page breaks.

Related information

Assembler option --list-file (Generate list file)

Assembler directive . PAGE

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Assembler option: --page-width

Menu entry

- 1. Select Assembler » Miscellaneous.
- 2. Add the option --page-width to the Additional options field.

Command line syntax

--page-width=number

Default: 132

Description

If you generate a list file with the assembler option **--list-file**, this option sets the number of columns per line on a page in the list file. The default is 132, the minimum is 40.

Related information

Assembler option --list-file (Generate list file)

Assembler directive . PAGE

Assembler option: --preprocess (-E)

Menu entry

-

Command line syntax

--preprocess

-E

Description

With this option the assembler will only preprocess the assembly source file. The assembler sends the preprocessed file to stdout.

Related information

Assembler option: --preprocessor-type (-m)

Menu entry

- 1. Select Assembler » Preprocessing.
- 2. Enable or disable the option Use TASKING preprocessor.

Command line syntax

```
--preprocessor-type=type
-mtype
```

You can set the following preprocessor types:

none n No preprocessor

tasking t TASKING preprocessor

Default: --preprocessor-type=tasking

Description

With this option you select the preprocessor that the assembler will use. By default, the assembler uses the TASKING preprocessor.

When the assembly source file does not contain any preprocessor symbols, you can specify to the assembler not to use a preprocessor.

Related information

Assembler option: --relaxed

Menu entry

- 1. Select Assembler » Miscellaneous.
- 2. Enable the option Allow 2-operand form for 3-operand instructions.

Command line syntax

--relaxed

Description

With this option you tell the assembler that a relaxed 2-operand syntax is allowed on 3-operand instructions. If the first two register operands are equal, you can replace the two registers by one.

Example

With this option enabled, instead of

```
add r1,r1,#4

you can write

add r1,#4

and instead of

add r1,r1,r2

you can write

add r1,r2
```

Related information

Assembler option: --section-info (-t)

Menu entry

- 1. Select Assembler » List File.
- 2. Enable the option Generate list file.
- 3. Enable the option List section summary.

and/or

- 1. Select Assembler » Diagnostics.
- 2. Enable the option **Display section summary**.

Command line syntax

```
--section-info[=flag,...]
-t[flags]
```

You can set the following flags:

```
+/-console+/-listList section summary on console
```

Default: --section-info=CL

Default (without flags): --section-info=cl

Description

With this option you tell the assembler to display section information. For each section its memory space, size, total cycle counts and name is listed on stdout and/or in the list file.

The cycle count consists of two parts: the total accumulated count for the section and the total accumulated count for all repeated instructions. In the case of nested loops it is possible that the total supersedes the section total.

Example

To writes the section information to the list file and also display the section information on stdout, enter:

```
asarm --list-file --section-info asm.src
```

Related information

Assembler option --list-file (Generate list file)

Assembler option: --symbol-scope (-i)

Menu entry

- 1. Select Assembler » Symbols.
- 2. Enable or disable the option **Set default symbol scope to global**.

Command line syntax

- $\verb|--symbol-scope| = scope|$
- -iscope

You can set the following scope:

globalgDefault symbol scope is globallocalIDefault symbol scope is local

Default: --symbol-scope=local

Description

With this option you tell the assembler how to treat symbols that you have not specified explicitly as global or local. By default the assembler treats all symbols as local symbols unless you have defined them explicitly as global.

Related information

Assembler directive .GLOBAL

Assembler option: --thumb

Menu entry

- Select Assembler » Miscellaneous.
- 2. Enable the option Assemble Thumb instructions by default.

Command line syntax

--thumb

Description

With this option you tell the assembler that the input file contains Thumb code. By default the assembler assumes that the input file contains ARM code. The assembler will complain if --thumb is used in combination with --cpu=ARMv4. Specifying --thumb with --cpu=ARMv7M is not required.

Note that the input may still contain mixed Thumb and ARM code because the .ARM, .THUMB, .CODE16 and .CODE32 directives overrule the **--thumb** option. Assembly code can check the setting of the **--thumb** option by means of the built-in assembly function @THUMB(). So, if you use @THUMB() in a .ARM part and you specified **--thumb**, @THUMB() still returns 1.

Related information

Assembly function @THUMB()

Assembler directives . CODE16, . CODE32, . ARM, . THUMB

Assembler option: --version (-V)

Menu entry

_

Command line syntax

--version

-v

Description

Display version information. The assembler ignores all other options or input files.

Related information

Assembler option: --warnings-as-errors

Menu entry

- Select Global Options.
- 2. Enable the option Treat warnings as errors.

Command line syntax

```
--warnings-as-errors[=number,...]
```

Description

If the assembler encounters an error, it stops assembling. When you use this option without arguments, you tell the assembler to treat all warnings as errors. This means that the exit status of the assembler will be non-zero after one or more assembler warnings. As a consequence, the assembler now also stops after encountering a warning.

You can also limit this option to specific warnings by specifying a comma-separated list of warning numbers.

Related information

Assembler option --no-warnings (Suppress some or all warnings)

12.4. Linker Options

This section lists all linker options.

Options in Eclipse versus options on the command line

Most command line options have an equivalent option in Eclipse but some options are only available on the command line. Eclipse invokes the linker via the control program. Therefore, it uses the syntax of the control program to pass options and files to the linker. If there is no equivalent option in Eclipse, you can specify a command line option in Eclipse as follows:

1. From the Project menu, select Properties

The Properties dialog appears.

2. In the left pane, expand C/C++ Build and select Settings.

In the right pane the Settings appear.

- 3. On the Tool Settings tab, select **Linker** » **Miscellaneous**.
- 4. In the **Additional options** field, enter one or more command line options.

Because Eclipse uses the control program, Eclipse automatically precedes the option with **-WI** to pass the option via the control program directly to the linker.

Be aware that some command line options are not useful in Eclipse or just do not have any effect. For example, the option --keep-output-files keeps files after an error occurred. When you specify this option in Eclipse, it will have no effect because Eclipse always removes the output file after an error had occurred.

Short and long option names

Options can have both short and long names. Short option names always begin with a single minus (-) character, long option names always begin with two minus (--) characters. You can abbreviate long option names as long as it forms a unique name. You can mix short and long option names on the command line.

Options can have flags or suboptions. To switch a flag 'on', use a lowercase letter or a +longflag. To switch a flag off, use an uppercase letter or a -longflag. Separate longflags with commas. The following two invocations are equivalent:

```
lkarm -mfkl test.obj
lkarm --map-file-format=+files,+link,+locate test.obj
```

When you do not specify an option, a default value may become active.

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Linker option: --case-insensitive

Menu entry

- 1. Select Linker » Miscellaneous.
- 2. Enable the option Link case insensitive.

Command line syntax

--case-insensitive

Default: case sensitive

Description

With this option you tell the linker not to distinguish between upper and lower case characters in symbols. By default the linker considers upper and lower case characters as different characters.

Assembly source files that are generated by the compiler must *always* be assembled and thus linked case sensitive. When you have written your own assembly code and specified to assemble it case insensitive, you must also link the .obj file case insensitive.

Related information

Assembler option --case-insensitive

Linker option: --chip-output (-c)

Menu entry

- 1. Select Linker » Output Format.
- 2. Enable the option Generate Intel Hex format file and/or Generate S-records file.
- 3. Enable the option Create file for each memory chip.
- 4. Optionally, specify the Size of addresses.

Eclipse always uses the project name as the basename for the output file.

Command line syntax

```
--chip-output=[basename]:format[:addr_size],...
-c[basename]:format[:addr_size],...
```

You can specify the following formats:

IHEX Intel Hex

SREC Motorola S-records

The addr_size specifies the size of the addresses in bytes (record length). For Intel Hex you can use the values 1, 2 or 4 bytes (default). For Motorola-S you can specify: 2 (S1 records), 3 (S2 records) or 4 bytes (S3 records, default).

Description

With this option you specify the Intel Hex or Motorola S-record output format for loading into a PROM-programmer. The linker generates a file for each ROM memory defined in the LSL file, where sections are located:

```
memory memname
{ type=rom; }
```

The name of the file is the name of the Eclipse project or, on the command line, the name of the memory device that was emitted with extension . hex or . sre. Optionally, you can specify a basename which prepends the generated file name.

The linker always outputs a debugging file in ELF/DWARF format and optionally an absolute object file in Intel Hex-format and/or Motorola S-record format.

Example

To generate Intel Hex output files for each defined memory, enter the following on the command line:

```
lkarm --chip-output=myfile:IHEX test1.obj
```

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In this case, this generates the file $myfile_memname.hex$.

Related information

Linker option --output (Output file)

Linker option: --cpu (-C)

Menu entry

- 1. Expand C/C++ Build and select Processor.
- 2. From the Processor Selection list, make a selection by Architecture, Core or Manufacturer.

Command line syntax

```
--cpu=architecture
```

You can specify the following architectures:

ARMv4 Link for ARMv4 architecture
ARMv4T Link for ARMv4T architecture
ARMv5T Link for ARMv5T architecture
ARMv5TE Link for ARMv5TE architecture

ARMv6M Link for ARMv6-M architecture profile
ARMv7M Link for ARMv7-M architecture profile

XS Link for XScale core

Description

With this option you specify the ARM architecture for which you create your application. The linker uses the architecture to determine which libraries must be linked and what kind of veneers to generate. If the architecture is ARMv4 the linker will replace BX instructions in ARMv4T code by MOV PC instructions. If the architecture is ARMv5T, ARMv5TE or XScale the linker will replace unconditional BL instructions by BLX instructions if the branch target requires a state change between ARM and Thumb ot vice versa. The default architecture is ARMv4T and the complete list of supported architectures is: ARMv4, ARMv4T, ARMv5T, ARMv5TE, ARMv6-M, ARMv7-M, XScale.

Architecture ARMv4 does not support the Thumb instruction set. Architecture ARMv7-M only supports the Thumb-2 instruction set.

Related information

C compiler option --cpu (Select architecture)

⁻Carchitecture

Linker option: --define (-D)

Menu entry

1. Select Linker » Script File.

The Defined symbols box shows the symbols that are currently defined.

- 2. To define a new symbol, click on the **Add** button in the **Defined symbols** box.
- 3. Type the symbol definition (for example, demo=1)

Use the Edit and Delete button to change a macro definition or to remove a macro from the list.

Command line syntax

```
--define=macro_name[=macro_definition]
-Dmacro_name[=macro_definition]
```

Description

With this option you can define a macro and specify it to the linker LSL file preprocessor. If you only specify a macro name (no macro definition), the macro expands as '1'.

You can specify as many macros as you like; just use the option --define (-D) multiple times. If the command line exceeds the limit of the operating system, you can define the macros in an option file which you then must specify to the linker with the option --option-file (-f) file.

The definition can be tested by the preprocessor with #if, #ifdef and #ifndef, for conditional locating.

Example

To define the stack size and start address which are used in the linker script file arm.lsl, enter:

Related information

Linker option --option-file (Specify an option file)

Linker option: --diag

Menu entry

1. From the Window menu, select Show View » Other » Basic » Problems.

The Problems view is added to the current perspective.

2. In the Problems view right-click on a message.

A popup menu appears.

3. Select Detailed Diagnostics Info.

A dialog box appears with additional information.

Command line syntax

```
--diag=[format:]{all | nr,...}
```

You can set the following output formats:

html HTML output.
rtf Rich Text Format.

text ASCII text.

Default format: text

Description

With this option you can ask for an extended description of error messages in the format you choose. The output is directed to stdout (normally your screen) and in the format you specify. You can specify the following formats: **html**, **rtf** or **text** (default). To create a file with the descriptions, you must redirect the output.

With the suboption **all**, the descriptions of all error messages are given. If you want the description of one or more selected error messages, you can specify the error message numbers, separated by commas.

With this option the linker does not link/locate any files.

Example

To display an explanation of message number 106, enter:

```
lkarm --diaq=106
```

This results in the following message and explanation:

```
E106: unresolved external: <message>
The linker could not resolve all external symbols.
```

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This is an error when the incremental linking option is disabled. The <message> indicates the symbol that is unresolved.

To write an explanation of all errors and warnings in HTML format to file lkerrors.html, use redirection and enter:

lkarm --diag=html:all > lkerrors.html

Related information

Section 8.10, Linker Error Messages

Linker option: --endianness

Menu entry

- 1. Select Global Options.
- 2. Specify the Endianness:Little-endian mode or Big-endian mode.

Command line syntax

--endianness=endianness

-B

--big-endian

You can specify the following endianness:

big b Big endian

little I Little endian (default)

Description

By default, the linker links objects in little-endian mode. With **--endianness=big** you tell the linker to link the input files in big-endian mode. The endianess used must be valid for the architecture you are linking for. Depending on the endianess used, the linker links different libraries. **-B** is an alias for option **--endianness=big**.

Related information

_

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Linker option: --error-file

Menu entry

_

Command line syntax

```
--error-file[=file]
```

Description

With this option the linker redirects error messages to a file. If you do not specify a filename, the error file is lkarm.elk.

Example

To write errors to errors.elk instead of stderr, enter:

```
lkarm --error-file=errors.elk test.obj
```

Related information

Section 8.10, Linker Error Messages

Linker option: --error-limit

Menu entry

_

Command line syntax

--error-limit=number

Default: 42

Description

With this option you tell the linker to only emit the specified maximum number of errors. When 0 (null) is specified, the linker emits all errors. Without this option the maximum number of errors is 42.

Related information

Section 8.10, Linker Error Messages

Linker option: --extern (-e)

Menu entry

-

Command line syntax

```
--extern=symbol,...
-esymbol,...
```

Description

With this option you force the linker to consider the given symbol as an undefined reference. The linker tries to resolve this symbol, either the symbol is defined in an object file or the linker extracts the corresponding symbol definition from a library.

This option is, for example, useful if the startup code is part of a library. Because your own application does not refer to the startup code, you can force the startup code to be extracted by specifying the symbol _START as an unresolved external.

Example

Consider the following invocation:

```
lkarm mylib.lib
```

Nothing is linked and no output file will be produced, because there are no unresolved symbols when the linker searches through mylib.lib.

```
lkarm --extern=_START mylib.lib
```

In this case the linker searches for the symbol _START in the library and (if found) extracts the object that contains _START, the startup code. If this module contains new unresolved symbols, the linker looks again in mylib.lib. This process repeats until no new unresolved symbols are found.

Related information

Section 8.3, Linking with Libraries

Linker option: --first-library-first

Menu entry

_

Command line syntax

--first-library-first

Description

When the linker processes a library it searches for symbols that are referenced by the objects and libraries processed so far. If the library contains a definition for an unresolved reference the linker extracts the object that contains the definition from the library.

By default the linker processes object files and libraries in the order in which they appear on the command line. If you specify the option **--first-library-first** the linker always tries to take the symbol definition from the library that appears first on the command line before scanning subsequent libraries.

This is for example useful when you are working with a newer version of a library that partially overlaps the older version. Because they do not contain exactly the same functions, you have to link them both. However, when a function is present in both libraries, you may want the linker to extract the most recent function.

Example

Consider the following example:

```
lkarm --first-library-first a.lib test.obj b.lib
```

If the file test.obj calls a function which is both present in a.lib and b.lib, normally the function in b.lib would be extracted. With this option the linker first tries to extract the symbol from the first library a.lib.

Note that routines in b.lib that call other routines that are present in both a.lib and b.lib are now also resolved from a.lib.

Related information

Linker option --no-rescan (Rescan libraries to solve unresolved externals)

Linker option: --global-type-checking

Menu entry

_

Command line syntax

--global-type-checking

Description

Use this option when you want the linker to check the types of variable and function references against their definitions, using DWARF 2 or DWARF 3 debug information.

This check should give the same result as the C compiler when you use MIL linking.

Related information

C compiler option --global-type-checking (Global type checking)

Linker option: --help (-?)

Menu entry

_

Command line syntax

```
--help[=item]
--?
```

You can specify the following arguments:

options

Show extended option descriptions

Description

Displays an overview of all command line options. When you specify the argument **options** you can list detailed option descriptions.

Example

The following invocations all display a list of the available command line options:

```
lkarm -?
lkarm --help
lkarm
```

To see a detailed description of the available options, enter:

```
lkarm --help=options
```

Related information

Linker option: --hex-format

Menu entry

- 1. Select Linker » Output Format.
- 2. Enable the option Generate Intel Hex format file.
- 3. Enable or disable the option Emit start address record.

Command line syntax

```
--hex-format=flag,...
```

You can set the following flag:

+/-start-address s/S Emit start address record

Default: --hex-format=s

Description

With this option you can specify to emit or omit the start address record from the hex file.

Related information

Linker option --output (Output file)

Linker option: --hex-record-size

Menu entry

- 1. Select Linker » Output Format.
- 2. Enable the option Generate Intel Hex format file.
- 3. Select Linker » Miscellaneous.
- 4. Add the option --hex-record-size to the Additional options field.

Command line syntax

--hex-record-size=size

Default: 32

Description

With this option you can set the size (width) of the Intel Hex data records.

Related information

Linker option --output (Output file)

Section 15.2, Intel Hex Record Format

Linker option: --import-object

Menu entry

Select Linker » Data Objects.

The Data objects box shows the list of object files that are imported.

- 2. To add a data object, click on the **Add** button in the **Data objects** box.
- 3. Type or select a binary file (including its path).

Use the Edit and Delete button to change a filename or to remove a data object from the list.

Command line syntax

```
--import-object=file,...
```

Description

With this option the linker imports a binary *file* containing raw data and places it in a section. The section name is derived from the filename, in which dots are replaced by an underscore. So, when importing a file called my.jpg, a section with the name my_jpg is created. In your application you can refer to the created section by using linker labels.

Related information

Section 8.5, Importing Binary Files

Linker option: --include-directory (-I)

Menu entry

-

Command line syntax

```
--include-directory=path,...
-Ipath,...
```

Description

With this option you can specify the path where your LSL include files are located. A relative path will be relative to the current directory.

The order in which the linker searches for LSL include files is:

- 1. The pathname in the LSL file and the directory where the LSL file is located (only for #include files that are enclosed in "")
- 2. The path that is specified with this option.
- 3. The default directory \$(PRODDIR)\include.lsl.

Example

Suppose that your linker script file mylsl.lsl contains the following line:

```
#include "myinc.inc"
```

You can call the linker as follows:

```
lkarm --include-directory=c:\proj\include --lsl-file=mylsl.lsl test.obj
```

First the linker looks for the file myinc.inc in the directory where mylsl.lsl is located. If it does not find the file, it looks in the directory c:\proj\include (this option). Finally it looks in the directory \$(PRODDIR)\include.lsl.

Related information

Linker option --IsI-file (Specify linker script file)

Linker option: --incremental (-r)

Menu entry

_

Command line syntax

--incremental

-r

Description

Normally the linker links and locates the specified object files. With this option you tell the linker only to link the specified files. The linker creates a linker output file .out. You then can link this file again with other object files until you have reached the final linker output file that is ready for locating.

In the last pass, you call the linker without this option with the final linker output file .out. The linker will now locate the file.

Example

In this example, the files test1.obj, test2.obj and test3.obj are incrementally linked:

```
1. lkarm --incremental test1.obj test2.obj --output=test.out
    test1.obj and test2.obj are linked
```

 lkarm --incremental test3.obj test.out test3.obj and test.out are linked, task1.out is created

3. lkarm task1.out

task1.out is located

Related information

Section 8.4, Incremental Linking

Linker option: --keep-output-files (-k)

Menu entry

Eclipse always removes the output files when errors occurred.

Command line syntax

```
--keep-output-files
```

-k

Description

If an error occurs during linking, the resulting output file may be incomplete or incorrect. With this option you keep the generated output files when an error occurs.

By default the linker removes the generated output file when an error occurs. This is useful when you use the make utility. If the erroneous files are not removed, the make utility may process corrupt files on a subsequent invocation.

Use this option when you still want to use the generated file. For example when you know that a particular error does not result in a corrupt object file, or when you want to inspect the output file, or send it to Altium support.

Related information

Linker option --warnings-as-errors (Treat warnings as errors)

Linker option: --library (-I)

Menu entry

1. Select Linker » Libraries.

The Libraries box shows the list of libraries that are linked with the project.

- 2. To add a library, click on the **Add** button in the **Libraries** box.
- 3. Type or select a library (including its path).
- Optionally, disable the option Link default libraries.

Use the Edit and Delete button to change a library name or to remove a library from the list.

Command line syntax

--library=name

-lname

Description

With this option you tell the linker to use system library *name*.lib, where *name* is a string. The linker first searches for system libraries in any directories specified with --library-directory, then in the directories specified with the environment variables LIBARM, unless you used the option --ignore-default-library-path.

Example

To search in the system library carm.lib (C library):

```
lkarm test.obj mylib.lib --library=carm
```

The linker links the file test.obj and first looks in library mylib.lib (in the current directory only), then in the system library carm.lib to resolve unresolved symbols.

Related information

Linker option --library-directory (Additional search path for system libraries)

Section 8.3, Linking with Libraries

Linker option: --library-directory (-L) / --ignore-default-library-path

Menu entry

1. Select Linker » Libraries.

The Library search path box shows the directories that are added to the search path for library files.

- To define a new directory for the search path, click on the Add button in the Library search path box.
- 3. Type or select a path.

Use the **Edit** and **Delete** button to change a path or to remove a path from the list.

Command line syntax

```
--library-directory=path,...
-Lpath,...
--ignore-default-library-path
-L
```

Description

With this option you can specify the path(s) where your system libraries, specified with the option --library (-I), are located. If you want to specify multiple paths, use the option --library-directory for each separate path.

The default path is (PRODDIR) \lib\architecture\endianness.

If you specify only **-L** (without a pathname) or the long option **--ignore-default-library-path**, the linker will not search the default path and also not in the paths specified in the environment variables LIBARM. So, the linker ignores steps 2 and 3 as listed below.

The priority order in which the linker searches for system libraries specified with the option --library (-I) is:

- 1. The path that is specified with the option --library-directory.
- 2. The path that is specified in the environment variables LIBARM.
- 3. The default directory \$(PRODDIR)\libarchitecture\endianness.

Example

Suppose you call the linker as follows:

```
lkarm test.obj --library-directory=c:\mylibs --library=carm
```

First the linker looks in the directory c:\mylibs for library carm.lib (this option). If it does not find the requested libraries, it looks in the directory that is set with the environment variables LIBARM. Then the linker looks in the default directory \$(PRODDIR)\libarchitecture\endianness for libraries.

Related information

Linker option --library (Link system library)

Linker option --cpu (Select architecture)

Linker option --endianness (Specify endianness)

Section 8.3.1, How the Linker Searches Libraries

Linker option: --link-only

Menu entry

_

Command line syntax

--link-only

Description

With this option you suppress the locating phase. The linker stops after linking and informs you about unresolved references.

Related information

Control program option --create=relocatable (-cl) (Stop after linking)

Linker option: --long-branch-veneers

Menu entry

- Select Linker » Miscellaneous.
- Enable the option Generate long-branch veneers.

Command line syntax

--long-branch-veneers

Description

With this option you enable the linker to generate a long-branch veneer if the target of a B (ARM only, not for Thumb), BL or BLX instruction is out-of-range. The locating process of the linker may become less efficient if this option is switched on, even if no long-branch veneers are required after all. Therefore it is better to first see if out-of-range branches are in the code (unlikely) before switching on this option. You cannot use this option with the ARMv6-M architecture profile.

Related information

Linker option: --Isl-check

Menu entry

_

Command line syntax

--1sl-check

Description

With this option the linker just checks the syntax of the LSL file(s) and exits. No linking or locating is performed. Use the option --IsI-file to specify the name of the Linker Script File you want to test.

Related information

Linker option --IsI-file (Linker script file)

Linker option --IsI-dump (Dump LSL info)

Section 8.7, Controlling the Linker with a Script

Linker option: --Isl-dump

Menu entry

_

Command line syntax

--lsl-dump[=file]

Description

With this option you tell the linker to dump the LSL part of the map file in a separate file, independent of the option --map-file (generate map file). If you do not specify a filename, the file lkarm.ldf is used.

Related information

Linker option --map-file-format (Map file formatting)

Linker option: --IsI-file (-d)

Menu entry

An LSL file can be generated when you create your project in Eclipse:

 From the File menu, select File » New » Other... » TASKING C/C++ » TASKING VX-toolset for ARM C/C++ Project.

The New C/C++ Project wizard appears.

- 2. Fill in the project settings in each dialog and click **Next** > until the **ARM Project Settings** appear.
- 3. Enable the option Add Linker script file to the project and click Finish.

Eclipse creates your project and the file project. 1s1 in the project directory.

The LSL file can be specified in the Properties dialog:

- 1. Select Linker » Script File.
- 2. Specify a LSL file in the Linker script file (.Isl) field (default .../\${PROJ}.lsl).

Command line syntax

```
\textbf{--lsl-file} = file
```

-dfile

Description

A linker script file contains vital information about the core for the locating phase of the linker. A linker script file is coded in LSL and contains the following types of information:

- the architecture definition describes the core's hardware architecture.
- · the memory definition describes the physical memory available in the system.
- the section layout definition describes how to locate sections in memory.

With this option you specify a linker script file to the linker. If you do not specify this option, the linker uses a default script file. You can specify the existing file <code>arm.lsl</code> or the name of a manually written linker script file. You can use this option multiple times. The linker processes the LSL files in the order in which they appear on the command line.

Related information

Linker option --IsI-check (Check LSL file(s) and exit)

Section 8.7. Controlling the Linker with a Script

Linker option: --map-file (-M)

Menu entry

- 1. Select Linker » Map File.
- 2. Enable the option Generate map file.
- 3. Enable or disable the types of information to be included.

Command line syntax

```
--map-file[=file]
-M[file]
```

Default: no map file is generated

Description

With this option you tell the linker to generate a linker map file. If you do not specify a filename and you specified the option --output, the linker uses the same basename as the output file with the extension .map. If you did not specify the option --output, the linker uses the file task1.map. Eclipse names the .map file after the project.

A linker map file is a text file that shows how the linker has mapped the sections and symbols from the various object files (.obj) to the linked object file. A locate part shows the absolute position of each section. External symbols are listed per space with their absolute address, both sorted on symbol and sorted on address.

Related information

Linker option --map-file-format (Format map file)

Section 14.2, Linker Map File Format

Linker option: --map-file-format (-m)

Menu entry

- 1. Select Linker » Map File.
- 2. Enable the option Generate map file.
- 3. Enable or disable the types of information to be included.

Command line syntax

```
--map-file-format=flag,...
-mflags
```

You can set the following flags:

+/-callgraph	c/C	Include call graph information
+/-removed	d/D	Include information on removed sections
+/-files	f/F	Include processed files information
+/-invocation	i/I	Include information on invocation and tools
+/-link	k/K	Include link result information
+/-locate	I/L	Include locate result information
+/-memory	m/M	Include memory usage information
+/-nonalloc	n/N	Include information of non-alloc sections
+/-overlay	o/O	Include overlay information
+/-statics	q/Q	Include module local symbols information
+/-crossref	r/R	Include cross references information
+/-IsI	s/S	Include processor and memory information
+/-rules	u/U	Include locate rules

Use the following options for predefined sets of flags:

map-file-format=0	-m0	Link information Alias for -mcDfikLMNoQrSU
map-file-format=1	-m1	Locate information Alias for -mCDfiKIMNoQRSU
map-file-format=2	-m2	Most information Alias for -mcdfiklmNoQrSu

Default: --map-file-format=2

Description

With this option you specify which information you want to include in the map file.

On the command line you must use this option in combination with the option --map-file (-M).

Related information

Linker option --map-file (Generate map file)

Section 14.2, Linker Map File Format

Linker option: --misra-c-report

Menu entry

_

Command line syntax

```
--misra-c-report[=file]
```

Description

With this option you tell the linker to create a MISRA-C Quality Assurance report. This report lists the various modules in the project with the respective MISRA-C settings at the time of compilation. If you do not specify a filename, the file <code>basename.mcr</code> is used.

Related information

C compiler option --misrac (MISRA-C checking)

Linker option: --munch

Menu entry

_

Command line syntax

--munch

Description

With this option you tell the linker to activate the muncher in the pre-locate phase.

The muncher phase is a special part of the linker that creates sections containing a list of pointers to the initialization and termination routines. The list of pointers is consulted at run-time by startup code invoked from main, and the routines on the list are invoked at the appropriate times.

Related information

Linker option: --non-romable

Menu entry

- 1. Select Linker » Miscellaneous.
- 2. Enable the option **Application is not romable**.

Command line syntax

--non-romable

Description

With this option you tell the linker that the application is not romable. The linker will locate all ROM sections in RAM. A copy table is generated and is located in RAM. When the application is started, that data and BSS sections are re-initialized.

Related information

Linker option: --no-rescan

Menu entry

- Select Linker » Libraries.
- 2. Disable the option Rescan libraries to solve unresolved externals.

Command line syntax

--no-rescan

Description

When the linker processes a library it searches for symbol definitions that are referenced by the objects and libraries processed so far. If the library contains a definition for an unresolved reference the linker extracts the object that contains the definition from the library. The linker processes object files and libraries in the order in which they appear on the command line.

When all objects and libraries are processed the linker checks if there are unresolved symbols left. If so, the default behavior of the linker is to rescan all libraries in the order given at the command line. The linker stops rescanning the libraries when all symbols are resolved, or when the linker could not resolve any symbol(s) during the rescan of all libraries. Notice that resolving one symbol may introduce new unresolved symbols.

With this option, you tell the linker to scan the object files and libraries only once. When the linker has not resolved all symbols after the first scan, it reports which symbols are still unresolved. This option is useful if you are building your own libraries. The libraries are most efficiently organized if the linker needs only one pass to resolve all symbols.

Related information

Linker option --first-library-first (Scan libraries in given order)

Linker option: --no-rom-copy (-N)

Menu entry

-

Command line syntax

```
--no-rom-copy
```

-N

Description

With this option the linker will not generate a ROM copy for data sections. A copy table is generated and contains entries to clear BSS sections. However, no entries to copy data sections from ROM to RAM are placed in the copy table.

The data sections are initialized when the application is downloaded. The data sections are not re-initialized when the application is restarted.

Related information

Linker option: --no-warnings (-w)

Menu entry

1. Select Linker » Diagnostics.

The Suppress warnings box shows the warnings that are currently suppressed.

- 2. To suppress a warning, click on the **Add** button in the **Suppress warnings** box.
- 3. Enter the numbers, separated by commas, of the warnings you want to suppress (for example 135,136). Or you can use the **Add** button multiple times.
- 4. To suppress all warnings, enable the option Suppress all warnings.

Use the Edit and Delete button to change a warning number or to remove a number from the list.

Command line syntax

```
--no-warnings[=number,...]
-w[number,...]
```

Description

With this option you can suppresses all warning messages or specific warning messages.

On the command line this option works as follows:

- If you do not specify this option, all warnings are reported.
- If you specify this option but without numbers, all warnings are suppressed.
- If you specify this option with a number, only the specified warning is suppressed. You can specify the
 option --no-warnings=number multiple times.

Example

To suppress warnings 135 and 136, enter:

```
lkarm --no-warnings=135,136 test.obj
```

Related information

Linker option --warnings-as-errors (Treat warnings as errors)

Linker option: --optimize (-O)

Menu entry

- 1. Select Linker » Optimization.
- 2. Select one or more of the following options:
 - · Delete unreferenced sections
 - Use a 'first-fit decreasing' algorithm
 - · Compress copy table
 - · Delete duplicate code
 - Delete duplicate data

Command line syntax

```
--optimize=flag,...
```

-Oflags

You can set the following flags:

+/-delete-unreferenced-sections	c/C	Delete unreferenced sections from the output file
+/-first-fit-decreasing	I/L	Use a 'first-fit decreasing' algorithm to locate unrestricted sections in memory
+/-copytable-compression	t/T	Emit smart restrictions to reduce copy table size
+/-delete-duplicate-code	x/X	Delete duplicate code sections from the output file
+/-delete-duplicate-data	y/Y	Delete duplicate constant data from the output file

Use the following options for predefined sets of flags:

optimize=0	-00	No optimization Alias for -OCLTXY
optimize=1	-01	Default optimization Alias for -OcLtXY
optimize=2	-02	All optimizations Alias for -Ocltxy

Default: --optimize=1

Description

With this option you can control the level of optimization.

Related information

For details about each optimization see Section 8.6, Linker Optimizations.

Linker option: --option-file (-f)

Menu entry

- 1. Select Linker » Miscellaneous.
- 2. Add the option **--option-file** to the **Additional options** field.

Be aware that the options in the option file are added to the linker options you have set in the other pages. Only in extraordinary cases you may want to use them in combination.

Command line syntax

```
--option-file=file,...
-f file,...
```

Description

This option is primarily intended for command line use. Instead of typing all options on the command line, you can create an option file which contains all options and flags you want to specify. With this option you specify the option file to the linker.

Use an option file when the command line would exceed the limits of the operating system, or just to store options and save typing.

Option files can also be generated on the fly, for example by the make utility. You can specify the option **--option-file** multiple times.

Format of an option file

- Multiple arguments on one line in the option file are allowed.
- To include whitespace in an argument, surround the argument with single or double quotes.
- If you want to use single quotes as part of the argument, surround the argument by double quotes and vise versa:

```
"This has a single quote ' embedded"

'This has a double quote " embedded'

'This has a double quote " and a single quote '"' embedded"
```

When a text line reaches its length limit, use a \ to continue the line. Whitespace between quotes is
preserved.

```
"This is a continuation \ line" -> "This is a continuation line"
```

• It is possible to nest command line files up to 25 levels.

Example

Suppose the file myoptions contains the following lines:

```
--map-file=my.map (generate a map file)
test.obj (input file)
--library-directory=c:\mylibs (additional search path for system libraries)
```

Specify the option file to the linker:

```
lkarm --option-file=myoptions
```

This is equivalent to the following command line:

```
lkarm --map-file=my.map test.obj --library-directory=c:\mylibs
```

Related information

Linker option: --output (-o)

Menu entry

- 1. Select Linker » Output Format.
- 2. Enable one or more output formats.

For some output formats you can specify a number of suboptions.

Eclipse always uses the project name as the basename for the output file.

Command line syntax

```
--output=[filename][:format[:addr_size][,space_name]]...
-o[filename][:format[:addr_size]]...
```

You can specify the following formats:

ELF ELF/DWARF
IHEX Intel Hex

SREC Motorola S-records

Description

By default, the linker generates an output file in ELF/DWARF format, with the name task1.abs.

With this option you can specify an alternative *filename*, and an alternative output *format*. The default output format is the format of the first input file.

You can use the **--output** option multiple times. This is useful to generate multiple output formats. With the first occurrence of the **--output** option you specify the basename (the filename without extension), which is used for subsequent **--output** options with no filename specified. If you do not specify a filename, or you do not specify the **--output** option at all, the linker uses the default basename task *n*.

IHEX and SREC formats

If you specify the Intel Hex format or the Motorola S-records format, you can use the argument *addr_size* to specify the size of addresses in bytes (record length). For Intel Hex you can use the values: 1, 2, and 4 (default). For Motorola S-records you can specify: 2 (S1 records), 3 (S2 records, default) or 4 bytes (S3 records).

The name of the output file will be *filename* with the extension .hex or .sre and contains the code and data allocated in the default address space. If they exist, any other address spaces are also emitted whereas their output files are named *filename_spacename* with the extension .hex or .sre.

Use option **--chip-output** (**-c**) to create Intel Hex or Motorola S-record output files for each chip defined in the LSL file (suitable for loading into a PROM-programmer).

Example

To create the output file myfile.hex of the default address space, enter:

lkarm test.obj --output=myfile.hex:IHEX:4

Related information

Linker option --chip-output (Generate an output file for each chip)

Linker option --hex-format (Specify Hex file format settings)

Linker option: --print-mangled-symbols (-P)

Menu entry

-

Command line syntax

--print-mangled-symbols

-P

Description

C++ compilers generate unreadable symbol names. These symbols cannot easily be related to your C++ source file anymore. Therefore the linker will by default decode these symbols conform the IA64 ABI when printed to stdout. With this option you can override this default setting and print the mangled names instead.

Related information

Linker option: --strip-debug (-S)

Menu entry

- 1. Select Linker » Miscellaneous.
- 2. Enable the option **Strip symbolic debug information**.

Command line syntax

```
--strip-debug
```

-s

Description

With this option you specify not to include symbolic debug information in the resulting output file.

Related information

Linker option: --user-provided-initialization-code (-i)

Menu entry

- 1. Select Linker » Miscellaneous.
- 2. Enable the option **Do not use standard copy table for initialization**.

Command line syntax

--user-provided-initialization-code

-i

Description

It is possible to use your own initialization code, for example, to save ROM space. With this option you tell the linker *not* to generate a copy table for initialize/clear sections. Use linker labels in your source code to access the positions of the sections when located.

If the linker detects references to the TASKING initialization code, an error is emitted: it is either the TASKING initialization routine or your own, not both.

Note that the options --no-rom-copy and --non-romable, may vary independently. The 'copytable-compression' optimization (--optimize=t) is automatically disabled when you enable this option.

Related information

Linker option --no-rom-copy (Do not generate ROM copy)

Linker option --non-romable (Application is not romable)

Linker option --optimize (Specify optimization)

Linker option: --verbose (-v) / --extra-verbose (-vv)

Menu entry

- 1. Select Linker » Miscellaneous.
- Enable the option Show link phases during processing.

The verbose output is displayed in the Problems view and the Console view.

Command line syntax

```
--verbose / --extra-verbose
-v / -vv
```

Description

With this option you put the linker in *verbose* mode. The linker prints the link phases while it processes the files. In the *extra verbose* mode, the linker also prints the filenames and it shows which objects are extracted from libraries. With this option you can monitor the current status of the linker.

Related information

Linker option: --version (-V)

Menu entry

_

Command line syntax

--version

-v

Description

Display version information. The linker ignores all other options or input files.

Related information

-

Linker option: --warnings-as-errors

Menu entry

- Select Global Options.
- 2. Enable the option **Treat warnings as errors**.

Command line syntax

```
--warnings-as-errors[=number,...]
```

Description

When the linker detects an error or warning, it tries to continue the link process and reports other errors and warnings. When you use this option without arguments, you tell the linker to treat all warnings as errors. This means that the exit status of the linker will be non-zero after the detection of one or more linker warnings. As a consequence, the linker will not produce any output files.

You can also limit this option to specific warnings by specifying a comma-separated list of warning numbers.

Related information

Linker option --no-warnings (Suppress some or all warnings)

12.5. Control Program Options

The control program **ccarm** facilitates the invocation of the various components of the ARM toolset from a single command line.

Options in Eclipse versus options on the command line

Eclipse invokes the compiler, assembler and linker via the control program. Therefore, it uses the syntax of the control program to pass options and files to the tools. The control program processes command line options either by itself, or, when the option is unknown to the control program, it looks whether it can pass the option to one of the other tools. However, for directly passing an option to the C++ compiler, C compiler, assembler or linker, it is recommended to use the control program options --pass-c++, --pass-c, --pass-assembler, --pass-linker.

See the previous sections for details on the options of the tools.

Short and long option names

Options can have both short and long names. Short option names always begin with a single minus (-) character, long option names always begin with two minus (--) characters. You can abbreviate long option names as long as it forms a unique name. You can mix short and long option names on the command line.

Options can have flags or suboptions. To switch a flag 'on', use a lowercase letter or a +longflag. To switch a flag off, use an uppercase letter or a -longflag. Separate longflags with commas. The following two invocations are equivalent:

```
ccarm -Wc-Oac test.c
ccarm --pass-c=--optimize=+coalesce,+cse test.c
```

When you do not specify an option, a default value may become active.

Control program option: --address-size

Menu entry

- Select Linker » Output Format.
- 2. Enable the option Generate Intel Hex format file and/or Generate S-records file.
- 3. Specify the Size of addresses.

Eclipse always uses the project name as the basename for the output file.

Command line syntax

--address-size=addr_size

Description

If you specify IHEX or SREC with the control option **--format**, you can additionally specify the record length to be emitted in the output files.

With this option you can specify the size of the addresses in bytes (record length). For Intel Hex you can use the values 1, 2 or 4 bytes (default). For Motorola-S you can specify: 2 (S1 records), 3 (S2 records) or 4 bytes (S3 records, default).

If you do not specify addr_size, the default address size is generated.

Example

To create the SREC file test.sre with S1 records, type:

```
ccarm --format=SREC --address-size=2 test.c
```

Related information

Control program option --format (Set linker output format)

Control program option --output (Output file)

Control program option: --check

Menu entry

_

Command line syntax

--check

Description

With this option you can check the source code for syntax errors, without generating code. This saves time in developing your application because the code will not actually be compiled.

The compiler/assembler reports any warnings and/or errors.

This option is available on the command line only.

Related information

C compiler option --check (Check syntax)

Assembler option --check (Check syntax)

Control program option: --cpu (-C)

Menu entry

- 1. Expand C/C++ Build and select Processor.
- 2. From the Processor Selection list, make a selection by Architecture, Core or Manufacturer.

Command line syntax

--cpu=architecture

-Carchitecture

You can specify the following architectures:

ARMv4 Compile/assemble for ARMv4 architecture
ARMv4T Compile/assemble for ARMv4T architecture
ARMv5T Compile/assemble for ARMv5T architecture
ARMv5TE Compile/assemble for ARMv5TE architecture

ARMv6M Compile/assemble for ARMv6-M architecture profile
ARMv7M Compile/assemble for ARMv7-M architecture profile

XS Compile/assemble for XScale core

Description

With this option you specify the ARM architecture for which you create your application. The architecture determines which instructions are valid and which are not. If the architecture is ARMv4 the linker replaces BX instructions by MOV PC instructions. The default architecture is ARMv4T and the complete list of supported architectures is: ARMv4, ARMv4T, ARMv5T, ARMv5TE, ARMv6-M, ARMv7-M or XScale.

Assembly code can check the value of the option by means of the built-in function @CPU(). Architecture ARMv4 does not support the Thumb instruction set. Architecture profile ARMv7-M only supports the Thumb-2 instruction set, i.e. it has no ARM execution state.

Related information

C compiler option --cpu (Select architecture)

Assembler option --cpu (Select architecture)

Assembly function @CPU()

Control program option: --create (-c)

Menu entry

_

Command line syntax

```
--create[=stage]
-c[stage]
```

You can specify the following stages:

intermediate-c	С	Stop after C++ files are compiled to intermediate C files (.ic)
relocatable	I	Stop after the files are linked to a linker object file (.out)
mil	m	Stop after C++ files or C files are compiled to MIL (.mil)
object	ο	Stop after the files are assembled to objects (.obj)
assembly	s	Stop after C++ files or C files are compiled to assembly (.src)

Default (without flags): --create=object

Description

Normally the control program generates an absolute object file of the specified output format from the file you supplied as input. With this option you tell the control program to stop after a certain number of phases.

Example

To generate the object file test.obj:

```
ccarm --create test.c
```

The control program stops after the file is assembled. It does not link nor locate the generated output.

Related information

Linker option --link-only (Link only, no locating)

Control program option: --debug-info (-g)

Menu entry

- Select C/C++ Compiler » Debugging.
- To generate symbolic debug information, select Default, Call-frame only or Full.
 To disable the generation of debug information, select None.

Command line syntax

```
--debug-info
```

-g

Description

With this option you tell the control program to include debug information in the generated object file.

The control program passes the option **--debug-info** (**-g**) to the C compiler and calls the assembler with **--debug-info=+smart** (**-g**).

Related information

C compiler option --debug-info (Generate symbolic debug information)

Assembler option --debug-info (Generate symbolic debug information)

Control program option: --define (-D)

Menu entry

1. Select C/C++ Compiler » Preprocessing and/or Assembler » Preprocessing.

The Defined symbols box right-below shows the symbols that are currently defined.

- 2. To define a new symbol, click on the **Add** button in the **Defined symbols** box.
- 3. Type the symbol definition (for example, demo=1)

Use the Edit and Delete button to change a macro definition or to remove a macro from the list.

Command line syntax

```
--define=macro_name[=macro_definition]
-Dmacro_name[=macro_definition]
```

Description

With this option you can define a macro and specify it to the preprocessor. If you only specify a macro name (no macro definition), the macro expands as '1'.

You can specify as many macros as you like. Simply use the Add button to add new macro definitions.

On the command line, use the option **--define** (**-D**) multiple times. If the command line exceeds the limit of the operating system, you can define the macros in an option file which you then must specify to the compiler with the option **--option-file** (**-f**) *file*.

Defining macros with this option (instead of in the C source) is, for example, useful to compile conditional C source as shown in the example below.

The control program passes the option --define (-D) to the compiler and the assembler.

Example

Consider the following C program with conditional code to compile a demo program and a real program:

```
void main( void )
{
#if DEMO
    demo_func();    /* compile for the demo program */
#else
    real_func();    /* compile for the real program */
#endif
}
```

You can now use a macro definition to set the DEMO flag:

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```
ccarm --define=DEMO test.c
ccarm --define=DEMO=1 test.c
```

Note that both invocations have the same effect.

The next example shows how to define a macro with arguments. Note that the macro name and definition are placed between double quotes because otherwise the spaces would indicate a new option.

```
ccarm --define="MAX(A,B)=((A) > (B) ? (A) : (B))" test.c
```

Related information

Control program option --undefine (Remove preprocessor macro)

Control program option --option-file (Specify an option file)

Control program option: --diag

Menu entry

1. From the Window menu, select Show View » Other » General » Problems.

The Problems view is added to the current perspective.

2. In the Problems view right-click on a message.

A popup menu appears.

3. Select Detailed Diagnostics Info.

A dialog box appears with additional information.

Command line syntax

```
--diag=[format:]{all | nr,...}
```

You can set the following output formats:

html HTML output.

rtf Rich Text Format.

text ASCII text.

Default format: text

Description

With this option you can ask for an extended description of error messages in the format you choose. The output is directed to stdout (normally your screen) and in the format you specify. You can specify the following formats: **html**, **rtf** or **text** (default). To create a file with the descriptions, you must redirect the output.

With the suboption **all**, the descriptions of all error messages are given. If you want the description of one or more selected error messages, you can specify the error message numbers, separated by commas.

Example

To display an explanation of message number 103, enter:

```
ccarm --diag=103
```

This results in message 103 with explanation.

To write an explanation of all errors and warnings in HTML format to file ccerrors.html, use redirection and enter:

```
ccarm --diag=html:all > ccerrors.html
```

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Related information

Section 4.7, C Compiler Error Messages

Control program option: --dry-run (-n)

Menu entry

_

Command line syntax

```
--dry-run
```

-n

Description

With this option you put the control program in verbose mode. The control program prints the invocations of the tools it would use to process the files without actually performing the steps.

Related information

Control program option --verbose (Verbose output)

Control program option: --endianness

Menu entry

- 1. Select Global Options.
- 2. Specify the Endianness:Little-endian mode or Big-endian mode.

Command line syntax

--endianness=endianness

-B

--big-endian

You can specify the following endianness:

big b Big endian

little I Little endian (default)

Description

By default, the compiler generates code for a little-endian target (least significant byte of a word at lowest byte address). With **--endianness=big** the compiler generates code for a big-endian target (most significant byte of a word at lowest byte address). **-B** is an alias for option **--endianness=big**.

Related information

-

Control program option: --error-file

Menu entry

_

Command line syntax

```
--error-file
```

Description

With this option the control program tells the compiler, assembler and linker to redirect error messages to a file.

The error file will be named after the input file with extension .err (for compiler) or .ers (for assembler). For the linker, the error file is <code>lkarm.elk</code>.

Example

To write errors to error files instead of stderr, enter:

```
ccarm --error-file -t test.c
```

Related information

Control Program option --warnings-as-errors (Treat warnings as errors)

Control program option: --exceptions

Menu entry

- 1. Select C/C++ Compiler » Language.
- 2. Enable the option Support for C++ exception handling.

Command line syntax

--exceptions

Description

With this option you enable support for exception handling in the C++ compiler.

Related information

-

Control program option: --force-c

Menu entry

_

Command line syntax

--force-c

Description

With this option you tell the control program to treat all . cc files as C files instead of C++ files. This means that the control program does not call the C++ compiler and forces the linker to link C libraries.

Related information

Control program option --force-c++ (Force C++ compilation and linking)

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Control program option: --force-c++

Menu entry

Eclipse always uses this option for a C++ project.

Command line syntax

--force-c++

Description

With this option you tell the control program to treat all . c files as C++ files instead of C files. This means that the control program calls the C++ compiler prior to the C compiler and forces the linker to link C++ libraries.

Related information

Control program option --force-c (Treat C++ files as C files)

Control program option: --force-munch

Menu entry

Eclipse always uses this option for a C++ project.

Command line syntax

--force-munch

Description

With this option you force the control program to activate the muncher in the pre-locate phase.

Related information

-

Control program option: --format

Menu entry

- Select Linker » Output Format.
- 2. Enable the option Generate Intel Hex format file and/or Generate S-records file.
- 3. Optionally, specify the Size of addresses.

Eclipse always uses the project name as the basename for the output file.

Command line syntax

```
--format=format
```

You can specify the following formats:

ELF ELF/DWARF
IHEX Intel Hex

SREC Motorola S-records

Description

With this option you specify the output format for the resulting (absolute) object file. The default output format is ELF/DWARF, which can directly be used by the debugger.

If you choose IHEX or SREC, you can additionally specify the address size of the chosen format (option **--address-size**).

Example

To generate a Motorola S-record output file:

```
ccarm --format=SREC test1.c test2.c --output=test.sre
```

Related information

Control program option --address-size (Set address size for linker IHEX/SREC files)

Control program option --output (Output file)

Linker option --chip-output (Generate an output file for each chip)

Control program option: --help (-?)

Menu entry

_

Command line syntax

```
--help[=item]
--?
```

You can specify the following argument:

options

Show extended option descriptions

Description

Displays an overview of all command line options. When you specify the argument **options** you can list detailed option descriptions.

Example

The following invocations all display a list of the available command line options:

```
ccarm -?
ccarm --help
ccarm
```

To see a detailed description of the available options, enter:

```
ccarm --help=options
```

Related information

-

Control program option: --include-directory (-I)

Menu entry

1. Select C/C++ Compiler » Include Paths.

The Include paths box shows the directories that are added to the search path for include files.

- 2. To define a new directory for the search path, click on the **Add** button in the **Include paths** box.
- 3. Type or select a path.

Use the Edit and Delete button to change a path or to remove a path from the list.

Command line syntax

```
--include-directory=path,...
-Ipath,...
```

Description

With this option you can specify the path where your include files are located. A relative path will be relative to the current directory.

The control program passes this option to the compiler and the assembler.

Example

Suppose that the C source file test.c contains the following lines:

```
#include <stdio.h>
#include "myinc.h"
```

You can call the control program as follows:

```
ccarm --include-directory=myinclude test.c
```

First the compiler looks for the file stdio.h in the directory myinclude relative to the current directory. If it was not found, the compiler searches in the environment variable and then in the default include directory.

The compiler now looks for the file myinc.h in the directory where test.c is located. If the file is not there the compiler searches in the directory myinclude. If it was still not found, the compiler searches in the environment variable and then in the default include directory.

Related information

C compiler option --include-directory (Add directory to include file search path)

C compiler option --include-file (Include file at the start of a compilation)

Control program option: --instantiate

Menu entry

- Select C/C++ Compiler » Miscellaneous.
- 2. Select an instantiation mode in the Instantiation mode of external template entities box.

Command line syntax

--instantiate=mode

You can specify the following modes:

used

all

local

Default: --instantiate=used

Description

local

Control instantiation of external template entities. External template entities are external (that is, non-inline and non-static) template functions and template static data members. The instantiation mode determines the template entities for which code should be generated based on the template definition. Normally, when a file is compiled, template entities are instantiated wherever they are used (the linker will discard duplicate definitions). The overall instantiation mode can, however, be changed with this option. You can specify the following modes:

used	Instantiate those template entities that were used in the compilation. This will include all static data members for which there are template definitions. This is the default.
all	Instantiate all template entities declared or referenced in the compilation unit. For each fully instantiated template class, all of its member functions and static data members will be instantiated whether or not they were used. Non-member template functions will be instantiated even if the only reference was a declaration.

Similar to --instantiate=used except that the functions are given internal linkage. This is intended to provide a very simple mechanism for those getting started with templates. The compiler will instantiate the functions that are used in each compilation unit as local functions, and the program will link and run correctly (barring

compilation unit as local functions, and the program will link and run correctly (barring problems due to multiple copies of local static variables). However, one may end up with many copies of the instantiated functions, so this is not suitable for production use.

use.

You cannot use **--instantiate=local** in conjunction with automatic template instantiation.

Related information

Control program option --no-auto-instantiation (Disable automatic C++ instantiation)

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Section 2.5, Template Instantiation

Control program option: --io-streams

Menu entry

- 1. Select C/C++ Compiler » Language.
- 2. Enable the option **Support for C++ I/O streams**.

Command line syntax

--io-streams

Description

As I/O streams require substantial resources they are disabled by default. Use this option to enable I/O streams support in the C++ library.

This option also enables exception handling.

Related information

-

Control program option: --iso

Menu entry

- Select C/C++ Compiler » Language.
- 2. From the Comply to C standard list, select ISO C99 or ISO C90.

Command line syntax

```
--iso=\{90 \,|\, 99\}
```

Default: --iso=99

Description

With this option you select the ISO C standard. C90 is also referred to as the "ANSI C standard". C99 refers to the newer ISO/IEC 9899:1999 (E) standard. C99 is the default.

Independent of the chosen ISO standard, the control program always links libraries with C99 support.

Example

To select the ISO C90 standard on the command line:

```
ccarm --iso=90 test.c
```

Related information

C compiler option --iso (ISO C standard)

Control program option: --keep-output-files (-k)

Menu entry

Eclipse always removes generated output files when an error occurs.

Command line syntax

```
--keep-output-files
```

-k

Description

If an error occurs during the compilation, assembling or linking process, the resulting output file may be incomplete or incorrect. With this option you keep the generated output files when an error occurs.

By default the control program removes generated output files when an error occurs. This is useful when you use the make utility. If the erroneous files are not removed, the make utility may process corrupt files on a subsequent invocation.

Use this option when you still want to use the generated files. For example when you know that a particular error does not result in a corrupt file, or when you want to inspect the output file, or send it to Altium support.

The control program passes this option to the compiler, assembler and linker.

Example

```
ccarm --keep-output-files test.c
```

When an error occurs during compiling, assembling or linking, the erroneous generated output files will not be removed.

Related information

C compiler option --keep-output-files

Assembler option --keep-output-files

Linker option --keep-output-files

Control program option: --keep-temporary-files (-t)

Menu entry

- Select Global Options.
- Enable the option Keep temporary files.

Command line syntax

```
--keep-temporary-files
```

-t

Description

By default, the control program removes intermediate files like the .src file (result of the compiler phase) and the .obj file (result of the assembler phase).

With this option you tell the control program to keep temporary files it generates during the creation of the absolute object file.

Example

```
ccarm --keep-temporary-files test.c
```

The control program keeps all intermediate files it generates while creating the absolute object file test. abs.

Related information

-

Control program option: --library (-I)

Menu entry

1. Select Linker » Libraries.

The Libraries box shows the list of libraries that are linked with the project.

- 2. To add a library, click on the **Add** button in the **Libraries** box.
- Type or select a library (including its path).
- 4. Optionally, disable the option **Link default libraries**.

Use the **Edit** and **Delete** button to change a library name or to remove a library from the list.

Command line syntax

- --library=name
- -lname

Description

With this option you tell the linker via the control program to use system library *name*.lib, where *name* is a string. The linker first searches for system libraries in any directories specified with --library-directory, then in the directories specified with the environment variables LIBARM, unless you used the option --ignore-default-library-path.

Example

To search in the system library carm. lib (C library):

```
ccarm test.obj mylib.lib --library=carm
```

The linker links the file test.obj and first looks in library mylib.lib (in the current directory only), then in the system library carm.lib to resolve unresolved symbols.

Related information

Control program option --no-default-libraries (Do not link default libraries)

Control program option --library-directory (Additional search path for system libraries)

Section 8.3, Linking with Libraries

Control program option: --library-directory (-L) / --ignore-default-library-path

Menu entry

Select Linker » Libraries.

The Library search path box shows the directories that are added to the search path for library files.

- To define a new directory for the search path, click on the Add button in the Library search path box.
- Type or select a path.

Use the Edit and Delete button to change a path or to remove a path from the list.

Command line syntax

```
--library-directory=path,...
-Lpath,...
--ignore-default-library-path
-L
```

Description

With this option you can specify the path(s) where your system libraries, specified with the option --library (-I), are located. If you want to specify multiple paths, use the option --library-directory for each separate path.

The default path is (PRODDIR) \lib\architecture\endianness.

If you specify only **-L** (without a pathname) or the long option **--ignore-default-library-path**, the linker will not search the default path and also not in the paths specified in the environment variables LIBARM. So, the linker ignores steps 2 and 3 as listed below.

The priority order in which the linker searches for system libraries specified with the option --library (-I) is:

- 1. The path that is specified with the option --library-directory.
- 2. The path that is specified in the environment variables LIBARM.
- 3. The default directory \$(PRODDIR)\libarchitecture\endianness.

Example

Suppose you call the control program as follows:

```
ccarm test.c --library-directory=c:\mylibs --library=carm
```

First the linker looks in the directory c:\mylibs for library carm.lib (this option). If it does not find the requested libraries, it looks in the directory that is set with the environment variables LIBARM. Then the linker looks in the default directory \$(PRODDIR)\libarchitecture\endianness for libraries.

Related information

Control program option --library (Link system library)

Section 8.3.1, How the Linker Searches Libraries

TASKING VX-toolset for ARM User Guide

Control program option: --list-files

Menu entry

_

Command line syntax

```
--list-files[=file]
```

Default: no list files are generated

Description

With this option you tell the assembler via the control program to generate a list file for each specified input file. A list file shows the generated object code and the relative addresses. Note that the assembler generates a relocatable object file with relative addresses.

With the optional *file* you can specify a name for the list file. This is only possible if you specify only one input file to the control program. If you do not specify a file name, or you specify more than one input file, the control program names the generated list file(s) after the specified input file(s) with extension .lst.

Note that object files and library files are not counted as input files.

Related information

Assembler option --list-file (Generate list file)

Assembler option --list-format (Format list file)

Control program option: --IsI-file (-d)

Menu entry

An LSL file can be generated when you create your project in Eclipse:

 From the File menu, select File » New » Other... » TASKING C/C++ » TASKING VX-toolset for ARM C/C++ Project.

The New C/C++ Project wizard appears.

- 2. Fill in the project settings in each dialog and click **Next** > until the **ARM Project Settings** appear.
- 3. Enable the option Add Linker script file to the project and click Finish.

Eclipse creates your project and the file project. 1s1 in the project directory.

The LSL file can be specified in the Properties dialog:

- 1. Select Linker » Script File.
- 2. Specify a LSL file in the **Linker script file (.IsI)** field (default .../\${PROJ}.ls1).

Command line syntax

```
--lsl-file=file
```

Description

-dfile

A linker script file contains vital information about the core for the locating phase of the linker. A linker script file is coded in LSL and contains the following types of information:

- the architecture definition describes the core's hardware architecture.
- the memory definition describes the physical memory available in the system.
- the section layout definition describes how to locate sections in memory.

With this option you specify a linker script file via the control program to the linker. If you do not specify this option, the linker uses a default script file. You can specify the existing file *target*. lsl or the name of a manually written linker script file. You can use this option multiple times. The linker processes the LSL files in the order in which they appear on the command line.

Related information

Section 8.7, Controlling the Linker with a Script

Control program option: --mil-link / --mil-split

Menu entry

-

Command line syntax

```
--mil-link
--mil-split[=file,...]
```

Description

With option --mil-link the C compiler links the optimized intermediate representation (MIL) of all input files and MIL libraries specified on the command line in the compiler. The result is one single module that is optimized another time.

Option --mil-split does the same as option --mil-link, but in addition, the resulting MIL representation is written to a file with the suffix .mil and the C compiler also splits the MIL representation and writes it to separate files with suffix .ms. One file is written for each input file or MIL library specified on the command line. The .ms files are only updated on a change.

With option --mil-split you can perform application-wide optimizations during the frontend phase by specifying all modules at once, and still invoke the backend phase one module at a time to reduce the total compilation time.

Optionally, you can specify another filename for the .ms file the C compiler generates. Without an argument, the basename of the C source file is used to create the .ms filename. Note that if you specify a filename, you have to specify one filename for every input file.

Related information

Section 4.1, Compilation Process

C compiler option --mil / --mil-split

Control program option: --no-auto-instantiation

Menu entry

_

Command line syntax

--no-auto-instantiation

Default: the C++ compiler automatically instantiates templates.

Description

With this option automatic instantiation of templates is disabled.

Related information

Control program option --instantiate (Set instantiation mode)

Section 2.5, Template Instantiation

Control program option: --no-default-libraries

Menu entry

- Select Linker » Libraries.
- Disable the option Link default libraries.

Command line syntax

--no-default-libraries

Description

By default the control program specifies the standard C libraries (C99) and run-time library to the linker. With this option you tell the control program not to specify the standard C libraries and run-time library to the linker.

In this case you must specify the libraries you want to link to the linker with the option --library=library_name or pass the libraries as files on the command line. The control program recognizes the option --library (-I) as an option for the linker and passes it as such.

Example

```
ccarm --no-default-libraries test.c
```

The control program does not specify any libraries to the linker. In normal cases this would result in unresolved externals.

To specify your own libraries (carm.lib) and avoid unresolved externals:

```
ccarm --no-default-libraries --library=carm test.c
```

Related information

Control program option --library (Link system library)

Section 8.3.1, How the Linker Searches Libraries

Control program option: --no-double (-F)

Menu entry

- 1. Select C/C++ Compiler » Language.
- 2. Enable the option **Treat double as float**.

Command line syntax

--no-double

-F

Description

With this option you tell the compiler to treat variables of the type double as float. Because the float type takes less space, execution speed increases and code size decreases, both at the cost of less precision.

The control program also tells the linker to link the single-precision C library.

Related information

Control program option: --no-map-file

Menu entry

- 1. Select Linker » Map File.
- 2. Disable the option Generate map file.

Command line syntax

--no-map-file

Description

By default the control program tells the linker to generate a linker map file.

A linker map file is a text file that shows how the linker has mapped the sections and symbols from the various object files (.obj) to the linked object file. A locate part shows the absolute position of each section. External symbols are listed per space with their absolute address, both sorted on symbol and sorted on address.

With this option you prevent the generation of a map file.

Related information

Control program option: --no-warnings (-w)

Menu entry

1. Select C/C++ Compiler » Diagnostics.

The Suppress C compiler warnings box shows the warnings that are currently suppressed.

- 2. To suppress a warning, click on the **Add** button in the **Suppress warnings** box.
- 3. Enter the numbers, separated by commas, of the warnings you want to suppress (for example 537,538). Or you can use the **Add** button multiple times.
- 4. To suppress all warnings, enable the option **Suppress all warnings**.

Use the Edit and Delete button to change a warning number or to remove a number from the list.

Command line syntax

```
--no-warnings[=number,...]
-w[number,...]
```

Description

With this option you can suppresses all warning messages for the various tools or specific compiler warning messages.

On the command line this option works as follows:

- If you do not specify this option, all warnings are reported.
- If you specify this option but without numbers, all warnings of all tools are suppressed.
- If you specify this option with a number, only the specified (compiler) warning is suppressed. You can specify the option --no-warnings=number multiple times.

Example

To suppress all warnings for all tools, enter:

```
ccarm test.c --no-warnings
```

Related information

Control program option --warnings-as-errors (Treat warnings as errors)

Control program option: --option-file (-f)

Menu entry

_

Command line syntax

```
--option-file=file,...
-f file,...
```

Description

This option is primarily intended for command line use. Instead of typing all options on the command line, you can create an option file which contains all options and flags you want to specify. With this option you specify the option file to the control program.

Use an option file when the command line would exceed the limits of the operating system, or just to store options and save typing.

You can specify the option --option-file multiple times.

Format of an option file

- Multiple arguments on one line in the option file are allowed.
- To include whitespace in an argument, surround the argument with single or double quotes.
- If you want to use single quotes as part of the argument, surround the argument by double quotes and vise versa:

```
"This has a single quote ' embedded"

'This has a double quote " embedded'

'This has a double quote " and a single quote '"' embedded"
```

When a text line reaches its length limit, use a \ to continue the line. Whitespace between quotes is preserved.

```
"This is a continuation \ line" -> "This is a continuation line"
```

It is possible to nest command line files up to 25 levels.

Example

Suppose the file myoptions contains the following lines:

```
--debug-info
--define=DEMO=1
test.c
```

Specify the option file to the control program:

```
ccarm --option-file=myoptions
```

This is equivalent to the following command line:

```
ccarm --debug-info --define=DEMO=1 test.c
```

Related information

Control program option: --output (-o)

Menu entry

Eclipse always uses the project name as the basename for the output file.

Command line syntax

```
--output=file
```

-o file

Description

By default, the control program generates a file with the same basename as the first specified input file. With this option you specify another name for the resulting absolute object file.

The default output format is ELF/DWARF, but you can specify another output format with option --format.

Example

```
ccarm test.c prog.c
```

The control program generates an ELF/DWARF object file (default) with the name test.abs.

To generate the file result.abs:

```
ccarm --output=result.abs test.c prog.c
```

Related information

Control program option --format (Set linker output format)

Linker option --output (Output file)

Linker option --chip-output (Generate an output file for each chip)

Control program option: --pass (-W)

Menu entry

- 1. Select C/C++ Compiler » Miscellaneous or Assembler » Miscellaneous or Linker » Miscellaneous.
- 2. Add an option to the Additional options field.

Be aware that the options in the option file are added to the options you have set in the other pages. Only in extraordinary cases you may want to use them in combination. The assembler options are preceded by **-WI**. For the C/C++ options you have to do this manually.

Command line syntax

pass-assembler=option	-Waoption	Pass option directly to the assembler
pass-c=option	-Wcoption	Pass option directly to the C compiler
pass-c++=option	-Wcpoption Pass option directly to the C++ compiler	
pass-linker=option	-WIoption	Pass option directly to the linker

Description

With this option you tell the control program to call a tool with the specified option. The control program does not use or interpret the option itself, but specifies it directly to the tool which it calls.

Example

To pass the option **--verbose** directly to the linker, enter:

```
ccarm --pass-linker=--verbose test.c
```

Related information

_

Control program option: --preprocess (-E) / --no-preprocessing-only

Menu entry

- 1. Select C/C++ Compiler » Preprocessing.
- 2. Enable the option Store C preprocessor output in <file>.pre.
- 3. (Optional) Enable the option Keep comments in preprocessor output.
- 4. (Optional) Enable the option **Keep #line info in preprocessor output**.

Command line syntax

```
--preprocess[=flags]
-E[flags]
--no-preprocessing-only
```

You can set the following flags:

+/-comments c/C keep comments

+/-make m/M generate dependencies for make+/-noline p/P strip #line source position information

Default: -ECMP

Description

With this option you tell the compiler to preprocess the C source. The C compiler sends the preprocessed output to the file <code>name.pre</code> (where <code>name</code> is the name of the C source file to compile). Eclipse also compiles the C source.

On the command line, the control program stops after preprocessing. If you also want to compile the C source you can specify the option **--no-preprocessing-only**. In this case the control program calls the compiler twice, once with option **--preprocess** and once for a regular compilation.

With --preprocess=+comments you tell the preprocessor to keep the comments from the C source file in the preprocessed output.

With --preprocess=+make the compiler will generate dependency lines that can be used in a Makefile. The preprocessor output is discarded.

With **--preprocess=+noline** you tell the preprocessor to strip the #line source position information (lines starting with #line). These lines are normally processed by the assembler and not needed in the preprocessed output. When you leave these lines out, the output is easier to read.

Example

```
ccarm --preprocess=+comments,-make,-noline --no-preprocessing-only test.c
```

The compiler preprocesses the file test.c and sends the output to the file test.pre. Comments are included but no dependencies are generated and the line source position information is not stripped from the output file. Next, the control program calls the compiler, assembler and linker to create the final object file test.abs

Related information

_

Control program option: --profile (-p)

Menu entry

- Select C/C++ Compiler » Debugging.
- 2. Enable or disable Static profiling.
- Enable or disable one or more of the following Generate profiling information options (dynamic profiling):
 - for block counters (not in combination with Call graph or Function timers)
 - · to build a call graph
 - · for function counters
 - · for function timers

Note that the more detailed information you request, the larger the overhead in terms of execution time, code size and heap space needed. The option **--debug** does not affect profiling, execution time or code size.

Command line syntax

```
--profile[=flag,...]
-p[flags]
```

Use the following option for a predefined set of flags:

profile=g	-pg	Profiling with call graph and function timers.
		Alias for: -pBcFSt

You can set the following flags:

+/-block	b/B	block counters
+/-callgraph	c/C	call graph
+/-function	f/F	function counte

+/-function f/F function counters

+/-static s/S static profile generation

+/-time t/T function timers

Default (without flags): -pBCfST

Description

Profiling is the process of collecting statistical data about a running application. With these data you can analyze which functions are called, how often they are called and what their execution time is.

Several methods of profiling exist. One method is *code instrumentation* which adds code to your application that takes care of the profiling process when the application is executed. Another method is *static profiling*.

For an extensive description of profiling refer to Chapter 6, *Profiling*.

You can obtain the following profiling data (see flags above):

Block counters (not in combination with Call graph or Function timers)

This will instrument the code to perform basic block counting. As the program runs, it counts the number of executions of each branch in an if statement, each iteration of a for loop, and so on. Note that though you can combine Block counters with Function counters, this has no effect because Function counters is only a subset of Block counters.

Call graph (not in combination with Block counters)

This will instrument the code to reconstruct the run-time call graph. As the program runs it associates the caller with the gathered profiling data.

Function counters

This will instrument the code to perform function call counting. This is a subset of the basic Block counters.

Function timers (not in combination with Block counters/Function counters)

This will instrument the code to measure the time spent in a function. This includes the time spent in all sub functions (callees).

Static profiling

With this option you do not need to run the application to get profiling results. The compiler generates profiling information at compile time, without adding extra code to your application.

Note that the more detailed information you request, the larger the overhead in terms of execution time, code size and heap space needed. The option **Generate symbolic debug information** (--debug) does not affect profiling, execution time or code size.

The control program automatically specifies the corresponding profiling libraries to the linker.

Example

To generate block count information for the module test.c during execution, compile as follows:

```
ccarm --profile=+block test.c
```

In this case the control program tells the linker to link the library pbarm. lib.

Related information

Chapter 6, Profiling

TASKING VX-toolset for ARM User Guide

Control program option: --show-c++-warnings

Menu entry

-

Command line syntax

--show-c++-warnings

Description

The C++ compiler may generate a compiled C++ file (.ic) that causes warnings during compilation or assembling. With this option you tell the control program to show these warnings. By default C++ warnings are suppressed.

Related information

Control program option: --signed-bitfields

Menu entry

- 1. Select C/C++ Compiler » Language.
- 2. Enable the option Treat "int" bit-fields as signed.

Command line syntax

--signed-bitfields

Description

For bit-fields it depends on the implementation whether a plain int is treated as signed int or unsigned int. By default an int bit-field is treated as unsigned int. This offers the best performance. With this option you tell the compiler to treat int bit-fields as signed int. In this case, you can still add the keyword unsigned to treat a particular int bit-field as unsigned.

Related information

C compiler option --signed-bitfields

Section 1.1, Data Types

TASKING VX-toolset for ARM User Guide

Control program option: --static

Menu entry

_

Command line syntax

--static

Description

This option is directly passed to the compiler.

With this option, the compiler treats external definitions at file scope (except for main) as if they were declared static. As a result, unused functions will be eliminated, and the alias checking algorithm assumes that objects with static storage cannot be referenced from functions outside the current module.

This option only makes sense when you specify all modules of an application on the command line.

Example

ccarm --static module1.c module2.c module3.c ...

Related information

Control program option: --thumb

Menu entry

- 1. Select C/C++ Compiler » Code Generation.
- 2. Enable the option **Use Thumb instruction set**.

Command line syntax

--thumb

Description

Generate code in Thumb mode. The Thumb instruction set is a subset of the ARM instruction set which is encoded using 16-bit instructions instead of 32-bit instructions.

Related information

Control program option: --uchar (-u)

Menu entry

- Select C/C++ Compiler » Language.
- 2. Enable the option Treat "char" variables as unsigned.

Command line syntax

--uchar

-u

Description

By default char is the same as specifying signed char. With this option char is the same as unsigned char. This option is passed to both the C++ compiler and the C compiler.

Related information

Section 1.1, Data Types

Control program option: --undefine (-U)

Menu entry

1. Select C/C++ Compiler » Preprocessing

The Defined symbols box shows the symbols that are currently defined.

To remove a defined symbol, select the symbol in the **Defined symbols** box and click on the **Delete** button.

Command line syntax

```
--undefine=macro_name
```

Description

With this option you can undefine an earlier defined macro as with #undef. This option is for example useful to undefine predefined macros.

The following predefined ISO C standard macros cannot be undefined:

FILE	current source filename
LINE	current source line number (int type)
TIME	hh:mm:ss
DATE	Mmm dd yyyy
STDC	level of ANSI standard

The control program passes the option --undefine (-U) to the compiler.

Example

```
To undefine the predefined macro __TASKING__:
ccarm --undefine=__TASKING__ test.c
```

Related information

Control program option --define (Define preprocessor macro)

Section 1.6, Predefined Preprocessor Macros

⁻Umacro_name

Control program option: --verbose (-v)

Menu entry

- Select Global Options.
- 2. Enable the option Verbose mode of control program.

Command line syntax

--verbose

-v

Description

With this option you put the control program in verbose mode. The control program performs it tasks while it prints the steps it performs to stdout.

Related information

Control program option --dry-run (Verbose output and suppress execution)

Control program option: --version (-V)

Menu entry

-

Command line syntax

--version

-v

Description

Display version information. The control program ignores all other options or input files.

Related information

Control program option: --warnings-as-errors

Menu entry

- Select Global Options.
- 2. Enable the option Treat warnings as errors.

Command line syntax

```
--warnings-as-errors[=number,...]
```

Description

If one of the tools encounters an error, it stops processing the file(s). With this option you tell the tools to treat warnings as errors or treat specific C compiler warning messages as errors:

- If you specify this option but without numbers, all warnings are treated as errors.
- If you specify this option with a number, only the specified C compiler warning is treated as an error.
 You can specify the option --warnings-as-errors=number multiple times.

Related information

Control program option --no-warnings (Suppress some or all warnings)

12.6. Make Utility Options

You can use the make utility **mkarm** from the command line to build your project. Note that this make utility is not the default make used by Eclipse. So, you have to create your own makefile.

The invocation syntax is:

```
mkarm [option...] [target...] [macro=def]
```

This section describes all options for the make utility. The make utility is a command line tool so there are no equivalent options in Eclipse.

For detailed information about the make utility and using makefiles see Section 10.2, Make Utility mkarm.

Defining Macros

Command line syntax

```
macro name[=macro definition]
```

Description

With this argument you can define a macro and specify it to the make utility.

A macro definition remains in existence during the execution of the makefile, even when the makefile recursively calls the make utility again. In the recursive call, the macro acts as an environment variable. This means that it is overruled by definitions in the recursive call. Use the option -e to prevent this.

You can specify as many macros as you like. If the command line exceeds the limit of the operating system, you can define the macros in an option file which you then must specify to the make utility with the option -m) file.

Defining macros on the command line is, for example, useful in combination with conditional processing as shown in the example below.

Example

Consider the following makefile with conditional rules to build a demo program and a real program:

```
ifdef DEMO
                 # the value of DEMO is of no importance
  real.abs : demo.obj main.obj
              lkarm demo.obj main.obj -darm.lsl -lcarm -lfparm -lrtarm
else
   real.abs : real.obj main.obj
              lkarm real.obj main.obj -darm.lsl -lcarm -lfparm -lrtarm
```

endif

You can now use a macro definition to set the DEMO flag:

```
mkarm real.abs DEMO=1
```

In both cases the absolute object file real.abs is created but depending on the DEMO flag it is linked with demo.obj or with real.obj.

Related information

Make utility option **-e** (Environment variables override macro definitions)

Make utility option **-m** (Name of invocation file)

Make utility option: -?

Command line syntax

-?

Description

Displays an overview of all command line options.

Example

The following invocation displays a list of the available command line options:

mkarm -?

Related information

TASKING VX-toolset for ARM User Guide

Make utility option: -a

Command line syntax

-a

Description

Normally the make utility rebuilds only those files that are out of date. With this option you tell the make utility to rebuild *all* files, without checking whether they are out of date.

Example

mkarm -a

Rebuilds all your files, regardless of whether they are out of date or not.

Related information

Make utility option: -c

Command line syntax

-c

Description

Eclipse uses this option when you create sub-projects. In this case the make utility calls another instance of the make utility for the sub-project. With the option **-c**, the make utility runs as a child process of the current make.

The option **-c** overrules the option **-err**.

Example

mkarm -c

The make utility runs its commands as a child processes.

Related information

Make utility option -err (Redirect error message to file)

TASKING VX-toolset for ARM User Guide

Make utility option: -D / -DD

Command line syntax

- -D
- -DD

Description

With the option **-D** the make utility prints every line of the makefile to standard output as it is read by **mkarm**.

With the option **-DD** not only the lines of the makefile are printed but also the lines of the mkarm.mk file (implicit rules).

Example

mkarm -D

Each line of the makefile that is read by the make utility is printed to standard output (usually your screen).

Related information

Make utility option: -d/ -dd

Command line syntax

-d

-dd

Description

With the option **-d** the make utility shows which files are out of date and thus need to be rebuild. The option **-dd** gives more detail than the option **-d**.

Example

mkarm -d

Shows which files are out of date and rebuilds them.

Related information

TASKING VX-toolset for ARM User Guide

Make utility option: -e

Command line syntax

-e

Description

If you use macro definitions, they may overrule the settings of the environment variables. With the option **-e**, the settings of the environment variables are used even if macros define otherwise.

Example

mkarm -e

The make utility uses the settings of the environment variables regardless of macro definitions.

Related information

Make utility option: -err

Command line syntax

-err file

Description

With this option the make utility redirects error messages and verbose messages to a specified file.

With the option **-s** the make utility only displays error messages.

Example

```
mkarm -err error.txt
```

The make utility writes messages to the file error.txt.

Related information

Make utility option -s (Do not print commands before execution)

Make utility option **-c** (Run as child process)

Make utility option: -f

Command line syntax

-f my_makefile

Description

By default the make utility uses the file makefile to build your files.

With this option you tell the make utility to use the specified file instead of the file makefile. Multiple -f options act as if all the makefiles were concatenated in a left-to-right order.

If you use '-' instead of a makefile name it means that the information is read from stdin.

Example

mkarm -f mymake

The make utility uses the file mymake to build your files.

Related information

Make utility option: -G

Command line syntax

-G path

Description

Normally you must call the make utility from the directory where your makefile and other files are stored.

With the option **-G** you can call the make utility from within another directory. The *path* is the path to the directory where your makefile and other files are stored and can be absolute or relative to your current directory.

Example

Suppose your makefile and other files are stored in the directory . . $\mbox{\ensuremath{\mbox{\sc Myfiles}}}$. You can call the make utility, for example, as follows:

mkarm -G ..\myfiles

Related information

TASKING VX-toolset for ARM User Guide

Make utility option: -i

Command line syntax

-i

Description

When an error occurs during the make process, the make utility exits with a certain exit code.

With the option -i, the make utility exits without an error code, even when errors occurred.

Example

mkarm -i

The make utility exits without an error code, even when an error occurs.

Related information

Make utility option: -K

Command line syntax

-ĸ

Description

With this option the make utility keeps temporary files it creates during the make process. The make utility stores temporary files in the directory that you have specified with the environment variable TMPDIR or in the default 'temp' directory of your system when the TMPDIR environment variable is not specified.

Example

mkarm -K

The make utility preserves all temporary files.

Related information

Make utility option: -k

Command line syntax

-k

Description

When during the make process the make utility encounters an error, it stops rebuilding your files.

With the option **-k**, the make utility only stops building the target that produced the error. All other targets defined in the makefile are built.

Example

mkarm -k

If the make utility encounters an error, it stops building the current target but proceeds with the other targets that are defined in the makefile.

Related information

Make utility option -S (Undo the effect of -k)

Make utility option: -m

Command line syntax

```
-m file
```

Description

Instead of typing all options on the command line, you can create an option file which contains all options and flags you want to specify. With this option you specify the option file to the make utility.

Use an option file when the command line would exceed the limits of the operating system, or just to store options and save typing.

You can specify the option -m multiple times.

If you use '-' instead of a filename it means that the options are read from stdin.

Format of an option file

- Multiple arguments on one line in the option file are allowed.
- To include whitespace in an argument, surround the argument with single or double quotes.
- If you want to use single quotes as part of the argument, surround the argument by double quotes and vise versa:

```
"This has a single quote ' embedded"

'This has a double quote " embedded'

'This has a double quote " and a single quote '"' embedded"
```

Note that adjacent strings are concatenated.

When a text line reaches its length limit, use a \ to continue the line. Whitespace between quotes is
preserved.

```
"This is a continuation \ line" -> "This is a continuation line"
```

• It is possible to nest command line files up to 25 levels.

Example

Suppose the file myoptions contains the following lines:

```
-k
-err errors.txt
test.abs
```

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Specify the option file to the make utility:

```
mkarm -m myoptions
```

This is equivalent to the following command line:

```
mkarm -k -err errors.txt test.abs
```

Related information

Make utility option: -n

Command line syntax

-n

Description

With this option you tell the make utility to perform a dry run. The make utility shows what it would do but does not actually perform these tasks.

This option is for example useful to quickly inspect what would happen if you call the make utility.

Example

mkarm -n

The make utility does not perform any tasks but displays what it would do if called without the option -n.

Related information

Make utility option -s (Do not print commands before execution)

Make utility option: -p

Command line syntax

-p

Description

Normally, if a command in a target rule in a makefile returns an error or when the target construction is interrupted, the make utility removes that target file. With this option you tell the make utility to make all target files precious. This means that all dependency files are never removed.

Example

mkarm -p

The make utility never removes target dependency files.

Related information

Special target . PRECIOUS in Section 10.2.2.1, Targets and Dependencies

Make utility option: -q

Command line syntax

-q

Description

With this option the make utility does not perform any tasks but only returns an exit code. A zero status indicates that all target files are up to date, a non-zero status indicates that some or all target files are out of date.

Example

mkarm -q

The make utility only returns an error code that indicates whether all target files are up to date or not. It does not rebuild any files.

Related information

Make utility option: -r

Command line syntax

-r

Description

When you call the make utility, it first reads the implicit rules from the file mkarm.mk, then it reads the makefile with the rules to build your files. (The file mkarm.mkis located in the \etc directory of the toolset.)

With this option you tell the make utility not to read mkarm.mk and to rely fully on the make rules in the makefile.

Example

mkarm -r

The make utility does not read the implicit make rules in mkarm.mk.

Related information

Make utility option: -S

Command line syntax

-s

Description

With this option you cancel the effect of the option -k. This is only necessary in a recursive make where the option -k might be inherited from the top-level make via MAKEFLAGS or if you set the option -k in the environment variable MAKEFLAGS.

With this option you tell the make utility not to read mkarm.mk and to rely fully on the make rules in the makefile.

Example

mkarm -S

The effect of the option **-k** is cancelled so the make utility stops with the make process after it encounters an error.

The option **-k** in this example may have been set with the environment variable MAKEFLAGS or in a recursive call to **mkarm** in the makefile.

Related information

Make utility option -k (On error, abandon the work for the current target only)

Make utility option: -s

Command line syntax

-s

Description

With this option you tell the make utility to perform its tasks without printing the commands it executes. Error messages are normally printed.

Example

mkarm -s

The make utility rebuilds your files but does not print the commands it executes during the make process.

Related information

Make utility option -n (Perform a dry run)

Make utility option: -t

Command line syntax

-t

Description

With this option you tell the make utility to *touch* the target files, bringing them up to date, rather than performing the rules to rebuild them.

Example

mkarm -t

The make utility updates out-of-date files by giving them a new date and time stamp. The files are not actually rebuild.

Related information

Make utility option: -time

Command line syntax

-time

Description

With this option you tell the make utility to display the current date and time on standard output.

Example

mkarm -time

The make utility displays the current date and time and updates out-of-date files.

Related information

Make utility option: -V

Command line syntax

-v

Description

Display version information. The make utility ignores all other options or input files.

Related information

Make utility option: -W

Command line syntax

-W target

Description

With this option the make utility considers the specified target file always as up to date and will not rebuild it.

Example

mkarm -W test.abs

The make utility rebuilds out of date targets in the makefile except the file test.abs which is considered now as up to date.

Related information

Make utility option: -w

Command line syntax

-w

Description

With this option the make utility sends error messages and verbose messages to standard output. Without this option, the make utility sends these messages to standard error.

This option is only useful on UNIX systems.

Example

mkarm -w

The make utility sends messages to standard out instead of standard error.

Related information

Make utility option: -x

Command line syntax

-x

Description

With this option the make utility shows extended error messages. Extended error messages give more detailed information about the exit status of the make utility after errors.

Example

mkarm -x

If errors occur, the make utility gives extended information.

Related information

12.7. Parallel Make Utility Options

When you build a project in Eclipse, Eclipse generates a makefile and uses the make utility **amk** to build all your files. However, you can also use the make utility directly from the command line to build your project.

The invocation syntax is:

```
amk [option...] [target...] [macro=def]
```

This section describes all options for the parallel make utility.

For detailed information about the parallel make utility and using makefiles see Section 10.3, *Make Utility amk*.

Parallel make utility option: -?

Command line syntax

-?

Description

Displays an overview of all command line options.

Example

The following invocation displays a list of the available command line options:

amk -?

Related information

Parallel make utility option: -a

Command line syntax

-a

Description

Normally the make utility rebuilds only those files that are out of date. With this option you tell the make utility to rebuild *all* files, without checking whether they are out of date.

Example

amk -a

Rebuilds all your files, regardless of whether they are out of date or not.

Related information

Parallel make utility option: -f

Command line syntax

-f my makefile

Description

By default the make utility uses the file makefile to build your files.

With this option you tell the make utility to use the specified file instead of the file makefile. Multiple -f options act as if all the makefiles were concatenated in a left-to-right order.

If you use '-' instead of a makefile name it means that the information is read from stdin.

Example

amk -f mymake

The make utility uses the file mymake to build your files.

Related information

Parallel make utility option: -G

Command line syntax

-G path

Description

Normally you must call the make utility from the directory where your makefile and other files are stored.

With the option **-G** you can call the make utility from within another directory. The *path* is the path to the directory where your makefile and other files are stored and can be absolute or relative to your current directory.

The macro SUBDIR is defined with the value of path.

Example

Suppose your makefile and other files are stored in the directory . . $\mbox{\ensuremath{$\setminus$}}$ Nou can call the make utility, for example, as follows:

amk -G ..\myfiles

Related information

Parallel make utility option: -j / -J

Menu

1. From the **Project** menu, select **Properties**

The Properties dialog appears.

2. In the left pane, select C/C++ Build.

In the right pane the C/C++ Build page appears.

- 3. On the Behaviour tab, select Use parallel build.
- 4. You can specify the number of parallel jobs, or you can use an optimal number of jobs. In the last case, **amk** will fork as many jobs in parallel as cores are available.

Command line syntax

```
-j[number]
```

-J[number]

Description

When these options you can limit the number of parallel jobs. The default is 1. Zero means no limit. When you omit the *number*, **amk** uses the number of cores detected.

Option -J is the same as -j, except that the number of parallel jobs is limited by the number of cores detected.

Example

amk -j3

Limit the number of parallel jobs to 3.

Related information

Parallel make utility option: -k

Command line syntax

-k

Description

When during the make process the make utility encounters an error, it stops rebuilding your files.

With the option **-k**, the make utility only stops building the target that produced the error. All other targets defined in the makefile are built.

Example

amk -k

If the make utility encounters an error, it stops building the current target but proceeds with the other targets that are defined in the makefile.

Related information

Parallel make utility option: -n

Command line syntax

-n

Description

With this option you tell the make utility to perform a dry run. The make utility shows what it would do but does not actually perform these tasks.

This option is for example useful to quickly inspect what would happen if you call the make utility.

Example

amk -n

The make utility does not perform any tasks but displays what it would do if called without the option -n.

Related information

Parallel make utility option -s (Do not print commands before execution)

Parallel make utility option: -s

Command line syntax

-s

Description

With this option you tell the make utility to perform its tasks without printing the commands it executes. Error messages are normally printed.

Example

amk -s

The make utility rebuilds your files but does not print the commands it executes during the make process.

Related information

Parallel make utility option -n (Perform a dry run)

Parallel make utility option: -V

Command line syntax

-v

Description

Display version information. The make utility ignores all other options or input files.

Related information

12.8. Archiver Options

The archiver and library maintainer **ararm** is a tool to build library files and it offers the possibility to replace, extract and remove modules from an existing library.

The invocation syntax is:

```
ararm key_option [sub_option...] library [object_file]
```

This section describes all options for the archiver. Some suboptions can only be used in combination with certain key options. They are described together. Suboptions that can always be used are described separately.

For detailed information about the archiver, see Section 10.4, Archiver.

Short and long option names

Options can have both short and long names. Short option names always begin with a single minus (-) character, long option names always begin with two minus (--) characters. You can abbreviate long option names as long as it forms a unique name. You can mix short and long option names on the command line.

Overview of the options of the archiver utility

The following archiver options are available:

Description	Option	Sub-option
Main functions (key options)	'	-
Replace or add an object module	-r	-a -b -c -u -v
Extract an object module from the library	-x	-o -v
Delete object module from library	-d	-v
Move object module to another position	-m	-a -b -v
Print a table of contents of the library	-t	-s0 -s1
Print object module to standard output	-p	
Sub-options Sub-options		
Append or move new modules after existing module name	-a name	
Append or move new modules before existing module name	-b name	
Create library without notification if library does not exist	-с	
Preserve last-modified date from the library	-0	
Print symbols in library modules	-s{0 1}	
Replace only newer modules	-u	
Verbose	-v	
Miscellaneous	•	

Description	Option	Sub-option
Display options	-?	
Display version header	-V	
Read options from file	-f file	
Suppress warnings above level <i>n</i>	-wn	

Archiver option: --delete (-d)

Command line syntax

```
--delete [--verbose]
-d [-v]
```

Description

Delete the specified object modules from a library. With the suboption **--verbose** (**-v**) the archiver shows which files are removed.

--verbose -v Verbose: the archiver shows which files are removed.

Example

```
ararm --delete mylib.lib obj1.obj obj2.obj

The archiver deletes obj1.obj and obj2.obj from the library mylib.lib.
```

```
ararm -d -v mylib.lib obj1.obj obj2.obj
```

The archiver deletes obj1.obj and obj2.obj from the library mylib.lib and displays which files are removed.

Related information

Archiver option: --dump (-p)

Command line syntax

--dump

-p

Description

Print the specified object module(s) in the library to standard output.

This option is only useful when you redirect or pipe the output to other files or tools that serve your own purposes. Normally you do not need this option.

Example

```
ararm --dump mylib.lib obj1.obj > file.obj
```

The archiver prints the file obj1.obj to standard output where it is redirected to the file file.obj. The effect of this example is very similar to extracting a file from the library but in this case the 'extracted' file gets another name.

Related information

Archiver option: --extract (-x)

Command line syntax

```
--extract [--modtime] [--verbose]
-x [-o] [-v]
```

Description

Extract an existing module from the library.

-modtime
 Give the extracted object module the same date as the last-modified date that was recorded in the library. Without this suboption it receives the last-modified date of the moment it is extracted.
 -verbose
 -v Verbose: the archiver shows which files are extracted.

Example

To extract the file obj1.obj from the library mylib.lib:

```
ararm --extract mylib.lib obj1.obj
```

If you do not specify an object module, all object modules are extracted:

```
ararm -x mylib.lib
```

Related information

_

Archiver option: --help (-?)

Command line syntax

```
--help[=item]
--?
```

You can specify the following argument:

options

Show extended option descriptions

Description

Displays an overview of all command line options. When you specify the argument **options** you can list detailed option descriptions.

Example

The following invocations all display a list of the available command line options:

```
ararm -?
ararm --help
ararm
```

To see a detailed description of the available options, enter:

```
ararm --help=options
```

Related information

Archiver option: --move (-m)

Command line syntax

```
--move [-a posname] [-b posname]
-m [-a posname] [-b posname]
```

Description

Move the specified object modules to another position in the library.

The ordering of members in a library can make a difference in how programs are linked if a symbol is defined in more than one member.

By default, the specified members are moved to the end of the archive. Use the suboptions **-a** or **-b** to move them to a specified place instead.

after=posname	-a posname	Move the specified object module(s) after the existing module posname.
before=posname	-b posname	Move the specified object module(s) before the existing module posname.

Example

Suppose the library mylib.lib contains the following objects (see option --print):

```
obj1.obj
obj2.obj
obj3.obj
To move obj1.obj to the end of mylib.lib:
ararm --move mylib.lib obj1.obj
To move obj3.obj just before obj2.obj:
ararm -m -b obj3.obj mylib.lib obj2.obj
```

The library mylib.lib after these two invocations now looks like:

```
obj3.obj
obj2.obj
obj1.obj
```

Related information

Archiver option --print (-t) (Print library contents)

Archiver option: --option-file (-f)

Command line syntax

```
--option-file=file
-f file
```

Description

Instead of typing all options on the command line, you can create an option file which contains all options and flags you want to specify. With this option you specify the option file to the archiver.

Use an option file when the command line would exceed the limits of the operating system, or just to store options and save typing.

You can specify the option --option-file (-f) multiple times.

If you use '-' instead of a filename it means that the options are read from stdin.

Format of an option file

- Multiple arguments on one line in the option file are allowed.
- To include whitespace in an argument, surround the argument with single or double quotes.
- If you want to use single quotes as part of the argument, surround the argument by double quotes and vise versa:

```
"This has a single quote ' embedded"

'This has a double quote " embedded'

'This has a double quote " and a single quote '"' embedded"
```

• When a text line reaches its length limit, use a \ to continue the line. Whitespace between quotes is preserved.

```
"This is a continuation \ line" -> "This is a continuation line"
```

It is possible to nest command line files up to 25 levels.

Example

Suppose the file myoptions contains the following lines:

```
-x mylib.lib obj1.obj
-w5
```

Specify the option file to the archiver:

```
ararm --option-file=myoptions
```

This is equivalent to the following command line:

```
ararm -x mylib.lib obj1.obj -w5
```

Related information

_

Archiver option: --print (-t)

Command line syntax

```
--print [--symbols=0|1]
-t [-s0|-s1]
```

Description

Print a table of contents of the library to standard output. With the suboption **-s0** the archiver displays all symbols per object file.

symbols=0	-s0	Displays per object the name of the object itself and all symbols in the object.
symbols=1	- s1	Displays the symbols of all object files in the library in the form library_name:object_name:symbol_name

Example

```
ararm --print mylib.lib
```

The archiver prints a list of all object modules in the library mylib.lib:

```
ararm -t -s0 mylib.lib
```

The archiver prints per object all symbols in the library. For example:

```
cstart.obj
  symbols:
    START
```

Related information

Archiver option: --replace (-r)

Command line syntax

```
--replace [--after=posname] [--before=posname][--create] [--newer-only] [--verbose]
-r [-a posname] [-b posname][-c] [-u] [-v]
```

Description

You can use the option --replace (-r) for several purposes:

- Adding new objects to the library
- Replacing objects in the library with the same object of a newer date
- Creating a new library

The option --replace (-r) normally adds a new module to the library. However, if the library already contains a module with the specified name, the existing module is replaced. If you specify a library that does not exist, the archiver creates a new library with the specified name.

If you add a module to the library without specifying the suboption -a or -b, the specified module is added at the end of the archive. Use the suboptions -a or -b to insert them after/before a specified place instead.

after=posname	-a posname	Insert the specified object module(s) after the existing module posname.
before=posname	-b posname	Insert the specified object module(s) before the existing module <i>posname</i> .
create	-c	Create a new library without checking whether it already exists. If the library already exists, it is overwritten.
newer-only	-u	Insert the specified object module only if it is newer than the module in the library.
verbose	-v	Verbose: the archiver shows which files are replaced.

The suboptions -a or -b have no effect when an object is added to the library.

Example

Suppose the library mylib.lib contains the following object (see option --print):

```
obj1.obj

To add obj2.obj to the end of mylib.lib:

ararm --replace mylib.lib obj2.obj

To insert obj3.obj just before obj2.obj:

ararm -r -b obj2.obj mylib.lib obj3.obj
```

The library mylib.lib after these two invocations now looks like:

```
obj1.obj
obj3.obj
obj2.obj
```

Creating a new library

To create a new library file, add an object file and specify a library that does not yet exist:

```
ararm --replace obj1.obj newlib.lib
```

The archiver creates the library newlib.lib and adds the object obj1.obj to it.

To create a new library file and overwrite an existing library, add an object file and specify an existing library with the supoption --create (-c):

```
ararm -r -c obj1.obj mylib.lib
```

The archiver overwrites the library mylib.lib and adds the object obj1.obj to it. The new library mylib.lib only contains obj1.obj.

Related information

Archiver option --print (-t) (Print library contents)

Archiver option: --version (-V)

Command line syntax

--version

-v

Description

Display version information. The archiver ignores all other options or input files.

Related information

Archiver option: --warning (-w)

Command line syntax

```
--warning=level
```

-wlevel

Description

With this suboption you tell the archiver to suppress all warnings above the specified level. The level is a number between 0 - 9.

The level of a message is printed between parentheses after the warning number. If you do not use the **-w** option, the default warning level is 8.

Example

To suppress warnings above level 5:

```
ararm --extract --warning=5 mylib.lib obj1.obj
```

Related information

Chapter 13. Libraries

This chapter contains an overview of all library functions that you can call in your C source. This includes all functions of the standard C library (ISO C99) and some functions of the floating-point library.

A number of standard operations within C are too complex to generate inline code for (too much code). These operations are implemented as run-time library functions to save code.

Section 13.1, *Library Functions*, gives an overview of all library functions you can use, grouped per header file. A number of functions declared in wchar. h are parallel to functions in other header files. These are discussed together.

Section 13.2, *C Library Reentrancy*, gives an overview of which functions are reentrant and which are not.

The following libraries are included in the ARM toolset. Both Eclipse and the control program **ccarm** automatically select the appropriate libraries depending on the specified options.

C library

Libraries	Description
carm[s].lib cthumb[s].lib	C libraries for ARM and Thumb instructions repectively Optional letter: s = single precision floating-point (compiler optionno-double)
fparm.lib fpthumb.lib	Floating-point libraries for ARM and Thumb
rtarm.lib rtthumb.lib	Run-time library for ARM and Thumb
pbarm.lib / pbthumb.lib pcarm.lib / pcthumb.lib pctarm.lib / pctthumb.lib pdarm.lib / pdthumb.lib ptarm.lib / ptthumb.lib	Profiling libraries for ARM and Thumb pb = block/function counter pc = call graph pct = call graph and timing pd = dummy pt = function timing
str*xstdlibarm.lib str*xstdlibthumb.lib	STMicroelectronics STR71x, STR73x, STR75x, STR91x software libraries

C++ Library

The TASKING C++ compiler supports the STLport C++ libraries. STLport is a multi-platform ISO C++ Standard Library implementation. It is a free, open-source product, which is delivered with the TASKING C++ compiler. The library supports standard templates and I/O streams.

The include files for the STLport C++ libraries are present in directory include.stl relative to the product installation directory.

You can find more information on the STLport library on the following site:http://stlport.sourgeforge.net/

Also read the license agreement on http://stlport.sourgeforge.net/License.shtml. This license agreement is applicable to the STLport C++ library only. All other product components fall under the TASKING license agreement.

For an STL Programmer's Guide you can see http://www.sgi.com/tech/stl/index.html

The following C++ libraries are delivered with the product:

Libraries	Description
cparm[s][x].lib cpthumb[s][x].lib	C++ libraries for ARM and Thumb Optional letter: s = single precision floating-point x = exception handling
stlarmx.lib stlthumbx.lib	STLport C++ libraries (exception handling variants only) Optional letter: s = single precision floating-point

To build an STLport library

- 1. Change to the directory installdir\lib\src.stl\[v4T][v5T][v6M][v7M]\[le][be]\stl[arm|thumb]x, depending on the library set used by your project.
- 2. Run the makefile by executing installdir\bin\mkarm.exe without arguments.
- 3. Copy the generated C++ library stl[arm|thumb]x.lib to the corresponding directory installdir\lib\[v4T][v5T][v6M][v7M]\[le][be].

where,

[v4T]	libraries for ARMv4T architectures
[v5T]	libraries for ARMv5T architectures
[v6M]	libraries for ARMv6M architectures
[v7M]	libraries for ARMv7M architectures
[le]	little-endian library variant
[be]	big-endian library variant

13.1. Library Functions

The tables in the sections below list all library functions, grouped per header file in which they are declared. Some functions are not completely implemented because their implementation depends on the context where your application will run. These functions are for example all I/O related functions. Where possible, these functions are implemented using file system simulation (FSS). This system can be used by the debugger to simulate an I/O environment which enables you to debug your application.

A number of wide-character functions are available as C source code, but have not been compiled with the C library. To use complete wide-character functionality, you must recompile the libraries with the macro WCHAR_SUPPORT_ENABLED and keep this macro also defined when compiling your own sources. See C compiler option --define (-D).

13.1.1. assert.h

```
assert(expr) Prints a diagnostic message if NDEBUG is not defined. (Implemented as macro)
```

13.1.2. complex.h

The complex number z is also written as x+yi where x (the real part) and y (the imaginary part) are real numbers of types float, double or long double. The real and imaginary part can be stored in structs or in arrays. This implementation uses arrays because structs may have different alignments.

The header file complex.h also defines the following macros for backward compatibility:

```
complex _Complex /* C99 keyword */
imaginary _Imaginary /* C99 keyword */
```

Parallel sets of functions are defined for double, float and long double. They are respectively named function, function£, function1. All long type functions, though declared in complex.h, are implemented as the double type variant which nearly always meets the requirement in embedded applications.

This implementation uses the obvious implementation for complex multiplication; and a more sophisticated implementation for division and absolute value calculations which handles underflow, overflow and infinities with more care. The ISO C99 #pragma CX_LIMITED_RANGE therefore has no effect.

Trigonometric functions

csin	csinf	csinl	Returns the complex sine of z.
ccos	ccosf	ccosl	Returns the complex cosine of z.
ctan	ctanf	ctanl	Returns the complex tangent of z.
casin	casinf	casinl	Returns the complex arc sine $\sin^{-1}(z)$.
cacos	cacosf	cacosl	Returns the complex arc cosine $\cos^{-1}(z)$.
catan	catanf	catanl	Returns the complex arc tangent $tan^{-1}(z)$.
csinh	csinhf	csinhl	Returns the complex hyperbolic sine of z.
ccosh	ccoshf	ccoshl	Returns the complex hyperbolic cosine of z.
ctanh	ctanhf	ctanhl	Returns the complex hyperbolic tangent of z.
casinh	casinhf	casinhl	Returns the complex arc hyperbolic sinus of z.
cacosh	cacoshf	cacoshl	Returns the complex arc hyperbolic cosine of z.
catanh	catanhf	catanhl	Returns the complex arc hyperbolic tangent of z.

Exponential and logarithmic functions

cexp	cexpf	cexpl	Returns the result of the complex exponential function e ^z .
clog	clogf	clogl	Returns the complex natural logarithm.

Power and absolute-value functions

cabs	cabsf	cabsl	Returns the complex absolute value of <i>z</i> (also known as <i>norm</i> , <i>modulus</i> or <i>magnitude</i>).
cpow	cpowf	cpowl	Returns the complex value of x raised to the power $y(x^y)$ where both x and y are complex numbers.
csqrt	csqrtf	csqrtl	Returns the complex square root of z.

Manipulation functions

carg	cargf	cargl	Returns the argument of z (also known as phase angle).
cimag	cimagf	cimagl	Returns the imaginary part of z as a real (respectively as a double, float, long double)
conj	conjf	conjl	Returns the complex conjugate value (the sign of its imaginary part is reversed).
cproj	cprojf	cprojl	Returns the value of the projection of <i>z</i> onto the Riemann sphere.
creal	crealf	creall	Returns the real part of z as a real (respectively as a double, float, long double)

13.1.3. cstart.h

The header file cstart.h controls the system startup code's general settings and register initializations. It contains defines only, no functions.

13.1.4. ctype.h and wctype.h

The header file ctype.h declares the following functions which take a character c as an integer type argument. The header file wctype.h declares parallel wide-character functions which take a character c of the $wchar_t$ type as argument.

ctype.h	wctype.h	Description
isalnum	iswalnum	Returns a non-zero value when c is an alphabetic character or a number ([A-Z][a-z][0-9]).
isalpha	iswalpha	Returns a non-zero value when c is an alphabetic character ([A-Z][a-z]).
isblank	iswblank	Returns a non-zero value when c is a blank character (tab, space)
iscntrl	iswcntrl	Returns a non-zero value when c is a control character.
isdigit	iswditit	Returns a non-zero value when c is a numeric character ([0-9]).
isgraph	iswgraph	Returns a non-zero value when c is printable, but not a space.
islower	iswlower	Returns a non-zero value when c is a lowercase character ([a-z]).
isprint	iswprint	Returns a non-zero value when c is printable, including spaces.
ispunct	iswpunct	Returns a non-zero value when c is a punctuation character (such as '.', ',', '!').

ctype.h	wctype.h	Description
isspace	iswspace	Returns a non-zero value when c is a space type character (space, tab, vertical tab, formfeed, linefeed, carriage return).
isupper	iswupper	Returns a non-zero value when c is an uppercase character ([A-Z]).
isxdigit	iswxdigit	Returns a non-zero value when c is a hexadecimal digit ([0-9][A-F][a-f]).
tolower	towlower	Returns c converted to a lowercase character if it is an uppercase character, otherwise c is returned.
toupper	towupper	Returns c converted to an uppercase character if it is a lowercase character, otherwise c is returned.
_tolower	-	Converts c to a lowercase character, does not check if c really is an uppercase character. Implemented as macro. This macro function is not defined in ISO C99.
_toupper	-	Converts c to an uppercase character, does not check if c really is a lowercase character. Implemented as macro. This macro function is not defined in ISO C99.
isascii		Returns a non-zero value when c is in the range of 0 and 127. This function is not defined in ISO C99.
toascii		Converts c to an ASCII value (strip highest bit). This function is not defined in ISO C99.

13.1.5. dbg.h

The header file $\mathtt{dbg.h}$ contains the debugger call interface for file system simulation. It contains low level functions. This header file is not defined in ISO C99.

_dbg_trap	Low level function to trap debug events
_argcv(const char	Low level function for command line argument passing
*buf,size_t <i>size</i>)	

13.1.6. errno.h

int errno External variable that holds implementation defined error codes.

The following error codes are defined as macros in errno.h:

EPERM	1	Operation not permitted
ENOENT	2	No such file or directory
EINTR	3	Interrupted system call
EIO	4	I/O error
EBADF	5	Bad file number
EAGAIN	6	No more processes
ENOMEM	7	Not enough core
EACCES	8	Permission denied
EFAULT	9	Bad address
EEXIST	10	File exists

ENOTDIR	11	Not a directory
EISDIR	12	Is a directory
EINVAL	13	Invalid argument
ENFILE	14	File table overflow
EMFILE	15	Too many open files
ETXTBSY	16	Text file busy
ENOSPC	17	No space left on device
ESPIPE	18	Illegal seek
EROFS	19	Read-only file system
EPIPE	20	Broken pipe
ELOOP	21	Too many levels of symbolic links
ENAMETOOLONG	22	File name too long

Floating-point errors

EDOM	23	Argument too large
ERANGE	24	Result too large

Errors returned by printf/scanf

ERR_FORMAT	25	Illegal format string for printf/scanf
ERR_NOFLOAT	26	Floating-point not supported
ERR_NOLONG	27	Long not supported
ERR_NOPOINT	28	Pointers not supported

Encoding errors set by functions like fgetwc, getwc, mbrtowc, etc ...

EILSEQ 29 Invalid or incomplete multibyte or wide character

Errors returned by RTOS

ECANCELED	30	Operation canceled
ENODEV	31	No such device

13.1.7. fcntl.h

The header file fcntl.h contains the function open(), which calls the low level function _open(), and definitions of flags used by the low level function _open(). This header file is not defined in ISO C99.

open Opens a file a file for reading or writing. Calls _open. (FSS implementation)

13.1.8. fenv.h

Contains mechanisms to control the floating-point environment. The functions in this header file are not implemented.

fegetenv Stores the current floating-point environment. (Not implemented)

feholdexept Saves the current floating-point environment and installs an environment

that ignores all floating-point exceptions. (*Not implemented*)

fesetenv Restores a previously saved (fegetenv or feholdexcept) floating-point

environment. (Not implemented)

feupdateenv Saves the currently raised floating-point exceptions, restores a previously

saved floating-point environment and finally raises the saved exceptions.

(Not implemented)

feclearexcept Clears the current exception status flags corresponding to the flags specified

in the argument. (Not implemented)

fegetexceptflag Stores the current setting of the floating-point status flags. (Not implemented)

feraiseexcept Raises the exceptions represented in the argument. As a result, other

exceptions may be raised as well.

(Not implemented)

fesetexceptflag Sets the current floating-point status flags.

(Not implemented)

fetestexcept Returns the bitwise-OR of the exception macros corresponding to the

exception flags which are currently set and are specified in the argument.

(Not implemented)

For each supported exception, a macro is defined. The following exceptions are defined:

FE_DIVBYZERO FE_INEXACT FE_INVALID
FE_OVERFLOW FE_UNDERFLOW FE_ALL_EXCEPT

fegetround Returns the current rounding direction, represented as one of the values of

the rounding direction macros.

(Not implemented)

fesetround Sets the current rounding directions. (Not implemented)

Currently no rounding mode macros are implemented.

13.1.9. float.h

The header file float.h defines the characteristics of the real floating-point types float, double and long double.

float.h used to contain prototypes for the functions copysign(f), isinf(f), isfinite(f), isnan(f) and scalb(f). These functions have accordingly to the ISO C99 standard been moved to the header file math.h. See also Section 13.1.17, math.h and tgmath.h.

The following functions are only available for ISO C90:

copysignf(float f, float s) Copies the sign of the second argument s to the value of the first argument f and returns the result.

copysign(double d,double s)	Copies the sign of the second argument s to the value of the first argument d and returns the result.
isinff(float f)	Test the variable f on being an infinite (IEEE-754) value.
isinf(double d);	Test the variable <i>d</i> on being an infinite (IEEE-754) value.
isfinitef(float f)	Test the variable f on being a finite (IEEE-754) value.
isfinite(double d)	Test the variable d on being a finite (IEEE-754) value.
isnanf(float f)	Test the variable f on being NaN (Not a Number, IEEE-754) .
isnan(double d)	Test the variable \emph{d} on being NaN (Not a Number, IEEE-754) .
scalbf(float f,int p)	Returns $f * 2^p$ for integral values without computing 2^N.
scalb(double d,int p)	Returns $d * 2^p$ for integral values without computing 2^N. (See also scalbn in Section 13.1.17, math.h and tgmath.h)

13.1.10. fpbits.h

The header file fpbits.h contains definitions for the internals of the run-time floating-point library implementation. This header file is not defined in ISO C99.

13.1.11. inttypes.h and stdint.h

The header files stdint.h and inttypes.h provide additional declarations for integer types and have various characteristics. The stdint.h header file contains basic definitions of integer types of certain sizes, and corresponding sets of macros. This header file clearly refers to the corresponding sections in the ISO C99 standard.

The inttypes.h header file includes stdint.h and adds portable formatting and conversion functions. Below the conversion functions from inttypes.h are listed.

<pre>imaxabs(intmax_t j)</pre>	Returns the absolute value of j
<pre>imaxdiv(intmax_t numer, intmax_t denom)</pre>	Computes $numer/denomand\ numer\ %\ denom.$ The result is stored in the quot and $rem\ components\ of\ the\ imaxdiv_t\ structure\ type.$
<pre>strtoimax(const char * restrict nptr, char ** restrict endptr, int base)</pre>	Convert string to maximum sized integer. (Compare strtoll)
<pre>strtoumax(const char * restrict nptr, char ** restrict endptr, int base)</pre>	Convert string to maximum sized unsigned integer. (Compare strtoull)
<pre>wcstoimax(const wchar_t * restrict nptr, wchar_t ** restrict endptr, int base)</pre>	Convert wide string to maximum sized integer. (Compare wcstoll)
<pre>wcstoumax(const wchar_t * restrict nptr, wchar_t ** restrict endptr, int base)</pre>	Convert wide string to maximum sized unsigned integer. (Compare wcstoull)

13.1.12. io.h

The header file io.h contains prototypes for low level I/O functions. This header file is not defined in ISO C99.

```
_close(fd) Used by the functions close and fclose. (FSS implementation)
_lseek(fd,offset,whence) Used by all file positioning functions: fgetpos, fseek, fsetpos, ftell, rewind. (FSS implementation)
_open(fd,flags) Used by the functions fopen and freopen. (FSS implementation)
_read(fd,*buff,cnt) Reads a sequence of characters from a file. (FSS implementation)
_unlink(*name) Used by the function remove. (FSS implementation)
_write(fd,*buffer,cnt) Writes a sequence of characters to a file. (FSS implementation)
```

13.1.13. iso646.h

The header file iso646.h adds tokens that can be used instead of regular operator tokens.

```
#define and &&
#define and_eq &=
#define bitand &
#define bitor |
#define compl ~
#define not !
#define not_eq !=
#define or ||
#define or_eq |=
#define xor ^
#define xor_eq ^=
```

13.1.14. limits.h

Contains the sizes of integral types, defined as macros.

13.1.15. locale.h

To keep C code reasonable portable across different languages and cultures, a number of facilities are provided in the header file local.h.

```
char *setlocale( int category, const char *locale )
```

The function above changes locale-specific features of the run-time library as specified by the category to change and the name of the locale.

The following categories are defined and can be used as input for this function:

```
LC_ALL 0 LC_NUMERIC 3
LC_COLLATE 1 LC_TIME 4
LC_CTYPE 2 LC_MONETARY 5
```

```
struct lconv *localeconv( void )
```

Returns a pointer to type struct lconv with values appropriate for the formatting of numeric quantities according to the rules of the current locale. The struct lconv in this header file is conforming the ISO standard.

13.1.16, malloc.h

The header file malloc.h contains prototypes for memory allocation functions. This include file is not defined in ISO C99, it is included for backwards compatibility with ISO C90. For ISO C99, the memory allocation functions are part of stdlib.h. See Section 13.1.25, stdlib.h and wchar.h.

malloc(size)	Allocates space for an object with size <i>size</i> . The allocated space is not initialized. Returns a pointer to the allocated space.
<pre>calloc(nobj,size)</pre>	Allocates space for n objects with size <i>size</i> . The allocated space is initialized with zeros. Returns a pointer to the allocated space.
free(*ptr)	Deallocates the memory space pointed to by <i>ptr</i> which should be a pointer earlier returned by the malloc or calloc function.
realloc(*ptr,size)	Deallocates the old object pointed to by <i>ptr</i> and returns a pointer to a new object with size <i>size</i> , while preserving its contents. If the new size is smaller than the old size, some contents at the end of the old region will be discarded. If the new size is larger than the old size, all of the old contents are preserved and any bytes in the new object beyond the size of the old object will have indeterminate values.

13.1.17. math.h and tgmath.h

The header file math.h contains the prototypes for many mathematical functions. Before ISO C99, all functions were computed using the double type (the float was automatically converted to double, prior to calculation). In this ISO C99 version, parallel sets of functions are defined for double, float and long double. They are respectively named function, functionf, function1. All long type functions, though declared in math.h, are implemented as the double type variant which nearly always meets the requirement in embedded applications.

The header file tgmath.h contains parallel type generic math macros whose expansion depends on the used type. tgmath.h includes math.h and the effect of expansion is that the correct math.h functions are called. The type generic macro, if available, is listed in the second column of the tables below.

Trigonometric and hyperbolic functions

math.h			tgmath.h	Description
sin	sinf	sinl	sin	Returns the sine of x.
cos	cosf	cosl	cos	Returns the cosine of x.
tan	tanf	tanl	tan	Returns the tangent of x.

math.h			tgmath.h	Description
asin	asinf	asinl	asin	Returns the arc sine sin ⁻¹ (x) of x.
acos	acosf	acosl	acos	Returns the arc cosine $\cos^{-1}(x)$ of x .
atan	atanf	atanl	atan	Returns the arc tangent $tan^{-1}(x)$ of x .
atan2	atan2f	atan21	atan2	Returns the result of: $tan^{-1}(y/x)$.
sinh	sinhf	sinhl	sinh	Returns the hyperbolic sine of \mathbf{x} .
cosh	coshf	coshl	cosh	Returns the hyperbolic cosine of x.
tanh	tanhf	tanhl	tanh	Returns the hyperbolic tangent of ${\bf x}$.
asinh	asinhf	asinhl	asinh	Returns the arc hyperbolic sine of x.
acosh	acoshf	acoshl	acosh	Returns the non-negative arc hyperbolic cosine of ${\bf x}$.
atanh	atanhf	atanhl	atanh	Returns the arc hyperbolic tangent of \mathbf{x} .

Exponential and logarithmic functions

All of these functions are new in ISO C99, except for exp, log and log10.

math.h			tgmath.h	Description
exp	expf	expl	exp	Returns the result of the exponential function e ^x .
exp2	exp2f	exp21	exp2	Returns the result of the exponential function 2 ^x . (<i>Not implemented</i>)
expm1	expm1f	expm11	expm1	Returns the result of the exponential function e ^x -1. (<i>Not implemented</i>)
log	logf	logl	log	Returns the natural logarithm $ln(x)$, $x>0$.
log10	log10f	log101	log10	Returns the base-10 logarithm of x , $x>0$.
log1p	log1pf	log1pl	log1p	Returns the base-e logarithm of $(1+x).x <> -1.$ (Not implemented)
log2	log2f	log21	log2	Returns the base-2 logarithm of $x.x>0$. (Not implemented)
ilogb	ilogbf	ilogbl	ilogb	Returns the signed exponent of x as an integer. $x>0$. (Not implemented)
logb	logbf	logbl	logb	Returns the exponent of x as a signed integer in value in floating-point notation. $x > 0$. (Not implemented)

frexp, Idexp, modf, scalbn, scalbln

math.h			tgmath.h	Description
frexp	frexpf	frexpl	frexp	Splits a float x into fraction f and exponent n , so that: $f = 0.0$ or $0.5 \le f \le 1.0$ and $f^*2^n = x$. Returns f , stores n .
ldexp	ldexpf	ldexpl	ldexp	Inverse of frexp. Returns the result of x^*2^n . (x and n are both arguments).
modf	modff	modfl	-	Splits a float x into fraction f and integer n , so that: $ f < 1.0$ and $f + n = x$. Returns f , stores n .

math.h			tgmath.h	Description
scalbn	scalbnf	scalbnl	scalbn	Computes the result of x*FLT_RADIX ⁿ . efficiently, not normally by computing FLT_RADIX ⁿ explicitly.
scalbln	scalblnf	scalblnl	scalbln	Same as scalbn but with argument n as long int.

Rounding functions

math.h			tgmath.h	Description
ceil	ceilf	ceill	ceil	Returns the smallest integer not less than \mathbf{x} , as a double.
floor	floorf	floorl	floor	Returns the largest integer not greater than $\mathbf{x},$ as a double.
rint	rintf	rintl	rint	Returns the rounded integer value as an int according to the current rounding direction. See fenv.h. (Not implemented)
lrint	lrintf	lrintl	lrint	Returns the rounded integer value as a long int according to the current rounding direction. See fenv.h. (Not implemented)
llrint	lrintf	lrintl	llrint	Returns the rounded integer value as a long long int according to the current rounding direction. See ${\tt fenv.h.}$ (Not implemented)
nearbyint	nearbyintf	nearbyintl	nearbyint	Returns the rounded integer value as a floating-point according to the current rounding direction. See $\mathtt{fenv.h.}$ (Not implemented)
round	roundf	roundl	round	Returns the nearest integer value of $\mathbf x$ as int. (Not implemented)
lround	lroundf	lroundl	lround	Returns the nearest integer value of $\mathbf x$ as long int. (Not implemented)
llround	lroundf	llroundl	llround	Returns the nearest integer value of $\mathbf x$ as long long int. (Not implemented)
trunc	truncf	truncl	trunc	Returns the truncated integer value ${\tt x.}$ (Not implemented)

Remainder after division

math.h			tgmath.h	Description
fmod	fmodf	fmodl	fmod	Returns the remainder r of x-ny. n is chosen as $trunc(x/y)$. r has the same sign as x.
remainder	remainderf	remainderl	remainder	Returns the remainder r of x-ny. n is chosen as $trunc(x/y)$. r may not have the same sign as x. (<i>Not implemented</i>)
remquo	remquof	remquol	remquo	Same as remainder. In addition, the argument *quo is given a specific value (see ISO). (<i>Not implemented</i>)

Power and absolute-value functions

math.h			tgmath.h	Description
cbrt	cbrtf	cbrtl	cbrt	Returns the real cube root of $x = x^{1/3}$. (Not implemented)
fabs	fabsf	fabsl	fabs	Returns the absolute value of $x(x)$. (abs, labs, llabs, div, ldiv, lldiv are defined in stdlib.h)
fma	fmaf	fmal	fma	Floating-point multiply add. Returns x*y+z. (Not implemented)
hypot	hypotf	hypotl	hypot	Returns the square root of x^2+y^2 .
pow	powf	powl	power	Returns x raised to the power y (x^y).
sqrt	sqrtf	sqrtl	sqrt	Returns the non-negative square root of x . x 0.

Manipulation functions: copysign, nan, nextafter, nexttoward

math.h			tgmath.h	Description
copysign	copysignf	copysignll	copysign	Returns the value of ${\bf x}$ with the sign of ${\bf y}$.
nan	nanf	nanl	_	Returns a quiet NaN, if available, with content indicated through tagp. (Not implemented)
nextafter	nextafterf	nextafterl	nextafter	Returns the next representable value in the specified format after x in the direction of y . Returns y is $x=y$. (Not implemented)
nexttoward	nexttowardf	nexttowardl	nexttoward	Same as nextafter, except that the second argument in all three variants is of type long double. Returns y if $x=y$. (Not implemented)

Positive difference, maximum, minimum

math.h			tgmath.h	Description
fdim	fdimf	fdiml	fdim	Returns the positive difference between: $ x-y $. (Not implemented)
fmax	fmaxf	fmaxl	fmax	Returns the maximum value of their arguments. (Not implemented)
fmin	fminf	fminl	fmin	Returns the minimum value of their arguments. (Not implemented)

Error and gamma (Not implemented)

math.h			tgmath.h	Description
erf	erff	erfl	erf	Computes the error function of x. (Not implemented)

math.h			tgmath.h	Description
erfc	erfcf	erfcl	erc	Computes the complementary error function of x. (Not implemented)
lgamma	lgammaf	lgammal	lgamma	Computes the $*log_e \Gamma(x) $ (Not implemented)
tgamma	tgammaf	tgammal	tgamma	Computes $\Gamma(x)$ (Not implemented)

Comparison macros

The next are implemented as macros. For any ordered pair of numeric values exactly one of the relationships - *less*, *greater*, and *equal* - is true. These macros are type generic and therefor do not have a parallel function in tgmath.h. All arguments must be expressions of real-floating type.

math.h	tgmath.h	Description
isgreater	-	Returns the value of (x) > (y)
isgreaterequal	-	Returns the value of $(x) >= (y)$
isless	-	Returns the value of $(x) < (y)$
islessequal	-	Returns the value of $(x) \ll (y)$
islessgreater	-	Returns the value of $(x) < (y) \mid (x) > (y)$
isunordered	-	Returns 1 if its arguments are unordered, 0 otherwise.

Classification macros

The next are implemented as macros. These macros are type generic and therefor do not have a parallel function in tgmath.h. All arguments must be expressions of real-floating type.

math.h	tgmath.h	Description
fpclassify	_	Returns the class of its argument: FP_INFINITE, FP_NAN, FP_NORMAL, FP_SUBNORMAL or FP_ZERO
isfinite	-	Returns a nonzero value if and only if its argument has a finite value
isinf	-	Returns a nonzero value if and only if its argument has an infinite value
isnan	-	Returns a nonzero value if and only if its argument has NaN value.
isnormal	-	Returns a nonzero value if an only if its argument has a normal value.
signbit	-	Returns a nonzero value if and only if its argument value is negative.

13.1.18. setjmp.h

The setjmp and longjmp in this header file implement a primitive form of non-local jumps, which may be used to handle exceptional situations. This facility is traditionally considered more portable than signal.h

```
int setjmp(jmp\_buf Records its caller's environment in env and returns 0. env) void longjmp(jmp\_buf Restores the environment previously saved with a call to setjmp(). env, int status
```

13.1.19. signal.h

Signals are possible asynchronous events that may require special processing. Each signal is named by a number. The following signals are defined:

```
SIGINT 1 Receipt of an interactive attention signal

SIGILL 2 Detection of an invalid function message

SIGFPE 3 An erroneous arithmetic operation (for example, zero divide, overflow)

SIGSEGV 4 An invalid access to storage

SIGTERM 5 A termination request sent to the program

SIGABRT 6 Abnormal termination, such as is initiated by the abort function
```

The next function sends the signal sig to the program:

```
int raise(int sig)
```

The next function determines how subsequent signals will be handled:

```
signalfunction *signal (int, signalfunction *);
```

The first argument specifies the signal, the second argument points to the signal-handler function or has one of the following values:

```
SIG_DFL Default behavior is used
SIG_IGN The signal is ignored
```

The function returns the previous value of signalfunction for the specific signal, or SIG_ERR if an error occurs.

13.1.20. stdarg.h

The facilities in this header file gives you a portable way to access variable arguments lists, such as needed for as fprintf and vfprintf. va_copy is new in ISO C99. This header file contains the following macros:

<pre>va_arg(va_list ap,type)</pre>	Returns the value of the next argument in the variable argument list. It's return type has the type of the given argument type. A next call to this macro will return the value of the next argument.
<pre>va_copy(va_list dest, va_list src)</pre>	This macro duplicates the current state of src in dest, creating a second pointer into the argument list. After this call, va_arg() may be used on src and dest independently.
<pre>va_end(va_list ap)</pre>	This macro must be called after the arguments have been processed. It should be called before the function using the macro 'va_start' is terminated.
<pre>va_start(va_list ap, lastarg)</pre>	This macro initializes ap. After this call, each call to va_arg() will return the value of the next argument. In our implementation, va_list cannot contain any bit type variables. Also the given argument lastarg must be the last non-bit type argument in the list.

13.1.21. stdbool.h

This header file contains the following macro definitions. These names for boolean type and values are consistent with C++. You are allowed to #undefine or redefine the macros below.

#define	bool	_Bool
#define	true	1
#define	false	0
#define	bool_true_false_are_defined	1

13.1.22. stddef.h

This header file defines the types for common use:

ptrdiff_t	Signed integer type of the result of subtracting two pointers.
size_t	Unsigned integral type of the result of the sizeof operator.
wchar_t	Integer type to represent character codes in large character sets.

Besides these types, the following macros are defined:

NULL	Expands to the null pointer constant for C or 0 (zero) for C++.
offsetof(_type,	Expands to an integer constant expression with type size_t that is the offset
_member)	in bytes of _member within structure type _type.

13.1.23. stdint.h

See Section 13.1.11, inttypes.h and stdint.h

13.1.24. stdio.h and wchar.h

Types

The header file stdio.h contains functions for performing input and output. A number of functions also have a parallel wide character function or macro, defined in wchar.h. The header file wchar.h also includes stdio.h.

In the C language, many I/O facilities are based on the concept of streams. The stdio.h header file defines the data type FILE which holds the information about a stream. A FILE object is created with the function fopen. The pointer to this object is used as an argument in many of the in this header file. The FILE object can contain the following information:

- the current position within the stream
- · pointers to any associated buffers
- indications of for read/write errors
- end of file indication

The header file also defines type fpos_t as an unsigned long.

Macros

stdio.h	Description
NULL	Expands to the null pointer constant for C or 0 (zero) for C++.
BUFSIZ	Size of the buffer used by the setbuf/setvbuf function: 512
EOF	End of file indicator. Expands to -1.
WEOF	End of file indicator. Expands to UINT_MAX (defined in limits.h) NOTE: WEOF need not to be a negative number as long as its value does not correspond to a member of the wide character set. (Defined in wchar.h).
FOPEN_MAX	Number of files that can be opened simultaneously: 10
FILENAME_MAX	Maximum length of a filename: 100
_IOFBF _IOLBF _IONBF	Expand to an integer expression, suitable for use as argument to the setvbuf function.
L_tmpnam	Size of the string used to hold temporary file names: 8 (tmpxxxxx)
TMP_MAX	Maximum number of unique temporary filenames that can be generated: 0x8000
SEEK_CUR SEEK_END SEEK_SET	Expand to an integer expression, suitable for use as the third argument to the ${\tt fseek}$ function.
stderr stdin stdout	Expressions of type "pointer to FILE" that point to the FILE objects associated with standard error, input and output streams.

File access

stdio.h	Description		
fopen(name, mode)	Opens a file for a given mode. Available modes are:		
	"r" read; open text file for reading write; create text file for writing; if the file already exists, its contents is discarded append; open existing text file or create new text file for writing at end of file r+ open text file for update; reading and writing w+ create text file for update; previous contents if any is discarded append; open or create text file for update, writes at end of file		
	(FSS implementation)		
fclose(name)	Flushes the data stream and closes the specified file that was previously opened with fopen. (FSS implementation)		
fflush(name)	If stream is an output stream, any buffered but unwritten date is written. Else, the effect is undefined. (FSS implementation)		
<pre>freopen(name, mode, stream)</pre>	Similar to fopen, but rather than generating a new value of type FILE *, the existing value is associated with a new stream. (FSS implementation)		
setbuf(stream,buffer)	If buffer is NULL, buffering is turned off for the stream. Otherwise, setbuf is equivalent to: (void) setvbuf(stream, buffer,_IOFBF,BUFSIZ).		
setvbuf(stream,buffer,mode, size)	Controls buffering for the <i>stream</i> ; this function must be called before reading or writing. <i>Mode</i> can have the following values:IOFBF causes full bufferingIOLBF causes line buffering of text filesIONBF causes no buffering. If <i>buffer</i> is not NULL, it will be used as a buffer; otherwise a buffer will be allocated. <i>size</i> determines the buffer size.		

Formatted input/output

The format string of printf related functions can contain plain text mixed with conversion specifiers. Each conversion specifier should be preceded by a '%' character. The conversion specifier should be built in order:

- Flags (in any order):
 - specifies left adjustment of the converted argument.
 - + a number is always preceded with a sign character.
 - + has higher precedence than space.

space a negative number is preceded with a sign, positive numbers with a space.

o specifies padding to the field width with zeros (only for numbers).

- # specifies an alternate output form. For o, the first digit will be zero. For x or X, "0x" and "0X" will be prefixed to the number. For e, E, f, g, G, the output always contains a decimal point, trailing zeros are not removed.
- A number specifying a minimum field width. The converted argument is printed in a field with at least the length specified here. If the converted argument has fewer characters than specified, it will be padded at the left side (or at the right when the flag '-' was specified) with spaces. Padding to numeric fields will be done with zeros when the flag '0' is also specified (only when padding left). Instead of a numeric value, also '*' may be specified, the value is then taken from the next argument, which is assumed to be of type int.
- A period. This separates the minimum field width from the precision.
- A number specifying the maximum length of a string to be printed. Or the number of digits printed after
 the decimal point (only for floating-point conversions). Or the minimum number of digits to be printed
 for an integer conversion. Instead of a numeric value, also '*' may be specified, the value is then taken
 from the next argument, which is assumed to be of type int.
- A length modifier 'h', 'hh', 'l', 'll', 'L', 'j', 'z' or 't'. 'h' indicates that the argument is to be treated as a short or unsigned short. 'hh' indicates that the argument is to be treated as a char or unsigned char. 'l' should be used if the argument is a long integer, 'll' for a long long. 'L' indicates that the argument is a long double. 'j' indicates a pointer to intmax_t or uintmax_t, 'z' indicates a pointer to size_t and 't' indicates a pointer to ptrdiff_t.

Flags, length specifier, period, precision and length modifier are optional, the conversion character is not. The conversion character must be one of the following, if a character following '%' is not in the list, the behavior is undefined:

Character	Printed as
d, i	int, signed decimal
0	int, unsigned octal
x, X	int, unsigned hexadecimal in lowercase or uppercase respectively
u	int, unsigned decimal
С	int, single character (converted to unsigned char)
S	char *, the characters from the string are printed until a NULL character is found. When the given precision is met before, printing will also stop
f	double
e, E	double
g, G	double
a, A	double
n	int *, the number of characters written so far is written into the argument. This should be a pointer to an integer in default memory. No value is printed.
р	pointer
%	No argument is converted, a '%' is printed.

printf conversion characters

All arguments to the scanf related functions should be pointers to variables (in default memory) of the type which is specified in the format string.

The format string can contain:

- · Blanks or tabs, which are skipped.
- Normal characters (not '%'), which should be matched exactly in the input stream.
- Conversion specifications, starting with a '%' character.

Conversion specifications should be built as follows (in order):

- A '*', meaning that no assignment is done for this field.
- A number specifying the maximum field width.
- The conversion characters d, i, n, o, u and x may be preceded by 'h' if the argument is a pointer to short rather than int, or by 'hh' if the argument is a pointer to char, or by 'l' (letter ell) if the argument is a pointer to long or by 'll' for a pointer to long long, 'j' for a pointer to intmax_t or uintmax_t, 'z' for a pointer to size_t or 't' for a pointer to ptrdiff_t. The conversion characters e, f, and g may be preceded by 'l' if the argument is a pointer to double rather than float, and by 'L' for a pointer to a long double.
- A conversion specifier. '*', maximum field width and length modifier are optional, the conversion character
 is not. The conversion character must be one of the following, if a character following '%' is not in the
 list, the behavior is undefined.

Length specifier and length modifier are optional, the conversion character is not. The conversion character must be one of the following, if a character following '%' is not in the list, the behavior is undefined.

Character Scanned as

- d int, signed decimal. i int, the integer may be given octal (i.e. a leading 0 is entered) or hexadecimal (leading "0x" or "0X"), or just decimal. int, unsigned octal. 0 u int, unsigned decimal. int, unsigned hexadecimal in lowercase or uppercase. Х single character (converted to unsigned char). С char *, a string of non white space characters. The argument should point to an array of s characters, large enough to hold the string and a terminating NULL character.
- f, F float
- e, E float
- g, G float
- a. A float

Character Scanned as	
n	int *, the number of characters written so far is written into the argument. No scanning is done.
p	pointer; hexadecimal value which must be entered without 0x- prefix.
[]	Matches a string of input characters from the set between the brackets. A NULL character is added to terminate the string. Specifying []] includes the ']' character in the set of scanning characters.
[^]	Matches a string of input characters not in the set between the brackets. A NULL character is added to terminate the string. Specifying [^]] includes the ']' character in the set.
%	Literal '%', no assignment is done.

scanf conversion characters

stdio.h	wchar.h	Description
fscanf(stream, format,)	<pre>fwscanf(stream, format,)</pre>	Performs a formatted read from the given <i>stream</i> . Returns the number of items converted successfully. (FSS implementation)
<pre>scanf(format,)</pre>	wscanf(format,)	Performs a formatted read from stdin. Returns the number of items converted successfully. (FSS implementation)
<pre>sscanf(*s, format,)</pre>	<pre>swscanf(*s, format,)</pre>	Performs a formatted read from the string s. Returns the number of items converted successfully.
<pre>vfscanf(stream, format, arg)</pre>	<pre>vfwscanf(stream, format, arg)</pre>	Same as fscanf/fwscanf, but extra arguments are given as variable argument list <i>arg.</i> (See Section 13.1.20, <i>stdarg.h</i>)
vscanf(format, arg)	vwscanf(format, arg)	Same as sscanf/swscanf, but extra arguments are given as variable argument list <i>arg.</i> (See Section 13.1.20, <i>stdarg.h</i>)
<pre>vsscanf(*s, format, arg)</pre>	<pre>vswscanf(*s, format, arg)</pre>	Same as scanf/wscanf, but extra arguments are given as variable argument list <i>arg.</i> (See Section 13.1.20, <i>stdarg.h</i>)
<pre>fprintf(stream, format,)</pre>	<pre>fwprintf(stream, format,)</pre>	Performs a formatted write to the given <i>stream</i> . Returns EOF/WEOF on error. (<i>FSS implementation</i>)
<pre>printf(format,)</pre>	wprintf(format,)	Performs a formatted write to the stream stdout. Returns EOF/WEOF on error. (FSS implementation)
<pre>sprintf(*s, format,)</pre>	-	Performs a formatted write to string s. Returns EOF/WEOF on error.
<pre>snprintf(*s, n, format,)</pre>	<pre>swprintf(*s, n, format,)</pre>	Same as sprintf, but n specifies the maximum number of characters (including the terminating null character) to be written.

stdio.h	wchar.h	Description
vfprintf(stream, format, arg)	<pre>vfwprintf(stream, format, arg)</pre>	Same as fprintf/fwprintf, but extra arguments are given as variable argument list arg. (See Section 13.1.20, stdarg.h) (FSS implementation)
<pre>vprintf(format, arg)</pre>	<pre>vwprintf(format, arg)</pre>	Same as printf/wprintf, but extra arguments are given as variable argument list <i>arg.</i> (See Section 13.1.20, <i>stdarg.h</i>) (FSS implementation)
<pre>vsprintf(*s, format, arg)</pre>	<pre>vswprintf(*s, format, arg)</pre>	Same as sprintf/swprintf, but extra arguments are given as variable argument list arg. (See Section 13.1.20, stdarg.h)

The C library functions printf(), fprintf(), vfprintf(), vsprintf(), ... call one single function, $_doprint()$, that deals with the format string and arguments. The same applies to all scanf type functions, which call the function $_doscan()$, and also for the wprintf and wscanf type functions which call $_dowprint()$ and $_dowscan()$ respectively. The C library contains three versions of these routines: int, long and long long versions. If you use floating-point the formatter function for floating-point $_doflt()$ or $_dowflt()$ is called. Depending on the formatting arguments you use, the correct routine is used from the library. Of course the larger the version of the routine the larger your produced code will be.

Note that when you call any of the printf/scanf routines indirect, the arguments are not known and always the long long version with floating-point support is used from the library.

Example:

```
#include <stdio.h>
long L;

void main(void)
{
    printf( "This is a long: %ld\n", L );
}
```

The linker extracts the long version without floating-point support from the library.

See also the description of #pragma weak in Section 1.5, Pragmas to Control the Compiler.

Character input/output

stdio.h	wchar.h	Description
fgetc(stream)	fgetwc(stream)	Reads one character from <i>stream</i> . Returns the read character, or EOF/WEOF on error. (<i>FSS implementation</i>)

stdio.h	wchar.h	Description
getc(stream)	getwc(stream)	Same as fgetc/fgetwc except that is implemented as a macro. (FSS implementation) NOTE: Currently #defined as getchar()/getwchar() because FILE I/O is not supported. Returns the read character, or EOF/WEOF on error.
getchar(stdin)	getwchar(stdin)	Reads one character from the stdin stream. Returns the character read or EOF/WEOF on error. Implemented as macro. (FSS implementation)
fgets(*s, n, stream)	fgetws(*s, n, stream)	Reads at most the next <i>n</i> -1 characters from the <i>stream</i> into array <i>s</i> until a newline is found. Returns s or NULL or EOF/WEOF on error. (<i>FSS implementation</i>)
gets(*s, n, stdin)	-	Reads at most the next <i>n</i> -1 characters from the stdin stream into array s. A newline is ignored. Returns s or NULL or EOF/WEOF on error. (<i>FSS implementation</i>)
ungetc(c, stream)	ungetwc(c, stream)	Pushes character <i>c</i> back onto the input <i>stream</i> . Returns EOF/WEOF on error.
<pre>fputc(c, stream)</pre>	<pre>fputwc(c, stream)</pre>	Put character <i>c</i> onto the given <i>stream</i> . Returns EOF/WEOF on error. (<i>FSS implementation</i>)
<pre>putc(c, stream)</pre>	<pre>putwc(c, stream)</pre>	Same as fpuc/fputwc except that is implemented as a macro. (FSS implementation)
<pre>putchar(c, stdout)</pre>	<pre>putwchar(c, stdout)</pre>	Put character c onto the stdout stream. Returns EOF/WEOF on error. Implemented as macro. (FSS implementation)
<pre>fputs(*s, stream)</pre>	<pre>fputws(*s, stream)</pre>	Writes string s to the given stream. Returns EOF/WEOF on error. (FSS implementation)
puts(*s)	-	Writes string s to the stdout stream. Returns EOF/WEOF on error. (FSS implementation)

Direct input/output

stdio.h	Description
<pre>fread(ptr,size,nobj,stream)</pre>	Reads <i>nobj</i> members of <i>size</i> bytes from the given <i>stream</i> into the array pointed to by <i>ptr</i> . Returns the number of elements successfully read. (<i>FSS implementation</i>)
<pre>fwrite(ptr,size,nobj,stream)</pre>	Writes <i>nobj</i> members of <i>size</i> bytes from to the array pointed to by <i>ptr</i> to the given <i>stream</i> . Returns the number of elements successfully written. (<i>FSS implementation</i>)

Random access

stdio.h		Description		
	fseek(stream, offset origin)	E, Sets the position indicator for stream. (FSS implementation)		
	When repositioning a binary file, the new position <i>origin</i> is given by the following macros:			
	SEEK_SET 0 offset characters from the beginning of the file SEEK_CUR 1 offset characters from the current position in the file SEEK_END 2 offset characters from the end of the file			
	ftell(stream)	Returns the current file position for <i>stream</i> , or -1L on error. (FSS implementation)		
	rewind(stream)	Sets the file position indicator for the <i>stream</i> to the beginning of the file. This function is equivalent to: (void) fseek(stream, OL, SEEK_SET); clearerr(stream); (FSS implementation)		
	fgetpos(stream,pos)	Stores the current value of the file position indicator for <i>stream</i> in the object pointed to by <i>pos.</i> (<i>FSS implementation</i>)		
	<pre>fsetpos(stream,pos)</pre>	Positions $stream$ at the position recorded by fgetpos in *pos. (FSS implementation)		

Operations on files

stdio.h	Description
remove(file)	Removes the named file, so that a subsequent attempt to open it fails. Returns a non-zero value if not successful.
rename(old,new)	Changes the name of the file from old name to new name. Returns a non-zero value if not successful.
<pre>tmpfile()</pre>	Creates a temporary file of the mode "wb+" that will be automatically removed when closed or when the program terminates normally. Returns a \mathtt{file} pointer.
tmpnam(buffer)	Creates new file names that do not conflict with other file names currently in use. The new file name is stored in a <i>buffer</i> which must have room for L_tmpnam characters. Returns a pointer to the temporary name. The file names are created in the current directory and all start with "tmp". At most TMP_MAX unique file names can be generated.

Error handling

stdio.h	Description
clearerr(stream)	Clears the end of file and error indicators for stream.
ferror(stream)	Returns a non-zero value if the error indicator for stream is set.
feof(stream)	Returns a non-zero value if the end of file indicator for stream is set.

stdio.h	Description
perror(*s)	Prints s and the error message belonging to the integer errno. (See
	Section 13.1.6, errno.h)

13.1.25, stdlib,h and wchar,h

The header file stdlib.h contains general utility functions which fall into the following categories (Some have parallel wide-character, declared in wchar.h)

- · Numeric conversions
- Random number generation
- · Memory management
- Environment communication
- · Searching and sorting
- Integer arithmetic
- Multibyte/wide character and string conversions.

Macros

```
EXIT_SUCCES Predefined exit codes that can be used in the exit function.

EXIT_FAILURE

RAND_MAX Highest number that can be returned by the rand/srand function.

MB_CUR_MAX 1 Maximum number of bytes in a multibyte character for the extended character set specified by the current locale (category LC_CTYPE, see Section 13.1.15, locale.h).
```

Numeric conversions

The following functions convert the initial portion of a string *s to a double, int, long int and long long int value respectively.

```
double atof(*s)
int atoi(*s)
long atol(*s)
long long atoll(*s)
```

The following functions convert the initial portion of the string *s to a float, double and long double value respectively. *endp will point to the first character not used by the conversion.

stdlib.h		wchar.h	
float	strtof(*s,**endp)	float	wcstof(*s,**endp)
double	strtod(*s,**endp)	double	<pre>wcstod(*s,**endp)</pre>
long double	strtold(*s,**endp)	long double	<pre>wcstold(*s,**endp)</pre>

The following functions convert the initial portion of the string *s to a long, long long, unsigned long and unsigned long long respectively. Base specifies the radix. *endp will point to the first character not used by the conversion.

stdlib.h	wchar.h
long strtol (*s,**endp,base)	long wcstol (*s,**endp,base)
long long strtoll	long long wcstoll
(*s,**endp,base)	(*s,**endp,base)
unsigned long strtoul	unsigned long wcstoul
(*s,**endp,base)	(*s,**endp,base)
unsigned long long strtoull	unsigned long long wcstoull
(*s,**endp,base)	(*s,**endp,base)

Random number generation

rand Returns a pseudo random integer in the range 0 to RAND_MAX.

srand(seed) Same as rand but uses seed for a new sequence of pseudo random numbers.

Memory management

malloc(size)	Allocates space for an object with size <i>size</i> . The allocated space is not initialized. Returns a pointer to the allocated space.
calloc(nobj,size)	Allocates space for n objects with size <i>size</i> . The allocated space is initialized with zeros. Returns a pointer to the allocated space.
free(*ptr)	Deallocates the memory space pointed to by <i>ptr</i> which should be a pointer earlier returned by the malloc or calloc function.
realloc(*ptr,size)	Deallocates the old object pointed to by <i>ptr</i> and returns a pointer to a new object with size <i>size</i> , while preserving its contents. If the new size is smaller than the old size, some contents at the end of the old region will be discarded. If the new size is larger than the old size, all of the old contents are preserved and any bytes in the new object beyond the size of the old object will have indeterminate values.

Environment communication

abort () Causes abnormal program termination. If the signal SIGABRT is caught, the signal handler may take over control. (See Section 13.1.19, signal.h).

atexit(*func)

func points to a function that is called (without arguments) when the program normally terminates.

exit(status)

Causes normal program termination. Acts as if main() returns with status as the return value. Status can also be specified with the predefined macros EXIT_SUCCES or EXIT_FAILURE.

_Exit(status)

Same as exit, but not registered by the atexit function or signal handlers registered by the signal function are called.

Searches an environment list for a string s. Returns a pointer to the contents of s.

NOTE: this function is not implemented because there is no OS.

Passes the string s to the environment for execution.

NOTE: this function is not implemented because there is no OS.

Searching and sorting

system(*s)

*cmp)

This function searches in an array of n members, for the object pointed to by key. The initial base of the array is given by base. The size of each member is specified by size. The given array must be sorted in ascending order, according to the results of the function pointed to by cmp. Returns a pointer to the matching member in the array, or NULL when not found.

This function sorts an array of n members using the quick sort algorithm. The initial base of the array is given by base. The size of each member is specified by size. The array is sorted in ascending order, according to the results of the function pointed to by cmp.

Integer arithmetic

mblen(*s,n)

int abs(j) Compute the absolute value of an int, long int, and long long int j respectively. long long llabs(j) div_t div(x,y) Compute x/y and x%y in a single operation. X and y have respectively type ldiv_t ldiv(x,y) int, long int and long long int. The result is stored in the members lldiv_t lldiv(x,y) quot and rem of struct div_t, ldiv_t and lldiv_t which have the same types.

Multibyte/wide character and string conversions

most *n* characters will be examined. (See also mbrlen in Section 13.1.29, wchar.h).

mbtowc(*pwc,*s,n) Converts the multi-byte character in s to a wide-character code and stores it in pwc. At most *n* characters will be examined.

wctomb(*s,wc) Converts the wide-character wc into a multi-byte representation and stores it in the string pointed to by s. At most MB_CUR_MAX characters are stored.

Determines the number of bytes in the multi-byte character pointed to by s. At

mbstowcs(*pwcs,*s,n)	Converts a sequence of multi-byte characters in the string pointed to by s into a sequence of wide characters and stores at most <i>n</i> wide characters into the array pointed to by <i>pwcs</i> . (See also mbsrtowcs in Section 13.1.29, <i>wchar.h</i>).
wcstombs(*s,*pwcs,n)	Converts a sequence of wide characters in the array pointed to by <i>pwcs</i> into multi-byte characters and stores at most <i>n</i> multi-byte characters into the string pointed to by <i>s</i> . (See also wcsrtowmb in Section 13.1.29, <i>wchar.h</i>).

13.1.26. string.h and wchar.h

This header file provides numerous functions for manipulating strings. By convention, strings in C are arrays of characters with a terminating null character. Most functions therefore take arguments of type *char. However, many functions have also parallel wide-character functions which take arguments of type *wchar_t. These functions are declared in wchar.h.

Copying and concatenation functions

string.h	wchar.h	Description
memcpy(*s1,*s2,n)	wmemcpy(*s1,*s2,n)	Copies <i>n</i> characters from *s2 into *s1 and returns *s1. If *s1 and *s2 overlap the result is undefined.
memmove(*s1,*s2,n)	wmemmove(*s1,*s2,n)	Same as memcpy, but overlapping strings are handled correctly. Returns *s1.
strcpy(*s1,*s2)	wcscpy(*s1,*s2)	Copies *s2 into *s1 and returns *s1. If *s1 and *s2 overlap the result is undefined.
strncpy(*s1,*s2,n)	wcsncpy(*s1,*s2,n)	Copies not more than n characters from *s2 into *s1 and returns *s1. If *s1 and *s2 overlap the result is undefined.
strcat(*s1,*s2)	wcscat(*s1,*s2)	Appends a copy of *s2 to *s1 and returns *s1. If *s1 and *s2 overlap the result is undefined.
strncat(*s1,*s2,n)	wcsncat(*s1,*s2,n)	Appends not more than n characters from *s2 to *s1 and returns *s1. If *s1 and *s2 overlap the result is undefined.

Comparison functions

string.h	wchar.h	Description
memcmp(*s1,*s2,n)	wmemcmp(*s1,*s2,n)	Compares the first n characters of *s1 to the first n characters of *s2. Returns < 0 if *s1 < *s2, 0 if *s1 = = *s2, or > 0 if *s1 > *s2.
strcmp(*s1,*s2)	wcscmp(*s1,*s2)	Compares string *s1 to *s2. Returns < 0 if *s1 < *s2, 0 if *s1 = = *s2, or > 0 if *s1 > *s2.
strncmp(*s1,*s2,n)	wcsncmp(*s1,*s2,n)	Compares the first n characters of *s1 to the first n characters of *s2. Returns < 0 if *s1 < *s2, 0 if *s1 = = *s2, or > 0 if *s1 > *s2.
strcoll(*s1,*s2)	wcscoll(*s1,*s2)	Performs a local-specific comparison between string *s1 and string *s2 according to the LC_COLLATE category of the current locale. Returns < 0 if *s1 < *s2, 0 if *s1 = = *s2, or > 0 if *s1 > *s2. (See Section 13.1.15, <i>locale.h</i>)

string.h	wchar.h	Description
strxfrm(*s1,*s2,n)	wcsxfrm(*s1,*s2,n)	Transforms (a local) string *s2 so that a comparison between transformed strings with strcmp gives the same result as a comparison between non-transformed strings with strcoll. Returns the transformed string *s1.

Search functions

string.h	wchar.h	Description
memchr(*s,c,n)	wmemchr(*s,c,n)	Checks the first <i>n</i> characters of *s on the occurrence of character <i>c</i> . Returns a pointer to the found character.
strchr(*s,c)	wcschr(*s,c)	Returns a pointer to the first occurrence of character <i>c</i> in *s or the null pointer if not found.
strrchr(*s,c)	wcsrchr(*s,c)	Returns a pointer to the last occurrence of character c in * s or the null pointer if not found.
strspn(*s,*set)	wcsspn(*s,*set)	Searches *s for a sequence of characters specified in *set. Returns the length of the first sequence found.
strcspn(*s,*set)	wcscspn(*s,*set)	Searches *s for a sequence of characters <i>not</i> specified in *set. Returns the length of the first sequence found.
strpbrk(*s,*set)	wcspbrk(*s,*set)	Same as strspn/wcsspn but returns a pointer to the first character in *s that also is specified in *set.
strstr(*s,*sub)	wcsstr(*s,*sub)	Searches for a substring * sub in * s . Returns a pointer to the first occurrence of * sub in * s .
strtok(*s,*dlm)	wcstok(*s,*dlm)	A sequence of calls to this function breaks the string * s into a sequence of tokens delimited by a character specified in * d Im. The token found in * s is terminated with a null character. Returns a pointer to the first position in * s of the token.

Miscellaneous functions

string.h	wchar.h	Description
memset(*s,c,n)	wmemset(*s,c,n)	Fills the first <i>n</i> bytes of *s with character <i>c</i> and returns *s.
strerror(errno)	-	Typically, the values for errno come from int errno. This function returns a pointer to the associated error message. (See also Section 13.1.6, errno.h)
strlen(*s)	wcslen(*s)	Returns the length of string *s.

13.1.27. time.h and wchar.h

The header file time.h provides facilities to retrieve and use the (calendar) date and time, and the process time. Time can be represented as an integer value, or can be broken-down in components. Two arithmetic data types are defined which are capable of holding the integer representation of times:

```
clock_t unsigned long long
time_t unsigned long
```

The type struct tm below is defined according to ISO C99 with one exception: this implementation does not support leap seconds. The struct tm type is defines as follows:

```
struct tm
                     /* seconds after the minute - [0, 59]
  int tm sec;
                                                                      * /
                      /* minutes after the hour - [0, 59]
  int tm_min;
                                                                      * /
  int tm_hour;  /* hours since midnight - [0, 23]
int tm_mday;  /* day of the month - [1, 31]
                                                                      * /
  int tm_mon;
                       /* months since January - [0, 11]
                                                                      * /
  int tm_year;
                       /* year since 1900
                                                                      * /
        tm_wday; /* days since Sunday - [0, 6]
tm_yday; /* days since January 1 - [0, 365]
  int tm_wday;
                                                                      * /
  int
                                                                      * /
  int
        tm_isdst;
                       /* Daylight Saving Time flag
                                                                      * /
};
```

Time manipulation

clock

Returns the application's best approximation to the processor time used by the program since it was started. This low-level routine is not implemented because it strongly depends on the hardware. To determine the time in seconds, the result of clock should be divided by the value defined by CLOCKS_PER_SEC.

difftime(t1,t0) Returns the difference t1-t0 in seconds.

mktime(tm *tp) Converts the broken-down time in the structure pointed to by tp, to a value of type time_t. The return value has the same encoding as the return value of the time function.

time(*timer)

Returns the current calendar time. This value is also assigned to *timer.

Time conversion

asctime (tm *tp) Converts the broken-down time in the structure pointed to by tp into a string in the form Mon Jan 22 16:15:14 2007\n\0. Returns a pointer to this string.

ctime(*timer) Converts the calender time pointed to by *timer* to local time in the form of a string. This is equivalent to: asctime(localtime(timer))

gmtime(*timer) Converts the calender time pointed to by timer to the broken-down time, expressed as UTC. Returns a pointer to the broken-down time.

localtime(*timer) Converts the calendar time pointed to by timer to the broken-down time, expressed as local time. Returns a pointer to the broken-down time.

Formatted time

The next function has a parallel function defined in wchar.h:

time.h wchar.h

```
strftime(*s,smax,*fmt,tm wstrftime(*s,smax,*fmt,tm *tp)
*tp)
```

Formats date and time information from struct tm *tp into *s according to the specified format *fmt. No more than smax characters are placed into *s. The formatting of strftime is locale-specific using the LC_TIME category (see Section 13.1.15, locale.h).

You can use the next conversion specifiers:

%a abbreviated weekday name %A full weekday name %b abbreviated month name %B full month name %с locale-specific date and time representation (same as %a %b %e %T %Y) %C last two digits of the year %d day of the month (01-31) %D same as %m/%d/%y day of the month (1-31), with single digits preceded by a space %e %F ISO 8601 date format: %Y-%m-%d last two digits of the week based year (00-99) %g %G week based year (0000-9999) %h same as %b %Н hour, 24-hour clock (00-23) %l hour, 12-hour clock (01-12) %i day of the year (001-366) %m month (01-12) %M minute (00-59) %n replaced by newline character %p locale's equivalent of AM or PM %r locale's 12-hour clock time; same as %I:%M:%S %p same as %H: %M %R %S second (00-59) %t replaced by horizontal tab character %T ISO 8601 time format: %H: %M: %S %u ISO 8601 weekday number (1-7), Monday as first day of the week %U week number of the year (00-53), week 1 has the first Sunday %V ISO 8601 week number (01-53) in the week-based year %w weekday (0-6, Sunday is 0)

%W week number of the year (00-53), week 1 has the first Monday
%x local date representation
%X local time representation
%y year without century (00-99)
%Y year with century
%z ISO 8601 offset of time zone from UTC, or nothing
%Z time zone name, if any
%%

13.1.28. unistd.h

The file unistd.h contains standard UNIX I/O functions. These functions are all implemented using file system simulation. Except for lstat and fstat which are not implemented. This header file is not defined in ISO C99.

access (*name, mode) Use file system simulation to check the permissions of a file on the host. mode specifies the type of access and is a bit pattern constructed by a logical OR of the following values:

		3
	R_OK W_OK X_OK F_OK	Checks read permission. Checks write permission. Checks execute (search) permission. Checks to see if the file exists.
	(FSS impl	ementation)
chdir(*path)	•	rstem simulation to change the current directory on the host to the indicated by path. (FSS implementation)
close(fd)		function. The given file descriptor should be properly closed. This alls _close(). (FSS implementation)
<pre>getcwd(*buf,size)</pre>	Use file system simulation to retrieve the current directory on the host. Returns the directory name. (FSS implementation)	
lseek(fd,offset,whence)	Moves rea	id-write file offset. Calls _lseek(). (FSS implementation)
<pre>read(fd,*buff,cnt)</pre>	Reads a so	equence of characters from a file. This function calls $_{\tt read}()$. (FSS tation)
<pre>stat(*name,*buff)</pre>	Use file sy implement	stem simulation to stat() a file on the host platform. (FSS tation)
<pre>lstat(*name,*buff)</pre>		on is identical to stat(), except in the case of a symbolic link, where elf is 'stat'-ed, not the file that it refers to. (<i>Not implemented</i>)
<pre>fstat(fd,*buff)</pre>		on is identical to stat(), except that it uses a file descriptor instead . (Not implemented)
unlink(*name)	Removes implement	the named file, so that a subsequent attempt to open it fails. (FSS tation)

write(fd,*buff,cnt) Write a sequence of characters to a file. Calls _write().(FSS implementation)

13.1.29. wchar.h

Many functions in wchar. h represent the wide-character variant of other functions so these are discussed together. (See Section 13.1.24, *stdio.h* and wchar.h, Section 13.1.25, *stdlib.h* and wchar.h, Section 13.1.26, *string.h* and wchar.h and Section 13.1.27, *time.h* and wchar.h).

The remaining functions are described below. They perform conversions between multi-byte characters and wide characters. In these functions, *ps* points to struct mbstate_t which holds the conversion state information necessary to convert between sequences of multibyte characters and wide characters:

When multibyte characters larger than 1 byte are used, this struct will be used to store the conversion information when not all the bytes of a particular multibyte character have been read from the source. In this implementation, multi-byte characters are 1 byte long (MB_CUR_MAX and MB_LEN_MAX are defined as 1) and this will never occur.

mbsinit(*ps)	Determines whether the object pointed to by <i>ps</i> , is an initial conversion state. Returns a non-zero value if so.
mbsrtowcs(*pwcs,**src,n,*ps)	Restartable version of mbstowcs. See Section 13.1.25, <i>stdlib.h</i> and <i>wchar.h</i> . The initial conversion state is specified by <i>ps</i> . The input sequence of multibyte characters is specified indirectly by <i>src</i> .
wcsrtombs(*s,**src,n,*ps)	Restartable version of wcstombs. See Section 13.1.25, <i>stdlib.h</i> and wchar.h. The initial conversion state is specified by ps. The input wide string is specified indirectly by src.
mbrtowc(*pwc,*s,n,*ps)	Converts a multibyte character *s to a wide character *pwc according to conversion state ps. See also mbtowc in Section 13.1.25, stdlib.h and wchar.h.
wcrtomb(*s,wc,*ps)	Converts a wide character wc to a multi-byte character according to conversion state <i>ps</i> and stores the multi-byte character in *s.
btowc(c)	Returns the wide character corresponding to character \emph{c} . Returns WEOF on error.
wctob(c)	Returns the multi-byte character corresponding to the wide character c . The returned multi-byte character is represented as one byte. Returns EOF on error.
mbrlen(*s,n,*ps)	Inspects up to n bytes from the string * s to see if those characters represent valid multibyte characters, relative to the conversion state held in * ps .

13.1.30. wctype.h

Most functions in wctype.h represent the wide-character variant of functions declared in ctype.h and are discussed in Section 13.1.4, *ctype.h* and *wctype.h*. In addition, this header file provides extensible, locale specific functions and wide character classification.

wctype(*property)	Constructs a value of type wctype_t that describes a class of wide characters identified by the string *property. If property identifies a valid class of wide characters according to the LC_TYPE category (see Section 13.1.15, locale.h) of the current locale, a non-zero value is returned that can be used as an argument in the iswctype function.
iswctyne(wc desc)	Tests whether the wide character wo is a member of the class represented by

iswctype(wc,desc) Tests whether the wide character wc is a member of the class represented by wctype_t desc. Returns a non-zero value if tested true.

Equivalent to locale specific test
iswctype(wc,wctype("alnum"))
<pre>iswctype(wc,wctype("alpha"))</pre>
<pre>iswctype(wc,wctype("cntrl"))</pre>
<pre>iswctype(wc,wctype("digit"))</pre>
<pre>iswctype(wc,wctype("graph"))</pre>
<pre>iswctype(wc,wctype("lower"))</pre>
<pre>iswctype(wc,wctype("print"))</pre>
<pre>iswctype(wc,wctype("punct"))</pre>
<pre>iswctype(wc,wctype("space"))</pre>
<pre>iswctype(wc,wctype("upper"))</pre>
<pre>iswctype(wc,wctype("xdigit"))</pre>
Constructs a value of type wctype_t that describes a mapping between wide characters identified by the string *property. If property identifies a valid mapping of wide characters according to the LC_TYPE category (see Section 13.1.15, locale.h) of the current locale, a non-zero value is returned that can be used as an argument in the towctrans function.

 ${\tt towctrans}(\textit{wc},\textit{desc}) \ \ \text{Transforms wide character } \textit{wc} \ \text{into another wide-character, described by } \textit{desc}.$

Function	Equivalent to locale specific transformation	
towlower(wc)	towctrans(wc,wctrans("tolower")	
towupper(wc)	<pre>towctrans(wc,wctrans("toupper")</pre>	

13.2. C Library Reentrancy

Some of the functions in the C library are reentrant, others are not. The table below shows the functions in the C library, and whether they are reentrant or not. A dash means that the function is reentrant. Note that some of the functions are not reentrant because they set the global variable 'errno' (or call other

functions that eventually set 'errno'). If your program does not check this variable and errno is the only reason for the function not being reentrant, these functions can be assumed reentrant as well.

The explanation of the cause why a function is not reentrant sometimes refers to a footnote because the explanation is to lengthy for the table.

Function	Not reentrant because
_close	Uses global File System Simulation buffer, _dbg_request
_doflt	Uses I/O functions which modify iob[]. See (1).
_doprint	Uses indirect access to static iob[] array. See (1).
_doscan	Uses indirect access to iob[] and calls ungetc (access to local static ungetc[] buffer). See (1).
_Exit	See exit.
_filbuf	Uses iob[], which is not reentrant. See (1).
_flsbuf	Uses iob[]. See (1).
_getflt	Uses iob[]. See (1).
_iob	Defines static iob[]. See (1).
_lseek	Uses global File System Simulation buffer, _dbg_request
_open	Uses global File System Simulation buffer, _dbg_request
_read	Uses global File System Simulation buffer, _dbg_request
_unlink	Uses global File System Simulation buffer, _dbg_request
_write	Uses global File System Simulation buffer, _dbg_request
abort	Calls exit
abs labs llabs	-
access	Uses global File System Simulation buffer, _dbg_request
acos acosf acosl	Sets errno.
acosh acoshf acoshl	Sets errno via calls to other functions.
asctime	asctime defines static array for broken-down time string.
asin asinf asinl	Sets errno.
asinh asinhf asinhl	Sets errno via calls to other functions.
atan atanf atanl	-
atan2 atan2f atan2l	-
atanh atanhf atanhl	Sets errno via calls to other functions.
atexit	atexit defines static array with function pointers to execute at exit of program.
atof	-
atoi	-
atol	-
bsearch	-

Firmation	Not recorded by a con-
Function	Not reentrant because
btowc	-
cabs cabsf cabsl	Sets errno via calls to other functions.
cacos cacosf cacosl	Sets errno via calls to other functions.
cacosh cacosh cfacoshl	Sets errno via calls to other functions.
calloc	calloc uses static buffer management structures. See malloc (5).
carg cargf cargl	-
casin casinf casinl	Sets errno via calls to other functions.
casinh casinh cfasinhl	Sets errno via calls to other functions.
catan catanf catanl	Sets errno via calls to other functions.
catanh catanhf catanhl	Sets errno via calls to other functions.
cbrt cbrtf cbrtl	(Not implemented)
ccos ccosf ccosl	Sets errno via calls to other functions.
ccosh ccoshf ccoshl	Sets errno via calls to other functions.
ceil ceilf ceill	-
cexp cexpf cexpl	Sets errno via calls to other functions.
chdir	Uses global File System Simulation buffer, _dbg_request
cimag cimagf cimagl	-
cleanup	Calls fclose. See (1)
clearerr	Modifies iob[]. See (1)
clock	Uses global File System Simulation buffer, _dbg_request
clog clogf clogl	Sets errno via calls to other functions.
close	Calls _close
conj conjf conjl	-
copysign copysignf	-
copysignl	
cos cosf cosl	-
cosh coshf coshl	cosh calls exp(), which sets errno. If errno is discarded, cosh is reentrant.
cpow cpowf cpowl	Sets errno via calls to other functions.
cproj cprojf cprojl	-
creal crealf creall	-
csin csinf csinl	Sets errno via calls to other functions.
csinh csinhf csinhl	Sets errno via calls to other functions.
csqrt csqrtf csqrtl	Sets errno via calls to other functions.
ctan ctanf ctanl	Sets errno via calls to other functions.
ctanh ctanhf ctanhl	Sets errno via calls to other functions.

Function	Not reentrant because			
ctime	Calls asctime			
difftime	-			
div ldiv lldiv	-			
erf erfl erff	(Not implemented)			
erfc erfcf erfcl	(Not implemented)			
exit	Calls fclose indirectly which uses iob[] calls functions in _atexit array. See (1). To make exit reentrant kernel support is required.			
exp expf expl	Sets errno.			
exp2 exp2f exp2l	(Not implemented)			
expm1 expm1f expm1l	(Not implemented)			
fabs fabsf fabsl	-			
fclose	Uses values in iob[]. See (1).			
fdim fdimf fdiml	(Not implemented)			
feclearexcept	(Not implemented)			
fegetenv	(Not implemented)			
fegetexceptflag	(Not implemented)			
fegetround	(Not implemented)			
feholdexept	(Not implemented)			
feof	Uses values in iob[]. See (1).			
feraiseexcept	(Not implemented)			
ferror	Uses values in iob[]. See (1).			
fesetenv	(Not implemented)			
fesetexceptflag	(Not implemented)			
fesetround	(Not implemented)			
fetestexcept	(Not implemented)			
feupdateenv	(Not implemented)			
fflush	Modifies iob[]. See (1).			
fgetc fgetwc	Uses pointer to iob[]. See (1).			
fgetpos	Sets the variable errno and uses pointer to iob[]. See (1) / (2).			
fgets fgetws	Uses iob[]. See (1).			
floor floorf floorl	-			
fma fmaf fmal	(Not implemented)			
fmax fmaxf fmaxl	(Not implemented)			
fmin fminf fminl	(Not implemented)			
fmod fmodf fmodl	-			

Function	Not reentrant because
fopen	Uses iob[] and calls malloc when file open for buffered IO. See (1)
fpclassify	-
fprintf fwprintf	Uses iob[]. See (1).
fputc fputwc	Uses iob[]. See (1).
fputs fputws	Uses iob[]. See (1).
fread	Calls fgetc. See (1).
free	free uses static buffer management structures. See malloc (5).
freopen	Modifies iob[]. See (1).
frexp frexpf frexpl	-
fscanf fwscanf	Uses iob[]. See (1)
fseek	Uses iob[] and calls _lseek. Accesses ungetc[] array. See (1).
fsetpos	Uses iob[] and sets errno. See (1) / (2).
fstat	(Not implemented)
ftell	Uses iob[] and sets errno. Calls _lseek. See (1) / (2).
fwrite	Uses iob[]. See (1).
getc getwc	Uses iob[]. See (1).
getchar getwchar	Uses iob[]. See (1).
getcwd	Uses global File System Simulation buffer, _dbg_request
getenv	Skeleton only.
gets getws	Uses iob[]. See (1).
gmtime	gmtime defines static structure
hypot hypotf hypotl	Sets errno via calls to other functions.
ilogb ilogbf ilogbl	(Not implemented)
imaxabs	-
imaxdiv	-
isalnum iswalnum	-
isalpha iswalpha	-
isascii iswascii	-
iscntrl iswcntrl	-
isdigit iswdigit	-
isfinite	-
isgraph iswgraph	-
isgreater	-
isgreaterequal	-
isinf	-

Function	Not reentrant because
isless	-
islessequal	-
islessgreater	-
islower iswlower	-
isnan	-
isnormal	-
isprint iswprint	-
ispunct iswpunct	-
isspace iswspace	-
isunordered	-
isupper iswupper	-
iswalnum	-
iswalpha	-
iswcntrl	-
iswctype	-
iswdigit	-
iswgraph	-
iswlower	-
iswprint	-
iswpunct	-
iswspace	-
iswupper	-
iswxditig	-
isxdigit iswxdigit	-
ldexp ldexpf ldexpl	Sets errno. See (2).
lgamma lgammaf lgammal	(Not implemented)
llrint lrintf lrintl	(Not implemented)
llround llroundf llroundl	(Not implemented)
localeconv	N.A.; skeleton function
localtime	-
log logf logl	Sets errno. See (2).
log10 log10f log101	Sets errno via calls to other functions.
log1p log1pf log1pl	(Not implemented)
log2 log2f log2l	(Not implemented)
logb logbf logbl	(Not implemented)

Function	Not reentrant because
longjmp	-
lrint lrintf lrintl	(Not implemented)
lround lroundf lroundl	(Not implemented)
lseek	Calls _lseek
lstat	(Not implemented)
malloc	Needs kernel support. See (5).
mblen	N.A., skeleton function
mbrlen	Sets errno.
mbrtowc	Sets errno.
mbsinit	-
mbsrtowcs	Sets errno.
mbstowcs	N.A., skeleton function
mbtowc	N.A., skeleton function
memchr wmemchr	-
memcmp wmemcmp	-
memcpy wmemcpy	-
memmove wmemmove	-
memset wmemset	-
mktime	-
modf modff modfl	-
nan nanf nanl	(Not implemented)
nearbyint nearbyintf nearbyintl	(Not implemented)
nextafter nextafterf nextafterl	(Not implemented)
nexttoward nexttowardf nexttowardl	(Not implemented)
offsetof	-
open	Calls _open
perror	Uses errno. See (2)
pow powf powl	Sets errno. See (2)
printf wprintf	Uses iob[]. See (1)
putc putwc	Uses iob[]. See (1)
putchar putwchar	Uses iob[]. See (1)
puts	Uses iob[]. See (1)
qsort	-

Function	Not reentrant because				
raise	Updates the signal handler table				
rand	Uses static variable to remember latest random number. Must diverge from ISO C standard to define reentrant rand. See (4).				
read	Calls _read				
realloc	See malloc (5).				
remainder remainderf remainderl	(Not implemented)				
remove	Uses global File System Simulation buffer, _dbg_request				
remquo remquof remquol	(Not implemented)				
rename	Uses global File System Simulation buffer, _dbg_request				
rewind	Eventually calls _lseek				
rint rintf rintl	(Not implemented)				
round roundf roundl	(Not implemented)				
scalbln scalblnf scalblnl	-				
scalbn scalbnf scalbnl	-				
scanf wscanf	Uses iob[], calls _doscan. See (1).				
setbuf	Sets iob[]. See (1).				
setjmp	-				
setlocale	N.A.; skeleton function				
setvbuf	Sets iob and calls malloc. See (1) / (5).				
signal	Updates the signal handler table				
signbit	-				
sin sinf sinl	-				
sinh sinhf sinhl	Sets errno via calls to other functions.				
snprintf swprintf	Sets errno. See (2).				
sprintf	Sets errno. See (2).				
sqrt sqrtf sqrtl	Sets errno. See (2).				
srand	See rand				
sscanf swscanf	Sets errno via calls to other functions.				
stat	Uses global File System Simulation buffer, _dbg_request				
strcat wcscat	-				
strchr weschr	-				
strcmp wcscmp	-				
strcoll wcscoll	-				
strcpy wcscpy	-				
strcspn wcscspn	-				

Function	Not reentrant because
strerror	-
strftime wstrftime	-
strlen wcslen	-
strncat wcsncat	-
strncmp wcsncmp	-
strncpy wcsncpy	-
strpbrk wcspbrk	-
strrchr wcsrchr	-
strspn wcsspn	-
strstr wcsstr	-
strtod wcstod	-
strtof wcstof	-
strtoimax	Sets errno via calls to other functions.
strtok wcstok	strtok saves last position in string in local static variable. This function is not reentrant by design. See (4).
strtol wcstol	Sets errno. See (2).
strtold wcstold	-
strtoul wcstoul	Sets errno. See (2).
strtoull wcstoull	Sets errno. See (2).
strtoumax	Sets errno via calls to other functions.
strxfrm wcsxfrm	-
system	N.A; skeleton function
tan tanf tanl	Sets errno. See (2).
tanh tanhf tanhl	Sets errno via call to other functions.
tgamma tgammaf tgammal	(Not implemented)
time	Uses static variable which defines initial start time
tmpfile	Uses iob[]. See (1).
tmpnam	Uses local buffer to build filename. Function can be adapted to use user buffer. This makes the function non ISO C. See (4).
toascii	-
tolower	-
toupper	-
towctrans	-
towlower	-
towupper	-

Function	Not reentrant because
trunc truncf truncl	(Not implemented)
ungetc ungetwc	Uses static buffer to hold unget characters for each file. Can be moved into iob structure. See (1).
unlink	Uses global File System Simulation buffer, _dbg_request
vfprintf vfwprintf	Uses iob[]. See (1).
vfscanf vfwscanf	Calls _doscan
vprintf vwprintf	Uses iob[]. See (1).
vscanf vwscanf	Calls _doscan
vsprintf vswprintf	Sets errno.
vsscanf vswscanf	Sets errno.
wcrtomb	Sets errno.
wcsrtombs	Sets errno.
wcstoimax	Sets errno via calls to other functions.
wcstombs	N.A.; skeleton function
wcstoumax	Sets errno via calls to other functions.
wctob	-
wctomb	N.A.; skeleton function
wctrans	-
wctype	-
write	Calls _write

Table: C library reentrancy

Several functions in the C library are not reentrant due to the following reasons:

- The iob[] structure is static. This influences all I/O functions.
- The ungetc[] array is static. This array holds the characters (one for each stream) when ungetc() is called.
- The variable errno is globally defined. Numerous functions read or modify errno
- _doprint and _doscan use static variables for e.g. character counting in strings.
- Some string functions use locally defined (static) buffers. This is prescribed by ANSI.
- malloc uses a static heap space.

The following description discusses these items into more detail. The numbers at the begin of each paragraph relate to the number references in the table above.

(1) iob structures

The I/O part of the C library is not reentrant by design. This is mainly caused by the static declaration of the iob[] array. The functions which use elements of this array access these elements via pointers (FILE *).

Building a multi-process system that is created in one link-run is hard to do. The C language scoping rules for external variables make it difficult to create a private copy of the $iob[\]$ array. Currently, the $iob[\]$ array has external scope. Thus it is visible in every module involved in one link phase. If these modules comprise several tasks (processes) in a system each of which should have its private copy of $iob[\]$, it is apparent that the $iob[\]$ declaration should be changed. This requires adaptation of the library to the multi-tasking environment. The library modules must use a process identification as an index for determining which $iob[\]$ array to use. Thus the library is suitable for interfacing to that kernel only.

Another approach for the <code>iob[]</code> declaration problem is to declare the array static in one of the modules which create a task. Thus there can be more than one <code>iob[]</code> array is the system without having conflicts at link time. This brings several restrictions: Only the module that holds the declaration of the static <code>iob[]</code> can use the standard file handles <code>stdin</code>, <code>stdout</code> and <code>stderr</code> (which are the first three entries in <code>iob[]</code>). Thus all I/O for these three file handles should be located in one module.

(2) errno declaration

Several functions in the C library set the global variable errno. After completion of the function the user program may consult this variable to see if some error occurred. Since most of the functions that set errno already have a return type (this is the reason for using errno) it is not possible to check successful completion via the return type.

The library routines can set errno to the values defined in errno.h. See the file errno.h for more information.

errno can be set to ERR_FORMAT by the print and scan functions in the C library if you specify illegal format strings.

errno will never be set to ERR_NOLONG or ERR_NOPOINT since the C library supports long and pointer conversion routines for input and output.

errno can be set to ERANGE by the following functions: exp(), strtol(), strtoul() and tan(). These functions may produce results that are out of the valid range for the return type. If so, the result of the function will be the largest representable value for that type and errno is set to ERANGE.

errno is set to EDOM by the following functions: acos(), asin(), log(), pow() and sqrt(). If the arguments for these functions are out of their valid range (e.g. sqrt(-1)), errno is set to EDOM.

errno can be set to ERR_POS by the file positioning functions ftell(), fsetpos() and fgetpos().

(3) ungetc

Currently the ungetc buffer is static. For each file entry in the <code>iob[]</code> structure array, there is one character available in the buffer to unget a character.

(4) local buffers

tmpnam() creates a temporary filename and returns a pointer to a local static buffer. This is according to the ANSI definition. Changing this function such that it creates the name in a user specified buffer requires another calling interface. Thus the function would be no longer portable.

strtok() scans through a string and remembers that the string and the position in the string for subsequent calls. This function is not reentrant by design. Making it reentrant requires support of a kernel to store the information on a per process basis.

rand() generates a sequence of random numbers. The function uses the value returned by a previous call to generate the next value in the sequence. This function can be made reentrant by specifying the previous random value as one of the arguments. However, then it is no longer a standard function.

(5) malloc

Malloc uses a heap space which is assigned at locate time. Thus this implementation is not reentrant. Making a reentrant malloc requires some sort of system call to obtain free memory space on a per process basis. This is not easy to solve within the current context of the library. This requires adaptation to a kernel.

This paragraph on reentrancy applies to multi-process environments only. If reentrancy is required for calling library functions from an exception handler, another approach is required. For such a situation it is of no use to allocate e.g. multiple <code>iob[]</code> structures. In such a situation several pieces of code in the library have to be declared 'atomic': this means that interrupts have to be disabled while executing an atomic piece of code.

Chapter 14. List File Formats

This chapter describes the format of the assembler list file and the linker map file.

14.1. Assembler List File Format

The assembler list file is an additional output file of the assembler that contains information about the generated code. For details on how to generate a list file, see Section 7.4, *Generating a List File*.

The list file consists of a page header and a source listing.

Page header

The page header is repeated on every page:

```
TASKING VX-toolset for ARM: assembler vx.yrz Build nnn SN 00000000 Title Page 1

ADDR CODE CYCLES LINE SOURCE LINE
```

The first line contains version information. The second line can contain a title which you can specify with the assembler directive .TITLE and always contains a page number. The third line is empty and the fourth line contains the headings of the columns for the source listing.

With the assembler directives .LIST/.NOLIST, .PAGE, and with the assembler option --list-format you can format the list file.

Source listing

The following is a sample part of a listing. An explanation of the different columns follows below.

ADDR CODE	CYC	LES	LINE	SOURCE	LINE	
			1		; Modu	ıle start
0000 08009FE5	1	1	16		ldr	r0,.L2
0004 001090E5	1	2	17		ldr	r1,[r0,#0]
0008 04009FE5	1	3	18		ldr	r0,.L2+4
000C rrrrrEA	3	6	19		b	printf
0000			38		.ds	2
RESERVED						
0001						

ADDR

This column contains the memory address. The address is a hexadecimal number that represents the offset from the beginning of a relocatable section or the absolute address for an absolute section. The address only appears on lines that generate object code.

CODE This is the object code generated by the assembler for this source line, displayed

in hexadecimal format. The displayed code need not be the same as the generated code that is entered in the object module. The code can also be relocatable code. In this case the letter 'r' is printed for the relocatable code part in the listing. For lines that allocate space, the code field contains the text "RESERVED". For lines

that initialize a buffer, the code field lists one value followed by the word

"REPEATS".

CYCLES The first number in this column is the number of instruction cycles needed to

execute the instruction(s) as generated in the CODE field. The second number is

the accumulated cycle count of this section.

LINE This column contains the line number. This is a decimal number indicating each

input line, starting from 1 and incrementing with each source line.

SOURCE LINE This column contains the source text. This is a copy of the source line from the

assembly source file.

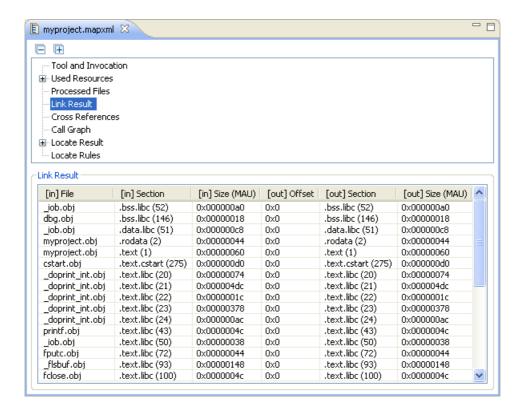
For the . SET and . EQU directives the ADDR and CODE columns do not apply. The symbol value is listed instead.

14.2. Linker Map File Format

The linker map file is an additional output file of the linker that shows how the linker has mapped the sections and symbols from the various object files (.obj) to output sections. The locate part shows the absolute position of each section. External symbols are listed per space with their absolute address, both sorted on symbol and sorted on address. For details on how to generate a map file, see Section 8.9, Generating a Map File.

With the linker option --map-file-format you can specify which parts of the map file you want to see.

In Eclipse the linker map file (project.mapxml) is generated in the output directory of the build configuration, usually Debug or Release. You can open the map file by double-clicking on the file name.



Each page displays a part of the map file. Use the \boxdot and \boxdot buttons to expand or collapse all items in the view. When you right-click in the view, a popup menu appears (for example, to reset the layout of a table). The meaning of the different parts is:

Tool and Invocation

This part of the map file contains information about the linker, its version header information, binary location and which options are used to call it.

Used Resources

This part of the map file shows the memory usage at memory level and space level. The largest free block of memory (Largest gap) is also shown. This part also contains an estimation of the stack usage.

Explanation of the columns:

Memory The names of the memory as defined in the linker script file (*.1s1).

Code The size of all executable sections.

Data The size of all non-executable sections (not including stacks, heaps, debug sections

in non-alloc space).

Reserved The total size of reserved memories, reserved ranges, reserved special sections,

stacks, heaps, alignment protections, sections located in non-alloc space (debug sections). In fact, this size is the same as the size in the Total column minus the

size of all other columns.

Free The free memory area addressable by this core. This area is accessible for

unrestricted items.

Total The total memory area addressable by this core.

Space The names of the address spaces as defined in the linker script file (* .1s1). The

names are constructed of the derivative name followed by a colon ':', the core name, another colon ':' and the space name. For example: ARM: ARM: linear.

Native used ... The size of sections located in this space.

Foreign used The size of all sections destined for/located in other spaces, but because of overlap

in spaces consume memory in this space.

Stack Name The name(s) of the stack(s) as defined in the linker script file (* . 1s1).

Used An estimation of the stack usage. The linker calculates the required stack size by

using information (.CALLS directives) generated by the compiler. If for example recursion is detected, the calculated stack size is inaccurate, therefore this is an estimation only. The calculated stack size is supposed to be smaller than the actual

allocated stack size. If that is not the case, then a warning is given.

Processed Files

This part of the map file shows all processed files. This also includes object files that are extracted from a library, with the symbol that led to the extraction.

Link Result

This part of the map file shows per object file how the link phase has mapped the sections from the various object files (.obj) to output sections.

[in] File The name of an input object file.

[in] Section A section name and id from the input object file. The number between '()' uniquely

identifies the section.

[in] Size The size of the input section.

[out] Offset The offset relative to the start of the output section.

[out] Section The resulting output section name and id.

[out] Size The size of the output section.

Module Local Symbols

This part of the map file shows a table for each local scope within an object file. Each table has three columns, 1 the symbol name, 2 the address of the symbol and 3 the space where the symbol resides in. The table is sorted on symbol name within each space.

By default this part is not shown in the map file. You have to turn this part on manually with linker option --map-file-format=+statics (module local symbols).

Cross References

This part of the map file lists all symbols defined in the object modules and for each symbol the object modules that contain a reference to the symbol are shown. Also, symbols that remain undefined are shown.

Call Graph

This part of the map file contains a schematic overview that shows how (library) functions call each other. To obtain call graph information, the assembly file must contain . CALLS directives.

You can click the + or - sign to expand or collapse a node.

Overlay

This part is empty for the ARM.

Locate Result: Sections

This part of the map file shows the absolute position of each section in the absolute object file. It is organized per address space, memory chip and group and sorted on space address.

+ Space	The names of the address spaces	ac defined in the link	or corint file (* 1 a1) The
+ Space	The names of the address spaces	as defined in the linke	er script lile (* . Ts D. The

names are constructed of the derivative name followed by a colon ':', the core name, another colon ':' and the space name. For example: ARM: ARM: linear.

Chip The names of the memory chips as defined in the linker script file (* .1s1) in the

memory definitions.

Group Sections can be ordered in groups. These are the names of the groups as defined

in the linker script file (*.1s1) with the keyword group in the section_layout definition. The name that is displayed is the name of the deepest nested group.

Section The name and id of the section. The number between '()' uniquely identifies the

section. Names within square brackets [] will be copied during initialization from

ROM to the corresponding section name in RAM.

Size (MAU) The size of the section in minimum addressable units.

Space addr

The absolute address of the section in the address space.

Chip addr The absolute offset of the section from the start of a memory chip.

Locate Result: Symbols

This part of the map file lists all external symbols per address space name.

Address The absolute address of the symbol in the address space.

Name The name of the symbol.

Space

The names of the address spaces as defined in the linker script file (*.ls1). The names are constructed of the derivative name followed by a colon '.', the core name, another colon '.' and the space name. For example: ARM: linear.

Processor and Memory

This part of the map file shows the processor and memory information of the linker script file.

By default this part is not shown in the map file. You have to turn this part on manually with linker option --map-file-format=+lsl (processor and memory info). You can print this information to a separate file with linker option --lsl-dump.

Locate Rules

This part of the map file shows the rules the linker uses to locate sections.

Address space

The names of the address spaces as defined in the linker script file (*.ls1). The names are constructed of the derivative name followed by a colon ':', the core name, another colon ':' and the space name.

Type

The rule type:

ordered/contiguous/clustered/unrestricted

Specifies how sections are grouped. By default, a group is 'unrestricted' which means that the linker has total freedom to place the sections of the group in the address space.

absolute

The section must be located at the address shown in the Properties column.

address range

The section must be located in the union of the address ranges shown in the Properties column; end addresses are not included in the range.

address range size

The sections must be located in some address range with size not larger than shown in the Properties column; the second number in that field is the alignment requirement for the address range.

ballooned

After locating all sections, the largest remaining gap in the space is used completely for the stack and/or heap.

Properties

The contents depends on the Type column.

Sections

The sections to which the rule applies;

restrictions between sections are shown in this column:

- < ordered
- contiguous
- + clustered

For contiguous sections, the linker uses the section order as shown here. Clustered sections can be located in any relative order.

Chapter 15. Object File Formats

This chapter describes the format of several object files.

15.1. ELF/DWARF Object Format

The TASKING toolset by default produces objects in the ELF/DWARF 2 format.

For a complete description of the ELF and DWARF formats, please refer to the *Tool Interface Standard (TIS)*.

15.2. Intel Hex Record Format

Intel Hex records describe the hexadecimal object file format for 8-bit, 16-bit and 32-bit microprocessors. The hexadecimal object file is an ASCII representation of an absolute binary object file. There are six different types of records:

- Data Record (8-, 16, or 32-bit formats)
- End of File Record (8-, 16, or 32-bit formats)
- Extended Segment Address Record (16, or 32-bit formats)
- Start Segment Address Record (16, or 32-bit formats)
- Extended Linear Address Record (32-bit format only)
- Start Linear Address Record (32-bit format only)

To generate an Intel Hex output file:

1. From the **Project** menu, select **Properties**

The Properties dialog appears.

2. In the left pane, expand **C/C++ Build** and select **Settings**.

In the right pane the Settings appear.

- 3. On the Tool Settings tab, select **Linker** » **Output Format**.
- 4. Enable the option **Generate Intel Hex format file**.
- 5. (Optional) Specify the Size of addresses (in bytes) for Intel Hex records.
- 6. (Optional) Enable or disable the optionEmit start address record.

By default the linker generates records in the 32-bit format (4-byte addresses).

General Record Format

In the output file, the record format is:

:	length	offset	type	content	checksum
---	--------	--------	------	---------	----------

where:

is the record header.

length is the record length which specifies the number of bytes of the content field. This

value occupies one byte (two hexadecimal digits). The linker outputs records of 255 bytes (32 hexadecimal digits) or less; that is, *length* is never greater than 0xFF.

offset is the starting load offset specifying an absolute address in memory where the

data is to be located when loaded by a tool. This field is two bytes long. This field is only used for Data Records. In other records this field is coded as four ASCII

zero characters ('0000').

type is the record type. This value occupies one byte (two hexadecimal digits). The

record types are:

Byte Type	Record Type
00	Data
01	End of file
02	Extended segment address (not used)
03	Start segment address (not used)
04	Extended linear address (32-bit)
05	Start linear address (32-bit)

content checksum is the information contained in the record. This depends on the record type.

is the record checksum. The linker computes the checksum by first adding the binary representation of the previous bytes (from length to content). The linker then computes the result of sum modulo 256 and subtracts the remainder from 256 (two's complement). Therefore, the sum of all bytes following the header is

zero.

Extended Linear Address Record

The Extended Linear Address Record specifies the two most significant bytes (bits 16-31) of the absolute address of the first data byte in a subsequent Data Record:

:	02	0000	04	upper_address	checksum
---	----	------	----	---------------	----------

The 32-bit absolute address of a byte in a Data Record is calculated as:

```
( address + offset + index ) modulo 4G
```

where:

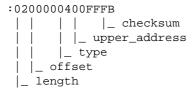
address is the base address, where the two most significant bytes are the upper_address

and the two least significant bytes are zero.

offset is the 16-bit offset from the Data Record.

index is the index of the data byte within the Data Record (0 for the first byte).

Example:



Data Record

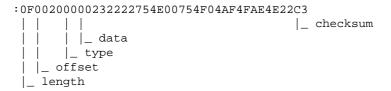
The Data Record specifies the actual program code and data.

•	lenath	offset	00	data	checksum
•	longur	Onoci	00	data	Onconsum

The *length* byte specifies the number of *data* bytes. The linker has an option (--hex-record-size) that controls the length of the output buffer for generating Data records. The default buffer length is 32 bytes.

The offset is the 16-bit starting load offset. Together with the address specified in the Extended Address Record it specifies an absolute address in memory where the data is to be located when loaded by a tool.

Example:



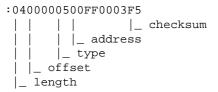
Start Linear Address Record

The Start Linear Address Record contains the 32-bit program execution start address.

:	04	0000	05	address	checksum

With linker option --hex-format=S you can prevent the linker from emitting this record.

Example:



End of File Record

The hexadecimal file always ends with the following end-of-file record:

15.3. Motorola S-Record Format

To generate a Motorola S-record output file:

1. From the **Project** menu, select **Properties**

The Properties dialog appears.

2. In the left pane, expand C/C++ Build and select Settings.

In the right pane the Settings appear.

- 3. On the Tool Settings tab, select **Linker** » **Output Format**.
- 4. Enable the option Generate S-records file.
- 5. (Optional) Specify the Size of addresses (in bytes) for Motorola S records.

By default, the linker produces output in Motorola S-record format with three types of S-records (4-byte addresses): S0, S3 and S7. Depending on the size of addresses you can force other types of S-records. They have the following layout:

S0 - record

S0 length 0000 comment checksum	checksum
---	----------

A linker generated S-record file starts with an S0 record with the following contents:

1 k a r m S00800006C6B61726DE0

The S0 record is a comment record and does not contain relevant information for program execution.

where:

S0 is a comment record and does not contain relevant information for program

execution.

length represents the number of bytes in the record, not including the record type and

length byte. This value occupies one byte (two hexadecimal digits).

comment contains the name of the linker.

checksum is the record checksum. The linker computes the checksum by first adding the

binary representation of the bytes following the record type (starting with the *length* byte) to just before the checksum. Then the one's complement is calculated of this sum. The least significant byte of the result is the checksum. The sum of all bytes

following the record type is 0xFF.

S1 / S2 / S3 - record

This record is the program code and data record for 2-byte, 3-byte or 4-byte addresses respectively.

S1	length	address	code bytes	checksum	
S2	length	address	address code bytes		
S 3	length	address	code bytes	checksum	

where:

st the program code and data record for 2-byte addresses.is the program code and data record for 3-byte addresses.

ss is the program code and data record for 4-byte addresses (this is the default).

length represents the number of bytes in the record, not including the record type and

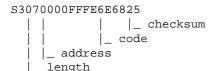
length byte. This value occupies one byte (two hexadecimal digits).

address contains the code or data address.

code bytes contains the actual program code and data.

checksum is the record checksum. The checksum calculation is identical to S0.

Example:



S7 / S8 / S9 - record

This record is the termination record for 4-byte, 3-byte or 2-byte addresses respectively.

S7	length	address	checksum
S8	length	address	checksum
S9	length	address	checksum

where:

\$7 is the termination record for 4-byte addresses (this is the default). \$7 is the

corresponding termination record for S3 records.

\$8 is the termination record for 3-byte addresses. \$8 is the corresponding termination

record for S2 records.

S9 is the termination record for 2-byte addresses. S9 is the corresponding termination

record for S1 records.

length represents the number of bytes in the record, not including the record type and

length byte. This value occupies one byte (two hexadecimal digits).

address contains the program start address.

checksum is the record checksum. The checksum calculation is identical to S0.

Example:

Chapter 16. Linker Script Language (LSL)

To make full use of the linker, you can write a script with information about the architecture of the target processor and locating information. The language for the script is called the *Linker Script Language (LSL)*. This chapter first describes the structure of an LSL file. The next section contains a summary of the LSL syntax. In the remaining sections, the semantics of the Linker Script Language is explained.

The TASKING linker is a target independent linker/locator that can simultaneously link and locate all programs for all cores available on a target board. The target board may be of arbitrary complexity. A simple target board may contain one standard processor with some external memory that executes one task. A complex target board may contain multiple standard processors and DSPs combined with configurable IP-cores loaded in an FPGA. Each core may execute a different program, and external memory may be shared by multiple cores.

LSL serves two purposes. First it enables you to specify the characteristics (that are of interest to the linker) of your specific target board and of the cores installed on the board. Second it enables you to specify how sections should be located in memory.

16.1. Structure of a Linker Script File

A script file consists of several definitions. The definitions can appear in any order.

The architecture definition (required)

In essence an *architecture definition* describes how the linker should convert logical addresses into physical addresses for a given type of core. If the core supports multiple address spaces, then for each space the linker must know how to perform this conversion. In this context a physical address is an offset on a given internal or external bus. Additionally the architecture definition contains information about items such as the (hardware) stack and the vector table.

This specification is normally written by Altium. Altium supplies LSL files in the include.lsl directory. The architecture definition of the LSL file should not be changed by you unless you also modify the core's hardware architecture. If the LSL file describes a multi-core system an architecture definition must be available for each different type of core.

See Section 16.4, Semantics of the Architecture Definition for detailed descriptions of LSL in the architecture definition.

The derivative definition

The *derivative definition* describes the configuration of the internal (on-chip) bus and memory system. Basically it tells the linker how to convert offsets on the buses specified in the architecture definition into offsets in internal memory. Microcontrollers and DSPs often have internal memory and I/O sub-systems apart from one or more cores. The design of such a chip is called a *derivative*.

When you build an ASIC or use a derivative that is not (yet) supported by the TASKING tools, you may have to write a derivative definition.

When you want to use multiple cores of the same type, you must instantiate the cores in a derivative definition, since the linker automatically instantiates only a single core for an unused architecture.

See Section 16.5, Semantics of the Derivative Definition for a detailed description of LSL in the derivative definition.

The processor definition

The *processor definition* describes an instance of a derivative. Typically the processor definition instantiates one derivative only (single-core processor). A processor that contains multiple cores having the same (homogeneous) or different (heterogeneous) architecture can also be described by instantiating multiple derivatives of the same or different types in separate processor definitions.

See Section 16.6, Semantics of the Board Specification for a detailed description of LSL in the processor definition.

The memory and bus definitions (optional)

Memory and bus definitions are used within the context of a derivative definition to specify internal memory and on-chip buses. In the context of a board specification the memory and bus definitions are used to define external (off-chip) memory and buses. Given the above definitions the linker can convert a logical address into an offset into an on-chip or off-chip memory device.

See Section 16.6.3, *Defining External Memory and Buses*, for more information on how to specify the external physical memory layout. *Internal* memory for a processor should be defined in the derivative definition for that processor.

The board specification

The processor definition and memory and bus definitions together form a *board specification*. LSL provides language constructs to easily describe single-core and heterogeneous or homogeneous multi-core systems. The board specification describes all characteristics of your target board's system buses, memory devices, I/O sub-systems, and cores that are of interest to the linker. Based on the information provided in the board specification the linker can for each core:

- · convert a logical address to an offset within a memory device
- locate sections in physical memory
- maintain an overall view of the used and free physical memory within the whole system while locating

The section layout definition (optional)

The optional section layout definition enables you to exactly control where input sections are located. Features are provided such as: the ability to place sections at a given load-address or run-time address, to place sections in a given order, and to overlay code and/or data sections.

Which object files (sections) constitute the task that will run on a given core is specified on the command line when you invoke the linker. The linker will link and locate all sections of all tasks simultaneously. From the section layout definition the linker can deduce where a given section may be located in memory, form the board specification the linker can deduce which physical memory is (still) available while locating the section.

See Section 16.8, Semantics of the Section Layout Definition, for more information on how to locate a section at a specific place in memory.

Skeleton of a Linker Script File

```
architecture architecture_name
{
    // Specification core architecture
}
derivative derivative_name
{
    // Derivative definition
}
processor processor_name
{
    // Processor definition
}
memory and/or bus definitions
section_layout space_name
{
    // section placement statements
```

16.2. Syntax of the Linker Script Language

This section describes what the LSL language looks like. An LSL document is stored as a file coded in UTF-8 with extension .1s1. Before processing an LSL file, the linker preprocesses it using a standard C preprocessor. Following this, the linker interprets the LSL file using a scanner and parser. Finally, the linker uses the information found in the LSL file to guide the locating process.

16.2.1. Preprocessing

When the linker loads an LSL file, the linker processes it with a C-style prepocessor. As such, it strips C and C++ comments. You can use the standard ISO C preprocessor directives, such as #include, #define, #if/#else/#endif.

For example:

```
#include "arch.lsl"
```

Preprocess and include the file arch.lsl at this point in the LSL file.

16.2.2. Lexical Syntax

The following lexicon is used to describe the syntax of the Linker Script Language:

```
A : := B
                          = A is defined as B
A ::= B C
                          = A is defined as B and C; B is followed by C
                          = A is defined as B or C
A ::= B \mid C
< B > 0 | 1
                          = zero or one occurrence of B
<B><sup>>=0</sup>
                               zero of more occurrences of B
<B>>=1
                               one of more occurrences of B
                               a character sequence starting with 'a'-'z', 'A'-'Z' or '_'. Following
IDENTIFIER
                               characters may also be digits and dots '.'
STRING
                               sequence of characters not starting with \n, \r or \t
                               " STRING " (double quoted string)
DQSTRING
                          =
OCT\_NUM
                               octal number, starting with a zero (06, 045)
                          =
DEC_NUM
                               decimal number, not starting with a zero (14, 1024)
                          =
HEX_NUM
                               hexadecimal number, starting with '0x' (0x0023, 0xFF00)
```

 OCT_NUM , DEC_NUM and HEX_NUM can be followed by a k (kilo), M (mega), or G (giga).

Characters in **bold** are characters that occur literally. Words in *italics* are higher order terms that are defined in the same or in one of the other sections.

To write comments in LSL file, you can use the C style '/* */' or C++ style '//'.

16.2.3. Identifiers and Tags

```
::=IDENTIFIER
arch_name
bus_name
               ::= IDENTIFIER
core_name
               ::=IDENTIFIER
derivative_name ::= IDENTIFIER
file_name ::= DQSTRING
group_name
               ::=IDENTIFIER
heap_name
               ::= section_name
mem_name
               ::= IDENTIFIER
proc_name
               ::= IDENTIFIER
section_name
               ::= DQSTRING
space_name
               ::= IDENTIFIER
stack_name
               ::= section_name
symbol name
               ::= DOSTRING
                ::= (tag<,tag><sup>>=0</sup>)
tag_attr
                ::= tag = DQSTRING
tag
```

A tag is an arbitrary text that can be added to a statement.

16.2.4. Expressions

The expressions and operators in this section work the same as in ISO C.

```
number
                ::= OCT_NUM
                  DEC_NUM
                  HEX_NUM
                ::= number
expr
                  symbol_name
                  | unary_op expr
                  | expr binary_op expr
                  expr ? expr : expr
                  ( expr )
                  | function_call
unary_op
                ::=!
                       // logical NOT
                       // bitwise complement
                      // negative value
                ::= ^
                      // exclusive OR
binary_op
                       // multiplication
                   /
                       // division
                       // modulus
                       // addition
                    +
                       // subtraction
                       // right shift
                  | >>
                  ==
                       // equal to
                       // not equal to
                  ! =
                   >
                       // greater than
                       // less than
                    <
                       // greater than or equal to
                    >=
                       // less than or equal to
                    <=
                       // bitwise AND
                    &
                       // bitwise OR
                    &&
                       // logical AND
                    Ш
                        // logical OR
```

16.2.5. Built-in Functions

- Every space, bus, memory, section or group your refer to, must be defined in the LSL file.
- The addressof() and sizeof() functions with the group or sect argument can only be used in the right hand side of an assignment. The sizeof() function with the mem argument can be used anywhere in section layouts.

You can use the following built-in functions in expressions. All functions return a numerical value. This value is a 64-bit signed integer.

absolute()

```
int absolute( expr )
```

Converts the value of expr to a positive integer.

```
absolute( "labelA"-"labelB" )
```

addressof()

```
int addressof( addr_id )
```

Returns the address of addr_id, which is a named section or group. To get the offset of the section with the name asect:

```
addressof( sect: "asect")
```

This function only works in assignments.

exists()

```
int exists( section_name )
```

The function returns 1 if the section section_name exists in one or more object file, 0 otherwise. If the section is not present in input object files, but generated from LSL, the result of this function is undefined.

To check whether the section mysection exists in one of the object files that is specified to the linker:

```
exists( "mysection" )
max()
```

int max(expr, expr)

Returns the value of the expression that has the largest value. To get the highest value of two symbols:

```
max( "sym1" , "sym2")
```

min()

```
int min( expr, expr )
```

Returns the value of the expression hat has the smallest value. To get the lowest value of two symbols:

```
min( "sym1" , "sym2")
sizeof()
```

```
int sizeof( size_id )
```

Returns the size of the object (group, section or memory) the identifier refers to. To get the size of the section "asection":

```
sizeof( sect: "asection" )
```

The group and sect arguments only works in assignments. The mem argument can be used anywhere in section layouts.

16.2.6. LSL Definitions in the Linker Script File

• At least one architecture_definition must be present in the LSL file.

16.2.7. Memory and Bus Definitions

```
mem_def ::= memory mem_name <tag_attr>0|1 { <mem_descr ;> >=0 }
```

• A mem_def defines a memory with the mem_name as a unique name.

- A mem_def contains exactly one type statement.
- A mem_def contains exactly one mau statement (non-zero size).
- A mem_def contains exactly one size statement.
- A mem_def contains zero or one speed statement (default value is 1).

• A mem_def contains at least one mapping

A bus_def statement defines a bus with the given bus_name as a unique name within a core
architecture.

- The mau and width statements appear exactly once in a bus_descr. The default value for width is
 the mau size.
- The bus width must be an integer times the bus MAU size.
- The MAU size must be non-zero.
- A bus can only have a mapping on a destination bus (through dest = bus:).

- A mapping requires at least the size and dest statements.
- Each map_descr can occur only once.
- You can define multiple mappings from a single source.
- Overlap between source ranges or destination ranges is not allowed.
- If the src_dbits or dest_dbits statement is not present, its value defaults to the width value if the source/destination is a bus, and to the mau size otherwise.

• A space name refers to a defined address space.

- A proc_name refers to a defined processor.
- A core name refers to a defined core.
- A bus_name refers to a defined bus.
- The following mappings are allowed (source to destination)
 - space => space
 - space => bus
 - bus => bus
 - memory => bus

```
range ::= expr .. expr
```

• With address ranges, the end address is not part of the range.

16.2.8. Architecture Definition

- An architecture_definition defines a core architecture with the given arch_name as a unique name.
- At least one <code>space_def</code> and at least one <code>bus_def</code> have to be present in an <code>architecture_definition</code>.
- An architecture_definition that uses the extends construct defines an architecture that inherits
 all elements of the architecture defined by the second arch_name. The parent architecture must be
 defined in the LSL file as well.

A space_def defines an address space with the given space_name as a unique name within an
architecture.

```
space_descr
                  ::= space_property ;
                    | section_definition //no space ref
                    | vector_table_statement
                    reserved_range
space_property
                  ::= id = number // as used in object
                    mau = expr
                    | align = expr
                    | page_size = expr <[ range ] <| [ range ]>^{>0}1
                    | direction = direction
                    | stack def
                    heap_def
                    | copy_table_def
                    | start address
                    mapping
```

- A space_def contains exactly one id and one mau statement.
- A space_def contains at most one align statement.
- A space_def contains at most one page_size statement.
- A space_def contains at most one mapping.

```
stack_def ::= stack stack_name ( stack_heap_descr
<, stack heap descr >>=0 )
```

• A stack def defines a stack with the stack name as a unique name.

• A heap_def defines a heap with the heap_name as a unique name.

- The min_size statement must be present.
- You can specify at most one align statement and one grows statement.
- Each stack definition has its own unique id, the number specified corresponds to the index in the .CALLS directive as generated by the compiler.

• If you do not specify the grows statement, the stack and heap grow low-to-high.

- A space_def contains at most one copytable statement.
- Exactly one copy table must be defined in one of the spaces.

- The copy_unit is defined by the size in MAUs in which the startup code moves data.
- The dest statement is only required when the startup code initializes memory used by another processor that has no access to ROM.
- A space_name refers to a defined address space.

• A symbol_name refers to the section that contains the startup code.

```
vector_table_statement
                  ::= vector_table section_name
                      ( vecttab_spec <, vecttab_spec> >= 0 )
                       { <vector_def> >= 0 }
vecttab spec
                  ::= vector_size = expr
                    size = expr
                    id symbol prefix = symbol name
                    | run addr = addr absolute
                    template = section_name
                    | template_symbol = symbol_name
                     vector_prefix = section_name
                    | fill = vector_value
                    no inline
                    copy
                    tag
vector_def
                  ::= vector ( vector_spec <, vector_spec> >=0 );
                  ::= id = vector_id_spec
vector_spec
                    | fill = vector_value
```

tag

16.2.9. Derivative Definition

 A derivative_definition defines a derivative with the given derivative_name as a unique name.

- A core_def defines a core with the given core_name as a unique name.
- At least one core_def must be present in a derivative_definition.

- An arch_name refers to a defined core architecture.
- Exactly one architecture statement must be present in a core_def.

16.2.10. Processor Definition and Board Specification

- A proc_def defines a processor with the proc_name as a unique name.
- If you do not explicitly define a processor for a derivative in an LSL file, the linker defines a processor
 with the same name as that derivative.
- A derivative name refers to a defined derivative.
- A proc_def contains exactly one derivative statement.

16.2.11. Section Layout Definition and Section Setup

- A section definition inside a space definition does not have a space_ref.
- All global section definitions have a space_ref.

- If more than one processor is present, the proc_name must be given for a global section lavout.
- If the section layout refers to a processor that has more than one core, the *core_name* must be given in the *space_ref*.
- A proc_name refers to a defined processor.
- A core_name refers to a defined core.
- A space_name refers to a defined address space.

- A section layout contains at most one direction statement.
- If you do not specify the direction statement, the locate direction of the section layout is low-to-high.

• Either a section name or at least one section selection must be defined.

- +attribute means; select all sections that have this attribute.
- -attribute means: select all sections that do not have this attribute.

· Special sections cannot be selected in load-time groups.

If a reserved section has attributes r, rw, x, rx or rwx, and no fill pattern is defined, the section is
filled with zeros. If no attributes are set, the section is created as a scratch section (attributes ws, no
image).

• No two groups for an address space can have the same group_name.

- The allow-cross-references property is only allowed for *overlay* groups.
- Sub groups inherit all properties from a parent group.

```
x // executable code sections
                         // initialized sections
                         // scratch sections
                         // blanked (cleared) sections
                   b
group load address
                 ::= load addr <= load or run addr>0|1
                 ::= page <= expr>0|1
group_page
                   | page_size = expr <[ range ] <| [ range ]>^{>0}1
group_run_address ::= run_addr <= load_or_run_addr>0|1
                 ::= clustered
group_type
                   contiguous
                    ordered
                    overlay
```

- For non-contiguous groups, you can only specify group_alignment and attributes.
- The overlay keyword also sets the contiguous property.
- The clustered property cannot be set together with contiguous or ordered on a single group.

• An absolute address can only be set on ordered groups.

- The parent of a group with an addr_range or page restriction cannot be ordered, contiguous or clustered.
- The end address is not part of the range.

```
memory_reference ::= mem : cproc_name :>0|1 <core_name :>0|1 mem_name
```

- A proc name refers to a defined processor.
- A core_name refers to a defined core.
- A mem_name refers to a defined memory.

```
section creation statement
                  ::= section section_name ( section_specs )
                      { <section_statement2> >= 0 }
                  ::= section_spec <, section_spec > >=0
section_specs
section spec
                  ::= attributes
                    | fill_spec
                     | size = expr
                     | blocksize = expr
                     overflow = section_name
                     tag
section_statement2
                  ::= select_section_statement ;
                    group_descr2
                    { <section_statement2> >=0 }
                  ::= group < group name > 0 | 1
group_descr2
                            ( group_specs2 )
                             section_statement2
                  ::= group_spec2 <, group_spec2 > >=0
group_specs2
group_spec2
                  ::= group_alignment
                    attributes
                    load addr
                    tag
                  ::= section_setup space_ref <tag_attr>0|1
section setup
                      { <section_setup_item> >= 0 }
section_setup_item
                  ::= vector_table_statement
                    reserved_range
                    | stack def ;
                    heap_def ;
```

16.3. Expression Evaluation

Only constant expressions are allowed, including sizes, but not addresses, of sections in object files.

All expressions are evaluated with 64-bit precision integer arithmetic. The result of an expression can be absolute or relocatable. A symbol you assign is created as an absolute symbol.

16.4. Semantics of the Architecture Definition

Keywords in the architecture definition

```
architecture
   extends
endianness
              big little
bus
  mau
  width
  map
space
   id
  mau
  align
  page_size
  page
  direction
                   low_to_high high_to_low
   stack
     min_size
     grows
                    low_to_high high_to_low
     align
     fixed
      id
  heap
     min_size
      grows
                    low_to_high high_to_low
      align
      fixed
      id
   copytable
     align
      copy_unit
      dest
      page
   vector_table
      vector_size
      id_symbol_prefix
      run addr
      template
      template_symbol
      vector_prefix
      fill
      no_inline
      сору
      vector
         id
         fill
                    1000
  reserved
```

16.4.1. Defining an Architecture

With the keyword architecture you define an architecture and assign a unique name to it. The name is used to refer to it at other places in the LSL file:

```
architecture name
{
     definitions
}
```

If you are defining multiple core architectures that show great resemblance, you can define the common features in a parent core architecture and extend this with a child core architecture that contains specific features. The child inherits all features of the parent. With the keyword extends you create a child core architecture:

```
architecture name_child_arch extends name_parent_arch
{
    definitions
}
```

A core architecture can have any number of parameters. These are identifiers which get values assigned on instantiation or extension of the architecture. You can use them in any expression within the core architecture. Parameters can have default values, which are used when the core architecture is instantiated with less arguments than there are parameters defined for it. When you extend a core architecture you can pass arguments to the parent architecture. Arguments are expressions that set the value of the parameters of the sub-architecture.

16.4.2. Defining Internal Buses

With the bus keyword you define a bus (the combination of data and corresponding address bus). The bus name is used to identify a bus and does not conflict with other identifiers. Bus descriptions in an architecture definition or derivative definition define *internal* buses. Some internal buses are used to

communicate with the components outside the core or processor. Such buses on a processor have physical pins reserved for the number of bits specified with the width statements.

- The mau field specifies the MAU size (Minimum Addressable Unit) of the data bus. This field is required.
- The width field specifies the width (number of address lines) of the data bus. The default value is the MAU size.
- The map keyword specifies how this bus maps onto another bus (if so). Mappings are described in Section 16.4.4, Mappings.

```
bus bus_name
{
    mau = 8;
    width = 8;
    map ( map_description );
}
```

16.4.3. Defining Address Spaces

With the space keyword you define a logical address space. The space name is used to identify the address space and does not conflict with other identifiers.

- The id field defines how the addressing space is identified in object files. In general, each address space has a unique ID. The linker locates sections with a certain ID in the address space with the same ID. This field is required.
- The mau field specifies the MAU size (Minimum Addressable Unit) of the space. This field is required.
- The align value must be a power of two. The linker uses this value to compute the start addresses when sections are concatenated. An align value of *n* means that objects in the address space have to be aligned on *n* MAUs.
- The page_size field sets the page alignment and page size in MAUs for the address space. It must
 be a power of 2. The default value is 1. If one or more page ranges are supplied the supplied value
 only sets the page alignment. The ranges specify the available space in each page, as offsets to the
 page start, which is aligned at the page alignment.

See also the page keyword in subsection Locating a group in Section 16.8.2, *Creating and Locating Groups of Sections*.

- With the optional direction field you can specify how all sections in this space should be located.

 This can be either from low to high addresses (this is the default) or from high to low addresses.
- The map keyword specifies how this address space maps onto an internal bus or onto another address space. Mappings are described in Section 16.4.4, Mappings.

Stacks and heaps

The stack keyword defines a stack in the address space and assigns a name to it. The architecture
definition must contain at least one stack definition. Each stack of a core architecture must have a
unique name. See also the stack keyword in Section 16.8.3, Creating or Modifying Special Sections.

The stack is described in terms of a minimum size (min_size) and the direction in which the stack grows (grows). This can be either from low_to_high addresses (stack grows upwards, this is the default) or from high to low addresses (stack grows downwards). The min size is required.

By default, the linker tries to maximize the size of the stacks and heaps. After locating all sections, the largest remaining gap in the space is used completely for the stacks and heaps. If you specify the keyword fixed, you can disable this so-called 'balloon behavior'. The size is also fixed if you used a stack or heap in the software layout definition in a restricted way. For example when you override a stack with another size or select a stack in an ordered group with other sections.

The id keyword matches stack information generated by the compiler with a stack name specified in LSL. This value assigned to this keyword is strongly related to the compiler's output, so users are not supposed to change this configuration.

Optionally you can specify an alignment for the stack with the argument align. This alignment must be equal or larger than the alignment that you specify for the address space itself.

The heap keyword defines a heap in the address space and assigns a name to it. The definition of a
heap is similar to the definition of a stack. See also the heap keyword in Section 16.8.3, Creating or
Modifying Special Sections.

Stacks and heaps are only generated by the linker if the corresponding linker labels are referenced in the object files.

See Section 16.8, Semantics of the Section Layout Definition, for information on creating and placing stack sections.

Copy tables

• The copytable keyword defines a copy table in the address space. The content of the copy table is created by the linker and contains the start address and size of all sections that should be initialized by the startup code. You must define exactly one copy table in one of the address spaces (for a core).

Optionally you can specify an alignment for the copy table with the argument align. This alignment must be equal or larger than the alignment that you specify for the address space itself. If smaller, the alignment for the address space is used.

The copy_unit argument specifies the size in MAUs of information chunks that are copied. If you do not specify the copy unit, the MAU size of the address space itself is used.

The dest argument specifies the destination address space that the code uses for the copy table. The linker uses this information to generate the correct addresses in the copy table. The memory into where the sections must be copied at run-time, must be accessible from this destination space.

Sections generated for the copy table may get a page restriction with the address space's page size, by adding the page argument.

Vector table

The vector_table keyword defines a vector table with n vectors of size m (This is an internal LSL object similar to an LSL group.) The run_addr argument specifies the location of the first vector (id=0).
 This can be a simple address or an offset in memory (see the description of the run-time address in

subsection Locating a group in Section 16.8.2, *Creating and Locating Groups of Sections*). A vector table defines symbols _lc_ub_foo and _lc_ue_foo pointing to start and end of the table.

```
vector_table "vector_table" (vector_size=m, size=n, run_addr=x, ...)
```

See the following example of a vector table definition:

```
vector_table "vector_table" (vector_size = 4, size = 16, run_addr=0,
                    template=".text.handler_address",
                    template_symbol="_lc_vector_handler",
                    vector_prefix="_vector_",
                    id_symbol_prefix="foo",
                    no inline,
                    /* default: empty, or */
                    fill="foo", /* or */
                    fill=[1,2,3,4], /* or */
                    fill=loop)
{
   vector (id=23, fill="main");
   vector (id=12, fill=[0xab, 0x21, 0x32, 0x43]);
   vector (id=[1..11], fill=[0]);
   vector (id=[18..23], fill=loop);
}
```

The template argument defines the name of the section that holds the code to jump to a handler function from the vector table. This template section does not get located and is removed when the locate phase is completed. This argument is required.

The template_symbol argument is the symbol reference in the template section that must be replaced by the address of the handler function. This symbol name should start with the linker prefix for the symbol to be ignored in the link phase. This argument is required.

The vector_prefix argument defines the names of vector sections: the section for a vector with id vector_id is \$(vector_prefix)\$(vector_id). Vectors defined in C or assembly source files that should be included in the vector table must have the correct symbol name. The compiler uses the prefix that is defined in the default LSL file(s); if this attribute is changed, the vectors declared in C source files are not included in the vector table. When a vector supplied in an object file has exactly one relocation, the linker will assume it is a branch to a handler function, and can be removed when the handler is inlined in the vector table. Otherwise, no inlining is done. This argument is required.

With the optional no_inline argument the vectors handlers are not inlined in the vector table.

With the optional **copy** argument a ROM copy of the vector table is made and the vector table is copied to RAM at startup.

With the optional id_symbol_prefix argument you can set an internal string representing a symbol name prefix that may be found on symbols in vector handler code. When the linker detects such a symbol in a handler, the symbol is assigned the vector number. If the symbol was already assigned a vector number, a warning is issued.

The fill argument sets the default contents of vectors. If nothing is specified for a vector, this setting is used. See below. When no default is provided, empty vectors may be used to locate large vector handlers and other sections. Only one fill argument is allowed.

The **vector** field defines the content of vector with the number specified by **id**. If a range is specified for **id** ([p..q,s..t]) all vectors in the ranges (inclusive) are defined the same way.

With fill=symbol_name, the vector must jump to this symbol. If the section in which the symbol is defined fits in the vector table (size may be >m), locate the section at the location of the vector. Otherwise, insert code to jump to the symbol's value. A template interrupt handler section name + symbol name for the target code must be supplied in the LSL file.

fill=[value(s)], fills the vector with the specified MAU values.

With fill=loop the vector jumps to itself. With the optional [offset] you can specify an offset from the vector table entry.

Reserved address ranges

 The reserved keyword specifies to reserve a part of an address space even if not all of the range is covered by memory. See also the reserved keyword in Section 16.8.3, Creating or Modifying Special Sections.

Start address

 The start_address keyword specifies the start address for the position where the C startup code is located. When a processor is reset, it initializes its program counter to a certain start address, sometimes called the reset vector. In the architecture definition, you must specify this start address in the correct address space in combination with the name of the label in the application code which must be located here.

The run_addr argument specifies the start address (reset vector). If the core starts executing using an entry from a vector table, and directly jumps to the start label, you should omit this argument.

The symbol argument specifies the name of the label in the application code that should be located at the specified start address. The symbol argument is required. The linker will resolve the start symbol and use its value after locating for the start address field in IEEE-695 files and Intel Hex files. If you also specified the run_addr argument, the start symbol (label) must point to a section. The linker locates this section such that the start symbol ends up on the start address.

```
map ( map_description );
}
```

16.4.4. Mappings

You can use a mapping when you define a space, bus or memory. With the map field you specify how addresses from the source (space, bus or memory) are translated to addresses of a destination (space, bus). The following mappings are possible:

- space => space
- space => bus
- bus => bus
- memory => bus

With a mapping you specify a range of source addresses you want to map (specified by a source offset and a size), the destination to which you want to map them (a bus or another address space), and the offset address in the destination.

- The dest argument specifies the destination. This can be a bus or another address space (only for a space to space mapping). This argument is required.
- The src_offset argument specifies the offset of the source addresses. In combination with size, this
 specifies the range of address that are mapped. By default the source offset is 0x0000.
- The size argument specifies the number of addresses that are mapped. This argument is required.
- The dest_offset argument specifies the position in the destination to which the specified range of addresses is mapped. By default the destination offset is 0x0000.

If you are mapping a bus to another bus, the number of data lines of each bus may differ. In this case you have to specify a range of source data lines you want to map (src_dbits = begin..end) and the range of destination data lines you want to map them to (dest_dbits = first..last).

- The src_dbits argument specifies a range of data lines of the source bus. By default all data lines are mapped.
- The dest_dbits argument specifies a range of data lines of the destination bus. By default, all data
 lines from the source bus are mapped on the data lines of the destination bus (starting with line 0).

From space to space

If you map an address space to another address space (nesting), you can do this by mapping the subspace to the containing larger space. In this example a small space of 64 kB is mapped on a large space of 16 MB.

```
space small
{
   id = 2;
   mau = 4;
```

From space to bus

All spaces that are not mapped to another space must map to a bus in the architecture:

From bus to bus

The next example maps an external bus called e_bus to an internal bus called i_bus . This internal bus resides on a core called mycore. The source bus has 16 data lines whereas the destination bus has only 8 data lines. Therefore, the keywords src_dbits and $dest_dbits$ specify which source data lines are mapped on which destination data lines.

```
architecture mycore
{
    bus i_bus
    {
       mau = 4;
    }

    space i_space
    {
       map (dest=bus:i_bus, size=256);
    }
}
bus e_bus
{
    mau = 16;
    width = 16;
    map (dest = bus:mycore:i_bus, src_dbits = 0..7, dest_dbits = 0..7)
}
```

It is not possible to map an internal bus to an external bus.

16.5. Semantics of the Derivative Definition

Keywords in the derivative definition

```
derivative
  extends
core
   architecture
bus
  mau
  width
  map
memory
                  reserved rom ram nvram
   type
   mau
   size
   speed
  map
section_layout
section_setup
   map
     dest bus space
      dest dbits
     dest_offset
      size
      src dbits
      src_offset
```

16.5.1. Defining a Derivative

With the keyword derivative you define a derivative and assign a unique name to it. The name is used to refer to it at other places in the LSL file:

```
derivative name
{
      definitions
}
```

If you are defining multiple derivatives that show great resemblance, you can define the common features in a parent derivative and extend this with a child derivative that contains specific features. The child inherits all features of the parent (cores and memories). With the keyword extends you create a child derivative:

```
derivative name_child_deriv extends name_parent_deriv
{
    definitions
}
```

As with a core architecture, a derivative can have any number of parameters. These are identifiers which get values assigned on instantiation or extension of the derivative. You can use them in any expression within the derivative definition.

16.5.2. Instantiating Core Architectures

With the keyword core you instantiate a core architecture in a derivative.

With the keyword architecture you tell the linker that the given core has a certain architecture. The
architecture name refers to an existing architecture definition in the same LSL file.

For example, if you have two cores (called mycore_1 and mycore_2) that have the same architecture (called mycorearch), you must instantiate both cores as follows:

```
core mycore_1
{
          architecture = mycorearch;
}
core mycore_2
{
          architecture = mycorearch;
}
```

If the architecture definition has parameters you must specify the arguments that correspond with the parameters. For example mycorearch1 expects two parameters which are used in the architecture definition:

```
core mycore
{
    architecture = mycorearch1 (1,2);
}
```

16.5.3. Defining Internal Memory and Buses

With the memory keyword you define physical memory that is present on the target board. The memory name is used to identify the memory and does not conflict with other identifiers. It is common to define internal memory (on-chip) in the derivative definition. External memory (off-chip memory) is usually defined in the board specification (See Section 16.6.3, *Defining External Memory and Buses*).

- The type field specifies a memory type:
 - rom: read-only memory it can only be written at load-time

- ram: random access volatile writable memory writing at run-time is possible while writing at load-time
 has no use since the data is not retained after a power-down
- nvram: non volatile ram writing is possible both at load-time and run-time

The optional reserved qualifier before the memory type, tells the linker not to locate any section in the memory by default. You can locate sections in such memories using an absolute address or range restriction (see subsection Locating a group in Section 16.8.2, Creating and Locating Groups of Sections).

- The mau field specifies the MAU size (Minimum Addressable Unit) of the memory. This field is required.
- The size field specifies the size in MAU of the memory. This field is required.
- The speed field specifies a symbolic speed for the memory (1..4): 1 is the slowest, 4 the fastest. The
 linker uses the relative speed of the memories in such a way, that faster memory is used before slower
 memory. The default speed is 1.
- The map field specifies how this memory maps onto an (internal) bus. Mappings are described in Section 16.4.4, Mappings.

```
memory mem_name
{
    type = rom;
    mau = 8;
    size = 64k;
    speed = 2;
    map ( map_description );
}
```

With the bus keyword you define a bus in a derivative definition. Buses are described in Section 16.4.2, Defining Internal Buses.

16.6. Semantics of the Board Specification

Keywords in the board specification

```
processor
   derivative
bus
   mau
   width
   map
memory
                   reserved rom ram nvram
   type
   mau
   size
   speed
   map
   map
      dest
                    bus space
```

```
dest_dbits
dest_offset
size
src_dbits
src_offset
```

16.6.1. Defining a Processor

If you have a target board with multiple processors that have the same derivative, you need to instantiate each individual processor in a processor definition. This information tells the linker which processor has which derivative and enables the linker to distinguish between the present processors.

If you use processors that all have a unique derivative, you may omit the processor definitions. In this case the linker assumes that for each derivative definition in the LSL file there is one processor. The linker uses the derivative name also for the processor.

With the keyword processor you define a processor. You can freely choose the processor name. The name is used to refer to it at other places in the LSL file:

```
processor proc_name
{
    processor definition
}
```

16.6.2. Instantiating Derivatives

With the keyword derivative you tell the linker that the given processor has a certain derivative. The derivative name refers to an existing derivative definition in the same LSL file.

For example, if you have two processors on your target board (called myproc_1 and myproc_2) that have the same derivative (called myderiv), you must instantiate both processors as follows:

```
processor myproc_1
{
         derivative = myderiv;
}
processor myproc_2
{
         derivative = myderiv;
}
```

If the derivative definition has parameters you must specify the arguments that correspond with the parameters. For example myderiv1 expects two parameters which are used in the derivative definition:

```
processor myproc
{
     derivative = myderiv1 (2,4);
}
```

16.6.3. Defining External Memory and Buses

It is common to define external memory (off-chip) and external buses at the global scope (outside any enclosing definition). Internal memory (on-chip memory) is usually defined in the scope of a derivative definition.

With the keyword memory you define physical memory that is present on the target board. The memory name is used to identify the memory and does not conflict with other identifiers. If you define memory parts in the LSL file, only the memory defined in these parts is used for placing sections.

If no external memory is defined in the LSL file and if the linker option to allocate memory on demand is set then the linker will assume that all virtual addresses are mapped on physical memory. You can override this behavior by specifying one or more memory definitions.

```
memory mem_name
{
    type = rom;
    mau = 8;
    size = 64k;
    speed = 2;
    map ( map_description );
}
```

For a description of the keywords, see Section 16.5.3, Defining Internal Memory and Buses.

With the keyword bus you define a bus (the combination of data and corresponding address bus). The bus name is used to identify a bus and does not conflict with other identifiers. Bus descriptions at the global scope (outside any definition) define external buses. These are buses that are present on the target board.

```
bus bus_name
{
     mau = 8;
     width = 8;
     map ( map_description );
}
```

For a description of the keywords, see Section 16.4.2, Defining Internal Buses.

You can connect off-chip memory to any derivative: you need to map the off-chip memory to a bus and map that bus on the internal bus of the derivative you want to connect it to.

16.7. Semantics of the Section Setup Definition

Keywords in the section setup definition

```
section_setup
  stack
    min_size
    grows    low_to_high high_to_low
    align
```

```
fixed
   iд
heap
   min_size
   grows
               low_to_high high_to_low
   align
   fixed
   id
vector_table
   vector size
   size
   id_symbol_prefix
   run_addr
   template
   template symbol
   vector_prefix
   fill
   no_inline
   сору
   vector
      id
      fill loop
reserved
```

16.7.1. Setting up a Section

With the keyword section_setup you can define stacks, heaps, vector tables, and/or reserved address ranges outside their address space definition.

```
section_setup ::my_space
{
   vector table statements
   reserved address range
   stack definition
   heap definition
}
```

See the subsections Stacks and heaps, Vector table and Reserved address ranges in Section 16.4.3, *Defining Address Spaces* for details on the keywords stack, heap, vector_table and reserved.

16.8. Semantics of the Section Layout Definition

Keywords in the section layout definition

```
section_layout
   direction low_to_high high_to_low
group
   align
   attributes + - r w x b i s
   copy
```

```
nocopy
   fil1
   ordered
   contiguous
   clustered
   overlay
   allow_cross_references
   load addr
      mem
   run addr
      mem
   page
   page_size
   priority
select
stack
   size
heap
   size
reserved
   size
   attributes r w x
   fill
   alloc_allowed absolute
copytable
section
   size
   blocksize
   attributes r w x
   fill
   overflow
if
else
```

16.8.1. Defining a Section Layout

With the keyword section_layout you define a section layout for exactly one address space. In the section layout you can specify how input sections are placed in the address space, relative to each other, and what the absolute run and load addresses of each section will be.

You can define one or more section definitions. Each section definition arranges the sections in one address space. You can precede the address space name with a processor name and/or core name, separated by colons. You can omit the processor name and/or the core name if only one processor is defined and/or only one core is present in the processor. A reference to a space in the only core of the only processor in the system would look like "::my_space". A reference to a space of the only core on a specific processor in the system could be "my_chip::my_space". The next example shows a section definition for sections in the my_space address space of the processor called my_chip:

```
section_layout my_chip::my_space ( locate_direction )
{
```

```
section statements
}
```

With the optional keyword direction you specify whether the linker starts locating sections from low_to_high (default) or from high_to_low. In the second case the linker starts locating sections at the highest addresses in the address space but preserves the order of sections when necessary (one processor and core in this example).

```
section_layout ::my_space ( direction = high_to_low )
{
    section statements
}
```

If you do not explicitly tell the linker how to locate a section, the linker decides on the basis of the section attributes in the object file and the information in the architecture definition and memory parts where to locate the section.

16.8.2. Creating and Locating Groups of Sections

Sections are located per group. A group can contain one or more (sets of) input sections as well as other groups. Per group you can assign a mutual order to the sets of sections and locate them into a specific memory part.

```
group ( group_specifications )
{
    section_statements
}
```

With the <code>section_statements</code> you generally select sets of sections to form the group. This is described in subsection Selecting sections for a group.

Instead of selecting sections, you can also modify special sections like stack and heap or create a reserved section. This is described in Section 16.8.3, *Creating or Modifying Special Sections*.

With the group_specifications you actually locate the sections in the group. This is described in subsection Locating a group.

Selecting sections for a group

With the keyword select you can select one or more sections for the group. You can select a section by name or by attributes. If you select a section by name, you can use a wildcard pattern:

- * matches with all section names
- ? matches with a single character in the section name
- \ takes the next character literally
- [abc] matches with a single 'a', 'b' or 'c' character
- [a-z] matches with any single character in the range 'a' to 'z'

```
group ( ... )
{
    select "mysection";
    select "*";
}
```

The first select statement selects the section with the name "mysection". The second select statement selects all sections that were not selected yet.

A section is selected by the first select statement that matches, in the union of all section layouts for the address space. Global section layouts are processed in the order in which they appear in the LSL file. Internal core architecture section layouts always take precedence over global section layouts.

- The attributes field selects all sections that carry (or do not carry) the given attribute. With +attribute you select sections that have the specified attribute set. With -attribute you select sections that do not have the specified attribute set. You can specify one or more of the following attributes:
 - · r readable sections
 - w writable sections
 - x executable sections
 - i initialized sections
 - **b** sections that should be cleared at program startup
 - s scratch sections (not cleared and not initialized)

To select all read-only sections:

```
group ( ... )
{
    select (attributes = +r-w);
}
```

Keep in mind that all section selections are restricted to the address space of the section layout in which this group definition occurs.

- With the ref_tree field you can select a group of related sections. The relation between sections is often expressed by means of references. By selecting just the 'root' of tree, the complete tree is selected. This is for example useful to locate a group of related sections in special memory (e.g. fast memory). The (referenced) sections must meet the following conditions in order to be selected:
 - 1. The sections are within the section layout's address space
 - 2. The sections match the specified attributes
 - 3. The sections have no absolute restriction (as is the case for all wildcard selections)

For example, to select the code sections referenced from fool:

```
group refgrp (ordered, contiguous, run_addr=mem:ext_c)
{
    select ref_tree "foo1" (attributes=+x);
}
```

If section foo1 references foo2 and foo2 references foo3, then all these sections are selected by the selection shown above.

Locating a group

```
group group_name ( group_specifications )
{
    section_statements
}
```

With the <code>group_specifications</code> you actually define how the linker must locate the group. You can roughly define three things: 1) assign properties to the group like alignment and read/write attributes, 2) define the mutual order in the address space for sections in the group and 3) restrict the possible addresses for the sections in a group.

The linker creates labels that allow you to refer to the begin and end address of a group from within the application software. Labels _lc_gb_group_name and _lc_ge_group_name mark the begin and end of the group respectively, where the begin is the lowest address used within this group and the end is the highest address used. Notice that a group not necessarily occupies all memory between begin and end address. The given label refers to where the section is located at run-time (versus load-time).

1. Assign properties to the group like alignment and read/write attributes.

These properties are assigned to all sections in the group (and subgroups) and override the attributes of the input sections.

- The align field tells the linker to align all sections in the group and the group as a whole according to the align value. By default the linker uses the largest alignment constraint of either the input sections or the alignment of the address space.
- The attributes field tells the linker to assign one or more attributes to all sections in the group. This overrules the default attributes. By default the linker uses the attributes of the input sections. You can set the **r**, **w**, or **rw** attributes and you can switch between the **b** and **s** attributes.
- The **copy** field tells the linker to locate a read-only section in RAM and generate a ROM copy and a copy action in the copy table. This property makes the sections in the group writable which causes the linker to generate ROM copies for the sections.
- The effect of the nocopy field is the opposite of the copy field. It prevents the linker from generating ROM copies of the selected sections.
- 2. Define the mutual order of the sections in the group.

By default, a group is *unrestricted* which means that the linker has total freedom to place the sections of the group in the address space.

• The ordered keyword tells the linker to locate the sections in the same order in the address space as they appear in the group (but not necessarily adjacent).

Suppose you have an ordered group that contains the sections 'A', 'B' and 'C'. By default the linker places the sections in the address space like 'A' - 'B' - 'C', where section 'A' gets the lowest possible address. With direction=high_to_low in the section_layout space properties, the linker places the sections in the address space like 'C' - 'B' - 'A', where section 'A' gets the highest possible address.

• The contiguous keyword tells the linker to locate the sections in the group in a single address range. Within a contiguous group the input sections are located in arbitrary order, however the group occupies one contiguous range of memory. Due to alignment of sections there can be 'alignment gaps' between the sections.

When you define a group that is both ordered and contiguous, this is called a sequential group. In a sequential group the linker places sections in the same order in the address space as they appear in the group and it occupies a contiguous range of memory.

 The clustered keyword tells the linker to locate the sections in the group in a number of contiguous blocks. It tries to keep the number of these blocks to a minimum. If enough memory is available, the group will be located as if it was specified as contiguous. Otherwise, it gets split into two or more blocks.

If a contiguous or clustered group contains alignment gaps, the linker can locate sections that are not part of the group in these gaps. To prevent this, you can use the fill keyword. If the group is located in RAM, the gaps are treated as reserved (scratch) space. If the group is located in ROM, the alignment gaps are filled with zeros by default. You can however change the fill pattern by specifying a bit pattern. The result of the expression, or list of expressions, is used as values to write to memory, each in MAU.

The overlay keyword tells the linker to overlay the sections in the group. The linker places all
sections in the address space using a contiguous range of addresses. (Thus an overlay group is
automatically also a contiguous group.) To overlay the sections, all sections in the overlay group
share the same run-time address.

For each input section within the overlay the linker automatically defines two symbols. The symbol _lc_cb_section_name is defined as the load-time start address of the section. The symbol _lc_ce_section_name is defined as the load-time end address of the section. C (or assembly) code may be used to copy the overlaid sections.

If sections in the overlay group contain references between groups, the linker reports an error. The keyword allow_cross_references tells the linker to accept cross-references. Normally, it does not make sense to have references between sections that are overlaid.

```
group ovl (overlay)
{
    group a
    {
        select "my_ovl_p1";
        select "my_ovl_p2";
    }
```

```
group b
{
     select "my_ovl_q1";
}
```

It may be possible that one of the sections in the overlay group already has been defined in another group where it received a load-time address. In this case the linker does not overrule this load-time address and excludes the section from the overlay group.

3. Restrict the possible addresses for the sections in a group.

The load-time address specifies where the group's elements are loaded in memory at download time. The run-time address specifies where sections are located at run-time, that is when the program is executing. If you do not explicitly restrict the address in the LSL file, the linker assigns addresses to the sections based on the restrictions relative to other sections in the LSL file and section alignments. The program is responsible for copying overlay sections at appropriate moment from its load-time location to its run-time location (this is typically done by the startup code).

The run_addr keyword defines the run-time address. If the run-time location of a group is set
explicitly, the given order between groups specify whether the run-time address propagates to the
parent group or not. The location of the sections a group can be restricted either to a single absolute
address, or to a number of address ranges (not including the end address). With an expression you
can specify that the group should be located at the absolute address specified by the expression:

```
group (run_addr = 0xa00f0000)
```

You can use the '[offset]' variant to locate the group at the given absolute offset in memory:

```
group (run_addr = mem:A[0x1000])
```

A range can be an absolute space address range, written as <code>[expr .. expr]</code>, a complete memory device, written as <code>mem:mem_name</code>, or a memory address range, <code>mem:mem_name[expr .. expr]</code>

```
group (run_addr = mem:my_dram)
```

You can use the 'I' to specify an address range of more than one physical memory device:

```
group (run_addr = mem:A | mem:B)
```

 The load_addr keyword changes the meaning of the section selection in the group: the linker selects the load-time ROM copy of the named section(s) instead of the regular sections. Just like run_addr you can specify an absolute address or an address range.

The load-time and run-time addresses of a group cannot be set at the same time. If the load-time property is set for a group, the group (only) restricts the positioning at load-time of the group's sections. It is not possible to set the address of a group that has a not-unrestricted parent group.

The properties of the load-time and run-time start address are:

- At run-time, before using an element in an overlay group, the application copies the sections from their load location to their run-time location, but only if these two addresses are different. For non-overlay sections this happens at program start-up.
- The start addresses cannot be set to absolute values for unrestricted groups.
- For non-overlay groups that do not have an overlay parent, the load-time start address equals the run-time start address.
- For any group, if the run-time start address is not set, the linker selects an appropriate address.
- If an ordered group or sequential group has an absolute address and contains sections that have separate page restrictions (not defined in LSL), all those sections are located in a single page. In other cases, for example when an unrestricted group has an address range assigned to it, the paged sections may be located in different pages.

For overlays, the linker reserves memory at the run-time start address as large as the largest element in the overlay group.

The page keyword tells the linker to place the group in one page. Instead of specifying a run-time
address, you can specify a page and optional a page number. Page numbers start from zero. If you
omit the page number, the linker chooses a page.

The page keyword refers to pages in the address space as defined in the architecture definition.

- With the page_size keyword you can override the page alignment and size set on the address space. When you set the page size to zero, the linker removes simple (auto generated) page restrictions from the selected sections. See also the page_size keyword in Section 16.4.3, Defining Address Spaces.
- With the priority keyword you can change the order in which sections are located. This is useful
 when some sections are considered important for good performance of the application and a small
 amount of fast memory is available. The value is a number for which the default is 1, so higher
 priorities start at 2. Sections with a higher priority are located before sections with a lower priority,
 unless their relative locate priority is already determined by other restrictions like run_addr and
 page.

```
group (priority=2)
{
   select "importantcode1";
   select "importantcode2";
}
```

16.8.3. Creating or Modifying Special Sections

Instead of selecting sections, you can also create a reserved section or an output section or modify special sections like a stack or a heap. Because you cannot define these sections in the input files, you must use the linker to create them.

Stack

The keyword stack tells the linker to reserve memory for the stack. The name for the stack section
refers to the stack as defined in the architecture definition. If no name was specified in the architecture
definition, the default name is stack.

With the keyword size you can specify the size for the stack. If the size is not specified, the linker uses the size given by the min_size argument as defined for the stack in the architecture definition. Normally the linker automatically tries to maximize the size, unless you specified the keyword fixed.

```
group ( ... )
{
    stack "mystack" ( size = 2k );
}
```

The linker creates two labels to mark the begin and end of the stack, _lc_ub_stack_name for the begin of the stack and _lc_ue_stack_name for the end of the stack. The linker allocates space for the stack when there is a reference to either of the labels.

See also the stack keyword in Section 16.4.3, Defining Address Spaces.

Heap

• The keyword heap tells the linker to reserve a dynamic memory range for the malloc() function. Each heap section has a name. With the keyword size you can change the size for the heap. If the size is not specified, the linker uses the size given by the min_size argument as defined for the heap in the architecture definition. Normally the linker automatically tries to maximize the size, unless you specified the keyword fixed.

```
group ( ... )
{
    heap "myheap" ( size = 2k );
}
```

The linker creates two labels to mark the begin and end of the heap, _lc_ub_heap_name for the begin of the heap and _lc_ue_heap_name for the end of the heap. The linker allocates space for the heap when a reference to either of the section labels exists in one of the input object files.

Reserved section

The keyword reserved tells the linker to create an area or section of a given size. The linker will not
locate any other sections in the memory occupied by a reserved section, with some exceptions. Each
reserved section has a name. With the keyword size you can specify a size for a given reserved area
or section.

```
group ( ... )
{
   reserved "myreserved" ( size = 2k );
}
```

The optional fill field contains a bit pattern that the linker writes to all memory addresses that remain unoccupied during the locate process. The result of the expression, or list of expressions, is used as values to write to memory, each in MAU. The first MAU of the fill pattern is always the first MAU in the section.

By default, no sections can overlap with a reserved section. With alloc_allowed=absolute sections that are located at an absolute address due to an absolute group restriction can overlap a reserved section.

With the attributes field you can set the access type of the reserved section. The linker locates the reserved section in its space with the restrictions that follow from the used attributes, **r**, **w** or **x** or a valid combination of them. The allowed attributes are shown in the following table. A value between < and > in the table means this value is set automatically by the linker.

Properties set in LSL		Resulting section properties		
attributes	filled	access	memory	content
х	yes		<rom></rom>	executable
r	yes	r	<rom></rom>	data
r	no	r	<rom></rom>	scratch
rx	yes	r	<rom></rom>	executable
rw	yes	rw	<ram></ram>	data
rw	no	rw	<ram></ram>	scratch
rwx	yes	rw	<ram></ram>	executable

If you do not specify any attributes, the linker will reserve the given number of maus, no matter what type of memory lies beneath. If you do not specify a fill pattern, no section is generated.

The linker creates two labels to mark the begin and end of the section, _lc_ub_name for the begin of the section and _lc_ue_name for the end of the reserved section.

Output sections

The keyword section tells the linker to accumulate sections obtained from object files ("input sections")
into an output section of a fixed size in the locate phase. You can select the input sections with select
statements. You can use groups inside output sections, but you can only set the align, attributes
and load_addr attributes.

The fill field contains a bit pattern that the linker writes to all unused space in the output section. When all input sections have an image (code/data) you must specify a fill pattern. If you do not specify a fill pattern, all input sections must be scratch sections. The fill pattern is aligned at the start of the output section.

As with a reserved section you can use the attributes field to set the access type of the output section.

The available room for input sections is determined by the size, blocksize and overflow fields. With the keyword size you specify the fixed size of the output section. Input sections are placed from output section start towards higher addresses (offsets). When the end of the output section is reached and one or more input sections are not yet placed, an error is emitted. If however, the overflow field is set to another output section, remaining sections are located as if they were selected for the overflow output section.

With the keyword blocksize, the size of the output section will adapt to the size of its content. For example:

```
select "*.flash";
}
```

If the content of the section is 1 mau, the size will be 4 kB, if the content is 11 kB, the section will be 12 kB, etc. If you use size in combination with blocksize, the size value is used as default (minimal) size for this section. If it is omitted, the default size will be of blocksize. It is not allowed to omit both size and blocksize from the section definition.

The linker creates two labels to mark the begin and end of the section, _lc_ub_name for the begin of the section and _lc_ue_name for the end of the output section.

Copy table

The keyword copytable tells the linker to select a section that is used as copy table. The content of
the copy table is created by the linker. It contains the start address and length of all sections that should
be initialized by the startup code.

The linker creates two labels to mark the begin and end of the section, _lc_ub_table for the begin of the section and _lc_ue_table for the end of the copy table. The linker generates a copy table when a reference to either of the section labels exists in one of the input object files.

16.8.4. Creating Symbols

You can tell the linker to create symbols before locating by putting assignments in the section layout definition. Symbol names are represented by double-quoted strings. Any string is allowed, but object files may not support all characters for symbol names. You can use two different assignment operators. With the simple assignment operator '=', the symbol is created unconditionally. With the ':=' operator, the symbol is only created if it already exists as an undefined reference in an object file.

The expression that represents the value to assign to the symbol may contain references to other symbols. If such a referred symbol is a special section symbol, creation of the symbol in the left hand side of the assignment will cause creation of the special section.

```
section_layout
{
    "_lc_bs" := "_lc_ub_stack";
    // when the symbol _lc_bs occurs as an undefined reference
    // in an object file, the linker allocates space for the stack
}
```

16.8.5. Conditional Group Statements

Within a group, you can conditionally select sections or create special sections.

- With the if keyword you can specify a condition. The succeeding section statement is executed if the condition evaluates to TRUE (1).
- The optional else keyword is followed by a section statement which is executed in case the if-condition evaluates to FALSE (0).

```
group ( ... )
{
   if ( exists( "mysection" ) )
      select "mysection";
   else
      reserved "myreserved" ( size=2k );
}
```

Chapter 17. Debug Target Configuration Files

DTC files (Debug Target Configuration files) define all possible configurations for a debug target. A debug target can be target hardware such as an evaluation board or a simulator. The DTC files are used by Eclipse to configure the project and the debugger. The information is used by the Target Board Configuration wizard and the debug configuration. DTC files are located in the etc directory of the installed product and use .dtc as filename suffix.

Based on the DTC files, the Target Board Configuration wizard adjust the project's LSL file and creates a debug launch configuration.

17.1. Custom Board Support

When you need support for a custom board and the board requires a different configuration than those that are in the product, it is necessary to create a dedicated DTC file.

To add a custom board

1. From the etc directory of the product, make a copy of a .dtc file and put it in your project directory (in the current workspace).

In Eclipse, the DTC file should now be visible as part of your project.

2. Edit the file and give it a name that reflects the custom board.

The Target Board Configuration wizard in Eclipse adds DTC files that are present in your current project to the list of available target boards.

Syntax of a DTC file

DTC files are XML files. Use a delivered . dtc file as a starting point for creating a custom board specification.

Basically a DTC file consists of the definition of the debug target (debugTarget element) which embodies one or more communication methods (communicationMethod element). Within each communication method, you can define multiple configurations (configuration element). The Target Board Configuration wizard in Eclipse reflects the structure of the DTC file. The elements that determine the settings that are applied by the wizard, can be found at any level in the DTC file. The wizard will apply all elements that are within the path to the selected configuration. This is best explained by an example of a DTC file with the following basic layout:

```
debugTarget: JLINK ARM
lsl
communicationMethod: DAS over MiniWigglerII
lsl
configuration: Single Chip
lsl
communicationMethod: DAS over USB-Wiggler
lsl
configuration: Single Chip
```

lsl

lsl

In this example there is an LSL element at every level. If, in the Target Board Configuration wizard in Eclipse, you set the debug target configuration to "DAS over MiniWigglerII" -> "Single Chip", the wizard puts the following LSL parts into the project's LSL file in this order:

- the Isl part under the debugTarget element
- the Isl part under the communicationMethod "DAS over MiniWigglerII" element
- the IsI part under the configuration "Single Chip" in the communicationMethod "DAS over MiniWigglerII" element
- the Isl part in the debugTarget element at the end of the DTC file

The same applies to all other elements that determine the underlying settings.

DTC macros in LSL

To protect the Target Board Configuration wizard from changing the LSL file, you can protect the LSL file by adding the macro __DTC_IGNORE. This can be useful for projects that need the same LSL file, but still need to run on different target boards.

#define __DTC_IGNORE

The following DTC macros can be present in the LSL file:

LSL Define	Description
	If defined, protects the LSL file against changes by the Target Board Configuration wizard.
DTC_START DTC_END	The LSL part that is between these macros can be replaced by LSL text from the DTC file. If the macros are not present in the LSL file, the Target Board Configuration wizard will add them.

17.2. Description of DTC Elements and Attributes

The following table contains a description of the DTC elements and attributes. For each element a list of allowed elements is listed and the available attributes are described.

Element / Attribute	Description	Allowed Elements
debugTarget	The debug target.	flashChips, lsl, communicationMethod, def, processor, resource, initialize
name	The name of the configuration.	
manufacturer	The manufacturer of the debug target.	
processor	Defines a processor that can be present on the debug target. Multiple processor definitions are allowed. The user should select the actual processor on the debug target.	

Element / Attribute	Description	Allowed Elements	
name	A descriptive name of the processor derivative.		
сри	Defines the CPU name, as for example supplied with the optioncpu of the C compiler.		
communicationMethod	Defines a communication method. A communication method is the channel that is used to communicate with the target.	ref, resource, initialize, configuration, IsI, processor	
name	A descriptive name of the communication method.		
debugInstrument	The debug instrument DLL/Shared library file to be used for this communication method. Do not supply a path or a filename suffix.		
gdiMethod	This is the method used for communication. Allowed values: rs232, tcpip, can, none		
def	Define a set of elements as a macro. The macro can be expanded using the ref element.	Isl, resource, initialize, ref, configuration, flashMonitor	
id	The macro name.		
resource	Defines a resource definition that can be used by Eclipse, the debugger or by the debug instrument.	-	
id	The identifier name used by the debugger or debug instrument to retrieve the value.		
value	The value assigned to the resource.		
ref	Reference to a macro defined with a def element. The elements contained in the def element with the same name will be expanded at the location of the ref. Multiple refs to the same def are allowed.	-	
id	The name of the referenced macro.		
configuration	Defines a configuration.	ref, initialize, resource,	
name	The descriptive name of the configuration.	IsI, flashMonitor, processor	
initialize	This element defines an initialization expression. Each initialize element contains a resourceId attribute. If the DI requests this resource the debugger will compose a string from all initialize elements with the same resourceId. This DI can use this string to initialize registers by passing it to the debugger as an expression to be evaluated.		
resourceId	The name of the resource to be used.		

Element / Attribute	Description	Allowed Elements
name	The name of the register to be initialized.	
value	When the cstart attribute is false, this is the value to be used, otherwise, it is the default value when using this configuration. It will be used by the startup code editor to set the default register values.	
cstart	A boolean value. If true the debugger should ask the C startup code editor for the value, otherwise the contents of the value attribute is used. The default value is true.	
flashMonitor	This element specifies the flash programming monitor to be used for this configuration.	-
monitor	Filename of the monitor, usually an Intel Hex or S-Record file.	
workspaceAddress	The address of the workspace of the flash programming monitor.	
flashSectorBufferSize	Specifies the buffer size for buffering a flash sector.	
chip	This element defines a flash chip. It must be used by the flash properties page to add it on request to the list of flash chips.	debugTarget
vendor	The vendor of this flash chip.	
chip	The name of the chip.	
width	The width of the chip in bits.	
chips	The number of chips present on the board.	
baseAddress	The base address of the chip.	
chipSize	The size of the chip in bytes.	
flashChips	Specify a list of flash chips that can be available on this debug target.	chip
lsl	Defines LSL pieces belonging to the configuration part. The LSL text must be defined between the start and end tag of this element. All LSL texts of the active selection will be placed in the project's LSL file.	-

17.3. Special Resource Identifiers

The following resource IDs are available in the TASKING VX-toolset for ARM:

DAS debug instrument (DI): gdi2das

Resource Name	Description	Possible Values
AccessPort	The port used to connect to the wiggler.	JTAG1, USB0
DASserver	The DAS Server used for communication.	JTAG JDRV LPT JTAG over USB Box JTAG over USB Chip
DasTimeOut	The timeout value for communication with the DAS server in milliseconds. The default is 0x4000.	
RegisterFile	The core register file that is used by the debug instrument. This is usually "regbase_f7e1.dat" or "regbase_ffff.dat", depending on the register base address.	
TerminateServer	Terminate the DAS server when the session is closed.	0, 1

17.4. Initialize Elements

The initialize elements are used to initialize SFRs at startup. This is also done using a resource of the debug instrument. The following resource Ids exist for the DAS debug instrument (gdi2das):

Resource Name	Description	
einit	Initialize an SFR that is protected with the ENDINIT flag.	
init	Initialize an SFR that is not protected with the ENDINIT flag.	

Chapter 18. MISRA-C Rules

This chapter contains an overview of the supported and unsupported MISRA C rules.

18.1. MISRA-C:1998

This section lists all supported and unsupported MISRA-C:1998 rules.

See also Section 4.6, C Code Checking: MISRA-C.

A number of MISRA-C rules leave room for interpretation. Other rules can only be checked in a limited way. In such cases the implementation decisions and possible restrictions for these rules are listed.

x means that the rule is not supported by the TASKING C compiler. (R) is a required rule, (A) is an advisory rule.

- 1. (R) The code shall conform to standard C, without language extensions
- x 2. (A) Other languages should only be used with an interface standard
 - 3. (A) Inline assembly is only allowed in dedicated C functions
- (A) Provision should be made for appropriate run-time checking
 - 5. (R) Only use characters and escape sequences defined by ISO C
- (R) Character values shall be restricted to a subset of ISO 106460-1
 - 7. (R) Trigraphs shall not be used
 - 8. (R) Multibyte characters and wide string literals shall not be used
 - 9. (R) Comments shall not be nested
 - 10. (A) Sections of code should not be "commented out"

In general, it is not possible to decide whether a piece of comment is C code that is commented out, or just some pseudo code. Instead, the following heuristics are used to detect possible C code inside a comment:

- · a line ends with ';', or
- a line starts with '}', possibly preceded by white space
- 11. (R) Identifiers shall not rely on significance of more than 31 characters
- 12. (A) The same identifier shall not be used in multiple name spaces
- 13. (A) Specific-length typedefs should be used instead of the basic types
- 14. (R) Use 'unsigned char' or 'signed char' instead of plain 'char'
- x 15. (A) Floating-point implementations should comply with a standard
 - 16. (R) The bit representation of floating-point numbers shall not be used A violation is reported when a pointer to a floating-point type is converted to a pointer to an integer type.
 - 17. (R) "typedef" names shall not be reused

	18.	(A)	Numeric constants should be suffixed to indicate type A violation is reported when the value of the constant is outside the range indicated by the suffixes, if any.
	19.	(R)	Octal constants (other than zero) shall not be used
	20.	(R)	All object and function identifiers shall be declared before use
	21.	(R)	Identifiers shall not hide identifiers in an outer scope
	22.	(A)	Declarations should be at function scope where possible
x	23.	(A)	All declarations at file scope should be static where possible
	24.	(R)	Identifiers shall not have both internal and external linkage
x	25.	(R)	Identifiers with external linkage shall have exactly one definition
	26.	(R)	Multiple declarations for objects or functions shall be compatible
x	27.	(A)	External objects should not be declared in more than one file
	28.	(A)	The "register" storage class specifier should not be used
	29.	(R)	The use of a tag shall agree with its declaration
	30.	(R)	All automatics shall be initialized before being used This rule is checked using worst-case assumptions. This means that violations are reported not only for variables that are guaranteed to be uninitialized, but also for variables that are uninitialized on some execution paths.
	31.	(R)	Braces shall be used in the initialization of arrays and structures
	32.	(R)	Only the first, or all enumeration constants may be initialized
	33.	(R)	The right hand operand of && or shall not contain side effects
	34.	(R)	The operands of a logical && or shall be primary expressions
	35.	(R)	Assignment operators shall not be used in Boolean expressions
	36.	(A)	Logical operators should not be confused with bitwise operators
	37.	(R)	Bitwise operations shall not be performed on signed integers
	38.	(R)	A shift count shall be between 0 and the operand width minus 1 This violation will only be checked when the shift count evaluates to a constant value at compile time.
	39.	(R)	The unary minus shall not be applied to an unsigned expression
	40.	(A)	"sizeof" should not be used on expressions with side effects
x	41.	(A)	The implementation of integer division should be documented
	42.	(R)	The comma operator shall only be used in a "for" condition
	43.	(R)	Don't use implicit conversions which may result in information loss
	44.	(A)	Redundant explicit casts should not be used
	45.	(R)	Type casting from any type to or from pointers shall not be used
	46.	(R)	The value of an expression shall be evaluation order independent This rule is checked using worst-case assumptions. This means that a violation will be reported when a possible alias may cause the result of an expression to be evaluation order dependent.
	47.	(A)	No dependence should be placed on operator precedence rules

- 48. (A) Mixed arithmetic should use explicit casting
- 49. (A) Tests of a (non-Boolean) value against 0 should be made explicit
- 50. (R) F.P. variables shall not be tested for exact equality or inequality
- 51. (A) Constant unsigned integer expressions should not wrap-around
- 52. (R) There shall be no unreachable code
- 53. (R) All non-null statements shall have a side-effect
- 54. (R) A null statement shall only occur on a line by itself
- 55. (A) Labels should not be used
- 56. (R) The "goto" statement shall not be used
- 57. (R) The "continue" statement shall not be used
- 58. (R) The "break" statement shall not be used (except in a "switch")
- 59. (R) An "if" or loop body shall always be enclosed in braces
- 60. (A) All "if", "else if" constructs should contain a final "else"
- 61. (R) Every non-empty "case" clause shall be terminated with a "break"
- 62. (R) All "switch" statements should contain a final "default" case
- 63. (A) A "switch" expression should not represent a Boolean case
- 64. (R) Every "switch" shall have at least one "case"
- 65. (R) Floating-point variables shall not be used as loop counters
- 66. (A) A "for" should only contain expressions concerning loop control A violation is reported when the loop initialization or loop update expression modifies an object that is not referenced in the loop test.
- 67. (A) Iterator variables should not be modified in a "for" loop
- 68. (R) Functions shall always be declared at file scope
- 69. (R) Functions with variable number of arguments shall not be used
- 70. (R) Functions shall not call themselves, either directly or indirectly A violation will be reported for direct or indirect recursive function calls in the source file being checked. Recursion via functions in other source files, or recursion via function pointers is not detected.
- 71. (R) Function prototypes shall be visible at the definition and call
- 72. (R) The function prototype of the declaration shall match the definition
- 73. (R) Identifiers shall be given for all prototype parameters or for none
- 74. (R) Parameter identifiers shall be identical for declaration/definition
- 75. (R) Every function shall have an explicit return type
- 76. (R) Functions with no parameters shall have a "void" parameter list
- 77. (R) An actual parameter type shall be compatible with the prototype
- 78. (R) The number of actual parameters shall match the prototype
- 79. (R) The values returned by "void" functions shall not be used
- 80. (R) Void expressions shall not be passed as function parameters

81.	(A)	"const" should be used for reference parameters not modified
82.	(A)	A function should have a single point of exit
83.	(R)	Every exit point shall have a "return" of the declared return type
84.	(R)	For "void" functions, "return" shall not have an expression
85.	(A)	Function calls with no parameters should have empty parentheses
86.	(A)	If a function returns error information, it should be tested A violation is reported when the return value of a function is ignored.
87.	(R)	#include shall only be preceded by other directives or comments
88.	(R)	Non-standard characters shall not occur in #include directives
89.	(R)	#include shall be followed by either <filename> or "filename"</filename>
90.	(R)	Plain macros shall only be used for constants/qualifiers/specifiers
91.	(R)	Macros shall not be #define'd and #undef'd within a block
92.	(A)	#undef should not be used
93.	(A)	A function should be used in preference to a function-like macro
94.	(R)	A function-like macro shall not be used without all arguments
95.	(R)	Macro arguments shall not contain pre-preprocessing directives A violation is reported when the first token of an actual macro argument is '#'.
96.	(R)	Macro definitions/parameters should be enclosed in parentheses
97.	(A)	Don't use undefined identifiers in pre-processing directives
98.	(R)	A macro definition shall contain at most one # or ## operator
99.	(R)	All uses of the #pragma directive shall be documented This rule is really a documentation issue. The compiler will flag all #pragma directives as violations.
100.	(R)	"defined" shall only be used in one of the two standard forms
101.	(A)	Pointer arithmetic should not be used
102.	(A)	No more than 2 levels of pointer indirection should be used A violation is reported when a pointer with three or more levels of indirection is declared.
103.	(R)	No relational operators between pointers to different objects In general, checking whether two pointers point to the same object is impossible. The compiler will only report a violation for a relational operation with incompatible pointer types.
104.	(R)	Non-constant pointers to functions shall not be used
105.	(R)	Functions assigned to the same pointer shall be of identical type
106.	(R)	Automatic address may not be assigned to a longer lived object
107.	(R)	The null pointer shall not be de-referenced A violation is reported for every pointer dereference that is not guarded by a NULL pointer test.
108	(R)	All struct/union members shall be fully specified

	109.	(R)	Overlapping variable storage shall not be used A violation is reported for every 'union' declaration.
	110.	(R)	Unions shall not be used to access the sub-parts of larger types A violation is reported for a 'union' containing a 'struct' member.
	111.	(R)	bit-fields shall have type "unsigned int" or "signed int"
	112.	(R)	bit-fields of type "signed int" shall be at least 2 bits long
	113.	(R)	All struct/union members shall be named
	114.	(R)	Reserved and standard library names shall not be redefined
	115.	(R)	Standard library function names shall not be reused
x	116.	(R)	Production libraries shall comply with the MISRA C restrictions
x	117.	(R)	The validity of library function parameters shall be checked
	118.	(R)	Dynamic heap memory allocation shall not be used
	119.	(R)	The error indicator "errno" shall not be used
	120.	(R)	The macro "offsetof" shall not be used
	121.	(R)	<locale.h> and the "setlocale" function shall not be used</locale.h>
	122.	(R)	The "setjmp" and "longjmp" functions shall not be used
	123.	(R)	The signal handling facilities of <signal.h> shall not be used</signal.h>
	124.	(R)	The <stdio.h> library shall not be used in production code</stdio.h>
	125.	(R)	The functions atof/atoi/atol shall not be used

18.2. MISRA-C:2004

(R)

This section lists all supported and unsupported MISRA-C:2004 rules.

See also Section 4.6, C Code Checking: MISRA-C.

A number of MISRA-C rules leave room for interpretation. Other rules can only be checked in a limited way. In such cases the implementation decisions and possible restrictions for these rules are listed.

The functions abort/exit/getenv/system shall not be used

The time handling functions of library <time.h> shall not be used

x means that the rule is not supported by the TASKING C compiler. (R) is a required rule, (A) is an advisory rule.

Environment

126.

127. (R)

- 1.1 (R) All code shall conform to ISO 9899:1990 "Programming languages - C", amended and corrected by ISO/IEC 9899/COR1:1995, ISO/IEC 9899/AMD1:1995, and ISO/IEC 9899/COR2:1996.
- 1.2 (R) No reliance shall be placed on undefined or unspecified behavior.

- x 1.3 (R) Multiple compilers and/or languages shall only be used if there is a common defined interface standard for object code to which the languages/compilers/assemblers conform.
- x 1.4 (R) The compiler/linker shall be checked to ensure that 31 character significance and case sensitivity are supported for external identifiers.
- x 1.5 (A) Floating-point implementations should comply with a defined floating-point standard.

Language extensions

- 2.1 (R) Assembly language shall be encapsulated and isolated.
- 2.2 (R) Source code shall only use /* ... */ style comments.
- 2.3 (R) The character sequence /* shall not be used within a comment.
- 2.4 (A) Sections of code should not be "commented out". In general, it is not possible to decide whether a piece of comment is C code that is commented out, or just some pseudo code. Instead, the following heuristics are used to detect possible C code inside a comment: a line ends with ';', or a line starts with '}', possibly preceded by white space

Documentation

- x 3.1 (R) All usage of implementation-defined behavior shall be documented.
- x 3.2 (R) The character set and the corresponding encoding shall be documented.
- x 3.3 (A) The implementation of integer division in the chosen compiler should be determined, documented and taken into account.
 - 3.4 (R) All uses of the #pragma directive shall be documented and explained. This rule is really a documentation issue. The compiler will flag all #pragma directives as violations.
 - 3.5 (R) The implementation-defined behavior and packing of bit-fields shall be documented if being relied upon.
- x 3.6 (R) All libraries used in production code shall be written to comply with the provisions of this document, and shall have been subject to appropriate validation.

Character sets

- 4.1 (R) Only those escape sequences that are defined in the ISO C standard shall be used.
- 4.2 (R) Trigraphs shall not be used.

Identifiers

- 5.1 (R) Identifiers (internal and external) shall not rely on the significance of more than 31 characters.
- 5.2 (R) Identifiers in an inner scope shall not use the same name as an identifier in an outer scope, and therefore hide that identifier.

- 5.3 (R) A typedef name shall be a unique identifier.
- 5.4 (R) A tag name shall be a unique identifier.
- x 5.5 (A) No object or function identifier with static storage duration should be reused.
 - 5.6 (A) No identifier in one name space should have the same spelling as an identifier in another name space, with the exception of structure and union member names.
- x 5.7 (A) No identifier name should be reused.

Types

- 6.1 (R) The plain char type shall be used only for storage and use of character values.
- x 6.2 (R) signed and unsigned char type shall be used only for the storage and use of numeric values.
 - 6.3 (A) typedefs that indicate size and signedness should be used in place of the basic types.
 - 6.4 (R) bit-fields shall only be defined to be of type unsigned int or signed int.
 - 6.5 (R) bit-fields of type signed int shall be at least 2 bits long.

Constants

7.1 (R) Octal constants (other than zero) and octal escape sequences shall not be used.

Declarations and definitions

- 8.1 (R) Functions shall have prototype declarations and the prototype shall be visible at both the function definition and call.
- 8.2 (R) Whenever an object or function is declared or defined, its type shall be explicitly stated.
- 8.3 (R) For each function parameter the type given in the declaration and definition shall be identical, and the return types shall also be identical.
- 8.4 (R) If objects or functions are declared more than once their types shall be compatible.
- 8.5 (R) There shall be no definitions of objects or functions in a header file.
- 8.6 (R) Functions shall be declared at file scope.
- 8.7 (R) Objects shall be defined at block scope if they are only accessed from within a single function.
- x 8.8 (R) An external object or function shall be declared in one and only one file.
- x 8.9 (R) An identifier with external linkage shall have exactly one external definition.
- x 8.10 (R) All declarations and definitions of objects or functions at file scope shall have internal linkage unless external linkage is required.
 - 8.11 (R) The static storage class specifier shall be used in definitions and declarations of objects and functions that have internal linkage.

8.12 (R) When an array is declared with external linkage, its size shall be stated explicitly or defined implicitly by initialization.

Initialization

- 9.1 (R) All automatic variables shall have been assigned a value before being used. This rule is checked using worst-case assumptions. This means that violations are reported not only for variables that are guaranteed to be uninitialized, but also for variables that are uninitialized on some execution paths.
- 9.2 (R) Braces shall be used to indicate and match the structure in the non-zero initialization of arrays and structures.
- 9.3 (R) In an enumerator list, the "=" construct shall not be used to explicitly initialize members other than the first, unless all items are explicitly initialized.

Arithmetic type conversions

- 10.1 (R) The value of an expression of integer type shall not be implicitly converted to a different underlying type if:
 - a) it is not a conversion to a wider integer type of the same signedness, or
 - b) the expression is complex, or
 - c) the expression is not constant and is a function argument, or
 - d) the expression is not constant and is a return expression.
- 10.2 (R) The value of an expression of floating type shall not be implicitly converted to a different type if:
 - a) it is not a conversion to a wider floating type, or
 - b) the expression is complex, or
 - c) the expression is a function argument, or
 - d) the expression is a return expression.
- 10.3 (R) The value of a complex expression of integer type may only be cast to a type that is narrower and of the same signedness as the underlying type of the expression.
- 10.4 (R) The value of a complex expression of floating type may only be cast to a narrower floating type.
- 10.5 (R) If the bitwise operators ~ and << are applied to an operand of underlying type unsigned char or unsigned short, the result shall be immediately cast to the underlying type of the operand.
- 10.6 (R) A "U" suffix shall be applied to all constants of unsigned type.

Pointer type conversions

- 11.1 (R) Conversions shall not be performed between a pointer to a function and any type other than an integral type.
- 11.2 (R) Conversions shall not be performed between a pointer to object and any type other than an integral type, another pointer to object type or a pointer to void.
- 11.3 (A) A cast should not be performed between a pointer type and an integral type.

- 11.4 (A) A cast should not be performed between a pointer to object type and a different pointer to object type.
- 11.5 (R) A cast shall not be performed that removes any const or volatile qualification from the type addressed by a pointer.

Expressions

- 12.1 (A) Limited dependence should be placed on C's operator precedence rules in expressions.
- 12.2 (R) The value of an expression shall be the same under any order of evaluation that the standard permits. This rule is checked using worst-case assumptions. This means that a violation will be reported when a possible alias may cause the result of an expression to be evaluation order dependent.
- 12.3 (R) The sizeof operator shall not be used on expressions that contain side effects.
- 12.4 (R) The right-hand operand of a logical && or | | operator shall not contain side effects.
- 12.5 (R) The operands of a logical && or | | shall be *primary-expressions*.
- 12.6 (A) The operands of logical operators (&&, | | and !) should be effectively Boolean. Expressions that are effectively Boolean should not be used as operands to operators other than (&&, | | and !).
- 12.7 (R) Bitwise operators shall not be applied to operands whose underlying type is signed.
- 12.8 (R) The right-hand operand of a shift operator shall lie between zero and one less than the width in bits of the underlying type of the left-hand operand. This violation will only be checked when the shift count evaluates to a constant value at compile time.
- 12.9 (R) The unary minus operator shall not be applied to an expression whose underlying type is unsigned.
- 12.10 (R) The comma operator shall not be used.
- 12.11 (A) Evaluation of constant unsigned integer expressions should not lead to wrap-around.
- 12.12 (R) The underlying bit representations of floating-point values shall not be used. A violation is reported when a pointer to a floating-point type is converted to a pointer to an integer type.
- 12.13 (A) The increment (++) and decrement (--) operators should not be mixed with other operators in an expression.

Control statement expressions

- 13.1 (R) Assignment operators shall not be used in expressions that yield a Boolean value.
- 13.2 (A) Tests of a value against zero should be made explicit, unless the operand is effectively Boolean.
- 13.3 (R) Floating-point expressions shall not be tested for equality or inequality.
- 13.4 (R) The controlling expression of a for statement shall not contain any objects of floating type.

- 13.5 (R) The three expressions of a for statement shall be concerned only with loop control. A violation is reported when the loop initialization or loop update expression modifies an object that is not referenced in the loop test.
- 13.6 (R) Numeric variables being used within a for loop for iteration counting shall not be modified in the body of the loop.
- 13.7 (R) Boolean operations whose results are invariant shall not be permitted.

Control flow

- 14.1 (R) There shall be no unreachable code.
- 14.2 (R) All non-null statements shall either:
 - a) have at least one side effect however executed, or
 - b) cause control flow to change.
- 14.3 (R) Before preprocessing, a null statement shall only occur on a line by itself; it may be followed by a comment provided that the first character following the null statement is a white-space character.
- 14.4 (R) The goto statement shall not be used.
- 14.5 (R) The continue statement shall not be used.
- 14.6 (R) For any iteration statement there shall be at most one break statement used for loop termination.
- 14.7 (R) A function shall have a single point of exit at the end of the function.
- 14.8 (R) The statement forming the body of a switch, while, do ... while or for statement be a compound statement.
- 14.9 (R) An if (expression) construct shall be followed by a compound statement. The else keyword shall be followed by either a compound statement, or another if statement.
- 14.10 (R) All if ... else if constructs shall be terminated with an else clause.

Switch statements

- 15.1 (R) A switch label shall only be used when the most closely-enclosing compound statement is the body of a switch statement.
- 15.2 (R) An unconditional break statement shall terminate every non-empty switch clause.
- 15.3 (R) The final clause of a switch statement shall be the default clause.
- 15.4 (R) A switch expression shall not represent a value that is effectively Boolean.
- 15.5 (R) Every switch statement shall have at least one case clause.

Functions

16.1 (R) Functions shall not be defined with variable numbers of arguments.

- 16.2 (R) Functions shall not call themselves, either directly or indirectly. A violation will be reported for direct or indirect recursive function calls in the source file being checked. Recursion via functions in other source files, or recursion via function pointers is not detected.
- 16.3 (R) Identifiers shall be given for all of the parameters in a function prototype declaration.
- 16.4 (R) The identifiers used in the declaration and definition of a function shall be identical.
- 16.5 (R) Functions with no parameters shall be declared with parameter type void.
- 16.6 (R) The number of arguments passed to a function shall match the number of parameters.
- 16.7 (A) A pointer parameter in a function prototype should be declared as pointer to const if the pointer is not used to modify the addressed object.
- 16.8 (R) All exit paths from a function with non-void return type shall have an explicit return statement with an expression.
- 16.9 (R) A function identifier shall only be used with either a preceding &, or with a parenthesized parameter list, which may be empty.
- 16.10 (R) If a function returns error information, then that error information shall be tested. A violation is reported when the return value of a function is ignored.

Pointers and arrays

- x 17.1 (R) Pointer arithmetic shall only be applied to pointers that address an array or array element.
- x 17.2 (R) Pointer subtraction shall only be applied to pointers that address elements of the same array.
 - 17.3 (R) >, >=, <, <= shall not be applied to pointer types except where they point to the same array. In general, checking whether two pointers point to the same object is impossible. The compiler will only report a violation for a relational operation with incompatible pointer types.
 - 17.4 (R) Array indexing shall be the only allowed form of pointer arithmetic.
 - 17.5 (A) The declaration of objects should contain no more than 2 levels of pointer indirection. A violation is reported when a pointer with three or more levels of indirection is declared.
 - 17.6 (R) The address of an object with automatic storage shall not be assigned to another object that may persist after the first object has ceased to exist.

Structures and unions

- 18.1 (R) All structure or union types shall be complete at the end of a translation unit.
- 18.2 (R) An object shall not be assigned to an overlapping object.
- x 18.3 (R) An area of memory shall not be reused for unrelated purposes.
 - 18.4 (R) Unions shall not be used.

Preprocessing directives

- 19.1 (A) #include statements in a file should only be preceded by other preprocessor directives or comments.
- 19.2 (A) Non-standard characters should not occur in header file names in #include directives.
- x 19.3 (R) The #include directive shall be followed by either a <filename> or "filename" sequence.
 - 19.4 (R) C macros shall only expand to a braced initializer, a constant, a parenthesized expression, a type qualifier, a storage class specifier, or a do-while-zero construct.
 - 19.5 (R) Macros shall not be #define'd or #undef'd within a block.
 - 19.6 (R) #undef shall not be used.
 - 19.7 (A) A function should be used in preference to a function-like macro.
 - 19.8 (R) A function-like macro shall not be invoked without all of its arguments.
 - 19.9 (R) Arguments to a function-like macro shall not contain tokens that look like preprocessing directives. A violation is reported when the first token of an actual macro argument is '#'.
 - 19.10 (R) In the definition of a function-like macro each instance of a parameter shall be enclosed in parentheses unless it is used as the operand of # or ##.
 - 19.11 (R) All macro identifiers in preprocessor directives shall be defined before use, except in #ifdef and #ifndef preprocessor directives and the defined() operator.
 - 19.12 (R) There shall be at most one occurrence of the # or ## preprocessor operators in a single macro definition.
 - 19.13 (A) The # and ## preprocessor operators should not be used.
 - 19.14 (R) The defined preprocessor operator shall only be used in one of the two standard forms.
 - 19.15 (R) Precautions shall be taken in order to prevent the contents of a header file being included twice.
 - 19.16 (R) Preprocessing directives shall be syntactically meaningful even when excluded by the preprocessor.
 - 19.17 (R) All #else, #elif and #endif preprocessor directives shall reside in the same file as the #if or #ifdef directive to which they are related.

Standard libraries

- 20.1 (R) Reserved identifiers, macros and functions in the standard library, shall not be defined, redefined or undefined.
- 20.2 (R) The names of standard library macros, objects and functions shall not be reused.
- x 20.3 (R) The validity of values passed to library functions shall be checked.
 - 20.4 (R) Dynamic heap memory allocation shall not be used.
 - 20.5 (R) The error indicator errno shall not be used.

- 20.6 (R) The macro offsetof, in library <stddef.h>, shall not be used.
- 20.7 (R) The setjmp macro and the longjmp function shall not be used.
- 20.8 (R) The signal handling facilities of <signal.h> shall not be used.
- 20.9 (R) The input/output library <stdio.h> shall not be used in production code.
- 20.10 (R) The library functions atof, atoi and atol from library <stdlib.h> shall not be used.
- 20.11 (R) The library functions abort, exit, getenv and system from library <stdlib.h> shall not be used.
- 20.12 (R) The time handling functions of library <time.h> shall not be used.

Run-time failures

- x 21.1 (R) Minimization of run-time failures shall be ensured by the use of at least one of:
 - a) static analysis tools/techniques;
 - b) dynamic analysis tools/techniques;
 - c) explicit coding of checks to handle run-time faults.